

# **NetXPTO - NetPlanner**

3 de Abril de 2018

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## **Capítulo 1**

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### **Introduction**

LinkPlanner is devoted to the simulation of point-to-point links.

## **Capítulo 2**

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### **Simulator Structure**

LinkPlanner is a signals open-source simulator.

The major entity is the system.

A system comprises a set of blocks.

The blocks interact with each other through signals.

#### **2.1 System**

#### **2.2 Blocks**

#### **2.3 Signals**

List of available signals:

- Signal

## **Capítulo 3**

## **Development Cycle**

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The NetXPTO-LinkPlanner has been developed by several people using git as a version control system. The NetXPTO-LinkPlanner repository is located in the GitHub site <http://github.com/netxpto/linkplanner>. The more updated functional version of the software is in the branch master. Master should be considered a functional beta version of the software. Periodically new releases are delivered from the master branch under the branch name Release<Year><Month><Day>. The integration of the work of all people is performed by Armando Nolasco Pinto in the branch Develop. Each developer has his/her own branch with his/her name.

## **Capítulo 4**

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## **Reference Network Specification**

The purpose of this chapter is to describe a reference network that will be used for the various types of dimensioning throughout this project. In addition to the reference network will also be described the various traffic models used in this network in question.

The organization of this chapter is done by creating two sub-chapters, the first to describe the physical topology of the network and a second to create the traffic matrix for the three existing traffic models (low, medium and high traffic).

## 4.1 Physical Topology

**Student Name :** Tiago Esteves (October 03, 2017 - )

In the following figure we can see that our reference network consists of 6 nodes and 8 bidirectional links. Besides this layout of links and nodes will also need to know the average length of the links. This value varies depending on the length of each link so it will be necessary to define all distances between the respective nodes. Finally, it is also necessary to indicate the total traffic used in this network so the ODU matrices will be created.

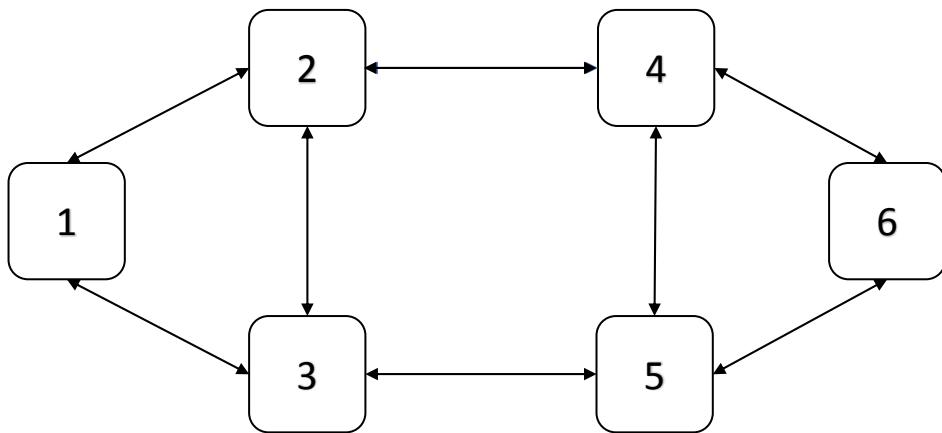


Figura 4.1: Physical topology of the reference network.

The distance matrix for this reference network is the same regardless of its associated traffic. The values indicated in the distance matrix, referred to below, are expressed in kilometers (Km) and, as it could not be otherwise, this matrix is symmetric because the distance from 1 to 2 must be the same as 2 to 1.

$$Dist = \begin{bmatrix} 0 & 460 & 663 & 0 & 0 & 0 \\ 460 & 0 & 75 & 684 & 0 & 0 \\ 663 & 75 & 0 & 0 & 890 & 0 \\ 0 & 684 & 0 & 0 & 103 & 764 \\ 0 & 0 & 890 & 103 & 0 & 361 \\ 0 & 0 & 0 & 764 & 361 & 0 \end{bmatrix}$$

For this project has to take into consideration the table 4.1 because in it we can see the values of the variables associated with this network.

Constant	Description	Value
N	Number of nodes	6
L	Number of bidirectional links	8
$\langle \delta \rangle$	Node out-degree	2.667
$\langle \text{len} \rangle$	Mean link length (km)	500
$\langle h \rangle$	Mean number of hops for working paths	1.533
$\langle h' \rangle$	Mean number of hops for backup paths	2.467

Tabela 4.1: Table of reference network values

## 4.2 Traffic Matrices

**Student Name :** Tiago Esteves (October 03, 2017 - )

For a better interpretation of the later results we will assume three traffic models for this network. Being the first model with a low traffic scenario, the second with a medium traffic scenario and a last one with a high traffic scenario. For each scenario it will be necessary to create different traffic matrices and to know the traffic of the network we will use five matrices of traffic. These traffic matrices are represented by ODU0, ODU1, ODU2, ODU3 and ODU4 where each one has a certain bit rate. The ODU0 corresponds to 1.25 Gbits/s, the ODU1 corresponds to 2.5 Gbits/s, the ODU2 corresponds to 10 Gbits/s, the ODU3 corresponds to 40 Gbits/s and finally the ODU4 corresponds to 100 Gbits/s. As we can see below, these arrays are bi-directional because they are symmetric arrays and as such, the traffic sent in a certain direction must be the same traffic sent in that opposite direction.

