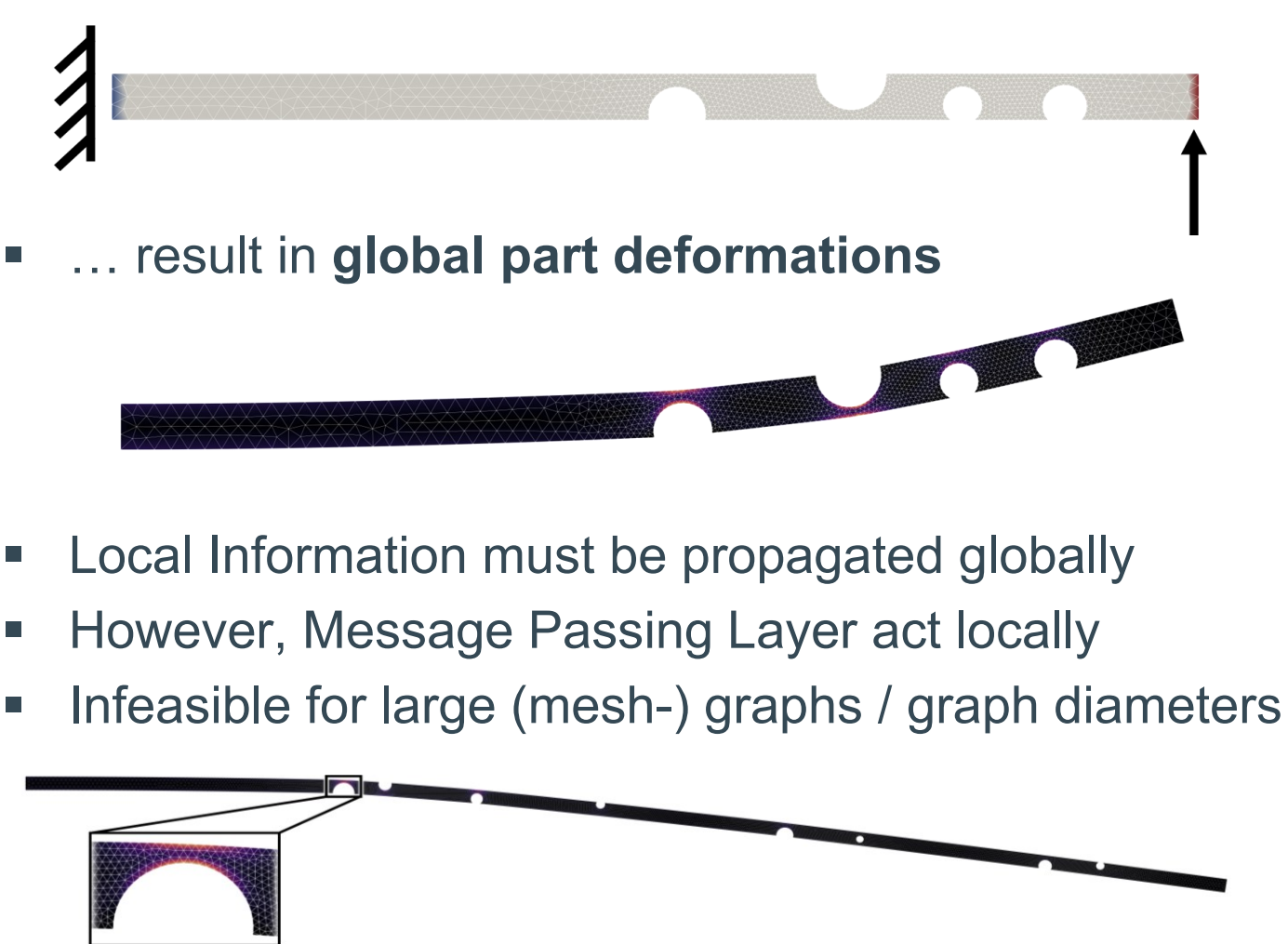


# Diffusion-Based Hierarchical Graph Neural Networks for Simulating Nonlinear Solid Mechanics

## Challenges


### Message Passing Bottleneck

- Local boundary conditions...
- ... result in global part deformations



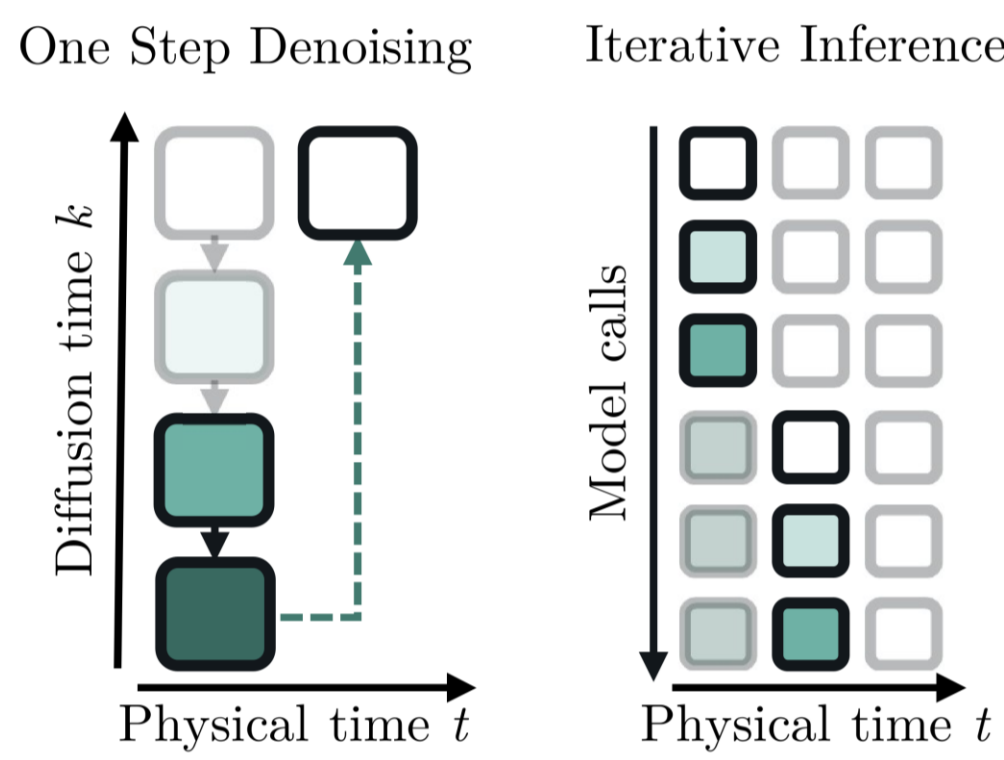
### Spectral bias of MSE-trained Model

- Ground truth
- Prediction with low frequency bias
- Prediction with high frequency bias
- Conventional MSE-based training is more sensitive to global deformation deviations than to local mesh distortions (spectral bias)



