

Time & Clocks

CS 475: Concurrent & Distributed Systems (Fall 2021)
Lecture 6

Yue Cheng

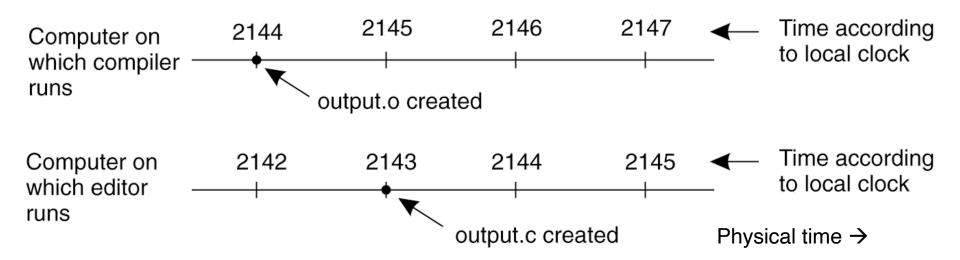
Some material taken/derived from:

- Princeton COS-418 materials created by Michael Freedman and Wyatt Lloyd.
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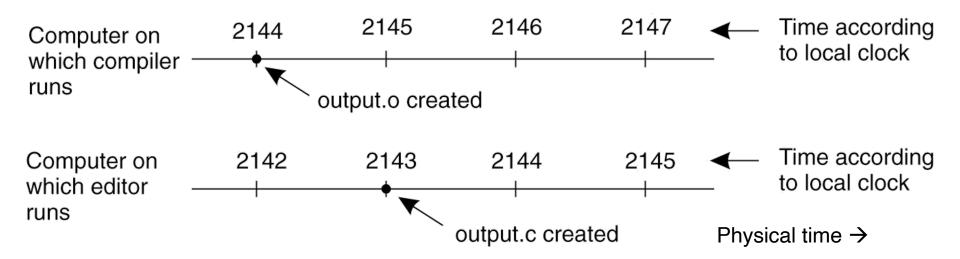
Today's outline

- The need for time synchronization
- "Wall clock time" synchronization
- Logical Time: Lamport Clocks
- Vector clocks

A distributed edit-compile workflow

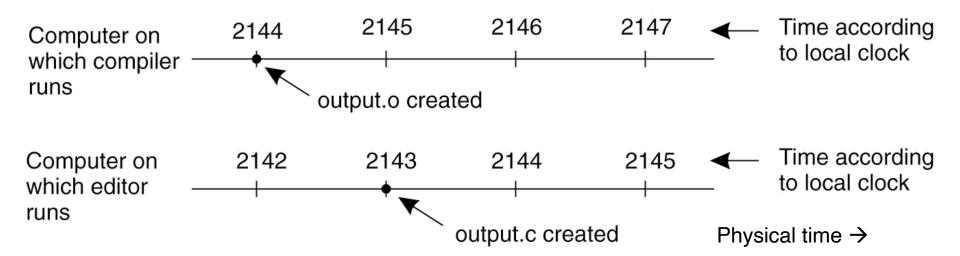


A distributed edit-compile workflow



• 2143 < 2144 → make doesn't call compiler

A distributed edit-compile workflow



• 2143 < 2144 → make doesn't call compiler

Lack of time synchronization result – possible object file mismatch

What makes time synchronization hard?

- 1. Quartz oscillator sensitive to temperature, age, vibration, radiation
 - Accuracy ~one part per million
 - (one second of clock drift over 12 days)
- 2. The internet is:
 - Asynchronous: arbitrary message delays
 - Best-effort: messages don't always arrive

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The need for time synchronization

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 - Cristian's algorithm
- Logical Time: Lamport Clocks

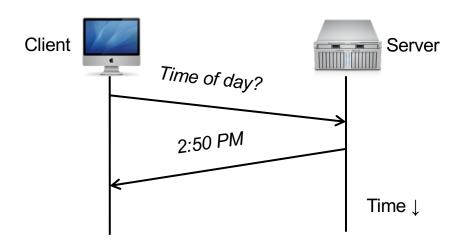
Vector clocks

Just use Coordinated Universal Time?

- UTC is broadcast from radio stations on land and satellite (e.g., the Global Positioning System)
 - Computers with receivers can synchronize their clocks with these timing signals
- Signals from land-based stations are accurate to about 0.1–10 milliseconds
- Signals from GPS are accurate to about one microsecond
 - Why can't we put GPS receivers on all our computers?

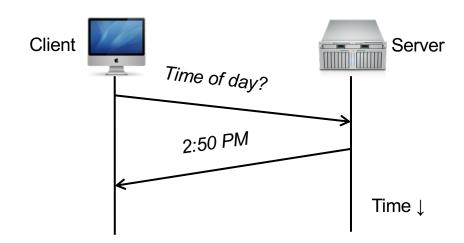
Synchronization to a time server

- Suppose a server with an accurate clock (e.g., GPS-receiver)
 - Could simply issue an RPC to obtain the time:



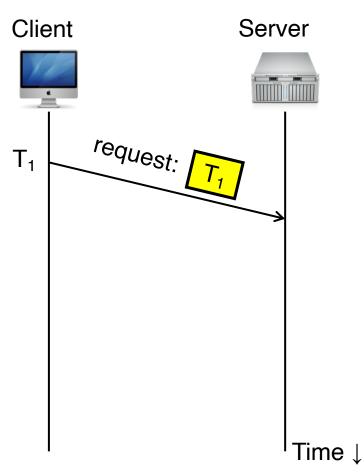
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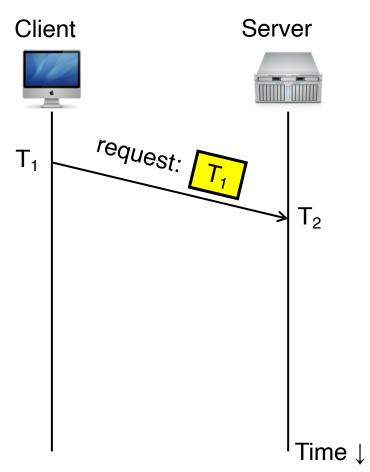


