

已知  $u=yt$ ,  $v=xt$ ,  $w=0$  求:

1. 加速度场 2. 流线及流线族 3. 速度及速度

4. 速度的拉格朗日描述.

解. 1. 加速度场  $u=yt$ ,  $v=xt$ ,  $w=0$  为欧拉描述

$$\text{质点加速度为 } \frac{Du}{Dt} = \frac{\partial u}{\partial t} + v \frac{\partial u}{\partial x} + u \frac{\partial u}{\partial y} + w \frac{\partial u}{\partial z} = y + xt^2$$

$$\frac{Dv}{Dt} = x + yt^2, \quad \frac{Dw}{Dt} = 0$$

即, 认为某微团时刻经过  $x, y$ , 它的加速度为

$$\frac{du}{dt} = \frac{\partial(yt)}{\partial t} = \frac{\partial y}{\partial t} t + y = xt^2 + y$$

$$\frac{dv}{dt} = \frac{\partial(xt)}{\partial t} = \frac{\partial x}{\partial t} t + x = yt^2 + x$$

2. 流线

$$dx/dt = u = yt$$

$$dy/dt = v = xt$$

$$dz/dt = w = 0$$

$$\left\{ \begin{array}{l} \frac{dy}{dx} = \frac{x}{y} \Rightarrow x^2 - y^2 = C_1 \\ dz = 0 \end{array} \right.$$

流线族

$$\frac{dx}{u} = \frac{dy}{v} = \frac{dz}{w}$$

$$\frac{dx}{yt} = \frac{dy}{xt}$$

$$\Rightarrow x^2 - y^2 = C_1$$

$$3. \text{散度 } \operatorname{div} \vec{V} = \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} = 0$$

$$\text{旋度 } \nabla \times \vec{V} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ yt & xt & 0 \end{vmatrix} = \vec{k} \left( \frac{\partial yt}{\partial y} - \frac{\partial xt}{\partial x} \right) = 0$$

$$4. \text{拉格朗日描述 } \frac{dx}{dt} = u = yt, \quad \frac{dy}{dt} = v = xt, \quad \frac{dz}{dt} = 0$$

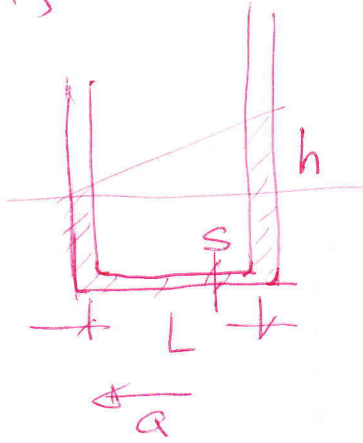
$$\frac{d(x+y)}{dt} = (x+y)t, \quad x+y = C_1 e^{\frac{t^2}{2}}$$

$$\frac{d(x-y)}{dt} = -(x-y)t, \quad x-y = C_2 e^{-\frac{t^2}{2}}$$

$$x = \frac{1}{2} C_1 e^{\frac{t^2}{2}} + \frac{1}{2} C_2 e^{-\frac{t^2}{2}}, \quad u = \frac{dx}{dt} = \frac{t}{2} (C_1 e^{\frac{t^2}{2}} - C_2 e^{-\frac{t^2}{2}})$$

2.5

2'a.

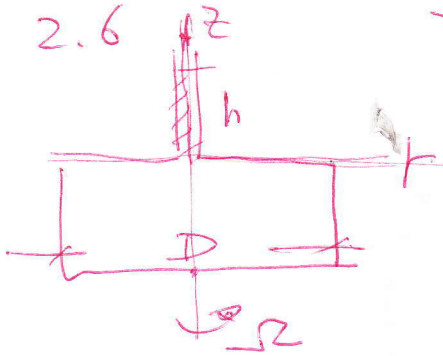


$$\rho g h s = \rho s L a$$

$$a = \frac{h}{L} g.$$

2.6

2' z=0 円筒軸力



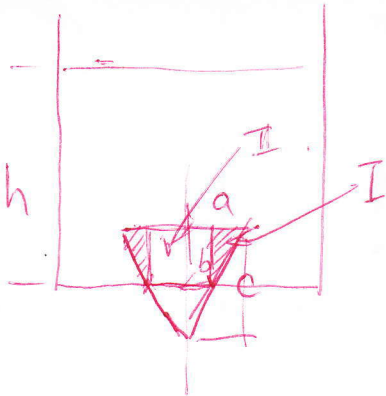
$$P = \frac{1}{2} \rho \omega^2 r^2 + \rho g h$$