### 4.2.1 Low traffic scenario (0.5 Tbits/s)

The traffic matrices for this scenario are:

$$ODU0 = \begin{bmatrix} 0 & 5 & 1 & 3 & 1 & 3 \\ 5 & 0 & 0 & 1 & 5 & 0 \\ 1 & 0 & 0 & 1 & 4 & 1 \\ 3 & 1 & 1 & 0 & 1 & 1 \\ 1 & 5 & 4 & 1 & 0 & 3 \\ 3 & 0 & 1 & 1 & 3 & 0 \end{bmatrix} \quad ODU1 = \begin{bmatrix} 0 & 2 & 4 & 2 & 0 & 5 \\ 2 & 0 & 0 & 3 & 1 & 1 \\ 4 & 0 & 0 & 1 & 1 & 0 \\ 2 & 3 & 1 & 0 & 1 & 3 \\ 0 & 1 & 1 & 1 & 0 & 1 \\ 5 & 1 & 0 & 3 & 1 & 0 \end{bmatrix}$$

$$ODU2 = \begin{bmatrix} 0 & 1 & 1 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 & 1 & 0 \\ 1 & 0 & 0 & 1 & 1 & 0 \\ 1 & 0 & 1 & 0 & 1 & 0 \\ 0 & 1 & 1 & 1 & 0 & 1 \\ 0 & 0 & 0 & 0 & 1 & 0 \end{bmatrix} \quad ODU3 = \begin{bmatrix} 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 1 \\ 0 & 1 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & 0 \end{bmatrix}$$

$$ODU4 = \begin{bmatrix} 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 \\ 0 & 1 & 0 & 0 & 1 & 0 \end{bmatrix}$$

Through these ODU's we can calculate total network traffic for the low traffic scenario:

$$T_1^0 = 60 \times 1.25 = 75 \text{ Gbits/s} \quad T_1^1 = 50 \times 2.5 = 125 \text{ Gbits/s} \quad T_1^2 = 16 \times 10 = 160 \text{ Gbits/s}$$

$$T_1^3 = 6 \times 40 = 240 \text{ Gbits/s} \quad T_1^4 = 4 \times 100 = 400 \text{ Gbits/s}$$

$$T_1 = 75 + 125 + 160 + 240 + 400 = 1000 \text{ Gbits/s} \quad T = 1000/2 = \mathbf{0.5 \text{ Tbits/s}}$$

Where the variable  $T_1^x$  represents the unidirectional traffic of the ODUx, for example,  $T_1^0$  represents the unidirectional traffic of the ODU0 and  $T_1^1$  represents the unidirectional traffic of the ODU1. The variable  $T_1$  represents the total of unidirectional traffic that is injected into the network and finally the variable  $T$  represents the total of bidirectional traffic.

#### 4.2.2 Medium traffic scenario (5 Tbits/s)

The traffic matrices for this scenario are:

$$ODU0 = \begin{bmatrix} 0 & 50 & 10 & 30 & 10 & 30 \\ 50 & 0 & 0 & 10 & 50 & 0 \\ 10 & 0 & 0 & 10 & 40 & 10 \\ 30 & 10 & 10 & 0 & 10 & 10 \\ 10 & 50 & 40 & 10 & 0 & 30 \\ 30 & 0 & 10 & 10 & 30 & 0 \end{bmatrix} \quad ODU1 = \begin{bmatrix} 0 & 20 & 40 & 20 & 0 & 50 \\ 20 & 0 & 0 & 30 & 10 & 10 \\ 40 & 0 & 0 & 10 & 10 & 0 \\ 20 & 30 & 10 & 0 & 10 & 30 \\ 0 & 10 & 10 & 10 & 0 & 10 \\ 50 & 10 & 0 & 30 & 10 & 0 \end{bmatrix}$$

$$\begin{aligned}
 ODU2 &= \begin{bmatrix} 0 & 10 & 10 & 10 & 0 & 0 \\ 10 & 0 & 0 & 0 & 10 & 0 \\ 10 & 0 & 0 & 10 & 10 & 0 \\ 10 & 0 & 10 & 0 & 10 & 0 \\ 0 & 10 & 10 & 10 & 0 & 10 \\ 0 & 0 & 0 & 0 & 10 & 0 \end{bmatrix} & ODU3 &= \begin{bmatrix} 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 10 & 0 & 0 & 10 \\ 0 & 10 & 0 & 0 & 10 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 10 & 0 & 0 & 0 \\ 0 & 10 & 0 & 0 & 0 & 0 \end{bmatrix} \\
 ODU4 &= \begin{bmatrix} 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 10 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 10 \\ 0 & 10 & 0 & 0 & 10 & 0 \end{bmatrix}
 \end{aligned}$$

Through these ODU's we can calculate total network traffic for the medium traffic scenario:

$$T_1^0 = 600 \times 1.25 = 750 \text{ Gbits/s} \quad T_1^1 = 500 \times 2.5 = 1205 \text{ Gbits/s} \quad T_1^2 = 160 \times 10 = 1600 \text{ Gbits/s}$$

$$T_1^3 = 60 \times 40 = 2400 \text{ Gbits/s} \quad T_1^4 = 40 \times 100 = 4000 \text{ Gbits/s}$$

$$T_1 = 750 + 1205 + 1600 + 2400 + 4000 = 10000 \text{ Gbits/s} \quad T = 10000/2 = 5 \text{ Tbits/s}$$