- But this doesn't account for network latency
 - Message delays will have outdated server's answer

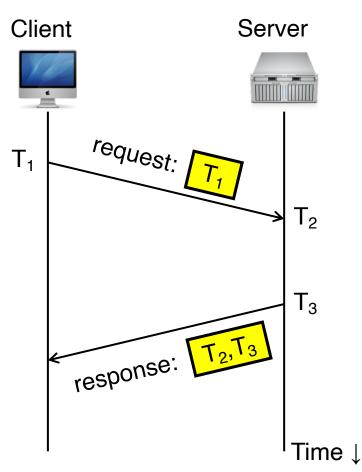
 Client sends a request packet, timestamped with its local clock T₁



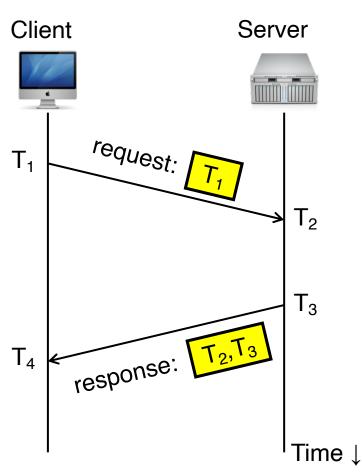
- 1. Client sends a request packet, timestamped with its local clock T₁
- 2. Server timestamps its receipt of the request T₂ with its local clock



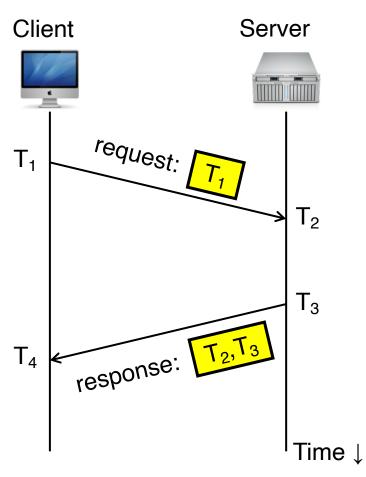
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- 3. Server sends a response packet with its local clock T₃ and T₂



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- 4. Client locally timestamps its receipt of the server's response T₄



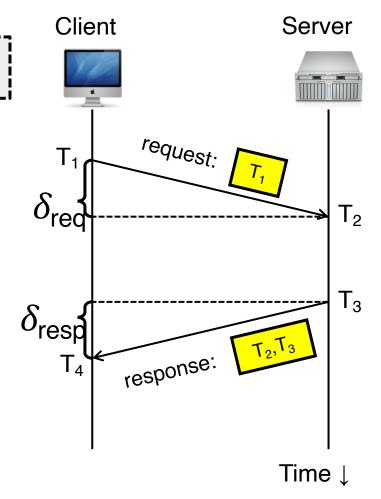
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How can the client use these timestamps to synchronize its local clock to the server's local clock?

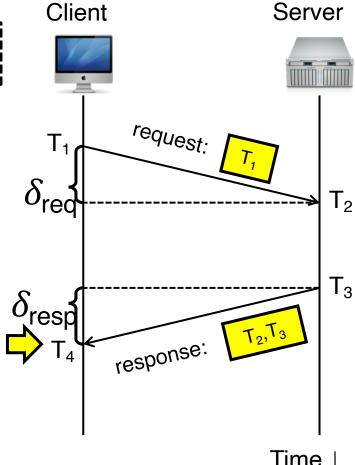
Goal: Client sets clock \leftarrow T₃ + δ_{resp}

• Client samples round trip time $\delta = \delta_{req} + \delta_{resp} = (T_4 - T_1) - (T_3 - T_2)$



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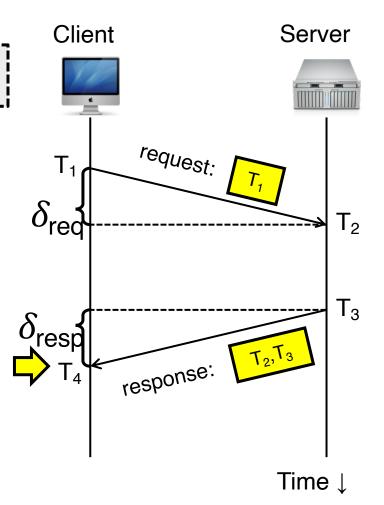


Time ↓

Goal: Client sets clock \leftarrow T₃ + δ_{resp}

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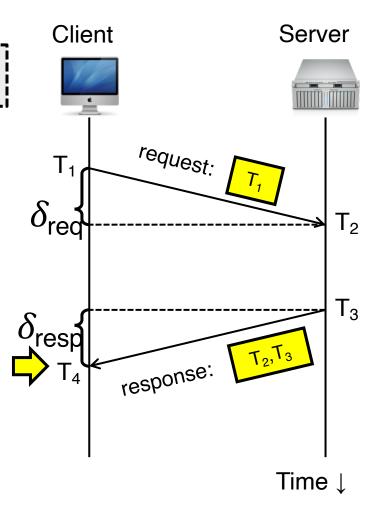


