Randomized matrix-free quadrature

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chen.pw/slides.pdf

What is a matrix function?

An $n \times n$ symmetric matrix **A** has real eigenvalues and orthonormal eigenvectors:

$$\mathbf{A} = \sum_{i=1}^{n} \lambda_i \mathbf{u}_i \mathbf{u}_i^{\mathsf{T}}.$$

The matrix function f(A) is defined as

$$f(\mathbf{A}) := \sum_{i=1}^n f(\lambda_i) \mathbf{u}_i \mathbf{u}_i^{\mathsf{T}}.$$

Trace estimation

We will look at some algorithms for estimating

$$\operatorname{tr}(f(\mathbf{A})) = f(\lambda_1) + \dots + f(\lambda_n).$$

These algorithms use:

- Stochastic trace estimation
- Krylov subspace methods

A number of widely used algorithms fall into this class, but it's still an active area of algorithm development 2

¹Skilling 1989; Silver and Röder 1994; Silver, Roeder, Voter, and Kress 1996; Weiße, Wellein, Alvermann, and Fehske 2006; Bai. Fahey, and Golub 1996.

²Lin 2016; Gambhir, Stathopoulos, and Orginos 2017; Saibaba, Alexanderian, and Ipsen 2017; Morita and Tohyama 2020; Meyer, Musco, Musco, and Woodruff 2021; Li and Zhu 2021; Chen and Hallman 2022: Persson and Kressner 2022.

Direct methods

Can compute f(A) via eigendecomposition of A. However,

- this is slow: n^3 computation
- intractable storage costs: even if **A** is sparse, $f(\mathbf{A})$ typically is not
 - for $n = 2^{20}$, a $n \times n$ matrix of 64bit numbers requires 8.8 terrabytes

However, matrix products with **A** might be tractable.

Integral representation

We can write the trace as an integral

$$\operatorname{tr}(f(\mathbf{A})) = n \int f d\Phi,$$

where the cumulative empirical spectral measure (CESM) Φ is

$$\Phi(x) := \sum_{i=1}^{n} \frac{1}{n} \mathbb{1}(\lambda_i \le x) = \operatorname{tr}(\mathbb{1}(\mathbf{A} \le x)).$$

Integral representation

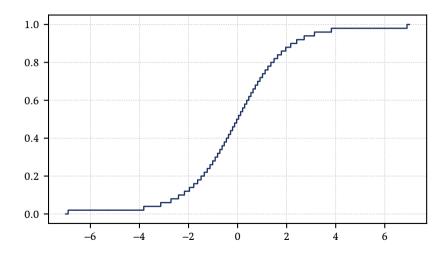
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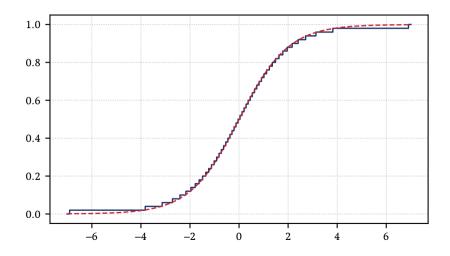
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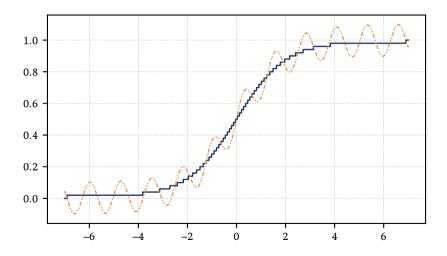
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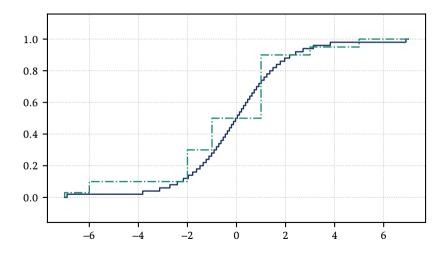
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trace approximation ↔ CESM approximation









Global approximation to CESM

Goal: Get a coarse approximation to Φ such that integrals are nearly preserved

Idea: Compute quadrature rule for Φ

$$-\int x^k d\Phi = \operatorname{tr}(\mathbf{A}^k)$$

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Idea: Compute quadrature rule for Φ

$$- \int x^k d\Phi = \operatorname{tr}(\mathbf{A}^k)$$

Problem: We can't compute integrals against Φ without computing traces

Idea: stochastic trace estimation

Stochastic trace estimation

It's well known that when **v** is such that $\mathbb{E}[\mathbf{v}\mathbf{v}^{\mathsf{T}}] = n^{-1}\mathbf{I}$, then

$$n\mathbb{E}[\mathbf{v}^{\mathsf{T}}\mathbf{B}\mathbf{v}] = \operatorname{tr}(\mathbf{B}).$$

We call an estimator $\mathbf{v}^{\mathsf{T}}\mathbf{B}\mathbf{v}$ a quadratic trace estimator.