#### 4.2.3 High traffic scenario (50 Tbits/s)

The traffic matrices for this scenario are:

$$\begin{aligned}
 ODU0 &= \begin{bmatrix} 0 & 500 & 100 & 300 & 100 & 300 \\ 500 & 0 & 0 & 100 & 500 & 0 \\ 100 & 0 & 0 & 100 & 400 & 100 \\ 300 & 100 & 100 & 0 & 100 & 100 \\ 100 & 500 & 400 & 100 & 0 & 300 \\ 300 & 0 & 100 & 100 & 300 & 0 \end{bmatrix} & ODU1 &= \begin{bmatrix} 0 & 200 & 400 & 200 & 0 & 500 \\ 200 & 0 & 0 & 300 & 100 & 100 \\ 400 & 0 & 0 & 100 & 100 & 0 \\ 200 & 300 & 100 & 0 & 100 & 300 \\ 0 & 100 & 100 & 100 & 0 & 100 \\ 500 & 100 & 0 & 300 & 100 & 0 \end{bmatrix} \\
 ODU2 &= \begin{bmatrix} 0 & 100 & 100 & 100 & 0 & 0 \\ 100 & 0 & 0 & 0 & 100 & 0 \\ 100 & 0 & 0 & 100 & 100 & 0 \\ 100 & 0 & 100 & 0 & 100 & 0 \\ 0 & 100 & 100 & 100 & 0 & 100 \\ 0 & 0 & 0 & 0 & 100 & 0 \end{bmatrix} & ODU3 &= \begin{bmatrix} 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 100 & 0 & 0 & 100 \\ 0 & 100 & 0 & 0 & 100 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 100 & 0 & 0 & 0 \\ 0 & 100 & 0 & 0 & 0 & 0 \end{bmatrix}
 \end{aligned}$$

$$ODU4 = \begin{bmatrix} 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 100 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 100 \\ 0 & 100 & 0 & 0 & 100 & 0 \end{bmatrix}$$

Through these ODU's we can calculate total network traffic for the high traffic scenario:

$$T_1^0 = 6000 \times 1.25 = 7500 \text{ Gbits/s} \quad T_1^1 = 5000 \times 2.5 = 12500 \text{ Gbits/s}$$

$$T_1^2 = 1600 \times 10 = 16000 \text{ Gbits/s} \quad T_1^3 = 600 \times 40 = 24000 \text{ Gbits/s}$$

$$T_1^4 = 400 \times 100 = 40000 \text{ Gbits/s}$$

$$T_1 = 750 + 1250 + 1600 + 2400 + 4000 = 100000 \text{ Gbits/s}$$

$$T = 100000 / 2 = \mathbf{50 \text{ Tbits/s}}$$

## **Capítulo 5**

### **Integer Linear Programming (ILP)**

---

ILP models are used to design networks that describe real components and their capabilities through a set of linear equations. Despite their quality, the solutions obtained through these models, depending on the number of variables and computational resources, can take days, months or even years.

The focus of the current chapter is to propose and describe an optimization model for calculating the CAPEX of the network, based on the three modes of transport (opaque, transparent and translucent) without survivability and protection.

In section 5.1, it is described how the network CAPEX is calculated as well as the objective function of the dimensioning problem. In the following subsections it is proposed in detail the restrictions of the three models previously mentioned, without survivability and with protection as well as a detailed report of the obtained results for each case.

## 5.1 CAPEX

<b>Student Name</b>	:	Tiago Esteves (October 03, 2017 - )
<b>Goal</b>	:	Implement of the ILP model to obtain the best possible CAPEX of a given network.

The cost of a telecommunications network can be divided into CAPEX and OPEX. CAPEX is the amount of money needed to set up and install a particular network. OPEX is the amount of money needed to run this network as well as its maintenance and operation over time. In this section we will only focus on CAPEX, that is, the costs of installing a particular network. As we know the telecommunications networks are made up of links and nodes, so it is possible to define the CAPEX as being the sum of the cost of links and cost of nodes. This can be said that the value of CAPEX is given by the equation 5.1.

$$C_C = C_L + C_N \quad (5.1)$$

- $C_C \rightarrow$  CAPEX cost in monetary units (e.g. euros, or dollars)
- $C_L \rightarrow$  Link cost in monetary units (e.g. euros, or dollars)
- $C_N \rightarrow$  Node cost in monetary units (e.g. euros, or dollars)

For this calculation first let's focus on the cost of the links and for this we have to take into account the figure 5.1 where we can see the design of a link. In this figure we can see that a link consists of two optical line terminals (one at each end), it also has several amplifiers (this number depends on the length of the link) placed at a certain distance (span) and finally it also consists of several optical channels each with a certain wavelength.

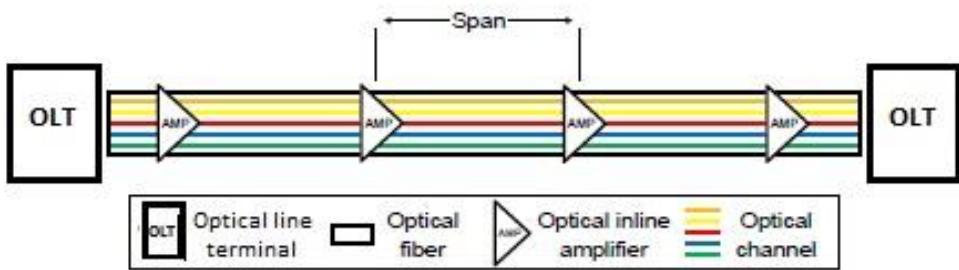


Figura 5.1: Design of a link.