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Assume: $\delta_{\text{req}} \approx \delta_{\text{resp}}$



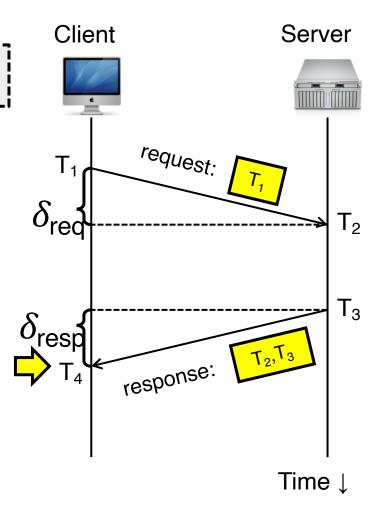
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Assume: $\delta_{\text{req}} \approx \delta_{\text{resp}}$

Client sets clock \leftarrow T₃ + $\frac{1}{2}\delta$



Clock synchronization: Takeaway points

- Clocks on different systems will always behave differently
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Clock synchronization: Takeaway points

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- Clock synchronization algorithms
 - Rely on timestamps to estimate network delays
 - 100s μ s-ms accuracy
 - Clocks never exactly synchronized

Clock synchronization: Takeaway points

- Clocks on different systems will always behave differently
 - Disagreement between machines can result in undesirable behavior
- Clock synchronization algorithms
 - Rely on timestamps to estimate network delays
 - 100s μ s-ms accuracy
 - Clocks never exactly synchronized
- Often inadequate for distributed systems
 - Often need to reason about the order of events
 - Might need precision on the order of ns

Today's outline

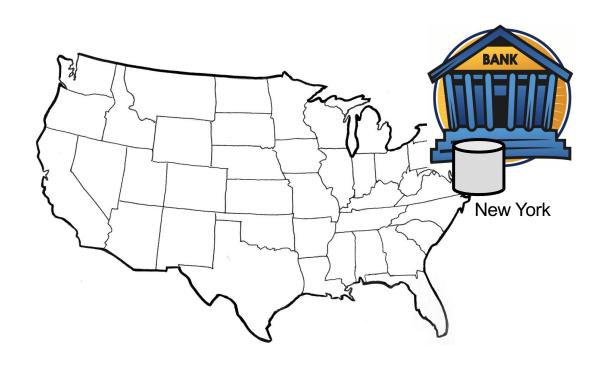
• The need for time synchronization

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Vector clocks

Motivation: Multi-site database replication

 A New York-based bank wants to make its transaction ledger database resilient to whole-site failures



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Replicate the database, keep one copy in SF, one in NYC



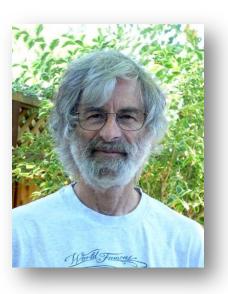
The consequences of concurrent updates

- Replicate the database, keep one copy in SF, one in NYC
 - Client sends reads to the nearest copy
 - Client sends update to both copies



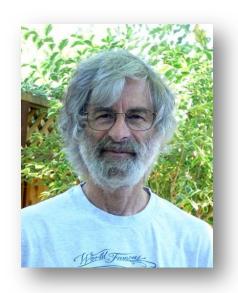
Idea: Logical clocks

Landmark 1978 paper by Leslie Lamport



Idea: Logical clocks

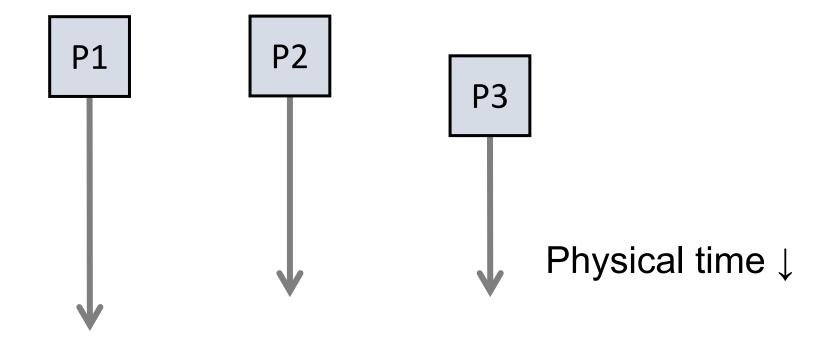
- Landmark 1978 paper by Leslie Lamport
- Insights: only the events themselves matter



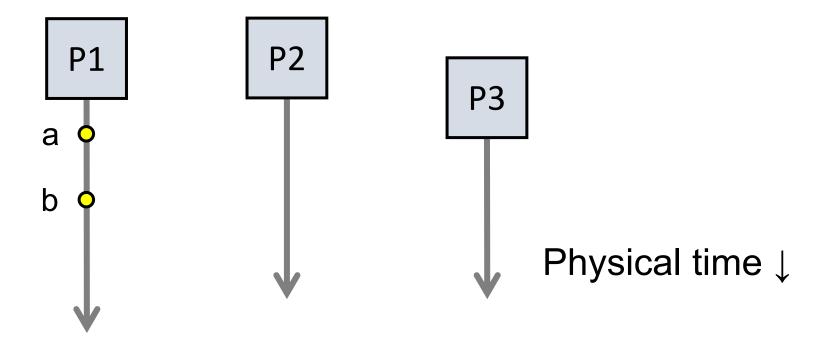
Idea: Disregard the precise clock time Instead, capture just a "happens before" relationship between a pair of events