### Conventional Denoising

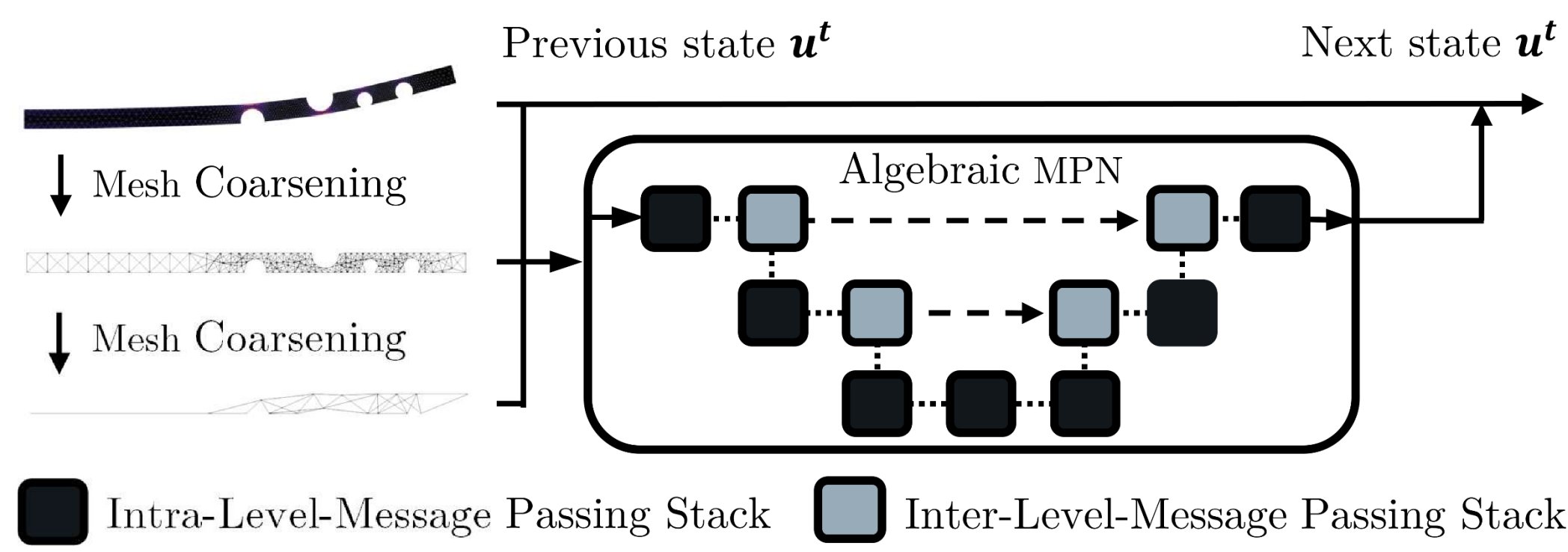
- Conventional diffusion-based simulators denoise step-wise  
→  $\sigma(KT)$  for K diffusion and T physical steps



## ROBIN: Rolling diffusion-Batched Inference Network

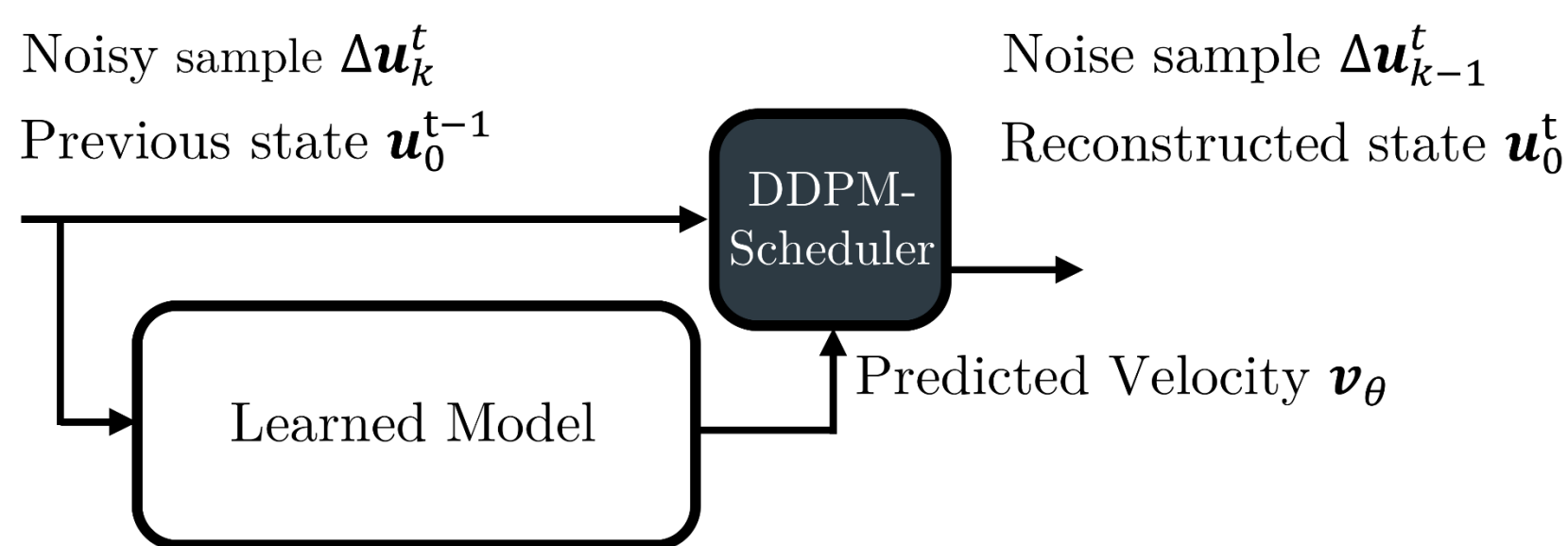
### Algebraic hierarchical Message Passing Networks

