notes

Taylor R. Brown

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## R Markdown

Ideally (why, though?) the posterior predictive distribution

$$p(y_{t+1} \mid y_{1:t}) = \int p(y_{t+1} \mid y_{1:t}, \theta) p(\theta \mid y_{1:t}) d\theta = \int p(y_{t+1} \mid y_{1:t}, \theta) \frac{p(y_{1:t} \mid \theta)}{p(y_{1:t})} p(\theta) d\theta$$

Instead

$$g(y_{t+1} \mid y_{1:t}) = \int p(y_{t+1} \mid y_{1:t}, \theta) p(\theta) d\theta = \int p(y_{t+1} \mid y_{1:t}, \theta) p(\theta) d\theta$$

## difference in expectations

As

$$p(y_{t+1} \mid y_{1:t}) - g(y_{t+1} \mid y_{1:t}) = \mathbb{E}_{\theta} \left[ p(y_{t+1} \mid y_{1:t}, \theta) \left( 1 - \frac{p(y_{1:t} \mid \theta)}{p(y_{1:t})} \right) \right]$$

Maybe the difference in these expectations itself can be monitored!

Let's say we're interested in some function f. Under certain conditions

$$\mathbb{E}_{p(y_{t+1}|y_{1:t})}[f] - \mathbb{E}_{g(y_{t+1}|y_{1:t})}[f] = \int f(y_{t+1}) \mathbb{E}_{\theta} \left[ p(y_{t+1} \mid y_{1:t}, \theta) \left( 1 - \frac{p(y_{1:t} \mid \theta)}{p(y_{1:t})} \right) \right] dy_{t+1}$$

$$= \mathbb{E}_{\theta} \left[ \int f(y_{t+1}) p(y_{t+1} \mid y_{1:t}, \theta) dy_{t+1} \left( 1 - \frac{p(y_{1:t} \mid \theta)}{\hat{p}(y_{1:t})} \right) \right]$$

## Our approach

$$\int f(y_{t+1})p(y_{t+1} \mid y_{1:t}, \theta)dy_{t+1} = \mathbb{E}\left[f(y_{t+1}) \mid y_{1:t}, \theta\right] = \mathbb{E}\left[\mathbb{E}\left\{f(y_{t+1}) \mid x_t\right\} \mid y_{1:t}, \theta\right] = n^{-1}\sum_{i=1}^n h(x_t^i, y_{1:t}, \theta)$$