Consider three processes: P1, P2, and P3

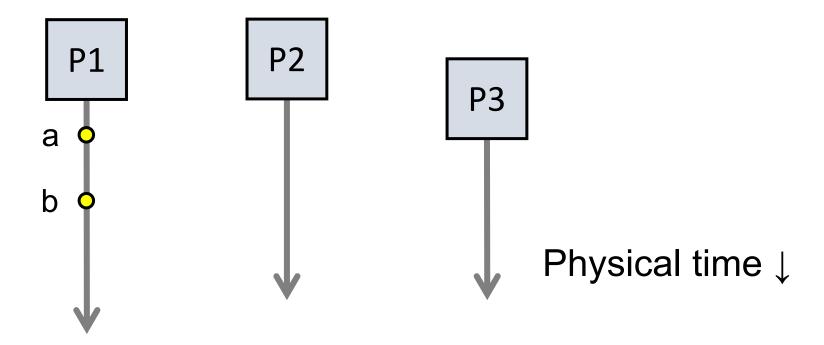
Notation: Event a happens before event b (a → b)



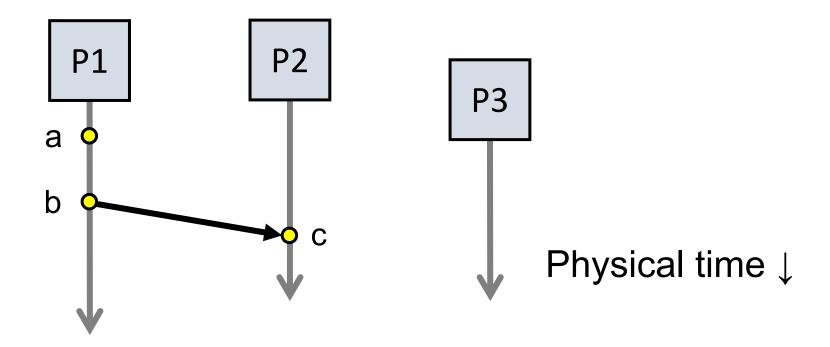
Can observe event order at a single process



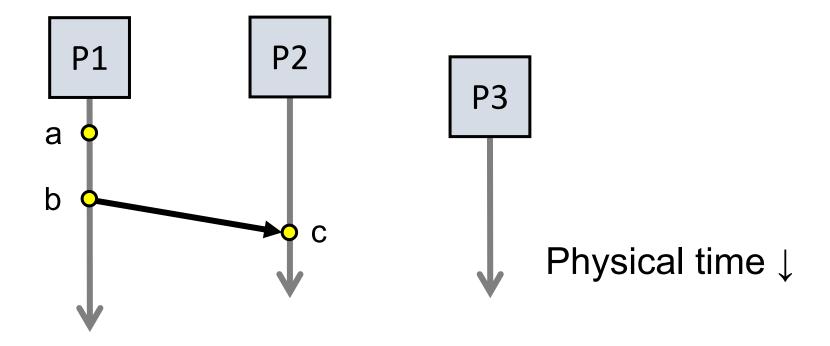
1. If same process and a occurs before b, then $a \rightarrow b$



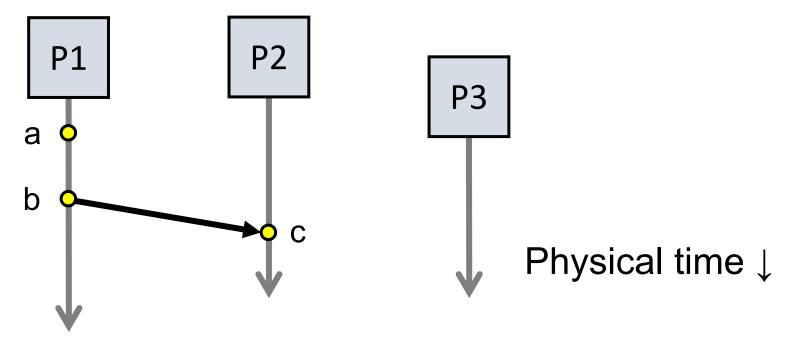
- 1. If same process and a occurs before b, then $a \rightarrow b$
- 2. Can observe ordering when processes communicate



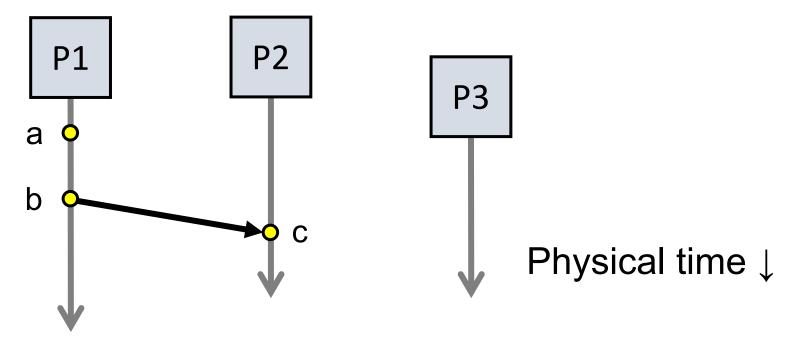
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- 3. Can observe ordering transitively

