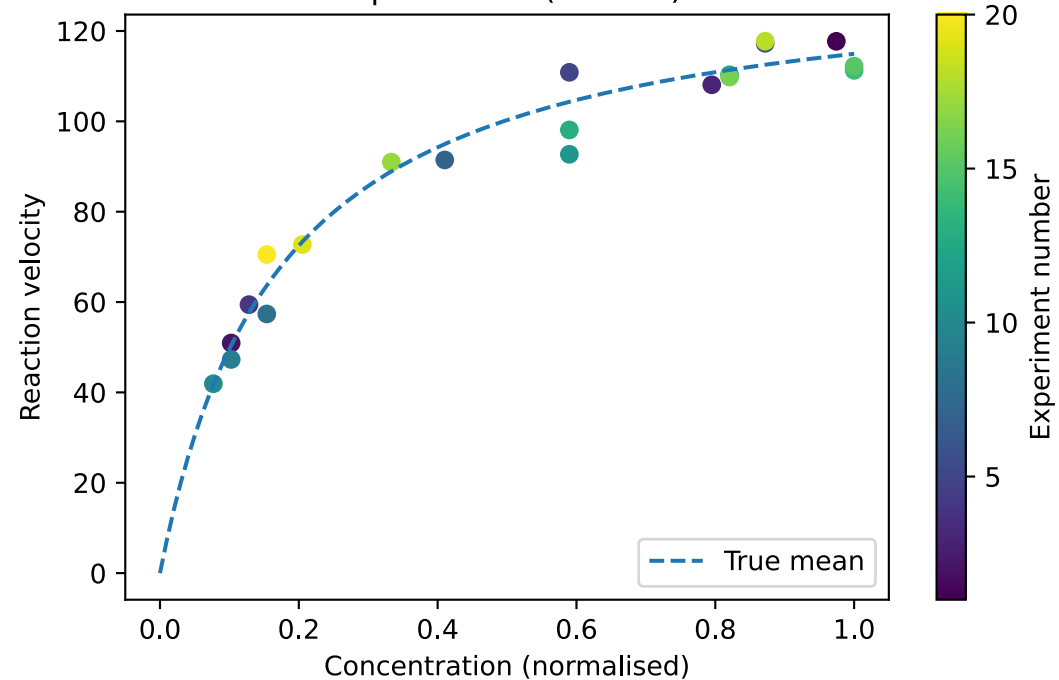


Experiments ($s = 1.0$)

Information gains and model probability