Thus, through the previous image, we can conclude that the link cost is calculated by the equation 5.2.

$$C_L = \sum_{i=1}^N \sum_{j=i+1}^N L_{ij} (2\gamma_0^{OLT} + 2\gamma_1^{OLT}\tau W_{ij} + N_{ij}^R c^R) \quad (5.2)$$

- $C_L \rightarrow$  Links cost in monetary units (e.g. euros, or dollars)
- $i \rightarrow$  Index for start node of a physical link
- $j \rightarrow$  Index for end node of a physical link
- $N \rightarrow$  Total number of nodes,  $N \in \mathbb{N}$
- $L_{ij} \rightarrow$  Binary variable indicating if link between the nodes  $i$  and  $j$  is used,  $L_{ij} \in 0, 1$
- $\gamma_0^{OLT} \rightarrow$  OLT cost in monetary units (e.g. euros, or dollars)
- $\gamma_1^{OLT} \rightarrow$  Transponder cost in monetary units (e.g. euros, or dollars)
- $\tau \rightarrow$  Line bit-rate
- $W_{ij} \rightarrow$  Number of optical channels in link  $i j$
- $N_{ij}^R \rightarrow$  Number of optical amplifiers in link  $i j$
- $c^R \rightarrow$  Optical amplifiers cost in monetary units (e.g. euros, or dollars)

The next step is to take into account the cost of the nodes, but for this we must first know how a node is constituted. The nodes have an electrical part and an optical part so we can conclude that the cost of the nodes is given by the sum of these two parts thus obtaining the equation 5.3.

$$C_N = C_{EXC} + C_{OXC} \quad (5.3)$$

In relation to the electric part we can see the figure 5.2 where it shows its constitution.

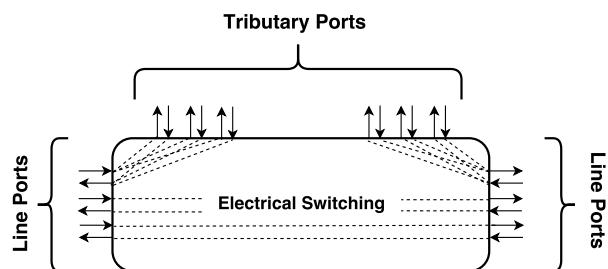


Figura 5.2: Design of a electrical switching.

Thus, through the previous image, we can conclude in a simple way that the electric cost is the sum of the fixed cost of the electrical connection with the total cost of all the electric ports. Therefore the electric cost is given by equation 5.4.

$$C_{EXC} = \sum_{n=1}^N N_{exc,n} \left( \gamma_{e0} + \sum_{c=-1}^B \gamma_{e1,c} P_{exc,c,n} \right) \quad (5.4)$$

- $C_{EXC}$  → Electrical cost in monetary units (e.g. euros, or dollars)
- $N$  → Total number of nodes,  $N \in \mathbb{N}$
- $N_{exc,n}$  → Binary variable indicating if node  $n$  is used,  $N_{exc,n} \in 0, 1$
- $\gamma_{e0}$  → EXC cost in monetary units (e.g. euros, or dollars)
- $\gamma_{e1,c}$  → EXC port cost in monetary units (e.g. euros, or dollars) with bit-rate  $B$  and with a given transceiver reach
- $P_{exc,c,n}$  → Number of ports of the electrical switch
- $B$  → A natural number corresponding to the maximum index of short-reach ports, see table below

Index	Bit rate
-1	100 Gbits/s line bit-rate (long-reach port)
0	1.25 Gbits/s tributary bit-rate (short-reach port)
1	2.5 Gbits/s tributary bit-rate (short-reach port)
2	10 Gbits/s tributary bit-rate (short-reach port)
3	40 Gbits/s tributary bit-rate (short-reach port)
4	100 Gbits/s tributary bit-rate (short-reach port)

Tabela 5.1: Table with index and your corresponding bit rate

In relation to the optical part we can see the figure 5.3 where it shows its constitution.

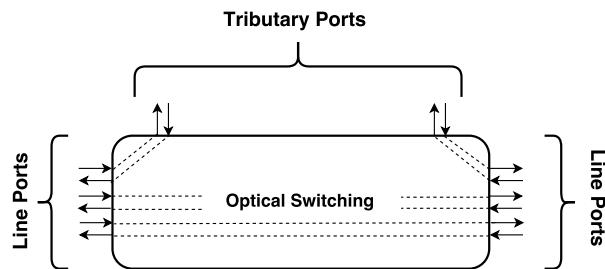


Figura 5.3: Design of a optical switching.

Thus, through the previous image, we can conclude in a simple way that the electric cost is the sum of the fixed cost of the optical connection with the total cost of all the optical ports. Therefore the optical cost is given by equation 5.5.

$$C_{OXC} = \sum_{n=1}^N N_{oxc,n} (\gamma_{o0} + \gamma_{o1} P_{oxc,n}) \quad (5.5)$$

- $C_{OXC}$  → Optical cost in monetary units (e.g. euros, or dollars)
- $N$  → Total number of nodes,  $N \in \mathbb{N}$
- $N_{oxc,n}$  → Binary variable indicating if node  $n$  is used,  $N_{oxc,n} \in 0, 1$
- $\gamma_{o0}$  → OXC cost in monetary units (e.g. euros, or dollars)
- $\gamma_{o1}$  → OXC port cost in monetary units (e.g. euros, or dollars)
- $P_{oxc,n}$  → Number of ports of the optical switch

We have to take into account that the calculated value for the variable  $P_{exc,c,n}$  and  $P_{oxc,n}$  will depend on the mode of transport used (opaque, transparent or translucent) but later on it will be explained how these values are calculated for each specific transport mode.

