

## 8.3: Intervals Based on a Normal Population Distribution

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This section talks about the difference between three types of intervals when dealing with normal data. Unlike last section, the assumption of normal data is required here.

# Proposition

First let's recall some facts about a  $t_\nu$  distribution:

- ① it has one parameter:  $\nu$
- ② it doesn't have an MGF
- ③ it only has a mean if  $\nu > 1$
- ④ it only has a variance if  $\nu > 2$
- ⑤ it's basically a standard normal distribution with fatter tails
- ⑥ as  $\nu \rightarrow \infty$ ,  $t_\nu \xrightarrow{D} \mathcal{N}(0, 1)$

In this chapter, we only use it for its percentiles:

$$t_{\alpha, \nu}$$

will denote the  $(1 - \alpha)$  100th percentile.

The book calls these **critical values**.

# Definition

Recall in section 6.4 We proved that  $T = \frac{(\bar{X} - \mu)}{s/\sqrt{n}} \sim t_{n-1}$  when  $X_1, \dots, X_n \stackrel{iid}{\sim} \mathcal{N}(\mu, \sigma^2)$ .

so

$$P(-t_{n-1, \alpha/2} \leq T \leq t_{n-1, \alpha/2}) = 1 - \alpha$$

and with a little algebra we can show that

$$P\left(\bar{X} - t_{n-1, \alpha/2} \frac{s}{\sqrt{n}} \leq \mu \leq \bar{X} + t_{n-1, \alpha/2} \frac{s}{\sqrt{n}}\right) = 1 - \alpha$$

...so our **confidence interval** for  $\mu$  is  $[\bar{x} \pm t_{n-1, \alpha/2} \frac{s}{\sqrt{n}}]$

This is an interval for  $\mu$ . That means that in the long run, CIs constructed this way will cover  $\mu$   $(1 - \alpha)100$  percent of the time.

What if our real goal is to predict the next data point? We want something like this:

$$P(\text{lower} \leq X_{n+1} \leq \text{upper}) = 1 - \alpha$$

# Prediction Error

First,  $X_{n+1} - \bar{X}$  is going to be the random prediction error.  $X_{n+1}$  is still coming from a normal distribution with center  $\mu$ , so we're going to use  $\bar{X}$  again as a point estimate.

$$E(\text{prediction error}) = E[X_{n+1} - \bar{X}] = EX_{n+1} - E\bar{X} = 0$$

and

$$V[\text{prediction error}] = V[X_{n+1} - \bar{X}] = V[X_{n+1}] + V[\bar{X}] = \sigma^2 + \frac{\sigma^2}{n}$$

We're using independence in the variance calculation.

Since a linear combination of normals is normally distributed, we have

$$\frac{(X_{n+1} - \bar{X}) - 0}{\sqrt{\sigma^2 + \frac{\sigma^2}{n}}} \sim \mathcal{N}(0, 1)$$

and by similar reasoning as in section 6.4 (this will be a quiz problem), we can show that

$$\frac{(X_{n+1} - \bar{X}) - 0}{\sqrt{s^2 + \frac{s^2}{n}}} \sim t_{n-1}$$



Last steps:

$$P \left( -t_{\alpha/2, n-1} \leq \frac{(X_{n+1} - \bar{X}) - 0}{\sqrt{S^2 + \frac{S^2}{n}}} \leq t_{\alpha/2, n-1} \right) = 1 - \alpha$$

$$P \left( -t_{\alpha/2, n-1} \sqrt{S^2 + \frac{S^2}{n}} \leq X_{n+1} - \bar{X} \leq t_{\alpha/2, n-1} \sqrt{S^2 + \frac{S^2}{n}} \right) = 1 - \alpha$$

$$P \left( \bar{X} - t_{\alpha/2, n-1} S \sqrt{1 + \frac{1}{n}} \leq X_{n+1} \leq \bar{X} + t_{\alpha/2, n-1} S \sqrt{1 + \frac{1}{n}} \right) = 1 - \alpha$$

so  $[\bar{X} \pm t_{\alpha/2, n-1} s \sqrt{1 + \frac{1}{n}}]$  is our  $(1 - \alpha)100$ th **prediction interval**

Key points so far

- 1 Cls are for inferring about *parameters*
- 2 Pls are for inferring about future *observations*
- 3 Prediction variance is non-vanishing, no matter how much data you throw at it