

# Unit 12: Forecasting

Jeffrey Woo

Department of Statistics, University of Virginia

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# Readings for Unit 12

Textbook chapter 3.4 (skip pages 103 to 106).

# Last Unit

- 1 ACF for  $MA(q)$
- 2 ACF for Causal  $ARMA(p,q)$
- 3 Partial Autocorrelation Function

# This Unit

- 1 Best linear predictor
- 2 ARMA forecasting

# Motivation

In this unit, we explore forecasting: predicting future values of a time series based on observed data.

# 1 Forecasting for Stationary Processes

## 2 ARMA Forecasting

# Forecasting

In forecasting, the goal is to predict future values of a time series,  $x_{n+m}$ , based on the observed data  $\mathbf{x} = \{x_n, x_{n-1}, \dots, x_1\}$ . In this unit, we assume  $\{x_t\}$  is stationary.

# Forecasting

The minimum mean square error predictor of  $x_{n+m}$  is

$$x_{n+m}^n = E(x_{n+m}|\mathbf{x}) \quad (1)$$

as the conditional expectation minimizes the mean square error  $E[x_{n+m} - g(\mathbf{x})]^2$ , where  $g(\mathbf{x})$  is a function of the observations.



# Forecasting

First, we restrict our attention to predictors that are linear functions of the observations, i.e.

$$x_{n+m}^n = \alpha_0 + \sum_{j=1}^n \alpha_j x_j \quad (2)$$

where  $\alpha_0, \alpha_1, \dots, \alpha_n \in \mathbb{R}$ . Linear predictors of the form (2) that minimize the mean square prediction error are called \_\_\_\_\_.

Linear prediction depends on the second-order moments of the process, which can be estimated from the data.

# Projection Theorem

## Theorem

*Let  $\mathcal{M}$  be a closed subspace of the Hilbert space  $\mathcal{H}$  and let  $y$  be an element in  $\mathcal{H}$ . Then,  $y$  can be uniquely represented as  $y = \hat{y} + z$  where  $\hat{y} \in \mathcal{M}$  and  $z$  is orthogonal to  $\mathcal{M}$ . Therefore, for any  $w \in \mathcal{M}$ ,*

- $\|y - w\| \geq \|y - \hat{y}\|$  and*
- $\langle z, w \rangle = 0$ .*

# Projection Theorem

# Projection Theorem: Linear Prediction

Given  $1, x_1, x_2, \dots, x_n \in \{X : E(X^2) < \infty\}$ , choose  $\alpha_0, \alpha_1, \dots, \alpha_n \in \mathbb{R}$  so that  $U = \alpha_0 + \sum_{j=1}^n \alpha_j x_j$  minimizes  $E(x_{n+m} - U)^2$ .

Note that:

$\mathcal{M} = \{U = \alpha_0 + \sum_{j=1}^n \alpha_j x_j : \alpha_j \in \mathbb{R}\} = \bar{s}p\{1, x_1, \dots, x_n\}$  and  $y = x_{n+m}$ .

# Projection Theorem: Linear Prediction

Let  $x_{n+m}^n$  denote the best linear predictor, i.e.

$$\|x_{n+m}^n - x_{n+m}\|^2 \leq \|U - x_{n+m}\|^2$$

for all  $U \in \mathcal{M}$ . The projection theorem implies

# Projection Theorem: Linear Prediction

- The prediction errors  $x_{n+m}^n - x_{n+m}$  are orthogonal to the prediction variables  $(1, x_1, \dots, x_n)$ .
- Orthogonality of prediction error and 1 implies we can \_\_\_\_\_ from all variables  $x_{n+m}$  and  $x_i$ .
- Therefore, we typically assume  $\mu = 0$  for forecasting.