- Algebraic Multigrid (AMG)-based Mesh Coarsening that preserves the geometry
- Maximize receptive field – One cycle propagates information across the entire mesh
- Mesh-size independent architecture by shared blocks
- Increase prediction fidelity by multiscale message passing



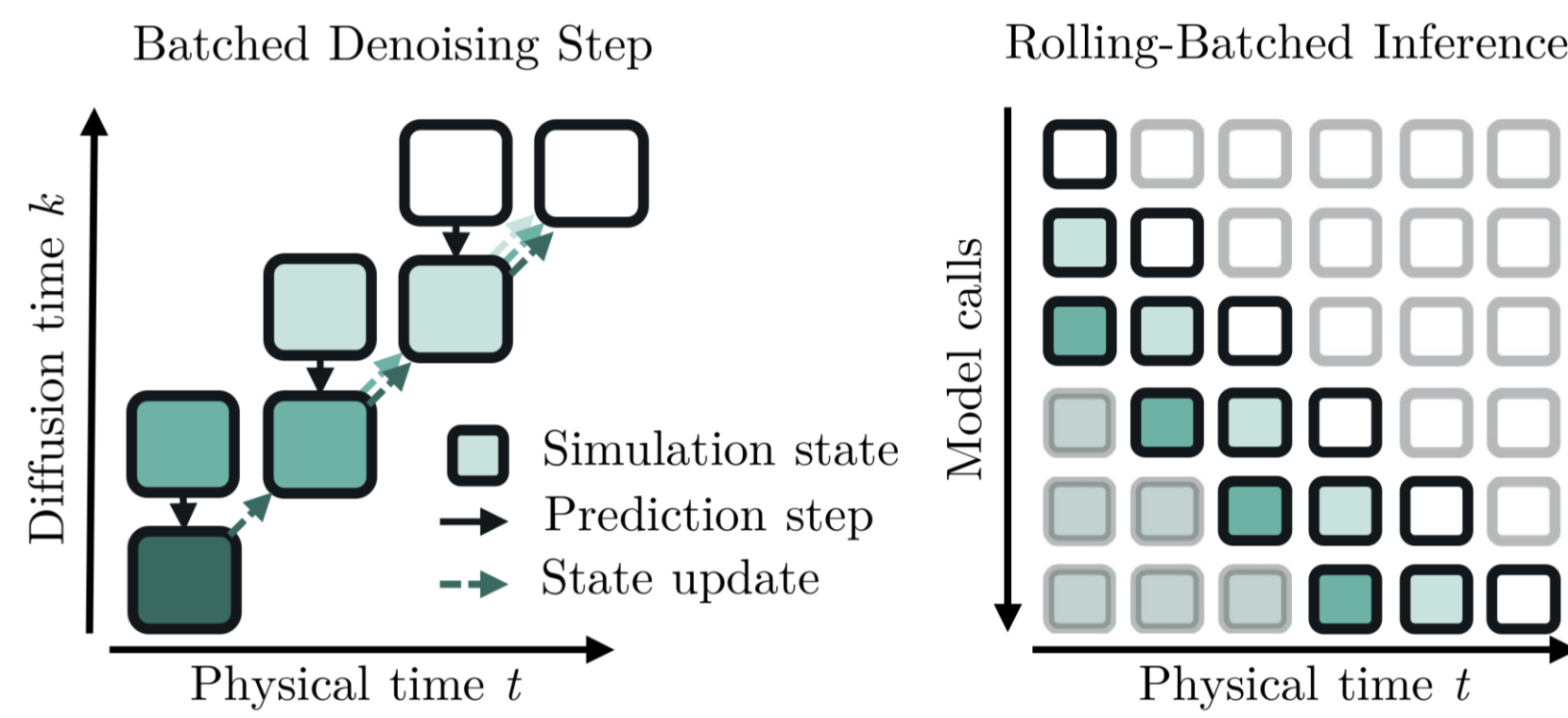
### Denoising Diffusion Probabilistic Models (DDPMs)

