

1.5: Estimation and Elimination of Trend and Seasonal Components

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All the material from last chapter was only for **stationary** time series only!

Before you use all of that:

- 1 plot the series (does it look stationary?)
- 2 Does it need to be broken up into homogeneous segments?
- 3 Do we need to discard outliers? Incorrectly recorded?
- 4 Do we need to decompose the data into trend, seasonal component and stationary component?
- 5 Do we need to transform the data? Take the logarithm? Take Differences? Take percents changes?

Approach 1: Classical Decomposition Model

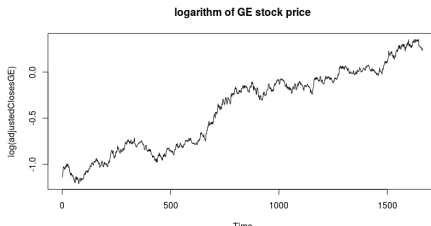
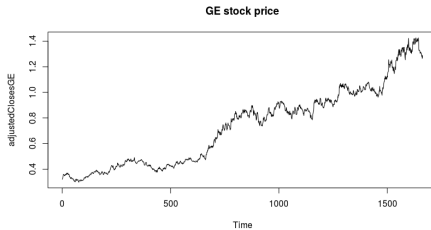
The **classical decomposition model** for a series $\{X_t\}$ is written as

$$X_t = m_t + s_t + Y_t,$$

where

- 1 m_t is the slowly changing trend component
- 2 s_t is the seasonal component with known frequency/period
- 3 Y_t is weakly stationary noise (something from last chapter)

Transforming the data by taking the log of each x_t is commonly done if the seasonal and noise fluctuations appear to increase with the level of the process.



Definition

With financial time series, people are usually interested in returns

- continuously compounded: $R_t = \log(X_t) - \log(X_{t-1})$
- compounded weekly, daily, etc.: $S_t = \left(\frac{X_t - X_{t-1}}{X_{t-1}} \right) = X_t/X_{t-1} - 1$

Running “Wealth”:

- Taking the log of each time point is looking at the cumulative sum of the first one
- You can take the arithmetic average of the log returns $\sum_{t=1}^T R_t / T$
- If you don't look at continuously compounded returns, you want the geometric average: $(\prod_{t=1}^T [1 + S_t])^{1/T}$
- We usually take the log

Fitting the trend?

If our model is

$$X_t = m_t + s_t + Y_t,$$

how do we get an idea of m_t and s_t ?

First, let's assume $s_t = 0$.

Method 1: Smoothing with finite moving average filter

Assume the model is

$$X_t = m_t + Y_t, \quad t = 1, \dots, n$$

with $E[Y_t] = 0$, then define

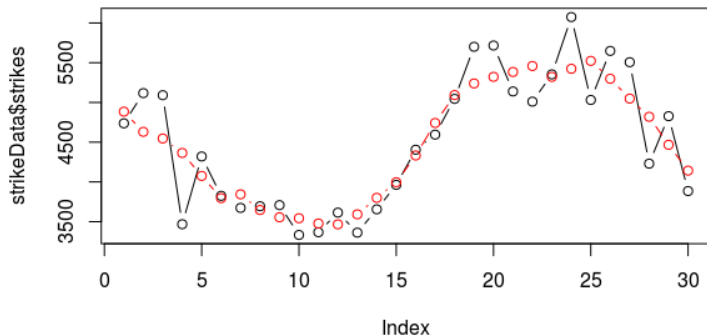
$$W_t = \frac{1}{2q+1} \sum_{j=-q}^q X_{t-j}.$$

Why? Because the mean shows up better and the noise is attenuated.

$$W_t = \frac{1}{2q+1} \sum_{j=-q}^q m_{t-j} + \frac{1}{2q+1} \sum_{j=-q}^q Y_{t-j} \approx \frac{1}{2q+1} \sum_{j=-q}^q m_{t-j}$$

for $q+1 \leq t \leq n-q$ because $\frac{1}{2q+1} \sum_{j=-q}^q Y_{t-j} \rightarrow 0$ by the law of large numbers.