# BLP for Stationary Process

Given  $x_1, \dots, x_n$ , the best linear predictor for stationary processes,  $x_{n+m}^n = \alpha_0 + \sum_{j=1}^n \alpha_j x_j$ , of  $x_{n+m}$ , for  $m \geq 1$ , is found by solving

$$E[(x_{n+m} - x_{n+m}^n)x_k] = 0 \text{ for } k = 0, 1, \dots, n, \quad (3)$$

where  $x_0 = 1$ , for  $\alpha_0, \alpha_1, \dots, \alpha_n$ . The equations (3) are called the **prediction equations**.

# One-Step-Ahead Linear Prediction

Consider one-step-ahead prediction. Given  $x_1, \dots, x_n$ , we want to forecast  $x_{n+1}$ . The BLP takes the form

$$x_{n+1}^n = \phi_{n1}x_n + \phi_{n2}x_{n-1} + \dots + \phi_{nn}x_1. \quad (4)$$

Therefore, the prediction equations (3) become



# One-Step-Ahead Linear Prediction

In matrix form:

# One-Step-Ahead Linear Prediction

The mean square one-step-ahead prediction error is

$$\begin{aligned} P_{n+1}^n &= E(x_{n+1} - x_{n+1}^n)^2 \\ &= \\ &= \\ &= \\ &= \\ &= \end{aligned} \tag{5}$$

# Prediction Intervals

Construct prediction interval:

$$x_{n+1}^n \pm 1.96 \sqrt{P_{n+1}^n}.$$

for Gaussian processes. The prediction error has distribution  $N(0, P_{n+1}^n)$ .

## 1 Forecasting for Stationary Processes

## 2 ARMA Forecasting

# ARMA Forecasting

Let's consider an ARMA model that is causal and invertible

$$\phi(B)X_t = \theta(B)w_t,$$

where

$$\phi(B) = 1 - \phi_1 B - \dots - \phi_p B^p \quad \text{and} \quad \theta(B) = 1 + \theta_1 B + \dots + \theta_q B^q.$$

# ARMA Forecasting

By causality and invertibility, we have

$$x_{n+m} = \sum_{j=0}^{\infty} \psi_j w_{n+m-j}, \quad \psi_0 = 1, \quad (6)$$

where  $\psi(z) = \frac{\theta(z)}{\phi(z)} = \sum_{j=0}^{\infty} \psi_j z^j$ , and

$$w_{n+m} = \sum_{j=0}^{\infty} \pi_j x_{n+m-j}, \quad \pi_0 = 1, \quad (7)$$

where  $\pi(z) = \frac{\phi(z)}{\theta(z)} = \sum_{j=0}^{\infty} \pi_j z^j$ .

# ARMA Forecasting

Given the past information  $x_n, x_{n-1}, \dots$ , we are interested in predicting  $x_{n+m}$ . We use  $\tilde{x}_{n+m} = E(x_{n+m} | x_n, x_{n-1}, \dots)$ , the conditional expectation of  $x_{n+m}$  given all the past  $x_n, x_{n-1}, \dots$ , to forecast  $x_{n+m}$ .

# ARMA Forecasting

Note also that

$$E(w_t | x_n, x_{n-1}, \dots) = 0$$

for  $t > n$  because of causality. For  $t \leq n$ ,  $w_t$  is determined by  $x_t, x_{t-1}, \dots$ , which are included in  $x_n, x_{n-1}, \dots$ . Thus,

$$E(w_t | x_n, x_{n-1}, \dots) = w_t.$$



# ARMA Forecasting

So

$$E(w_t | x_n, x_{n-1}, \dots) = \begin{cases} 0, & t > n, \\ w_t, & t \leq n. \end{cases} \quad (8)$$

# ARMA Forecasting

Now, we take the infinite AR representation (7) and take the conditional expectation (conditioning on  $x_n, x_{n-1}, \dots$ ) on both sides of (7) to get

# ARMA Forecasting

This leads to

$$\tilde{x}_{n+m} = - \sum_{j=1}^{m-1} \pi_j \tilde{x}_{n+m-j} - \sum_{j=m}^{\infty} \pi_j x_{n+m-j}. \quad (9)$$

Letting  $m = 1$  in (9), we have

$$\tilde{x}_{n+1} = - \sum_{j=1}^{\infty} \pi_j x_{n+1-j} = - \sum_{j'=0}^{\infty} \pi_{j'+1} x_{n-j'}.$$

So, start by finding  $\tilde{x}_{n+1}$  and then recursively use (9) to find the later  $\tilde{x}_{n+m}$ . This is called the \_\_\_\_\_.