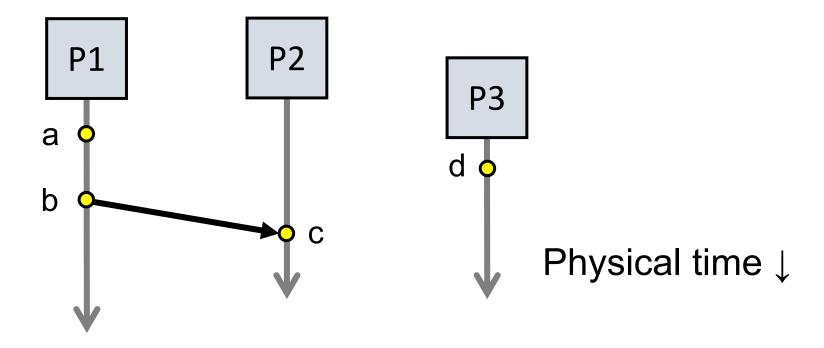


- 1. If same process and a occurs before b, then $a \rightarrow b$
- 2. If c is a message receipt of b, then $b \rightarrow c$
- 3. If $a \rightarrow b$ and $b \rightarrow c$, then $a \rightarrow c$



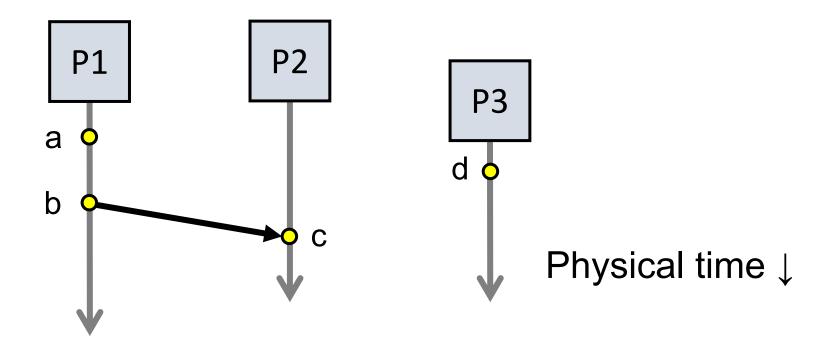
Defining "happens-before" (\rightarrow)

Not all events are related by →



Defining "happens-before" (\rightarrow)

- Not all events are related by →
- 2. a, d not related by \rightarrow so concurrent, written as $\mathbf{a} \parallel \mathbf{d}$



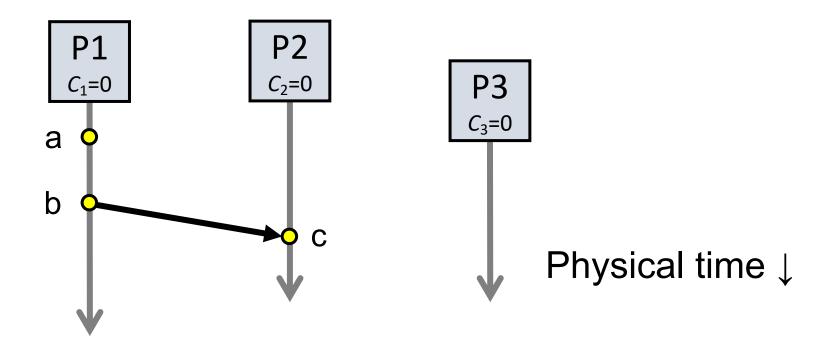
Lamport clocks: Objective

We seek a clock time C(a) for every event a

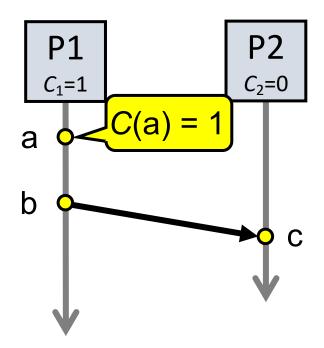
Plan: Tag events with clock times; use clock times to make distributed system correct

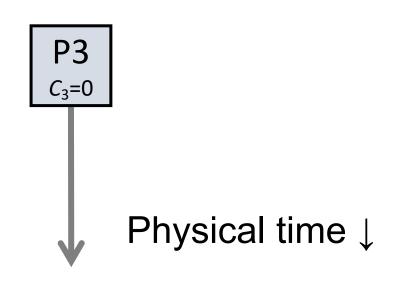
Clock condition: If a → b, then C(a) < C(b)

- Each process P_i maintains a local clock C_i
- 1. Before executing an event, $C_i \leftarrow C_i + 1$:

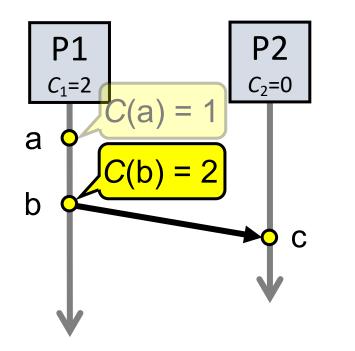


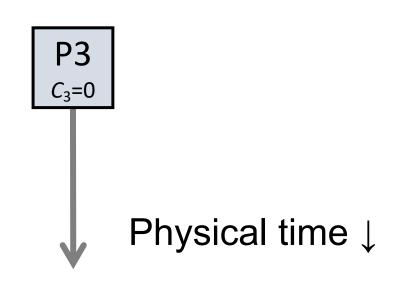
- 1. Before executing an event $a, C_i \leftarrow C_i + 1$:
 - Set event time $C(a) \leftarrow C_i$



