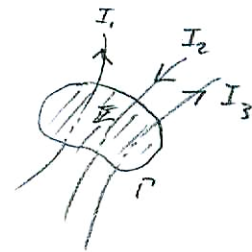


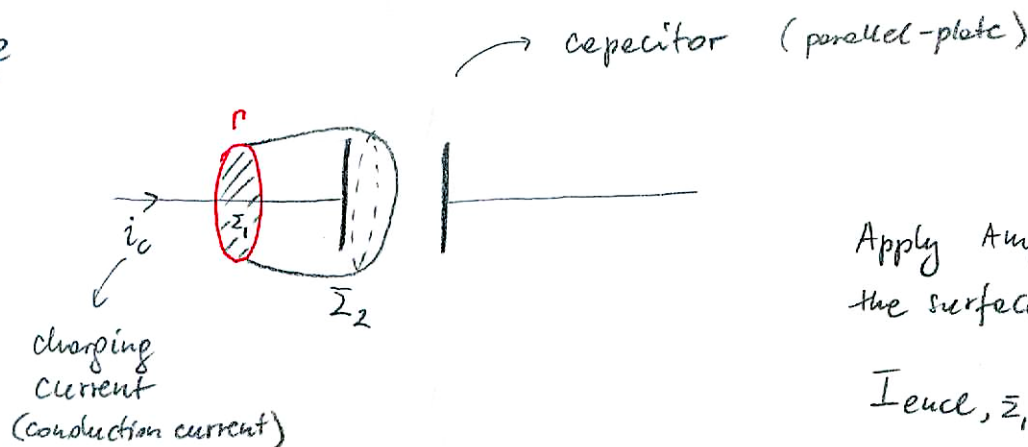
Displacement current. Ampère's law revisited

Recall:

$$\oint \vec{B} \cdot d\vec{l} = \mu_0 I_{\text{enc}} \quad (\text{Ampère's law magnetostatics})$$



Example



Apply Ampère's law with the surfaces chosen as Σ_1, Σ_2

$$I_{\text{enc}, \Sigma_1} = i_c$$

$$I_{\text{enc}, \Sigma_2} = 0 \quad ? \quad \text{contradiction}$$

Conclusion: Ampère's law is incomplete

What happens at Σ_2 ? $|\vec{E}|$ and Φ_E increase as the capacitor is being charged
 ↳ flux through Σ_2

$$q = C \cdot v = \epsilon_0 \frac{A}{d} E d = \epsilon_0 A E = \epsilon_0 \Phi_E$$

$$q = \epsilon_0 \Phi_E \Rightarrow \dot{q} = \epsilon_0 \dot{\Phi}_E = i \quad \text{corresponding current}$$

Define the displacement current through Σ_2

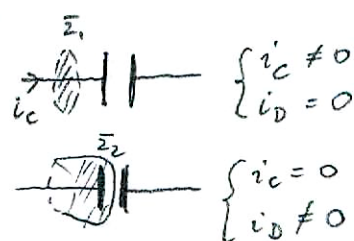
$$i_D \stackrel{\text{def}}{=} \epsilon_0 \frac{d\Phi_E}{dt}$$

(Maxwell's idea)

Hence the complete Ampère's law

$$\oint \vec{B} \cdot d\vec{l} = \mu_0 (i_c + i_D)_{\text{enc}}$$

↳ displacement current
 ↳ conduction current

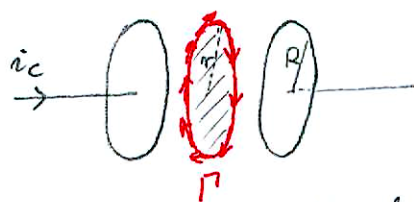


Notes: (1) corresponding displacement current density j_D may be defined, $j_D = i_D/A$

(2) Kirchhoff's junction rule is now fixed

$$i_c - i_D = 0$$

How to detect the displacement current?



circular-plate capacitor

Idea!

current \Rightarrow magnetic field

\Downarrow
look for magnetic field between the plates

Use Ampère's law with loop Γ (circle with radius r)

\rightarrow current density

$$1^\circ r < R \quad \oint_{\Gamma} \vec{B} \cdot d\vec{l} \stackrel{\text{symmetry}}{=} 2\pi r B(r) = \mu_0 I_{\text{enc}} = \mu_0 \left(\frac{i_D}{\pi R^2} \right) \pi r^2 = \mu_0 \frac{i_D}{R^2} r^2$$

$$\boxed{B(r) = \frac{\mu_0}{2\pi} \frac{\pi}{R^2} i_D}$$

$2^\circ r > R$

$$\oint_{\Gamma} \vec{B} \cdot d\vec{l} = 2\pi r B(r) = \mu_0 i_D \Rightarrow \boxed{B(r) = \frac{\mu_0}{2\pi r} i_D}$$

measurement

The displacement current may be detected by a magnetic field \checkmark .

