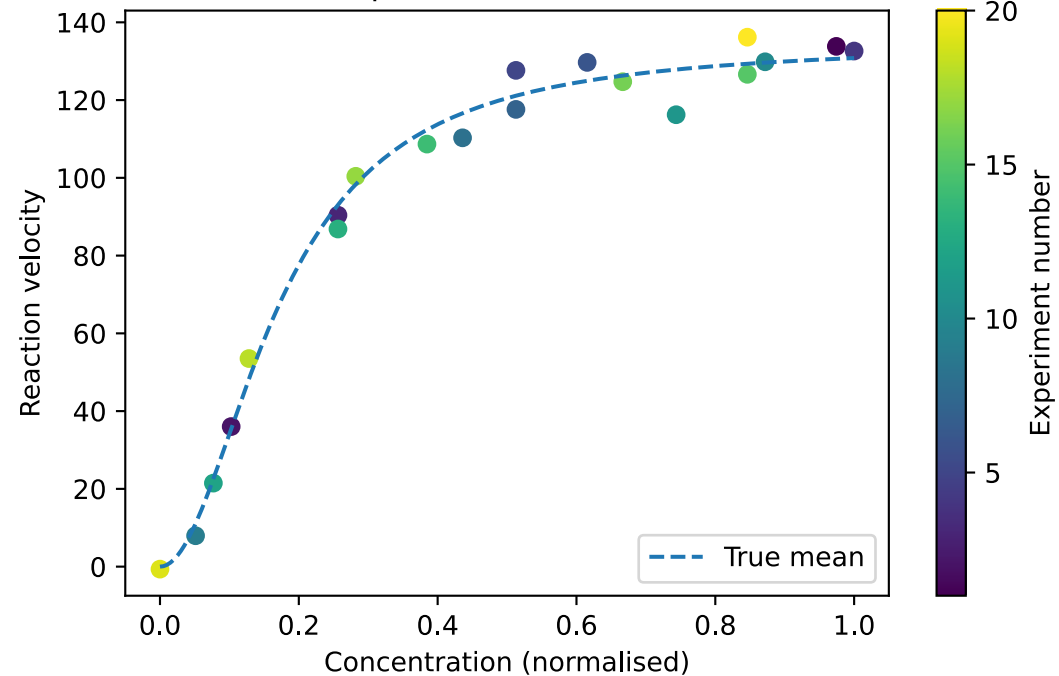


Experiments (s = 2.0)



Information gains and model probability

