

# Photoacoustic Ultrasound (PAUS) for Co-Registered Imaging of Bone Structure and Vasculature

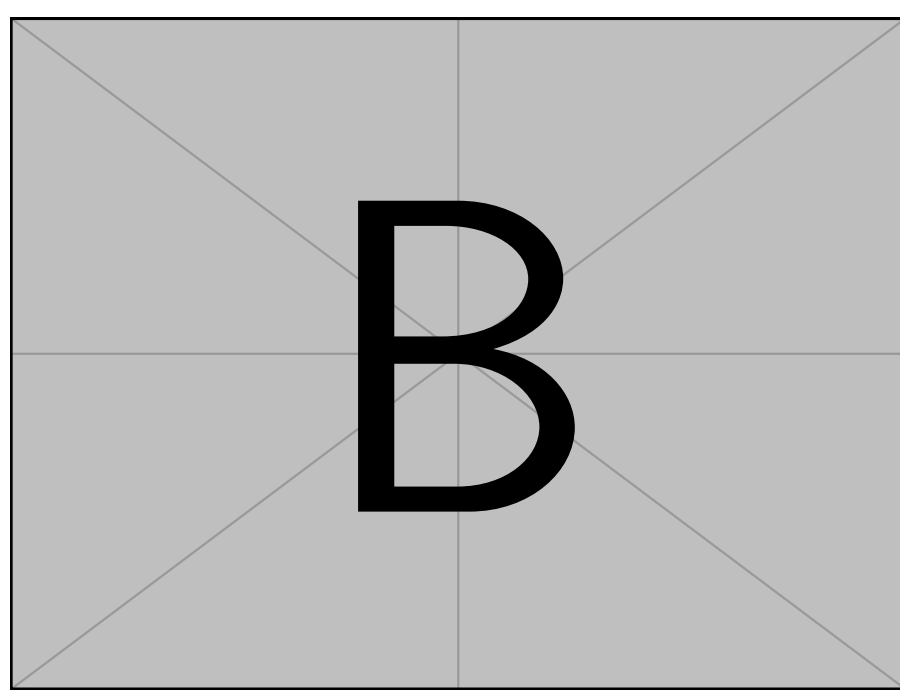
**Sponsor:** Shawn Ma, *Covidien*

**Team Members:** Song Guo, Yao Hou, Chen Li, Tianxiang Xu, Yuhan Zhang

**Faculty Advisor:** Prof. Sung-Liang Chen **Instructor:** Prof. Shane Johnson

## Problem Statement

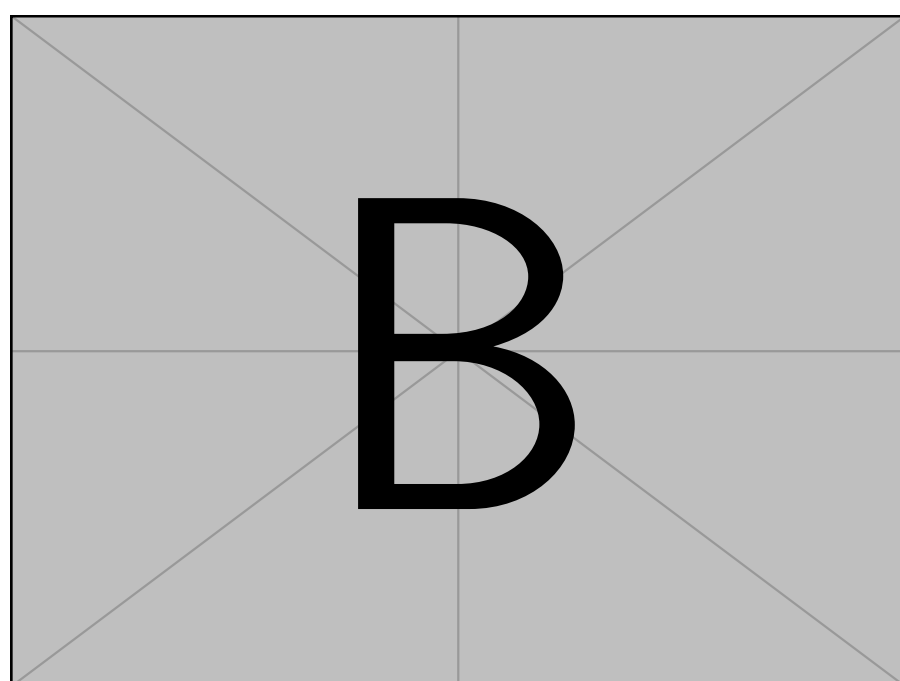
Some diseases, such as cancer, cannot be easily detected in early stage. Both the two existing imaging techniques, photoacoustic and ultrasound imaging are not able to detect the osseous and vascular structure simultaneously. This project is to combine these two techniques to build the dual modality system and reconstruct the 3D image of human tissue.