To obtain the best possible value, it will be necessary to minimize the cost of the capex mentioned above so that we can obtain the objective function 5.6.

$$\text{minimize} \quad C_C \quad (5.6)$$

Subject to the following restrictions where these restrictions are the flow conservation constraints.

$$\sum_{j \setminus \{o\}} f_{ij}^{od} = Z \quad \forall (o, d) : o < d, \forall i : i = o \quad (5.7)$$

This constraint ensures that, for all demand pairs  $(o, d)$ , it routes  $Z$  flow of traffic for all bidirectional links  $(i, j)$  when  $j$  is not equal to the origin of the demand. The variable  $Z$  depends of the transport mode and survivability mechanism.

$$\sum_{j \setminus \{o\}} f_{ij}^{od} = \sum_{j \setminus \{d\}} f_{ji}^{od} \quad \forall (o, d) : o < d, \forall i : i \neq o, d \quad (5.8)$$

In this constraint, assuming bidirectional traffic, so the number of flows in both directions of the link is the same.

$$\sum_{j \setminus \{d\}} f_{ji}^{od} = Z \quad \forall (o, d) : o < d, \forall i : i = d \quad (5.9)$$

This constraint ensures that, for all demand pairs  $(o, d)$ , it routes  $Z$  flow of traffic for all bidirectional links  $(j, i)$  when  $i$  is not equal to the destination of the demand. The variable  $Z$  depends of the transport mode and survivability mechanism.

$$f_{ij}^{od}, f_{ji}^{od} \in \mathbb{N} \quad \forall (i, j) : i < j, \forall (o, d) : o < d \quad (5.10)$$

The number of flows per demand can be a natural number depending the considered traffic.

Finally, one aspect to be taken into account is the cost of the equipment used in the network. Through the table 5.2 we can see the cost in euros of the equipment.

Equipment	Symbol	Cost
OLT without transponders	$\gamma_0^{OLT}$	15000 €
Transponder	$\gamma_1^{OLT}$	5000 €/Gb
Unidirectional Optical Amplifier	$c^R$	4000 €
EXC	$\gamma_{e0}$	10000 €
OXC	$\gamma_{o0}$	20000 €
EXC Port for line ports	$\gamma_{e1,-1}$	1000 €/Gb/s
EXC Port for ODU0	$\gamma_{e1,0}$	8 €/Gb/s
EXC Port for ODU1	$\gamma_{e1,1}$	6 €/Gb/s
EXC Port for ODU2	$\gamma_{e1,2}$	3 €/Gb/s
EXC Port for ODU3	$\gamma_{e1,3}$	1.5 €/Gb/s
EXC Port for ODU4	$\gamma_{e1,4}$	1 €/Gb/s
OXC Port	$\gamma_{o1}$	2500 €/porto

Tabela 5.2: Table with costs

### 5.1.1 Opaque without Survivability

<b>Student Name</b>	:	Tiago Esteves (October 03, 2017 - )
<b>Goal</b>	:	Implement the ILP model for the opaque transport mode without survivability.

#### Model description

First, for a better understanding of the functions and variables used in the ILP, a table 5.3 will be created with all indexes, inputs and variables and with their respective description.

Description of notation used in the objective function	
$i$	index for start node of a physical link
$j$	index for end node of a physical link
$o$	index for node that is origin of a demand
$d$	index for node that is destination of a demand
$c$	index for bit rate of the client signal
$(i,j)$	physical link between the nodes $i$ and $j$
$(o,d)$	demand between the nodes $o$ and $d$
$C$	set of the client signal
$f_{ij}^{od}$	binary variable indicating if link between the nodes $i$ and $j$ is used in the path between nodes $o$ and $d$
$L_{ij}$	binary variable indicating if link between the nodes $i$ and $j$ is used
$W_{ij}$	number of optical channels between the nodes $i$ and $j$
$B_c$	client signals granularities (1.25, 2.5, 10, 40, 100)
$D_{odc}$	client demands with bit rate $c$ between nodes $o$ and $d$
$G_{ij}$	network topology in form of adjacency matrix

Tabela 5.3: Table with description of variables

Before carrying out the description of the objective function we must take into account the following particularity of this mode of transport:

- $N_{OXC,n} = 0, \quad \forall n$
- $N_{EXC,n} = 1, \quad \forall n$  that process traffic

The objective function of following the ILP is a minimization of the CAPEX through the equation 5.1 where in this case for the cost of nodes we only have in consideration the electric cost 5.4 because of the particularity previously mentioned. In this case the value of  $P_{exc,c,n}$  is obtained by equation 5.11 for long-reach and by the equation 5.12 for short-reach.

As previously mentioned, equation 5.11 refers to the number of long-reach ports, that is, the number of line ports of node n is calculated.

$$P_{exc,-1,n} = \sum_{j=1}^N w_{nj} \quad (5.11)$$

- $P_{exc,-1,n}$  → Number of long-reach ports of the electrical switch, i.e. number of line ports
- $w_{nj}$  → Number of optical channels between node n and node j

As previously mentioned, equation 5.12 refers to the number of sort-reach ports, that is, the number of tributary ports with bit-rate c in node n is calculated.

$$P_{exc,c,n} = \sum_{d=1}^N D_{nd,c} \quad (5.12)$$

- $P_{exc,c,n}$  → Number of sort-reach ports of the electrical switch
- $D_{nj,c}$  → client demands between nodes n and d with bit rate c

In this case there is the following particularity:

- When  $n=j$  the value of client demands is always zero, i.e,  $D_{nn,c} = 0$

The objective function, to be minimized, is the expression 5.6.