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- Often attributed to Hutchinson 1989
- Earlier work by Girard 1987 and Skilling 1989
- Use of random states as algorithmic tool since at least 1970s³
- Morally equivalent to quantum typicality from late 1920s⁴

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The weighted CESM

We can write quadratic forms as an integral

$$\mathbf{v}^{\mathsf{T}} f(\mathbf{A}) \mathbf{v} = \int f \mathrm{d} \Psi$$

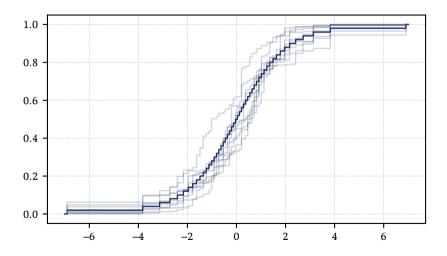
where

$$\Psi(x) := \sum_{i=1}^{n} |\mathbf{v}^{\mathsf{T}} \mathbf{u}_{i}|^{2} \mathbb{1}(\lambda_{i} \leq x).$$

If \mathbf{v} is an isotropic random vector,

$$\mathbb{E}[\Psi(x)] = \sum_{i=1}^{n} \mathbb{E}[|\mathbf{v}^{\mathsf{T}}\mathbf{u}_{i}|^{2}]\mathbb{1}(\lambda_{i} \leq x) = \sum_{i=1}^{n} \frac{1}{n}\mathbb{1}(\lambda_{i} \leq x) = \Phi(x).$$

The weighted CESM



Polynomial quadrature

Let $[f]_s^{\circ p}$ be a degree s polynomial approximation to f and $[\Psi]_s^{\circ q}$ the induced quadrature approximation to Ψ defined by

$$\int f d[\Psi]_s^{\circ q} = \int [f]_s^{\circ p} d\Psi.$$

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Given a distribution function μ , let $\{p_i\}_{i=0}^{\infty}$ be the (normalized) orthogonal polynomials. Define moments,

$$m_i := \int p_i d\Psi = \mathbf{v}^\mathsf{T} p_i(\mathbf{A}) \mathbf{v}.$$

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If $[f]_s^{\circ p} = c_0 p_0 + \cdots + c_s p_s$, then

$$\int f d[\Psi]_s^{\circ q} = \int \sum_{i=0}^s c_i p_i d\Psi = \sum_{i=0}^s c_i \int p_i d\Psi = \sum_{i=0}^s c_i m_i.$$

Algorithms

So, we get an algorithm:

$$\operatorname{tr}(f(\mathbf{A})) \approx \int f \mathrm{d} \langle [\Psi_i]_s^{\circ \mathbf{q}} \rangle = \frac{1}{n_{\mathrm{v}}} \sum_{i=1}^n \int f \mathrm{d} [\Psi_i]_s^{\circ \mathbf{q}}.$$

Different choices of $[f]_s^{\circ p}$ correspond to different algorithms:

- Kernel Polynomial Method: damped Chebyshev approximation
- Stochastic Lanczos Quadrature: Interpolation at zeros of orthogonal polynomials of $\boldsymbol{\Psi}$

Requires construction of Krylov subspaces

$$\mathrm{span}\{\mathbf{v}_i,\mathbf{A}\mathbf{v}_i,\ldots,\mathbf{A}^k\mathbf{v}_i\}.$$

A unified framework⁵

Traditionally, algorithms like KPM would be implemented using an explicit Chebyshev recurrence

⁵Chen, Trogdon, and Ubaru 2022.

A unified framework⁵

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A key observation: we could instead use the output of Lanczos

- allows a posteriori choice of hyperparameters
 - more stable implementations
 - can cheaply try different quadrature approximations
- allows simultaneous theoretical analysis of algorithms
- allows tradeoffs between algorithms to be more clearly understood

⁵Chen, Trogdon, and Ubaru 2022.