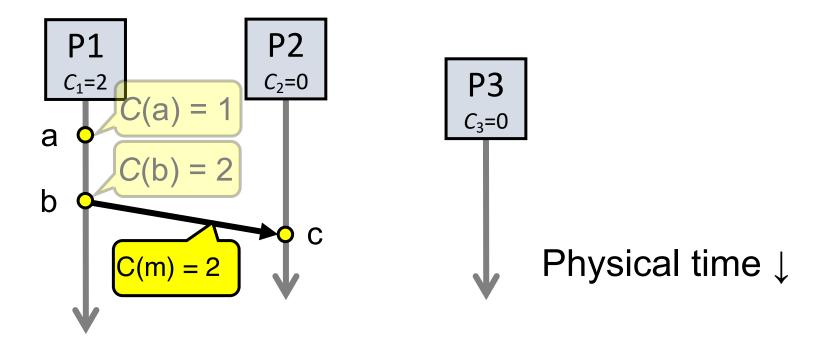


- 1. Before executing an event b, $C_i \leftarrow C_i + 1$:
 - Set event time $C(b) \leftarrow C_i$

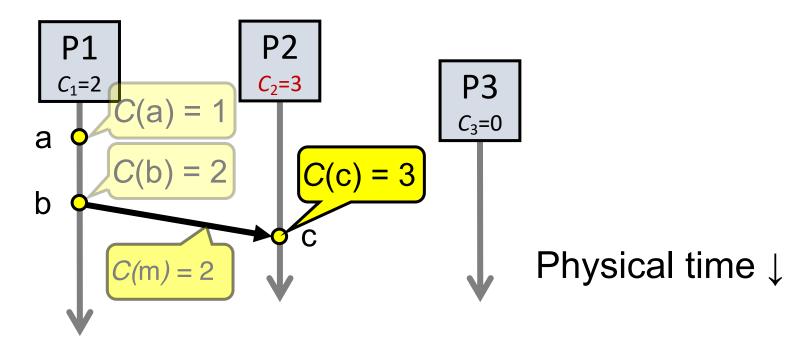




- 1. Before executing an event b, $C_i \leftarrow C_i + 1$
- 2. Send the local clock in the message m



- 3. On process P_i receiving a message m:
 - Set C_j and receive event time $C(c) \leftarrow 1 + \max\{C_j, C(m)\}$

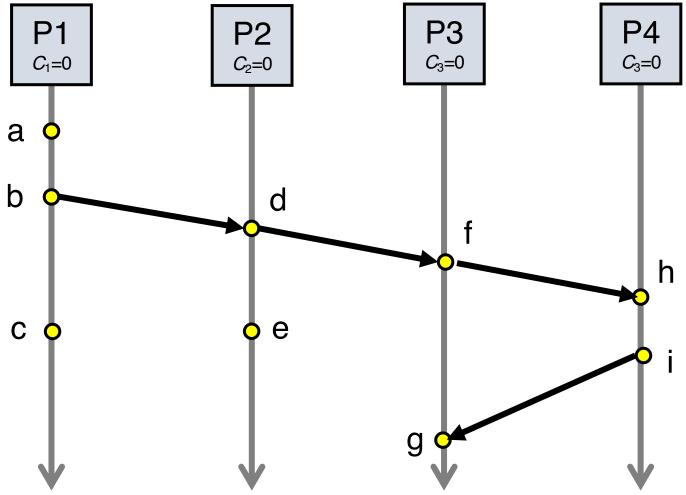


Lamport Timestamps: Ordering all events

- Break ties by appending the process number to each event:
 - 1. Process P_i timestamps event e with C_i (e).i
 - 2. C(a).i < C(b).j when:
 - C(a) < C(b), or C(a) = C(b) and i < j

- Now, for any two events a and b, C(a) < C(b) or C(b) < C(a)
 - This is called a total ordering of events

Order all these events



Physical time ↓

Totally-Ordered Multicast

Goal: All sites apply updates in (same) Lamport clock order

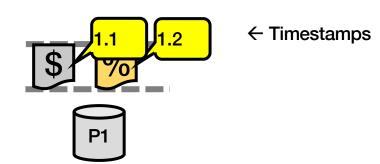
- Client sends update to one replica site j
 - Replica assigns it Lamport timestamp C_j. j

Totally-Ordered Multicast

Goal: All sites apply updates in (same) Lamport clock order

- Client sends update to one replica site j
 - Replica assigns it Lamport timestamp C_j. j
- Key idea: Place events into a sorted local queue
 - Sorted by increasing Lamport timestamps

Example: P1's local queue:



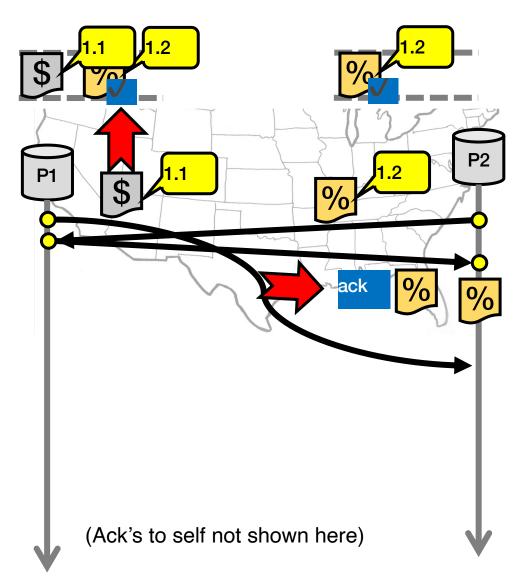
Totally-Ordered Multicast (Almost correct)

- 1. On receiving an update from client, broadcast to others (including yourself)
- 2. On receiving an update from replica:
 - a) Add it to your local queue
 - b) Broadcast an acknowledgement message to every replica (including yourself)
- 3. On receiving an acknowledgement:
 - Mark corresponding update acknowledged in your queue
- 4. Remove and process updates everyone has ack'ed from head of queue

Totally-Ordered Multicast (Almost correct)

- P1 queues \$, P2 queues %
- P1 queues and ack's %
 - P1 marks % fully ack'ed
- P2 marks % fully ack'ed