*subject to*

$$\sum_{j \setminus \{o\}} f_{ij}^{od} = 1 \quad \forall(o, d) : o < d, \forall i : i = o \quad (5.13)$$

This constraint are equal to the constraint 5.7 assuming that Z variable has the value of 1.

$$\sum_{j \setminus \{o\}} f_{ij}^{od} = \sum_{j \setminus \{d\}} f_{ji}^{od} \quad \forall(o, d) : o < d, \forall i : i \neq o, d \quad (5.14)$$

This constraint are equal to the constraint 5.8.

$$\sum_{j \setminus \{d\}} f_{ji}^{od} = 1 \quad \forall(o, d) : o < d, \forall i : i = d \quad (5.15)$$

This constraint are equal to the constraint 5.9 assuming that Z variable has the value of 1.

$$\sum_{(o,d):o < d} \left( f_{ij}^{od} + f_{ji}^{od} \right) \sum_{c \in C} (B(c) D_{odc} \leq \tau W_{ij} G_{ij} \quad \forall (i,j) : i < j \quad (5.16)$$

This restriction is considered grooming constraint, so it means the total client traffic flows can not be greater than the capacity of optical transmission system on all links where  $\tau$  is always 100.

$$W_{ij} \leq K_{ij} L_{ij} \quad \forall (i,j) : i < j \quad (5.17)$$

This restriction concerns the capacity of the optical channels which must be less or equal to the maximum number of optical channels. For any situation the maximum number of optical channels supported by each transmission system is 80, i.e.,  $K_{ij} = 80$ .

$$f_{ij}^{od}, f_{ji}^{od} \in \{0, 1\} \quad \forall (i,j) : i < j, \forall (o,d) : o < d \quad (5.18)$$

The number of flows per demand in this case can be zero if there are no traffic demands or one if considering traffic.

$$W_{ij} \in \mathbb{N} \quad \forall (i,j) : i < j \quad (5.19)$$

The last constraint is just needed to ensure the number of optical channels is a positive integer values greater than zero.

### Result description

To perform the calculations using the implementation of the models described previously it is necessary to use a mathematical software tool. For this we will use MATLAB which is ideal for dealing with linear programming problems and can call the LPsolve through an external interface.

We already have all the necessary to obtain the CAPEX value for the reference network 6.1. As described in the subsection of network traffic 6.1, we have three values of network traffic (low, medium and high traffic) so we have to obtain three different CAPEX. The value of the CAPEX of the network will be calculated based on the costs of the equipment present in the table 5.2.

#### Low Traffic Scenario:

In this scenario we have to take into account the traffic calculated in 6.1. In a first phase we will show the three topologies of the network, the first one already knew physical topology, the second the allowed optical topology and finally the resulting optical topology.

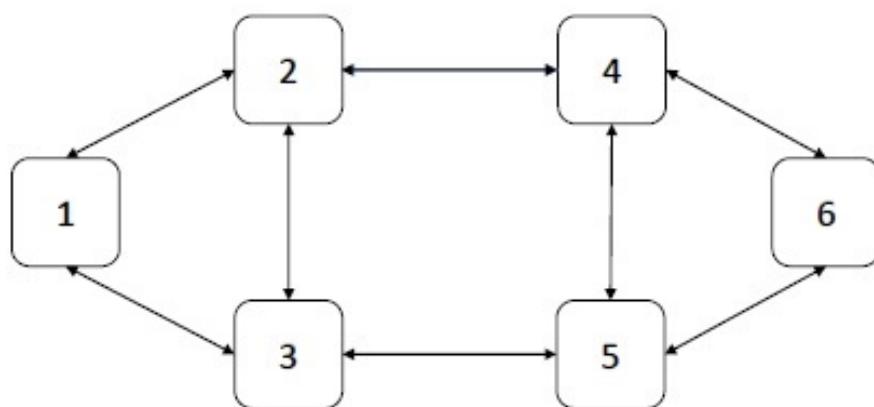


Figura 5.4: Physical topology of the reference network.

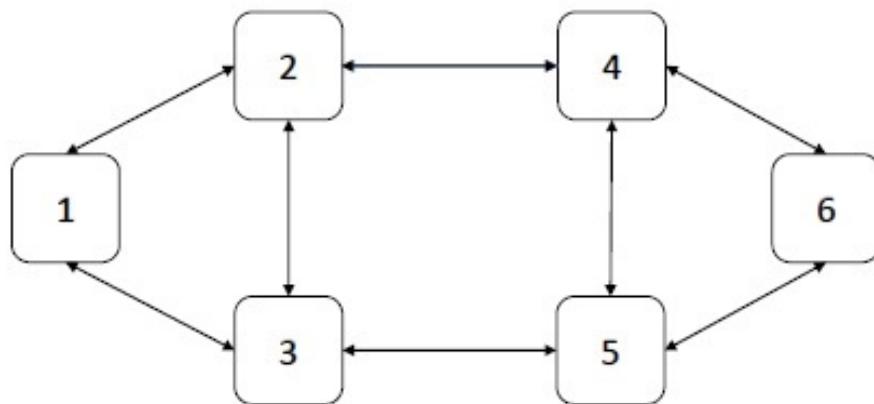


Figura 5.5: Allowed topology of the reference network.

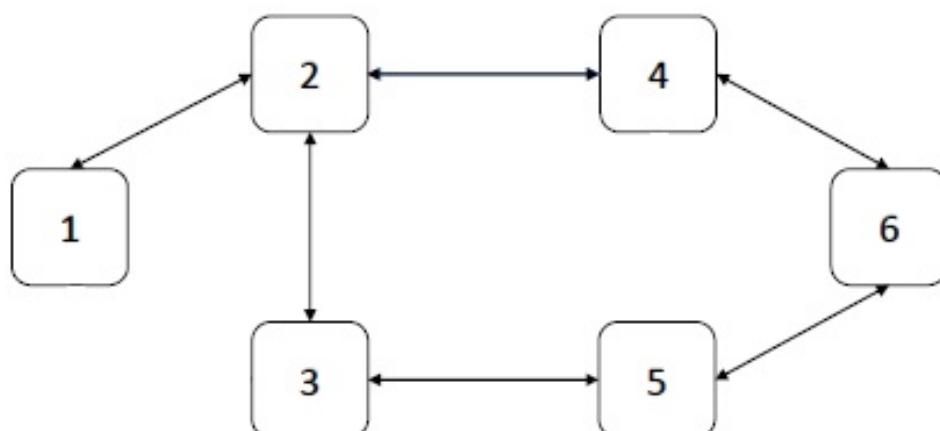


Figura 5.6: Optical topology of the reference network.

