terms) derivation (transformer & motional Appendix: loop moves & may be deformed; General Situation:  $\bar{B} = \bar{B}(\bar{r},t)$  $\mathcal{E} = \oint \frac{1}{9} \vec{F} d\vec{l} = \frac{1}{9} \oint (9\vec{E} + 9\vec{v} \times \vec{B}) d\vec{l} = \vec{l}$ = \$ (\varepsilon + \varphi \times \varphi) out Universal flux rule (always volid)  $E = -\frac{\partial \hat{\Phi}_{B}}{\partial t}$ . We will show  $\oint E dt = -\int \frac{\partial E}{\partial t} dS$ 

v - field of velocities (describes movement/ oleformation of loop 17)

(\*1

will use the identity ( w - any vector, see the moteriels on SAKAi for more motherwoodid

 $\frac{d}{dt} \int \cot \vec{w} \, d\vec{s} = \oint \frac{\partial \vec{w}}{\partial t} \, d\vec{t} - \oint [\vec{v} \times \cot \vec{w}] \, d\vec{t} = I$ depends on t

Stoke's Hun S & (not w) do - & [vx not w] dt applied to Et the former term

Revall: Stoke's them

the identity (\*) for  $\overline{w} = \overline{A}$  (vector potential, i.e.  $\overline{B} = not \overline{A}$ )

$$\frac{d}{dt} \int \cot \overline{A} d\overline{S} = \frac{d}{dt} \int \overline{B} d\overline{S} = \oint \frac{\partial \overline{A}}{\partial t} d\overline{t} - \oint (\overline{v} \times \operatorname{not} \overline{A}) d\overline{e} = \overline{E}$$

$$\overline{E}_{t} = \overline{E}$$

$$= \oint \left( \frac{\partial \bar{A}}{\partial t} + gnool V - \bar{t} \times 1\bar{3} \right) d\bar{l}$$

$$= -\bar{E}$$
Note.  $\oint gnool \varphi d\bar{l} = 0$ 
for any  $\varphi$ 

= -f (Ē+v×B) dī (\*\*)

and (now use 2nd line of identity)  $\frac{d}{dt}\int_{\overline{Z}_{1}}\overline{\delta}d\overline{\delta}=\int_{\overline{Z}_{1}}\frac{\partial}{\partial t}\left(\operatorname{rot}\overline{A}\right)d\overline{\delta}-\int_{r_{1}}(\overline{v}\times\overline{B})d\overline{c}$ 

terms of V(\*\*) and (\*\*\*) first  $\oint \overline{E} d\overline{L} = -\int \frac{2\overline{E}}{2\overline{L}} d\overline{L}$  
Thousformer confined that  $\Gamma_{t}$  - any loop