

# Linear algebra review

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If you're feeling a bit rusty, these are the linear algebra highlights that you will need to get started with some of the pages on this site.

This is by no means a comprehensive introduction to linear algebra, but hopefully can provide a refresher on the topics necessary to understand the conjugate gradient algorithm. I do assume that you have seen linear algebra before, so if everything here looks foreign, I suggest taking a look at [Khan Academy](#) videos first.

## Some notation

I'll generally use capital letters to denote matrices, and lower case letters to denote vectors.

When I am talking about the entries of a matrix (or vector), I will use brackets to indicate this. For instance,  $[A]_{4,2}$  is the 4, 2 entry of the matrix  $A$ . If I want to take an entire row or column I will indicate this with a colon. So  $[A]_{2,:}$  is the 2nd row of  $A$  (think of this as taking the  $(2, i)$ -entries for all  $i$ ) while  $[A]_{:,1}$  is the first column of  $A$ . If  $v$  is a vector, then I will often only write one index. Thus,  $[v]_3$  denotes the 3-rd element of  $v$  regardless of if  $v$  is a row or column vector.

## Some definitions

We will denote the *transpose* of a matrix by  $T$ , and the *conjugate transpose* (also known as *Hermitian transpose*) by  $H$ .

A matrix  $A$  is called *symmetric* if  $A^T = A$ , and is called *Hermitian* if  $A^H = A$ .

The identity matrix will be denoted  $I$ . Occasionally it may be denoted by  $I_k$  to emphasize that it is of size  $k$ .

A vector is called *normal* if it has norm one.

Two vectors are called *orthogonal* if their inner product is zero.

If two vectors are both normal, and are orthogonal to one another, they are called *orthonormal*.

A matrix  $U$  is called unitary if  $U^H U = U U^H = I$ . This is equivalent to all the columns being (pairwise) orthonormal.

A Hermitian (symmetric) matrix is called *positive definite* if  $x^H A x > 0$  ( $x^T A x > 0$ ) for all  $x$ . This is equivalent to having all positive eigenvalues.

An *eigenvalue* of a square matrix  $A$  is any scalar  $\lambda$  for which there exists a vector  $v$  so that  $Av = \lambda v$ . The vector  $v$  is called an *eigenvector*.

## Different perspectives on matrix multiplication

### Matrix vector products

Let's start with a matrix  $A$  of size  $m \times n$  ( $m$  columns and  $n$  rows), and a vector  $v$  of size  $n \times 1$  ( $n$  columns and 1 row).

Then the product  $Av$  is well defined, and the  $i$ -th entry of the product is given by,

$$[Av]_i = \sum_{j=1}^n [A]_{i,j} [v]_j$$

There are perhaps two dominant ways of thinking about this product. The first is that the  $i$ -th entry is the matrix product of the  $i$ -th row of  $A$  with  $v$ . That is,

$$[Av]_i = [A]_{i,:} v$$

Alternatively, and arguably more usefully, the product  $Av$  can be thought of as the linear combination of the columns of  $A$ , where the coefficients are the entries of  $v$ . That is,

$$Av = \sum_{k=1}^n [v]_k [A]_{:,k}$$

For example, suppose we have vectors  $q_1, q_2, \dots, q_k \in \mathbb{R}^n$ , and that  $Q$  is the  $n \times k$  matrix whose columns are  $\{q_1, q_2, \dots, q_k\}$ . Then saying  $x$  is in the span of  $\{q_1, q_2, \dots, q_k\}$  by definition means that there exists coefficients  $c_i$  such that,

$$x = c_1 q_1 + c_2 q_2 + \dots + c_k q_k$$

This is exactly the same as saying there exists a vector  $c \in \mathbb{R}^k$  such that,

$$x = Qc$$

Understanding this perspective on matrix vector products will be very useful in understanding the matrix form of the Arnoldi and Lanczos algorithms.