Method 1: Smoothing with finite moving average filter



Be careful though. Applying **linear filters** might wash away the trend component too!

Method 2: Exponential Smoothing

Assume the model is

$$X_t = m_t + Y_t, \quad t = 1, \dots, n$$

with $E[Y_t] = 0$ again. Then pick $\alpha \in [0, 1]$. Finally define the mean estimate recursively:

$$\hat{m}_t = \alpha X_t + (1 - \alpha) \hat{m}_{t-1}$$

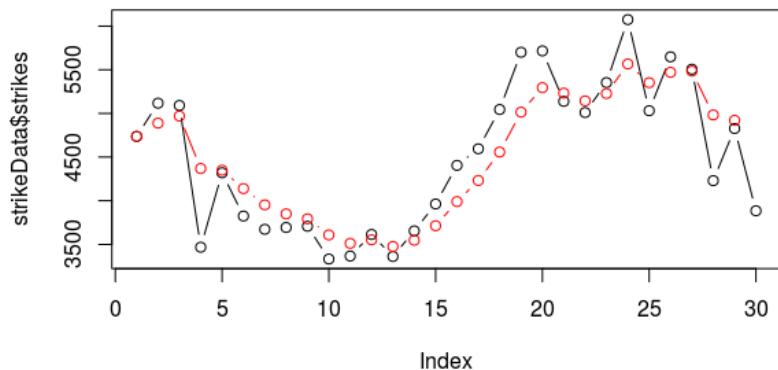
with the initial condition $\hat{m}_1 = x_1$.

They call it exponential smoothing because the weights decrease exponentially:

$$\begin{aligned} \hat{m}_t &= \alpha X_t + (1 - \alpha)[\alpha X_{t-1} + (1 - \alpha) \hat{m}_{t-2}] \\ &= \alpha X_t + \alpha(1 - \alpha) X_{t-1} + (1 - \alpha)^2 [\alpha X_{t-2} + (1 - \alpha) \hat{m}_{t-3}] \\ &= \alpha \sum_{j=0}^{t-2} (1 - \alpha)^j X_{t-j} + (1 - \alpha)^{t-1} X_1 \end{aligned}$$

Method 2: Exponential Smoothing

exponential smoothing for strike data



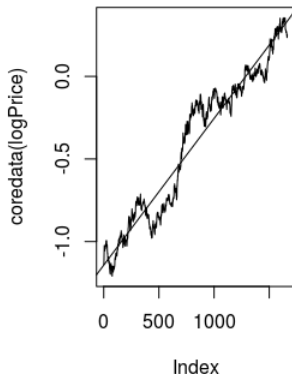
We can also

- 1 Smooth by fitting a Fourier series that lacks high frequency components
- 2 Smooth by fitting a polynomial to the data

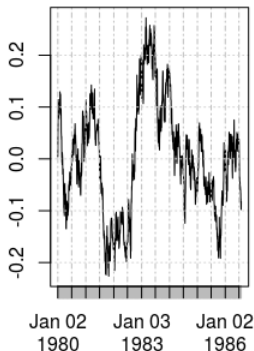
More on these later...

Method 4

logarithm of GE stock price



residuals



Equivalent to assuming

$$\log(P_t) = \beta_0 + \beta_1 t + W_t \text{ OR } \log(P_t) - \log(P_{t-1}) = \beta_1 + W_t - W_{t-1}$$

Preliminary Definitions

The Backshift Operator

The **backshift operator**, denoted by B , means

$$BX_t = X_{t-1}.$$

Note that $B^2 = BX_{t-1} = X_{t-2}$ and so on.

The Differencing Operator

The **differencing operator**, denoted by ∇ , means

$$\nabla X_t = X_t - X_{t-1} = (1 - B)X_t$$

Note that $\nabla^2 X_t = \nabla(1 - B)X_t = (1 - 2B + B^2)X_t = X_t - 2X_{t-1} + X_{t-2}$, and so on.

