

## 5.4: Transformations of Random Variables

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“In the previous chapter we discussed the problem of starting with a single random variable  $X$ , forming some function of  $X$ , such as  $X^2$  or  $e^X$ , to obtain a new random variable  $Y = h(X)$ , and investigating the distribution of this new random variable. We now generalize this scenario by starting with more than a single random variable.”

A few notes on notation:

- ①  $f(x_1, x_2)$  is the original pdf
- ②  $g(y_1, y_2)$  is the pdf of the two new rvs
- ③  $Y_1 = u_1(X_1, X_2)$  and  $Y_2 = u_2(X_1, X_2)$
- ④  $X_1 = v_1(Y_1, Y_2)$  and  $X_2 = v_2(Y_1, Y_2)$

...and in this section we're always talking about cts rvs...

# Motivation

Remember how in the univariate case, we needed that thing  $\left| \frac{d}{dy} g^{-1}(y) \right|$ ?

Now we have  $v_1$  and  $v_2$ , and we can differentiate with respect to  $y_1$  and  $y_2$ .

We can make this into a 2x2 matrix:

$$\begin{bmatrix} \frac{\partial v_1(y_1, y_2)}{\partial y_1} & \frac{\partial v_1(y_1, y_2)}{\partial y_2} \\ \frac{\partial v_2(y_1, y_2)}{\partial y_1} & \frac{\partial v_2(y_1, y_2)}{\partial y_2} \end{bmatrix}.$$

# Main Theorem

Let  $T = \{(y_1, y_2) : g(y_1, y_2) > 0\}$  and suppose that all the partial derivatives we write down exist for every  $(y_1, y_2)$  in  $T$ , and they are continuous. Let

$$M = \begin{bmatrix} \frac{\partial v_1(y_1, y_2)}{\partial y_1} & \frac{\partial v_1(y_1, y_2)}{\partial y_2} \\ \frac{\partial v_2(y_1, y_2)}{\partial y_1} & \frac{\partial v_2(y_1, y_2)}{\partial y_2} \end{bmatrix}.$$

Then  $\det(M)$  is called the **Jacobian**, and the new joint pdf for  $Y_1, Y_2$  is

$$g(y_1, y_2) = f[v_1(y_1, y_2), v_2(y_1, y_2)] |\det(M)|$$

# Example

Example 5.25 on page 267: Let's start off with  $X_1$  and  $X_2$  two independent exponential random variables both with parameter  $\lambda$ . Then  $f_{X_1, X_2}(x_1, x_2) = \lambda^2 e^{-\lambda x_1} e^{-\lambda x_2}$ . What's the distribution for  $Y_1 = X_1 + X_2$  and  $Y_2 = X_1/(X_1 + X_2)$ ?

# Example

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Original transformations are

$$\begin{bmatrix} Y_1 \\ Y_2 \end{bmatrix} = \begin{bmatrix} X_1 + X_2 \\ \frac{X_1}{X_1 + X_2} \end{bmatrix}$$

backwards transformations are

$$\begin{bmatrix} X_1 \\ X_2 \end{bmatrix} = \begin{bmatrix} Y_1 Y_2 \\ Y_1 (1 - Y_2) \end{bmatrix}$$

## Example (continued)

Now the jacobian

$$\begin{bmatrix} \frac{\partial v_1(y_1, y_2)}{\partial y_1} & \frac{\partial v_1(y_1, y_2)}{\partial y_2} \\ \frac{\partial v_2(y_1, y_2)}{\partial y_1} & \frac{\partial v_2(y_1, y_2)}{\partial y_2} \end{bmatrix} = \begin{bmatrix} y_2 & y_1 \\ (1 - y_2) & -y_1 \end{bmatrix}$$

So

$$|\det(M)| = |-y_1 y_2 - y_1(1 - y_2)| = |y_1|$$

...plug all this in to our formula and we get

$$\begin{aligned} g(y_1, y_2) &= \lambda^2 e^{-\lambda y_1 y_2} e^{-\lambda y_1(1-y_2)} |y_1|, \quad 0 < y_1 < \infty, 0 < y_2 < 1 \\ &= \lambda^2 e^{-\lambda y_1} y_1 \mathbf{1}(0 < y_1) \mathbf{1}(0 < y_2 < 1) \end{aligned}$$



## Example 5.26 on page 268

Let's start off with  $f_{X_1 X_2}(x_1, x_2) = x_1 + x_2$ ,  $0 < x_1, x_2 < 1$ . We ultimately want the distribution of  $X_1 X_2$ . We need an auxiliary random variable, though.

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Original transformations are

$$\begin{bmatrix} Y_1 \\ Y_2 \end{bmatrix} = \begin{bmatrix} X_1X_2 \\ X_2 \end{bmatrix}$$

backwards transformations are

$$\begin{bmatrix} X_1 \\ X_2 \end{bmatrix} = \begin{bmatrix} Y_1/Y_2 \\ Y_2 \end{bmatrix}$$

## Example 5.26 on page 268

Now the jacobian

$$\begin{bmatrix} \frac{\partial v_1(y_1, y_2)}{\partial y_1} & \frac{\partial v_1(y_1, y_2)}{\partial y_2} \\ \frac{\partial v_2(y_1, y_2)}{\partial y_1} & \frac{\partial v_2(y_1, y_2)}{\partial y_2} \end{bmatrix} = \begin{bmatrix} 1/y_2 & -y_1(y_2)^{-2} \\ 0 & 1 \end{bmatrix}$$

So

$$|\det(M)| = |1/y_2|$$

...plug all this in to our formula and we get

$$\begin{aligned} g(y_1, y_2) &= \left( \frac{y_1}{y_2} + y_2 \right) \frac{1}{y_2}, & 0 < \frac{y_1}{y_2} < 1, 0 < y_2 < 1 \\ &= \left( \frac{y_1}{y_2} + y_2 \right) \frac{1}{y_2}, & 0 < y_1 < y_2 < 1 \end{aligned}$$

## Example 5.26 on page 268

We aren't finished yet. We have

$$g(y_1, y_2) = \left( \frac{y_1}{y_2} + y_2 \right) \frac{1}{y_2}, \quad 0 < y_1 < y_2 < 1$$

but we want  $g_1(y_1)$ .

$$\begin{aligned} g_1(y_1) &= \int_{y_1}^1 g(y_1, y_2) dy_2 \\ &= \int_{y_1}^1 \left( \frac{y_1}{y_2} + y_2 \right) \frac{1}{y_2} dy_2 \\ &= \int_{y_1}^1 y_1 y_2^{-2} + 1 dy_2 \\ &= -y_1 y_2^{-1} \Big|_{y_2=y_1}^{y_2=1} + y_2 \Big|_{y_2=y_1}^{y_2=1} \\ &= -y_1 \left( 1 - \frac{1}{y_1} \right) + (1 - y_1) = 2(1 - y_1), \quad 0 < y_1 < 1 \end{aligned}$$

# Why does this work?

Recall  $g(y_1, y_2)dy_1dy_2 = f[v_1(y_1, y_2), v_2(y_1, y_2)]|\det(M)|dy_1dy_2$ . We need

$$\iint f[v_1(y_1, y_2), v_2(y_1, y_2)]|\det(M)|dy_1dy_2 = \iint f(x_1, x_2)dx_1dx_2$$

(integrating both sides gives you the same probabilities (or expected values))

Think of these as the sum of volumes of a bunch of prisms.

- ① heights are the same:  $f(x_1, x_2) = f[v_1(y_1, y_2), v_2(y_1, y_2)]$
- ② bases are the same:  $|\det(M)|dy_1dy_2 = dx_1dx_2$