$$F = \int_0^{D/2} P \cdot 2\pi r dr$$

$$F = \rho \frac{\pi \Omega^2 D^4}{64} + \rho g h \frac{\pi D^2}{4}$$

2.14

2' 鉛直軸力



$$\text{I 部分の合力 } F_1 = \frac{1}{3} \pi a^2 c \rho g - \frac{1}{3} \pi b^2 c \frac{b}{a} \rho g - \pi b^2 \frac{a-b}{a} \cdot c \rho g.$$

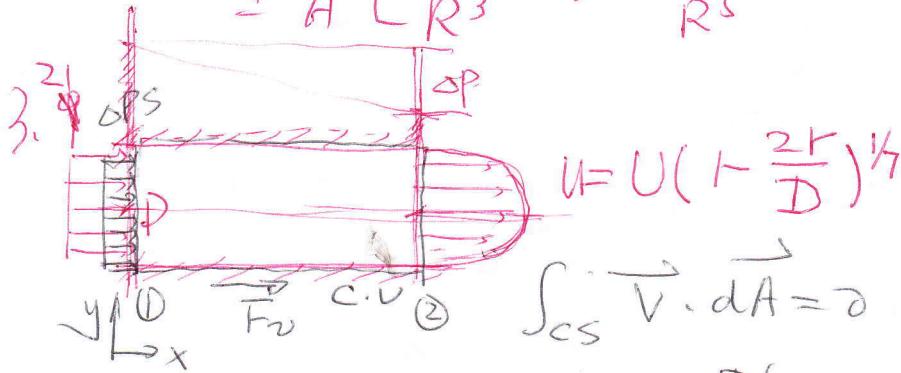
同上

$$\text{II 部分の合力 } F_2 = \pi b^2 \left( h - \frac{a-b}{a} c \right) \rho g.$$

$$\text{合力 } F = F_2 - F_1$$

3.8 证  $V_i = \frac{Ax_i}{R^3}$ ,  $i=1,2,3$  高维向量点积  $\frac{1}{R^3}$ ,  $R^2 = x^2 + y^2 + z^2$

$$\begin{aligned} \text{div } \vec{V} &= \frac{\partial (Ax/R^3)}{\partial x} + \frac{\partial (Ay/R^3)}{\partial y} + \frac{\partial (Az/R^3)}{\partial z} \\ &= A \left[ \frac{1}{R^3} - 3 \frac{x}{R^5} \frac{Ax}{R} + \frac{1}{R^3} - 3 \frac{y}{R^5} \frac{Ay}{R} + \frac{1}{R^3} - 3 \frac{z}{R^5} \frac{Az}{R} \right] \\ &= A \left[ \frac{3}{R^3} - 3 \frac{(x^2 + y^2 + z^2)}{R^5} \right] = 0 \end{aligned}$$



$$\int_{CS} \vec{V} \cdot d\vec{A} = 0 \quad \text{for } \vec{V} \perp d\vec{A}$$

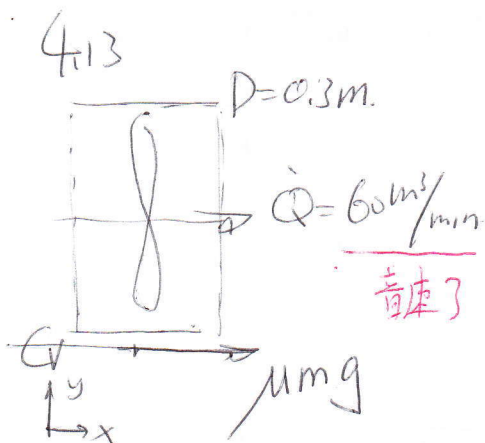
$$\frac{\pi D^2}{4} U_1 = \int_0^{D/2} U \left(1 - \frac{2r}{D}\right)^{1/2} 2\pi r dr$$

