CS 123: Group 2

Guide Pupper

A Seeing-Eye Quadruped to Aid the Visually Impaired

Only 2%

of visually impaired individuals in the US have guide dogs.

Walking faster.

Avoiding obstacles.

Following instructions.

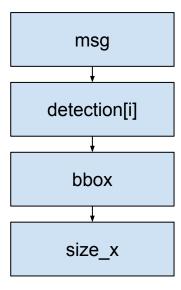
Guide dogs are scarce due to the time-consuming training process and relatively short duration of service.

The Goal

Guide Pupper should detect obstacles, navigate around them, and follow natural commands.

Step 1: Obstacle Detection

We use the the camera mounted on pupper to obtain all of the detected objects. We then identify the width of these objects relative to the camera frame.



We then tune a threshold to determine if the object is in the way of Pupper (i.e. if the ratio of size_x to camera width is greater than 0.08).

Pupper State Machine Step 2: Re-routing Moves left and returns to the original trajectory Moving upward along the side Obstacle of the obstacle Turns to the right after detecting object Pupper vocalizes how to avoid the obstacle Pupper

Step 3: Responsiveness