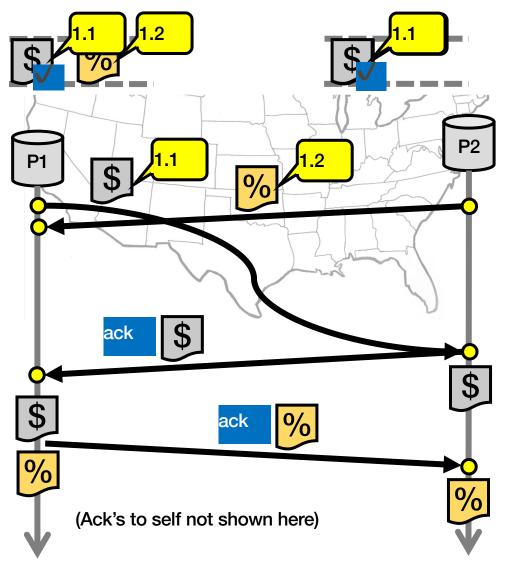
X P2 processes %



Totally-Ordered Multicast (Correct version)

- 1. On receiving an update from client, broadcast to others (including yourself)
- 2. On receiving or processing an update:
 - a) Add it to your local queue
 - b) Broadcast an acknowledgement message to every replica (including yourself) only from head of queue
- 3. On receiving an acknowledgement:
 - Mark corresponding update acknowledged in your queue
- 4. Remove and process updates everyone has ack'ed from head of queue

Totally-Ordered Multicast (Correct version)



 Does totally-ordered multicast solve the problem of multi-site replication in general?

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- Not by a long shot!
- 1. Our protocol assumed:
 - No node failures
 - No message loss
 - No message corruption
- 2. All-to-all communication does not scale
- 3. Waits forever for message delays (performance?)

Lamport Clocks: Takeaway points

- Can totally-order events in a distributed system: that's useful!
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- But: while by construction,
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 - The converse is not necessarily true:
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 - We saw an application of Lamport clocks for totallyordered multicast
- But: while by construction,
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Can't use Lamport timestamps to infer causal relationships between events

Today's outline

The need for time synchronization

- "Wall clock time" synchronization
 - Cristian's algorithm
- Logical Time: Lamport Clocks

Vector clocks

Lamport Clocks and causality

Lamport clock timestamps do not capture causality

 Given two timestamps C(a) and C(z), want to know whether there's a chain of events linking them:

$$a \rightarrow b \rightarrow ... \rightarrow y \rightarrow z$$

Vector clock: Introduction

One integer can't order events in more than one process

 So, a Vector Clock (VC) is a vector of integers, one entry for each process in the entire distributed system

- Label event e with $VC(e) = [c_1, c_2, ..., c_n]$
 - Each entry c_k is a count of events in process k that causally precede e

Vector clock: Update rules

• Initially, all vectors are [0, 0, ..., 0]

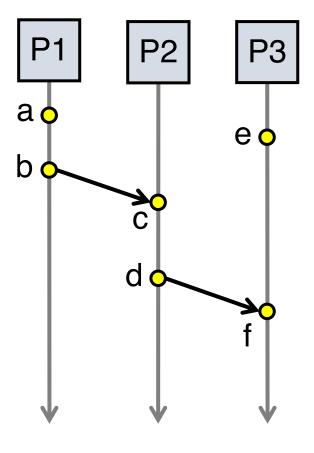
Two update rules:

1. For each local event on process i, increment local entry c_i

Vector clock: Update rules

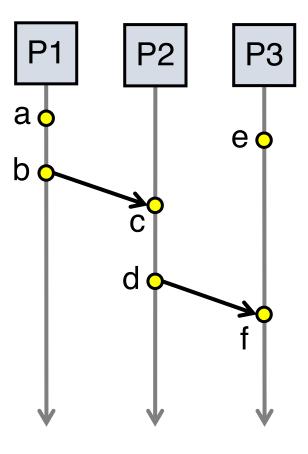
- Initially, all vectors are [0, 0, ..., 0]
- Two update rules:
- 1. For each local event on process i, increment local entry c_i
- 2. If process j receives message with vector [d₁, d₂, ..., d_n]:
 - Set each local entry $c_k = \max\{c_k, d_k\}$
 - Increment local entry c_i

• All processes' VCs start at [0, 0, 0]