To verify the resulting optical topology we can observe the results indicated below. In table 5.4 we can see the number of optical channels and the number of amplifiers for each link calculated through MatLab.

Information regarding links		
Bidirectional Link	Optical Channels	Amplifiers
Node 1 <-> Node 2	1	4
Node 1 <-> Node 3	0	6
Node 2 <-> Node 3	1	0
Node 2 <-> Node 4	2	6
Node 3 <-> Node 5	1	8
Node 4 <-> Node 5	0	1
Node 4 <-> Node 6	2	7
Node 5 <-> Node 6	2	3

Tabela 5.4: Table with information regarding links

In table 5.5 we can see the number of connections that each node has, the number of line ports and the number of tributary ports for each node.

Information regarding nodes			
Node	Resulting Nodal Degree	Line Ports	Tributary Ports
1	1	1	29
2	3	4	23
3	2	2	18
4	2	4	20
5	2	3	24
6	2	4	22

Tabela 5.5: Table with information regarding nodes

Through the information obtained previously on the nodes we can now create tables with detailed information about each node.

In each table mentioned below we can see how many ports are connected to a given node and its bit rate (in relation to the line ports) and how many ports are assigned to each different bit rate (in relation to the tributary ports).

Detailed description of Node 1		
1 line ports	1 connect to Node 2	100 Gbits/s
29 tributary ports	13 13 3	ODU0 ODU1 ODU2

Tabela 5.6: Table with detailed description of node 1

Detailed description of Node 2		
4 line ports	1 connect to Node 1 1 connect to Node 3 2 connect to Node 4	100 Gbits/s
23 tributary ports	11 7 2 2 1	ODU0 ODU1 ODU2 ODU3 ODU4

Tabela 5.7: Table with detailed description of node 2

Detailed description of Node 3		
2 line ports	1 connect to Node 2 1 connect to Node 5	100 Gbits/s
18 tributary ports	7 6 3 2	ODU0 ODU1 ODU2 ODU3

Tabela 5.8: Table with detailed description of node 3

Detailed description of Node 4		
4 line ports	2 connect to Node 2 2 connect to Node 6	100 Gbits/s
20 tributary ports	7 10 3	ODU0 ODU1 ODU2

Tabela 5.9: Table with detailed description of node 4

Detailed description of Node 5		
3 line ports	1 connect to Node 3 2 connect to Node 6	100 Gbits/s
24 tributary ports	14 4 4 1 1	ODU0 ODU1 ODU2 ODU3 ODU4

Tabela 5.10: Table with detailed description of node 5

Detailed description of Node 6		
4 line ports	2 connect to Node 4 2 connect to Node 5	100 Gbits/s
22 tributary ports	8 10 1 1 2	ODU0 ODU1 ODU2 ODU3 ODU4

Tabela 5.11: Table with detailed description of node 6

Now through the table 5.12 we can see the result of CAPEX obtained with this ILP model.

CAPEX of the Network					
		Quantity	Unit Price	Cost	Total
Link Cost	OLTs	12	15 000 €	180 000 €	9 404 000 €
	100 Gb/s Transceivers	18	5 000 €/Gb/s	9 000 000 €	
	Amplifiers	56	4 000 €	224 000 €	
Node Cost	Electrical	EXCs	10 000 €	60 000 €	1 862 590 €
		ODU0 Ports	8 €/Gb/s	600 €	
		ODU1 Ports	6 €/Gb/s	750 €	
		ODU2 Ports	3 €/Gb/s	480 €	
		ODU3 Ports	1.5 €/Gb/s	360 €	
		ODU4 Ports	1 €/Gb/s	400 €	
		Line Ports	1 000 €/Gb/s	1 800 000 €	
	Optical	OXCs	20 000 €	0 €	
		Ports	2 500 €/porto	0 €	
Total Network Cost					11 266 590 €

Tabela 5.12: Table with detailed description of capex

Through the formulas mentioned below we can see how all the values of the quantity column were calculated.

$$\begin{aligned}
 OLTs &: 2 \sum_{(i,j):i < j} L_{ij} & Transceivers &: 2 \sum_{(i,j):i < j} W_{ij} & Amplifiers &: \sum_{(i,j):i < j} N_{ij}^R L_{ij} \\
 EXCs &: \sum_n^N N_{EXC,n} & ODU0 &: \sum_{(o,d)}^N D_{od,0} & ODU1 &: \sum_{(o,d)}^N D_{od,1} & ODU2 &: \sum_{(o,d)}^N D_{od,2} \\
 ODU3 &: \sum_{(o,d)}^N D_{od,3} & ODU4 &: \sum_{(o,d)}^N D_{od,4} & Line &: \sum_{(i,j)}^N W_{ij}
 \end{aligned}$$

$OXC_s : \sum_n^N N_{OXC,n}$  but as mentioned initially this result is always zero

*Ports:* does not exist for this case then it is equal to zero

Finally let's focus on the routing information. These paths are bidirectional so the path from one node to another is the same path in the opposite direction. In table 5.13 we can see all the routing obtained for all nodes.