Finite precision arithmetic

It's well know that the Lanczos algorithm is unstable, so people are afraid of using it without reorthogonalization⁶ (expensive)

⁶Jaklič and Prelovšek 1994; Silver, Roeder, Voter, and Kress 1996; Aichhorn, Daghofer, Evertz, and Linden 2003; Weiße, Wellein, Alvermann, and Fehske 2006; Ubaru, Chen, and Saad 2017; Granziol, Wan, and Garipov 2019.

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However, for certain tasks, the algorithm is actually backwards stable in a certain (useful sense)⁷ even without reorthogonalization

- for these problems, "instability" is actually just an ill-conditioned task
- i.e. computing certain quantities is inherently hard, but we don't really need to compute them accurately to get what we want

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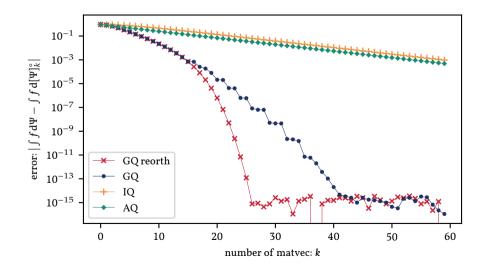
- for these problems, "instability" is actually just an ill-conditioned task
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Moreover, direct implementations of alternate algorithms like KPM are stable given good hyper-parameter choice, but exponentially unstable otherwise.

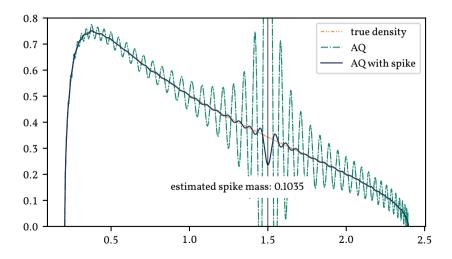
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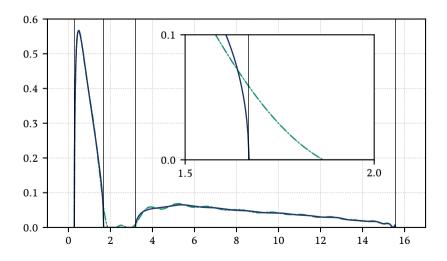
Example: Runge function



Example: random matrtix



Example: random matrtix



Beyond quadratic trace estimation

A simple analysis of the variance (for Gaussians) implies

$$|\mathbf{B} - \langle \mathbf{v}_{\ell}^{\mathsf{T}} \mathbf{B} \mathbf{v}_{\ell} \rangle| \sim \|\mathbf{B}\|_{\mathsf{F}} (n_{\mathsf{v}})^{-1/2}.$$

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More refined concentration inequalities

$$\mathbb{P}[|\mathbf{B} - \langle \mathbf{v}_{\ell}^{\mathsf{T}} \mathbf{B} \mathbf{v}_{\ell} \rangle| > \epsilon] \leq \delta.$$

- Applied Math/CS (iid entries): early analyses⁸, refined analyses⁹

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- Applied Math/CS (iid entries): early analyses⁸, refined analyses⁹
- Physics (uniform from hypersphere): Chebyshev¹⁰, sub-Gaussian¹¹(via Lèvy's Lemma). refined bounds for practical dimensions¹²

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Low rank approximation

We can always decompose

$$tr(\mathbf{B}) = tr(\widehat{\mathbf{B}}) + tr(\widehat{\mathbf{B}}), \quad where \quad \widetilde{\mathbf{B}} := \mathbf{B} - \widehat{\mathbf{B}}.$$

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So, let's output

$$\operatorname{tr}(\mathbf{B}) = \operatorname{tr}(\widehat{\mathbf{B}}) + \langle \mathbf{\psi}_{\ell}^{\mathsf{T}} \widetilde{\mathbf{B}} \mathbf{\psi}_{\ell} \rangle = \operatorname{tr}(\widehat{\mathbf{B}}) + \frac{1}{m} \operatorname{tr}(\mathbf{\Psi}^{\mathsf{T}} \widetilde{\mathbf{B}} \mathbf{\Psi})$$

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This is beneficial if:

- $tr(\widehat{\mathbf{B}})$ can be computed efficiently, and
- the variance of $tr(\mathbf{\Psi}^{\mathsf{T}}\mathbf{\tilde{B}}\mathbf{\Psi})$ is reduced compared to $tr(\mathbf{\Psi}^{\mathsf{T}}\mathbf{B}\mathbf{\Psi})$

A lot of recent work¹³ uses this idea to varying extent

¹³Lin 2016; Gambhir, Stathopoulos, and Orginos 2017; Saibaba, Alexanderian, and Ipsen 2017; Morita and Tohyama 2020; Li and Zhu 2021; Meyer, Musco, Musco, and Woodruff 2021; Chen and Hallman 2022; Persson and Kressner 2022.