- DDPMs and AMPNs allow for rich, high-fidelity predictions across frequencies
- Early denoising steps focus on global frequencies, and the later on local frequencies

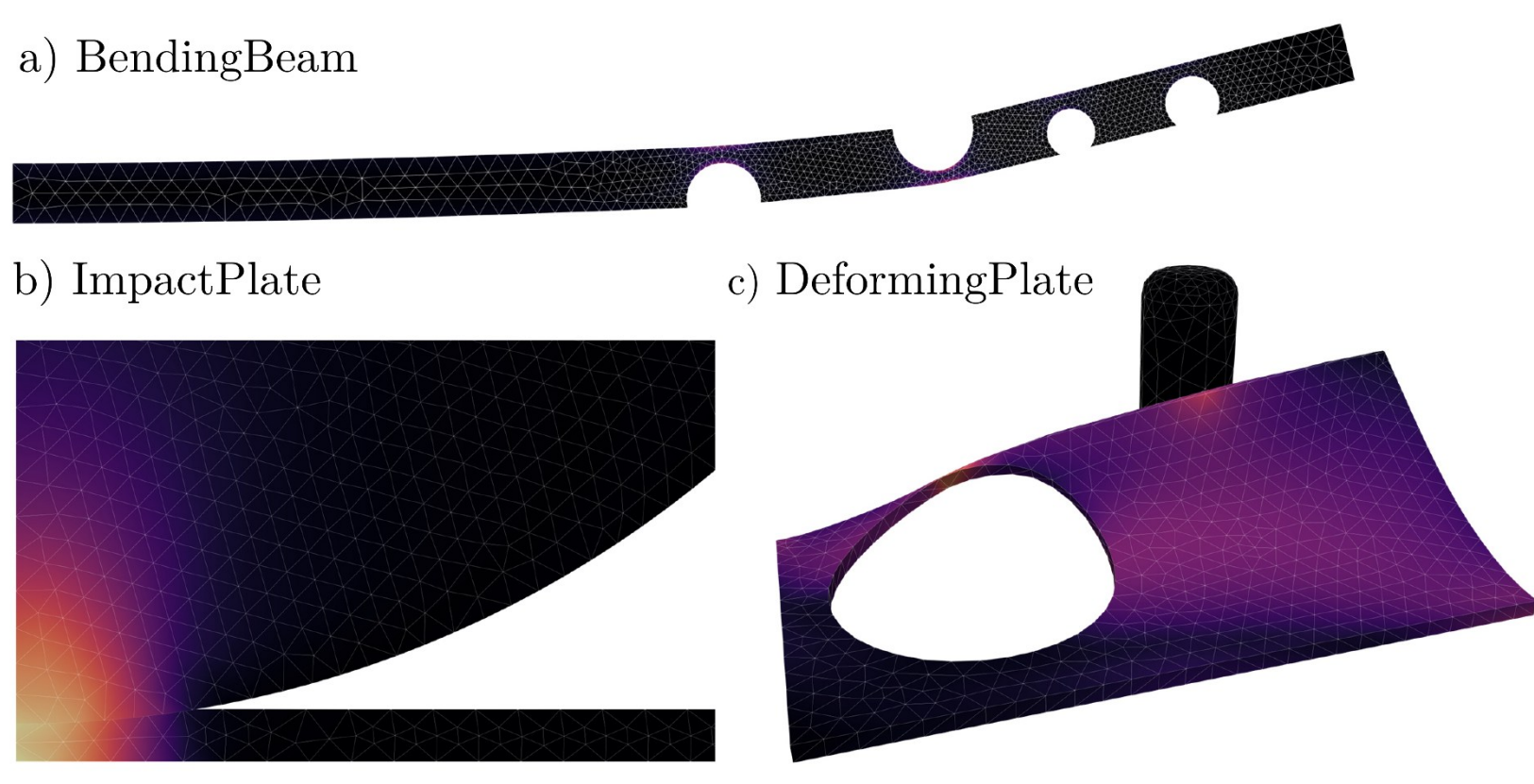


### ROBI: Rolling diffusion-Batched Inference

- ROBI parallelize the denoising of consecutive time steps →  $\approx \sigma(T)$
- The model prediction still only depends on the previous physical state, preserving training efficiency and time-shift equivariance
- Denoising stride and truncation step enable the trade-off of accuracy for speed