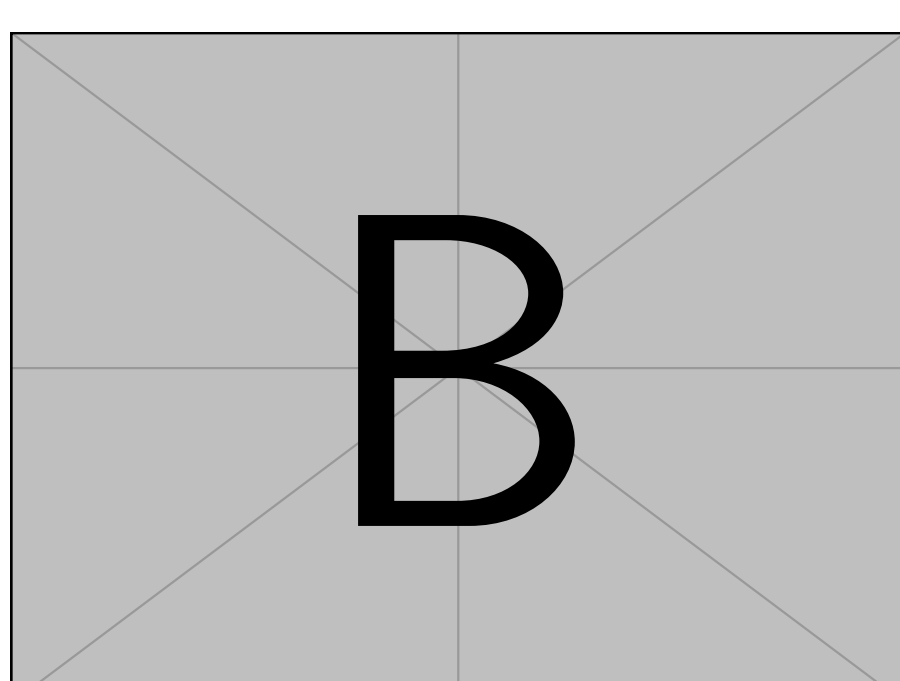
**Fig. 1:** 3D image of human bone and vasculature [1]

## Concept Generation

Sub-system concepts are converting the thermal energy caused by laser and energy of ultrasonic wave into digital signals. And a phantom should be designed to simulate the human tissue, since phantom can be easily used for validation.



