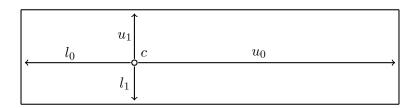
### **Box Spline Mesh Algorithm Summary**

June 5<sup>th</sup>, 2017 Thomas Lux

Given data  $N = \{x_1, x_2, \dots, x_n\} \mid x_i \in \mathbb{R}^d$ , and associated response values  $\{y_1, y_2, \dots, y_n\}$ .

#### 1 Construct Box Mesh

Each box in the box mesh will be specified by a center  $c \in \mathbb{R}^d$ , lower width  $l \in \mathbb{R}^d$ , and upper width  $u \in \mathbb{R}^d$ . A point  $x_i$  is contained by a box if  $(1 \le j \le d)(c_j - l_j < x_{i,j} < c_j + u_j)$ . A two dimensional visual example of the containment region of a box, as we refer to it:



The only restriction is that all widths must be greater than zero. This means that  $\min_i l_i > 0$  and  $\min_i u_i > 0$ . First, order the data in N appropriately (discussed later), initialize a single box with  $c = x_1$  and lower and upper widths of infinity. Now, proceed to add the rest of the points in N by:

# 2 Evaluating A Box

Interpolating and approximating requires using a set of boxes as regions of influence for response values. Given a new data point x is contained by a box b (with associated c,l, and u), we evaluate b(x) as:

- 1. Scale x according to the lower and upper widths of b such that all  $x_j < c_j$  map to (0,0.5) and all  $x_j > c_j$  map to (0.5,1).
- 2. Scale this box-normalized x to be in the appropriate range for the order of B-Spline chosen ( $\times 2$  for order 2, $\times 3$  for order 3, etc.)
- 3. Take the product of the B-Splines along each dimension for the box spline normalized x value.  $\prod_{j=1}^d f(x_j)$  where f is the piecewise polynomial defining the b-spline of the desired order.

## 3 Interpolate y for new x

Identify the set of boxes  $\mathbf{B} = \{b_i \mid b_i \text{ contains } x\}$ . Calculate the estimated response value by

$$\frac{\sum_{b \in \mathbf{B}} b\text{-response} \times b(x)}{\sum_{b \in \mathbf{B}} b(x)}$$

where b-response is the response value associated with each box. Notice that this is using the box functions as a weighted sum.

### **Notes**

The ordering that has been used when adding points to the box mesh thus far is:

- Add the  $x_i$  with the median valued  $y_i$ .
- Compute the approximation surface error at all remaining  $x_i$ , add the  $x_i$  to the surface with the most (relative) error.
- Repeat previous step until small enough maximum error is obtained.

It is important to note that this constant recalculation of error causes an increase in the runtime by a factor of n.