Take $\hat{\mathbf{B}}$ as low rank approximation $\hat{\mathbf{B}} = \mathbf{Q}\mathbf{Q}^{\mathsf{T}}\mathbf{B}\mathbf{Q}\mathbf{Q}^{\mathsf{T}}$

- Compute **Q** by sketching: **Q** = ORTH(**B** Ω) where Ω is $n \times b$ random matrix

Simplify a bit:

- $-\operatorname{tr}(\widehat{\mathbf{B}}) = \operatorname{tr}(\mathbf{Q}\mathbf{Q}^{\mathsf{T}}\mathbf{B}\mathbf{Q}\mathbf{Q}^{\mathsf{T}}) = \operatorname{tr}(\mathbf{Q}^{\mathsf{T}}\mathbf{B}\mathbf{Q})$
- $-\operatorname{tr}(\widetilde{\mathbf{B}}) = \operatorname{tr}((\mathbf{I} \mathbf{Q}\mathbf{Q}^{\mathsf{T}})\mathbf{B}(\mathbf{I} \mathbf{Q}\mathbf{Q}^{\mathsf{T}}))$
- $\operatorname{tr}(\boldsymbol{\Psi}^{\mathsf{T}}\widetilde{\mathbf{B}}\boldsymbol{\Psi}) = \operatorname{tr}(\mathbf{Y}^{\mathsf{T}}\mathbf{B}\mathbf{Y})$, where $\mathbf{Y} = (\mathbf{I} \mathbf{O}\mathbf{O}^{\mathsf{T}})\boldsymbol{\Psi}$.

Number of matvecs with **B** is: 2b + m, and if we set b = m, can get scaling

accuracy $\sim (\# \text{ matvecs})^{-1}$

¹⁴Meyer, Musco, Musco, and Woodruff 2021.

What about matrix functions? (i.e. $\mathbf{B} = f(\mathbf{A})$)

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Suppose we use q iterations of Lanczos to approximate $f(\mathbf{A})\Omega$. Then, at least implicitly, we construct

 $\operatorname{span}\{\mathbf{\Omega},\mathbf{A}\mathbf{\Omega},\ldots,\mathbf{A}^q\mathbf{\Omega}\}$

Naive Hutch++ would take $\mathbf{Q} \in \mathbb{R}^{n \times b}$ as a basis for our approximation to $f(\mathbf{A})\Omega$.

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Naive Hutch++ would take $\mathbf{Q} \in \mathbb{R}^{n \times b}$ as a basis for our approximation to $f(\mathbf{A})\Omega$.

Instead, take $\mathbf{Q} \in \mathbb{R}^{n \times (q+1)b}$ as basis for the whole Krylov subspace

- Same number of matvecs with A, but (much) larger search space..

Regardless of our choice of \mathbf{Q} , the next step is approximating $f(\mathbf{A})\mathbf{Q}$.

Suppose we use n iterations of Lanczos. Then we need to construct

$$\operatorname{span}\{\mathbf{Q}, \mathbf{AQ}, \dots, \mathbf{A}^n\mathbf{Q}\}$$

If **Q** has (q+1)b instead of b columns, this ostensibly requires n(q+1)b matvecs with **A** instead of nb required by a naive implementation.

Recall, **Q** is a basis for

$$\mathrm{span}\{\mathbf{\Omega},\mathbf{A}\mathbf{\Omega},\ldots,\mathbf{A}^q\mathbf{\Omega}\}.$$

Thus, the columns of $A^{j}Q$ span

$$\mathrm{span}\{\mathbf{A}\mathbf{\Omega},\mathbf{A}^2\mathbf{\Omega},\ldots,\mathbf{A}^{q+1}\mathbf{\Omega}\}.$$

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So actually,

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So actually,

$$span{\mathbf{Q}, \mathbf{AQ}, \dots, \mathbf{A}^{n}\mathbf{Q}} = span{\mathbf{\Omega}, \mathbf{AQ}, \dots, \mathbf{A}^{q+n}\mathbf{\Omega}}.$$

In other words, to approximate $f(\mathbf{A})\mathbf{Q}$ we only need nb matrix-vector products!