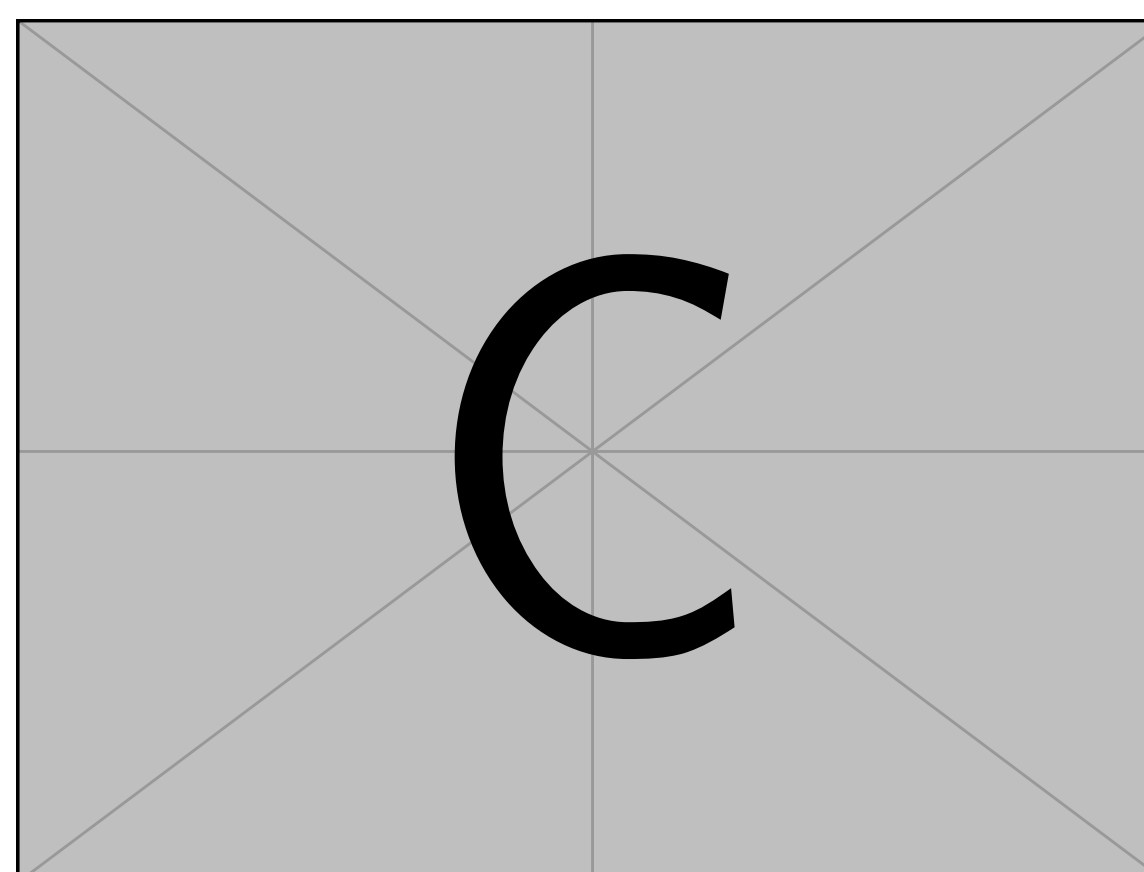
**Fig. 2:** Detailed structure function



**Fig. 3:** Concept Diagram

## Design Description

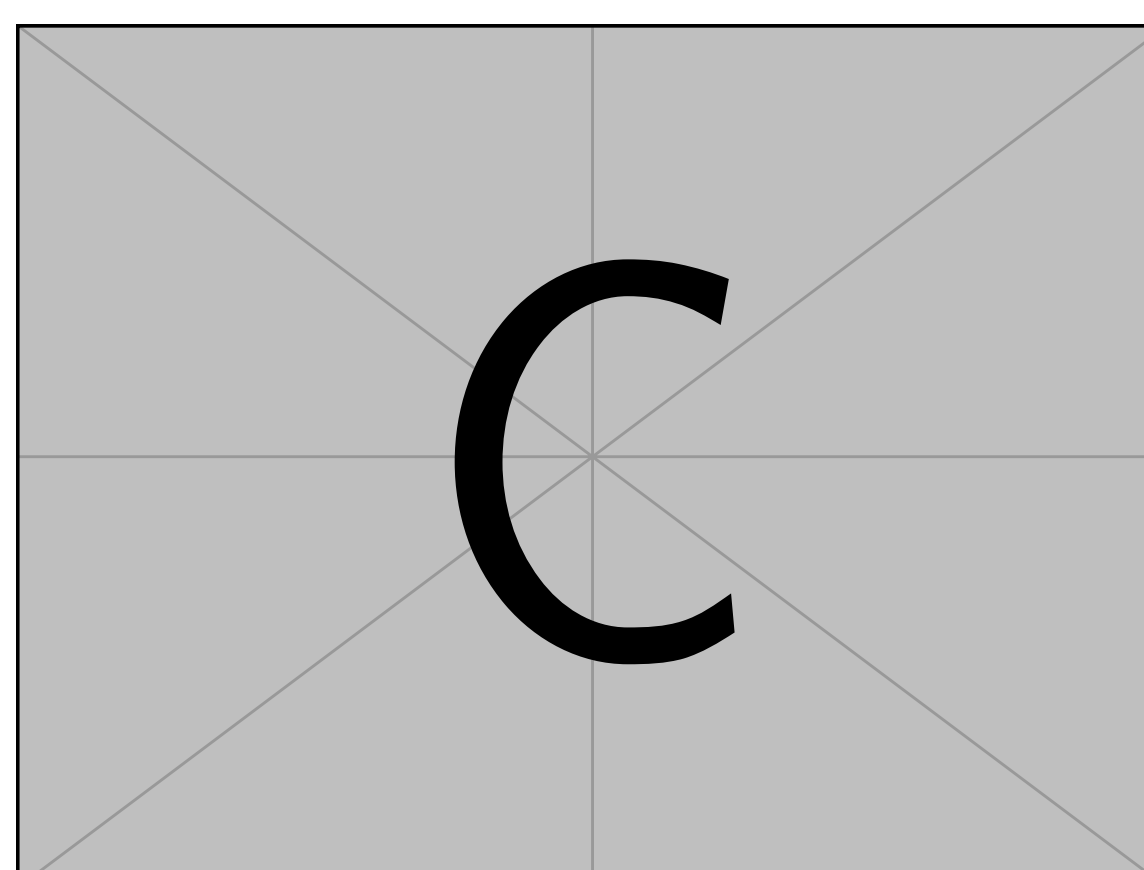
The design uses two step motors to move the phantom in XY plane. Three mirrors lead the green laser to shoot from the side of phantom to heat up the blood. The transducer receives the thermal signal reflected from vessels and also sends and receives the ultrasound signal reflected from the bone. The two signals of laser and ultrasound can alternately appear on the oscilloscope. Using labview, the signal can be transformed into data in Matlab. By dealing with the data of depth, the 3D image can be shown on the laptop screen.



**Fig. 4:** The whole set-up system

## Modeling and Analysis

A matlab model is built to transform the depth data into 3D image. It firstly transforms the raw data into 2D image. The following graph shows a 2D bone profile of the phantom. Same modeling method can be used to transform 2D image to 3D.



**Fig. 5:** 2D bone profile

## Validation

### Validation Process:

For step length, a ruler was set along the track and then the running time was set for 100. Then the system ran. When it stops, the distance between starting and end can be measured. For loading bearing, a 10kg