## Datasets

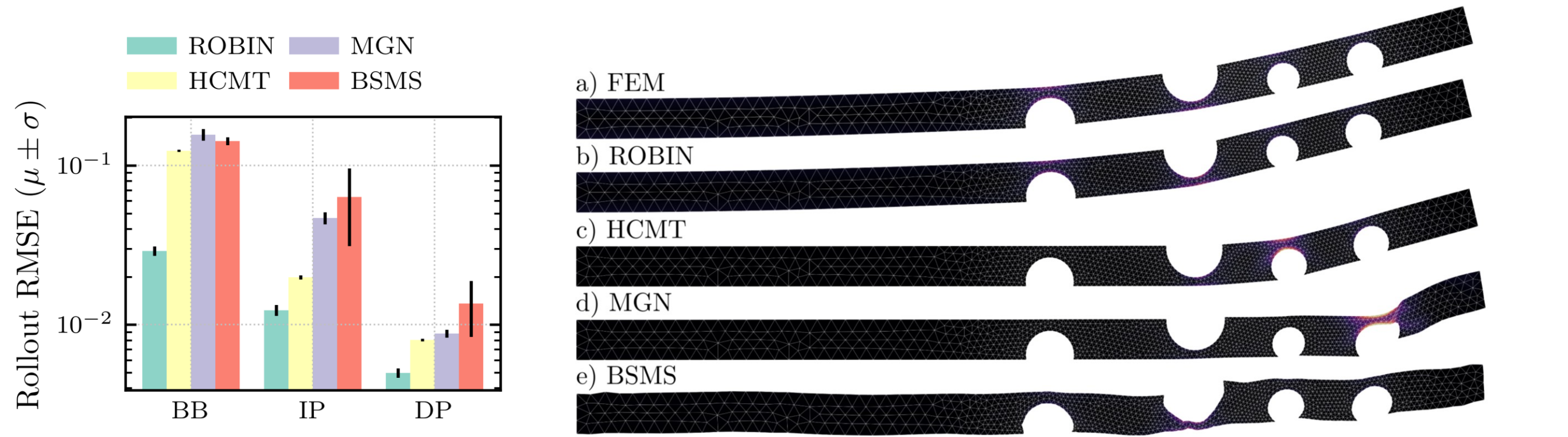


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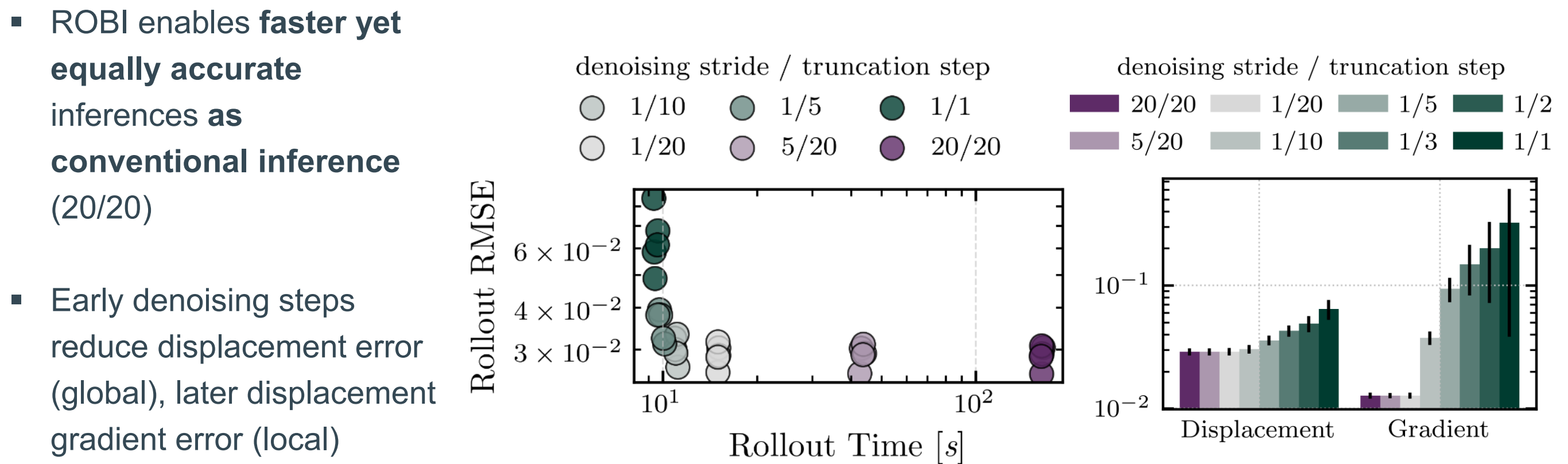