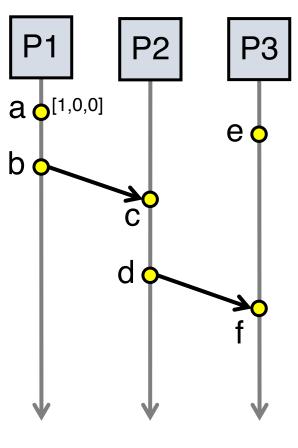
Physical time ↓

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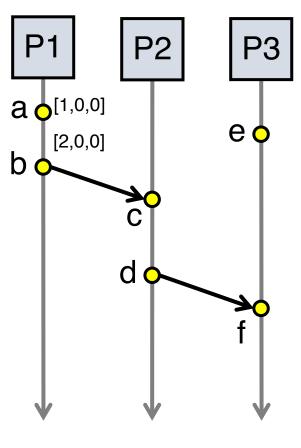
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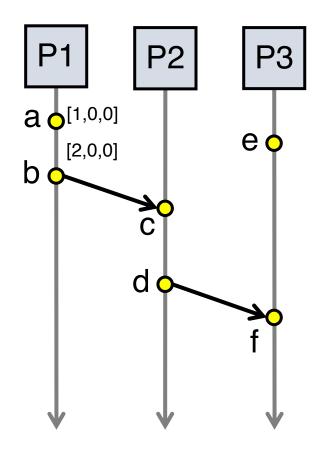
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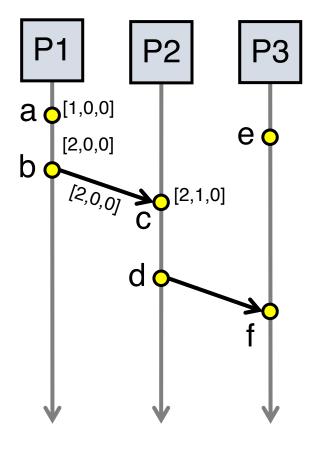
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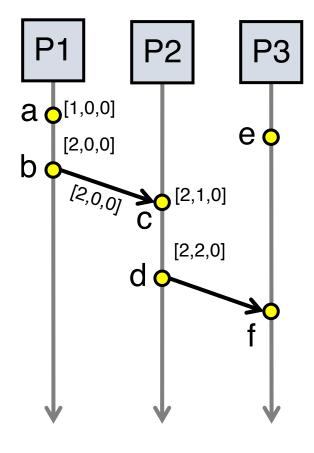
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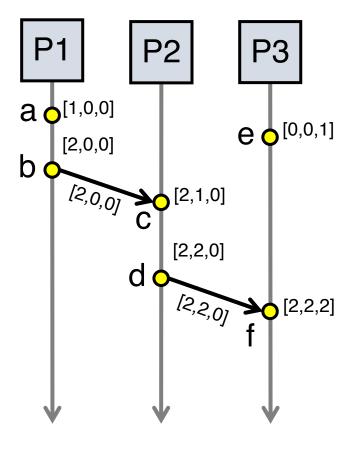
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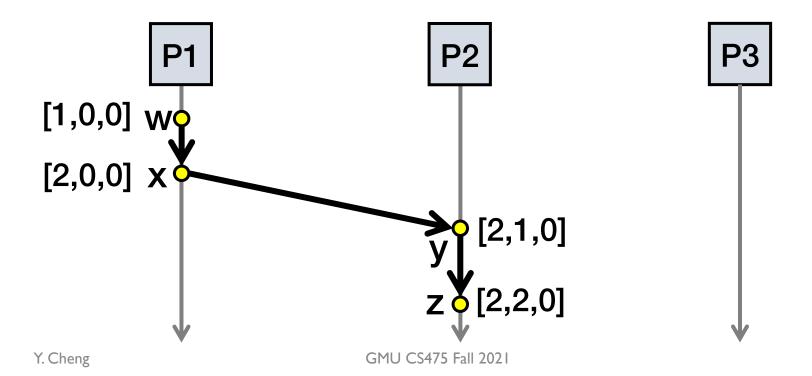
Physical time ↓

Comparing vector timestamps

- Rule for comparing vector timestamps:
 - V(a) = V(b) when $a_k = b_k$ for all k
 - V(a) < V(b) when $a_k \le b_k$ for all k and $V(a) \ne V(b)$
- Concurrency:
 - $V(a) \parallel V(b)$ if $a_i < b_i$ and $a_i > b_i$, some i, j

Vector clocks capture causality

 V(w) < V(z) then there is a chain of events linked by Happens-Before (→) between a and z

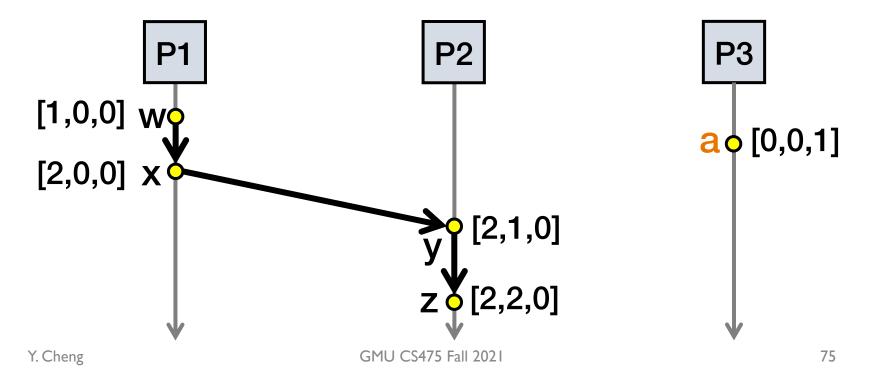


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Vector clocks capture causality

 V(w) < V(z) then there is a chain of events linked by Happens-Before (→) between a and z

 V(a) || V(w) then there is no such chain of events between a and w



Comparing vector timestamps

- Rule for comparing vector timestamps:
 - V(a) = V(b) when $a_k = b_k$ for all k
 - They are the same event
 - V(a) < V(b) when $a_k \le b_k$ for all k and $V(a) \ne V(b)$
 - a → b

- Concurrency:
 - $V(a) \parallel V(b)$ if $a_i < b_i$ and $a_i > b_i$, some i, j
 - a || b

Two events a, z

Lamport clocks: C(a) < C(z)Conclusion: z -/-> a, i.e., either $a \rightarrow z$ or $a \parallel z$

Vector clocks: V(a) < V(z)

Conclusion: a → z

Two events a, z

Lamport clocks: C(a) < C(z)Conclusion: z -/-> a, i.e., either $a \rightarrow z$ or $a \parallel z$

Vector clocks: V(a) < V(z)

Conclusion: $a \rightarrow z$

Vector clock timestamps precisely capture happens-before relation (potential causality)