Approach 2: Trend Elimination by Differencing

Approach 2: Trend Elimination by Differencing

The **differencing method** attempts to detrend the data by differencing the time series, and fitting a stationary model on the differenced series $\nabla^k X_t$, for some k .

Example: Assume $X_t = a_0 + a_1 t + a_2 t^2 + Y_t$.

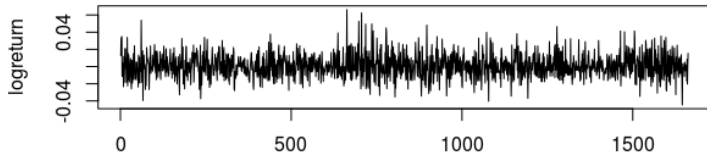
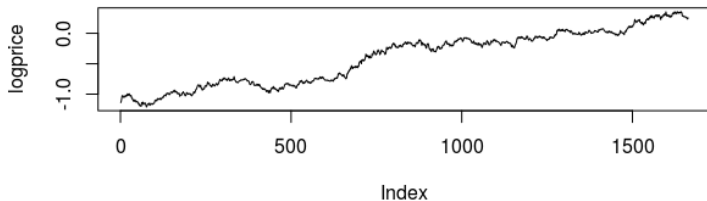
$$\nabla X_t = a_1 + 2a_2 t - a_2 + \nabla Y_t$$

$$\nabla^2 X_t = 2a_2 + \nabla^2 Y_t$$

So we would model $\nabla^2 X_t$ with a stationary time series model from last chapter.

Differencing Example

Differencing once gives us the log returns.



Fitting the trend?

If our model is

$$X_t = m_t + s_t + Y_t,$$

how do we get an idea of m_t and s_t ?

Now, let's assume $s_t \neq 0$. Specifically, let $s_{t+d} = s_t$ and $\sum_{j=1}^d s_j = 0$, for some period d .

Method S1: Estimation of Trend and Seasonal Components

If our model is

$$X_t = m_t + s_t + Y_t,$$

Step 1: Estimate m_t with \hat{m}_t . d is the period.

- If $d = 2q$, then $\hat{m}_t = (.5x_{t-q} + x_{t-q+1} + \cdots + x_{t+q-1} + .5x_{t+q})/d$
- If $d = 2q + 1$, then $\hat{m}_t = (\sum_{i=-q}^q x_{t-i})/(2q + 1)$

for $q < t \leq n - q$

Method S1: Estimation of Trend and Seasonal Components

If our model is

$$X_t = m_t + s_t + Y_t,$$

Step 2: Estimate s_t with \hat{s}_t . For times $k = 1, \dots, d$

- $w_k = \text{mean}_j(x_{k+jd} - \hat{m}_{k+jd})$
- $\hat{s}_k = w_k - d^{-1} \sum_{i=1}^d w_i$
- $\hat{s}_l = \hat{s}_{l-d}$ for $l > d$

for $q < k + jd \leq n - q$

Method S1: Estimation of Trend and Seasonal Components

If our model is

$$X_t = m_t + s_t + Y_t,$$

Step 3: Deseasonalize the data

- $d_t = x_t - \hat{s}_t$

for $0 < t \leq n$

Step 4: Re-estimate the trend m_t

- Use a method that we talked about in the prior section on the series d_t

Method S2: Elimination of Trend and Seasonal Components by Differencing

If our model is

$$X_t = m_t + s_t + Y_t,$$

then

$$\nabla_d X_t = m_t - m_{t-d} + Y_t - Y_{t-d}$$

where ∇_d is the lag-d difference, (not ∇^d !)

In R:

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diff(logRets, lag=12)
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Note that $\nabla \nabla_d X_t = \nabla_d \nabla X_t$, but it's recommended that you apply ∇_d first (left side).