## Results

### High-fidelity physical simulations

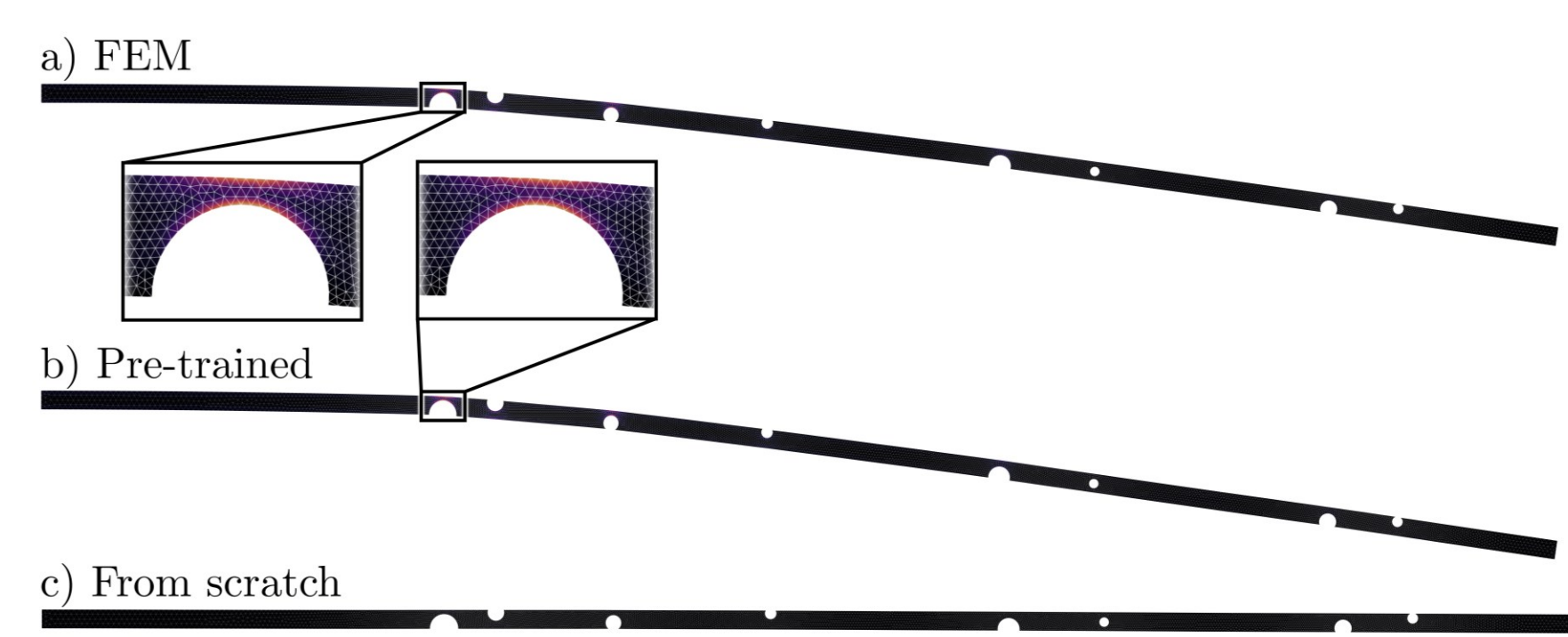


### Variable Inference with ROBI



### Generalization to large meshes

- The AMPN architecture enables quick transfers to much larger meshes



Project website