Maxwell's equations (free space; integral form)

Gauss's law for \vec{E} (1) $\oint_{\Sigma} \vec{E} \cdot d\vec{A} = \frac{Q_{\text{enc}}}{\epsilon_0}$ any closed surface Σ

Gauss's law for \vec{B} (2) $\oint_{\Sigma} \vec{B} \cdot d\vec{A} = 0$ any closed surface Σ

Ampère's law (3) $\oint_{\Gamma} \vec{B} \cdot d\vec{l} = \mu_0 \left(i + \epsilon_0 \frac{d\Phi_E}{dt} \right)_{\text{enc}}$ any loop Γ
conduction current

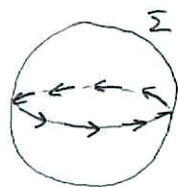
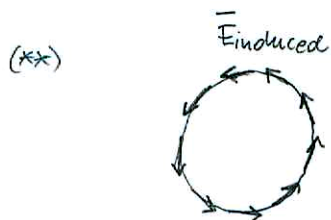
Faraday's law (4) $\oint_{\Gamma} \vec{E} \cdot d\vec{l} = - \frac{d\Phi_B}{dt}$ any stationary loop Γ

Comment on the electric field

$$\vec{E} = \vec{E}_{\text{charge}} + \vec{E}_{\text{induced}}$$

↓
due to charges
(conservative!)
↓
due to time-dependent magnetic field (flux)
(non-conservative!)

(*) $\oint_{\Gamma} \vec{E} \cdot d\vec{l} = \oint_{\Gamma} (\vec{E}_{\text{charge}} + \vec{E}_{\text{induced}}) = \underbrace{\oint_{\Gamma} \vec{E}_{\text{charge}} \cdot d\vec{l}}_{=0 \text{ always!}} + \oint_{\Gamma} \vec{E}_{\text{induced}} \cdot d\vec{l} =$
 $= \oint_{\Gamma} \vec{E}_{\text{induced}} \cdot d\vec{l}$ only \vec{E}_{induced} may contribute to circulation



→ flux
 here $\oint_{\Sigma} \vec{E}_{\text{induced}} \cdot d\vec{A} = 0$ (no charge enclosed)

so $\oint_{\Sigma} \vec{E} \cdot d\vec{A} = \oint_{\Sigma} \vec{E}_{\text{charge}} \cdot d\vec{A}$

only \vec{E}_{charge} contributes to flux

Maxwell's equations (free space; differential form)

Apply Gauss-Ostrogradsky theorem and Stokes theorem to (1) - (4)

$$(1') \quad \operatorname{div} \vec{E} = \frac{\rho}{\epsilon_0}$$

$$(2') \quad \operatorname{div} \vec{B} = 0$$

$$(3') \quad \operatorname{rot} \vec{B} = \mu_0 \vec{j} + \mu_0 \epsilon_0 \frac{\partial \vec{E}}{\partial t}$$

$$(4') \quad \operatorname{rot} \vec{E} = - \frac{\partial \vec{B}}{\partial t}$$

Comment (3) \rightarrow (3')

$$\oint_{\Gamma} \vec{B} \cdot d\vec{l} = \mu_0 \left(i + \epsilon_0 \frac{d\Phi_E}{dt} \right)_{\text{enc}}$$

lhs

$$\oint_{\Gamma} \vec{B} \cdot d\vec{l} \stackrel{\text{Stokes}}{=} \int_{\Sigma} \operatorname{rot} \vec{B} \cdot d\vec{A}$$



rhs

$$\begin{aligned} \mu_0 \left(i + \epsilon_0 \frac{d\Phi_E}{dt} \right)_{\text{enc}} &= \mu_0 \left(\int_{\Sigma} \vec{j} \cdot d\vec{A} + \epsilon_0 \frac{d}{dt} \int_{\Sigma} \vec{E} \cdot d\vec{A} \right) = \\ &= \mu_0 \int_{\Sigma} \left(\vec{j} + \epsilon_0 \frac{\partial \vec{E}}{\partial t} \right) \cdot d\vec{A} \end{aligned}$$

Additional comments

Scalar and vector potentials

The fields \vec{E} and \vec{B} can be described in terms of potentials:

Scalar potential V and vector potential \vec{A} , such that

$$\vec{E} = -\text{grad } V - \frac{\partial \vec{A}}{\partial t}$$

$$\vec{B} = \text{rot } \vec{A}$$

Note: $\text{div } \vec{B} = \text{div rot } \vec{A} \equiv 0$

$$\text{rot } \vec{E} = -\underbrace{\text{rot grad } V}_{\equiv 0} - \text{rot } \frac{\partial \vec{A}}{\partial t} = -\frac{\partial}{\partial t} \text{rot } \vec{A} = -\frac{\partial \vec{B}}{\partial t}$$

The potentials are not uniquely determined, i.e. different potentials may result in the same fields - choice of gauge.

Fields are invariant under the following gauge transformation

$$\vec{A}' = \vec{A} + \nabla f$$

$$V' = V - \frac{\partial f}{\partial t}$$

\Rightarrow

$$\vec{B}' = \text{rot}(\vec{A} + \nabla f) = \text{rot } \vec{A} + \underbrace{\text{rot grad } f}_{\equiv 0} = \vec{B} \quad \checkmark$$

$$\vec{E}' = -\text{grad } V' - \frac{\partial \vec{A}'}{\partial t} =$$

$$= -\text{grad } V - \frac{\partial}{\partial t} \text{grad } f - \frac{\partial \vec{A}}{\partial t} - \frac{\partial}{\partial t} \text{grad } f =$$

$$= \vec{E} \quad \checkmark$$

Examples (various ways of choosing the gauge)

(1) Coulomb gauge $\text{div } \vec{A} = 0$

(2) Lorentz gauge $\text{div } \vec{A} + \frac{1}{c^2} \frac{\partial V}{\partial t} = 0$

c - speed of light in vacuum

(3) $\vec{A} = -B_y \hat{u}_x$ for ^{uniform} magnetic field in z -direction (Landau gauge)

(or $\vec{A} = B_x \hat{u}_y$)