## Worked Example

We have an AR(2) model  $x_t = \phi_1 x_{t-1} + \phi_2 x_{t-2} + w_t$ . Suppose we have observations up to the  $n$ th term, i.e.  $x_n, x_{n-1}, \dots$ . So we wish to use the observed data and estimated AR(2) model to forecast the value of  $x_{n+1}$  and  $x_{n+2}$ . Writing out these two values, we have

$$x_{n+1} = \phi_1 x_n + \phi_2 x_{n-1} + w_{n+1},$$

$$x_{n+2} = \phi_1 x_{n+1} + \phi_2 x_n + w_{n+2}.$$

## Worked Example

To forecast  $x_{n+1}$ , we use the observed values of  $x_n$  and  $x_{n-1}$  and replace  $w_{n+1}$  by its expected value of 0.

Forecasting  $x_{n+2}$  poses a challenge, since it requires the unobserved value of  $x_{n+1}$ . We use the forecasted value of  $x_{n+1}$ .

# Framework in Forecasting

In general, the forecasting procedure for an ARMA(p,q) model is as follows:

- For any  $w_j$  with  $1 \leq j \leq n$ , use the sample residual at time  $j$ .
- For any  $w_j$  with  $j > n$ , use the expected value of  $w_j$ , which is 0.
- For any  $x_j$  with  $1 \leq j \leq n$ , use the observed value of  $x_j$ .
- For any  $x_j$  with  $j > n$ , use the forecasted value of  $x_j$ .

# Prediction Error

We use the infinite MA representation (6) and write

# Prediction Error

Therefore, the mean-squared prediction error, or variance of the difference between the forecasted value and the true value at time  $n + m$  is

$$P_{n+m}^n = E(x_{n+m} - \tilde{x}_{n+m})^2 = \sigma_w^2 \sum_{j=0}^{m-1} \psi_j^2, \quad (10)$$

and the standard error of the forecast error at time  $n + m$  is

$$\sqrt{\hat{\sigma}_w^2 \sum_{j=0}^{m-1} \psi_j^2}. \quad (11)$$



# Prediction Error

**Question:** Write out the standard error of the forecast error for  $m = 1$  and  $m = 2$ .

# Prediction Error

Notice that as  $m$  gets larger—i.e. as we predict further into the future, this is \_\_\_\_\_ but essentially asymptotes. This means that you are getting essentially a constant prediction interval after a certain distance into the future, as if we do not know what was going on previously.

# Prediction Error

Also, for fixed sample size  $n$ , the prediction errors are correlated.  
For  $h \geq 1$ ,

$$E \{ (x_{n+m} - \tilde{x}_{n+m})(x_{n+m+h} - \tilde{x}_{n+m+h}) \} = \sigma^2 \sum_{j=0}^{m-1} \psi_j \psi_{j+h}.$$

# Prediction Interval

For Gaussian processes, the 95% prediction interval for  $x_{n+m}$ , the future value of the series at time  $n + m$  is

$$x_{n+m}^n \pm 1.96 \sqrt{\hat{\sigma}_w^2 \sum_{j=0}^{m-1} \psi_j^2}. \quad (12)$$

## Worked Example

**Question:** We have an AR(1) model  $x_t = 40 + 0.6x_{t-1} + w_t$ . Suppose we have  $n = 100$  observations,  $\hat{\sigma}_w^2 = 1$  and  $x_{100} = 80$ . We wish to forecast the values at times 101 and 102.

# Worked Example