$$U_1 = 60/49 U_2$$

$$\vec{F} = \int_{CS} \vec{V} \rho \vec{V} \cdot d\vec{A} \quad \text{for } \vec{V} \perp d\vec{A}$$

$$\Delta P \frac{\pi D^2}{4} + F_v = \int_0^{D/2} U^2 \left(1 - \frac{2r}{D}\right)^{1/2} \rho 2\pi r dr - \text{for } \vec{V} \perp d\vec{A}$$

$$F_v = \frac{\pi D^2}{4} \left( -\Delta P + \frac{1}{49} \rho U_2^2 \right)$$



$$\vec{F} = \int_{CS} \vec{V} \rho \vec{V} \cdot d\vec{A}$$

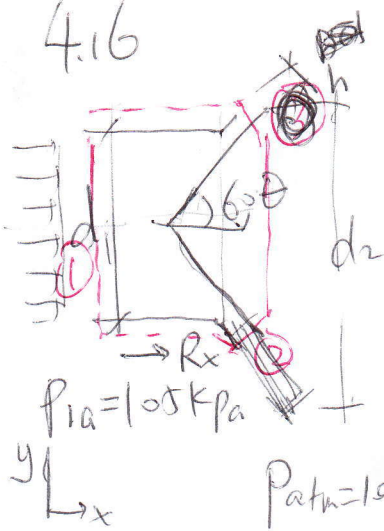
$$\mu mg = \rho \dot{Q} \frac{\dot{Q}}{\pi D^4/4}$$

$$\mu mg = \frac{4 \rho \dot{Q}^2}{\pi D^4}$$

$$\mu G = \rho \dot{Q} \left( \frac{\dot{Q}}{0.9 \pi D^2/4} - \frac{\dot{Q}}{1.1 \pi D^2/4} \right)$$

$$G = \frac{4 \rho \dot{Q}^2}{\mu \pi D^2} \left( \frac{1}{0.9} - \frac{1}{1.1} \right) = \frac{4 \times 1.2 \times 1}{0.1 \times 3.14 \times 0.3^2}$$

4.16



$$\frac{p_1}{\rho} + \frac{V_1^2}{2} = \frac{p_2}{\rho} + \frac{V_2^2}{2}$$

$$V_1 \cdot \frac{\pi d_1^2}{4} = V_2 \pi d_2 h$$

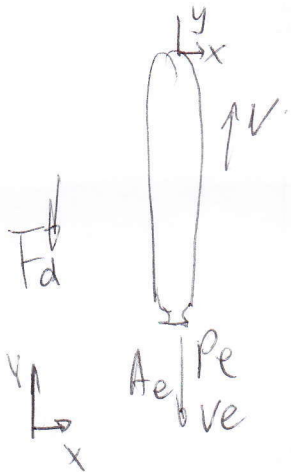
$$\int_{cs} \vec{V} \cdot \rho \vec{V} \cdot d\vec{A}$$

$$\vec{F} = \int_{cs} \vec{V} \cdot \rho \vec{V} \cdot d\vec{A}$$

$$(p_{1a} - p_{atm}) \frac{\pi d_1^2}{4} + R_x = \rho V_2 \cos \theta \pi d_2 h V_2$$

$$\int_{cs} R_x$$

$$- \rho V_1 s_1 V_1$$

4.25  $M_0, p_{atm}, g, \dot{m}_f, V_e, P_e$ 

$$-(M - \dot{m}t)g - D + \rho P A_e = (M - \dot{m}t)a + (-\dot{m}V_e)$$

$$a = \frac{\dot{m}V_e + \rho P A_e - D}{M - \dot{m}t} - g$$

$$T - D - Mg = Ma$$

$$T = M(a + g) + D$$

$$du = \frac{\partial u}{\partial t} dt + \frac{\partial u}{\partial y} dy$$