### Matrix matrix products

Now, lets keep our matrix  $A$  of size  $m \times n$ , and add a matrix  $B$  of size  $n \times p$ . Then the product  $AB$  is well defined, and the  $i, j$  entry of the product is given by,

$$[AB]_{i,j} = \sum_{k=1}^n [A]_{i,k} [B]_{k,j}$$

Again we can view the  $i, j$  entry as the matrix product of the  $i$ -th row of  $A$  with the  $j$ -th column of  $B$ . That is,

$$[AB]_{i,j} = [A]_{i,:} [B]_{:,j}$$

On the other hand, we can view the  $j$ -th column of  $AB$  as the product of  $A$  with the  $j$ -th column of  $B$ . That is,

$$[AB]_{:,j} = A B_{:,j}$$

We can now use either of our perspectives on matrix vector products to view  $AB_{:,j}$ . This perspective is again useful for understanding the matrix forms of the Arnoldi and Lanczos algorithms.

### Inner products and vector norms

Given two vectors  $x$  and  $y$ , the Euclidian inner product is defined as,

$$\langle x, y \rangle = x^H y$$

This naturally defines the Euclidian norm (also called 2-norm) of a vector,

$$\|x\| = \|x\|_2 = \sqrt{\langle x, x \rangle}$$

A symmetric positive definite matrix  $A$  naturally induces the  $A$ -inner product,  $\langle \cdot, \cdot \rangle_A$ , defined by

$$\langle x, y \rangle_A = \langle x, Ay \rangle = \langle Ax, y \rangle$$

The associated norm, called the  $A$ -norm will is denoted  $\|\cdot\|_A$  and is defined by,

$$\|x\|_A^2 = \langle x, x \rangle_A = \langle x, Ax \rangle = \|A^{1/2}x\|^2$$

### Matrix norms

Usually the matrix norm 2-norm (also called operator norm, spectral norm, Euclidian norm) is defined by,

$$\|A\| = \sup_{v \neq 0} \frac{\|Av\|}{\|v\|}$$

It's always the case that the 2-norm of a matrix is the largest singular value of that matrix.

Since the singular values and eigenvalues of a positive definite matrix are the same, the 2-norm of a positive definite matrix is the largest eigenvalue.

The 2-norm is *submultiplicative*. That is, for any two matrices  $A$  and  $B$ ,

$$\|AB\| \leq \|A\|\|B\|$$

The 2-norm is *unitarily invariant*. That is, if  $U$  is unitary then  $\|UA\| = \|AU\| = \|A\|$ .

## Projections

The projection of  $x$  onto  $q$  is

$$\text{proj}_q(x) = \frac{\langle x, q \rangle}{\langle q, q \rangle} q$$

If we *orthogonalize*  $x$  against  $q$ , we mean take the component of  $x$  orthogonal to  $q$ . That is,

$$x - \text{proj}_q(x) = x - \frac{\langle x, q \rangle}{\langle q, q \rangle} q$$

In both cases, if  $q$  is normal, then  $\langle q, q \rangle = 1$

A matrix is called a projection if  $P^2 = P$ . However, we will generally be more concerned with projecting onto a subspace. If  $Q$  has orthonormal columns, then  $QQ^H$  is a projector onto the span of the columns.

In particular, if  $q_1, q_2, \dots, q_k$  are the columns of  $Q$ , then,

$$\begin{aligned} QQ^H x &= q_1 q_1^H x + q_2 q_2^H x + \dots + q_k q_k^H x \\ &= \langle q_1, x \rangle q_1 + \langle q_2, x \rangle q_2 + \dots + \langle q_k, x \rangle q_k \end{aligned}$$

This is just the sum of the projections of  $x$  onto each of  $\{q_1, q_2, \dots, q_k\}$ . Therefore, if we want to project onto a subspace  $V$ , it is generally helpful to have an orthonormal basis for this subspace.

The point in a subspace  $V$  nearest to a point  $x$  is the projection of  $x$  onto  $V$  (where projection is done with respect to the inner product and distance is measured with the induced norm).

Similarly, if we want to orthogonalize  $x$  against  $q_1, q_2, \dots, q_k$  we simply remove the projection of  $x$  onto this space from  $x$ . That is,

$$x - QQ^* x = (I - QQ^*)x = x - \langle q_1, x \rangle q_1 - \langle q_2, x \rangle q_2 - \dots - \langle q_k, x \rangle q_k$$

The resulting vector is orthogonal to each of  $\{q_1, q_2, \dots, q_k\}$ .