object was put on the track and then system can be started. If the track can run normally and no deflections happen, it can meet this specification. For data processing speed, a timer can be used to measure. Some other specifications can also be verified using easy experiments.

### Validation Results:

According to validation part, most specifications can be met.

✓ Transducer frequency  $\geq 10\text{MHz}$

✓ Wavelength of laser  $\geq 523\text{nm}$

✓ Motor speed  $\geq 1200\text{mm/s}$

✓ Step length  $\leq 50\mu\text{m/step}$

✓ Load bearing  $\geq 10\text{kg}$

✓ Weight  $\leq 100\text{kg}$

✓ Cost  $\leq 500000\text{RMB}$

▪ Time for data processing  $\leq 30\text{min}$

✓ means having been verified and • means to be determined.

## Conclusion

Photoacoustic and ultrasound imaging techniques can be used for detecting osseous and vascular structures simultaneously. The key to achieve this goal is to set up the dual modality system. And also, the accuracy and speed of the detection is very important to form the images.

## Acknowledgement

Sponsor: Shawn Ma from Covidien  
Shane Johnson, Sung-Liang Chen and Huan Qi from UM-SJTU Joint Institute  
Hongkun Lai and Xunjie Cai from UM-SJTU Joint Institute

## Reference

[1] <http://labs.seas.wustl.edu/bme/Wang/index.html>