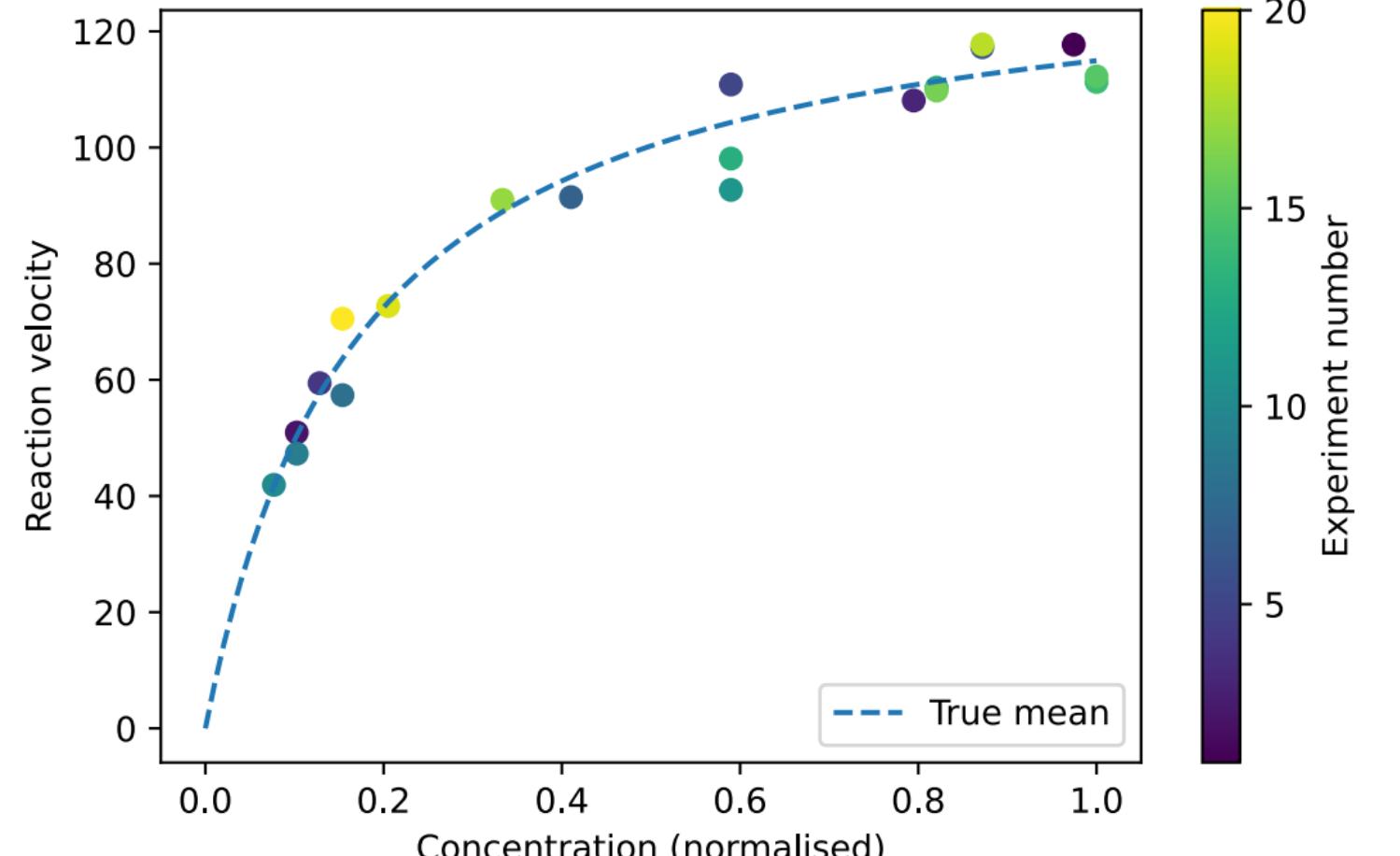


Experiments ( $s = 1.0$ )



Information gains and model probability