Krylov aware stochastic trace estimation¹⁵

This "Krylov aware" idea is simple, but provides many benefits.

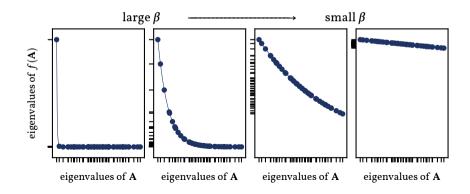
- use a (much) larger projection space "for free"
- algorithm is now agnostic to f
 - we can easily compute approximations to $tr(f(\mathbf{A}))$ for multiple f without additional matrix products with \mathbf{A} .
 - in particular, the approximation we get is a quadrature approximation for Ψ

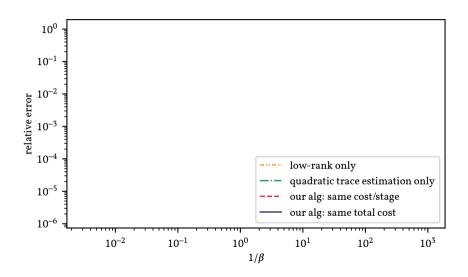
¹⁵Chen and Hallman 2022.

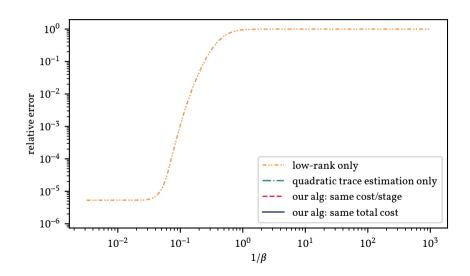
Example: equilibrium thermodynamics of quantum spin systems

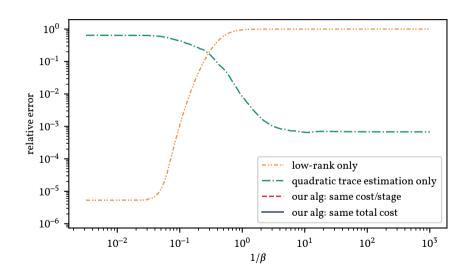
In quantum physics, we often wish to compute $tr(f(\mathbf{A})) = tr(\exp(-\beta \mathbf{A}))$ for all $\beta > 0$.

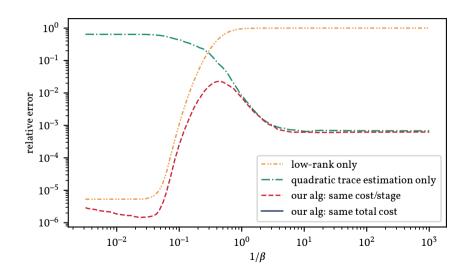
- if $\beta = \infty$ (zero temperature), then we only need ground state(s)
- if $\beta = 0$ (high temperature), then quadratic trace estimation works very well
- for intermediate beta, we might expect low-rank approaches to work well

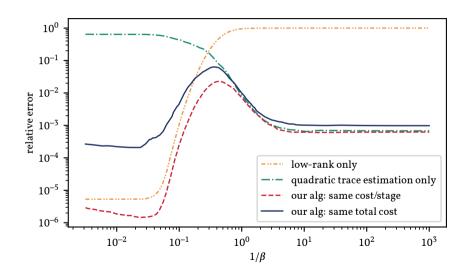












Variants

We also have a number of modifications to make this idea more practical:

- Using the information in the space span $\{\Omega, A\Omega, ..., A^{q+n}\Omega\}$ we can approximate

$$\|(\mathbf{I} - \mathbf{Q}\mathbf{Q}^{\mathsf{T}}f(\mathbf{A})(\mathbf{I} - \mathbf{Q}\mathbf{Q}^{\mathsf{T}})\|$$

in order to determine a good value of q.

– If memory or reorthogonalization costs are an issue, we can use restarting, and pick $\mathbf{Q} \subset \operatorname{span}\{\Omega, \mathbf{A}\Omega, \dots, \mathbf{A}^{q+1}\Omega\}$

- e.g.
$$\mathbf{Q} = \mathbf{A}^{q+1} \mathbf{\Omega}$$

Future work

- $\operatorname{tr}(\exp(-\beta(\mathbf{A} + h\mathbf{B})))$ for all $\beta > 0$, $h \in [-h_0, h_0]$.
- generalize low-rank algorithms to partial traces
- better understanding of stability
- lower bounds in matrix-vector query models
- better relationships between physics, applied math, and CS

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