Routing		
o	d	Links
1	2	{(1,2)}
1	3	{(1,2),(2,3)}
1	4	{(1,2),(2,4)}
1	5	{(1,2),(2,3),(3,5)}
1	6	{(1,2),(2,4),(4,6)}
2	3	{(2,3)}
2	4	{(2,4)}
2	5	{(2,3),(3,5)}
2	6	{(2,4),(4,6)}
3	4	{(3,2),(2,4)}
3	5	{(3,5)}
3	6	{(3,5),(5,6)}
4	5	{(4,6),(6,5)}
4	6	{(4,6)}
5	6	{(5,6)}

Tabela 5.13: Table with description of routing

**Medium Traffic Scenario:**

In this scenario we have to take into account the traffic calculated in 4.2.2. In a first phase, we will show the various topologies of the network (physical topology, allowed optical topology and resulting optical topology) where in this specific case the three topologies are the same.

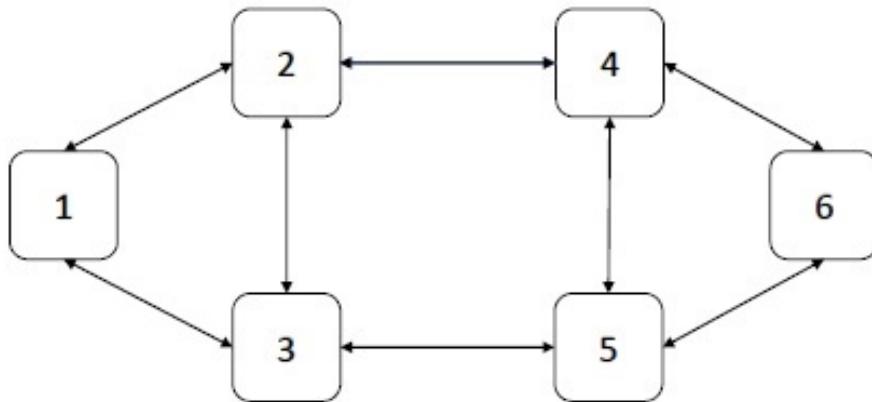


Figura 5.7: Physical, allowed and optical topology of the reference network.

To verify the resulting optical topology we can observe the results indicated below. In table 5.14 we can see the number of optical channels and the number of amplifiers for each link calculated through MatLab.

Information regarding links		
Bidirectional Link	Optical Channels	Amplifiers
Node 1 <-> Node 2	4	4
Node 1 <-> Node 3	4	6
Node 2 <-> Node 3	4	0
Node 2 <-> Node 4	19	6
Node 3 <-> Node 5	9	8
Node 4 <-> Node 5	5	1
Node 4 <-> Node 6	16	7
Node 5 <-> Node 6	14	3

Tabela 5.14: Table with information regarding links

In table 5.15 we can see the number of connections that each node has, the number of line ports and the number of tributary ports for each node.

Information regarding nodes			
Node	Resulting Nodal Degree	Line Ports	Tributary Ports
1	2	8	290
2	3	27	230
3	3	17	180
4	3	40	200
5	3	28	240
6	2	30	220

Tabela 5.15: Table with information regarding nodes

Through the information obtained previously on the nodes we can now create tables with detailed information about each node. In each table mentioned below we can see how many ports are connected to a given node and its bit rate (in relation to the line ports) and how many ports are assigned to each different bit rate (in relation to the tributary ports).

Detailed description of Node 1		
8 line ports	4 connect to Node 2 4 connect to Node 3	100 Gbtis/s
290 tributary ports	130 130 30	ODU0 ODU1 ODU2

Tabela 5.16: Table with detailed description of node 1

Detailed description of Node 2		
27 line ports	4 connect to Node 1 4 connect to Node 3 19 connect to Node 4	100 Gbtis/s
230 tributary ports	110 70 20 20 10	ODU0 ODU1 ODU2 ODU3 ODU4

Tabela 5.17: Table with detailed description of node 2

Detailed description of Node 3		
17 line ports	4 connect to Node 1 4 connect to Node 2 9 connect to Node 5	100 Gbtis/s
180 tributary ports	70 60 30 20	ODU0 ODU1 ODU2 ODU3

Tabela 5.18: Table with detailed description of node 3

Detailed description of Node 4		
40 line ports	19 connect to Node 2 5 connect to Node 5 16 connect to Node 6	100 Gbtis/s
200 tributary ports	70 100 30	ODU0 ODU1 ODU2

Tabela 5.19: Table with detailed description of node 4

Detailed description of Node 5		
28 line ports	9 connect to Node 3 5 connect to Node 4 14 connect to Node 6	100 Gbtis/s
240 tributary ports	140 40 40 10 10	ODU0 ODU1 ODU2 ODU3 ODU4

Tabela 5.20: Table with detailed description of node 5

Detailed description of Node 6		
30 line ports	16 connect to Node 4 14 connect to Node 5	100 Gbtis/s
220 tributary ports	80 100 10 10 20	ODU0 ODU1 ODU2 ODU3 ODU4

Tabela 5.21: Table with detailed description of node 6

Now through the table 5.22 we can see the result of CAPEX obtained with this ILP model.

CAPEX of the Network					
		Quantity	Unit Price	Cost	Total
Link Cost	OLTs	16	15 000 €	240 000 €	75 520 000 €
	100 Gb/s Transceivers	150	5 000 €/Gb/s	750 000 000 €	
	Amplifiers	70	4 000 €	280 000 €	
Node Cost	Electrical	EXCs	6	10 000 €	60 000 €
		ODU0 Ports	600	8 €/Gb/s	6 000 €
		ODU1 Ports	500	6 €/Gb/s	7 500 €
		ODU2 Ports	160	3 €/Gb/s	4 800 €
		ODU3 Ports	60	1.5 €/Gb/s	3 600 €
		ODU4 Ports	40	1 €/Gb/s	4 000 €
		Line Ports	150	1 000 €/Gb/s	15 000 000 €
	Optical	OXC	0	20 000 €	0 €
		Ports	0	2 500 €/porto	0 €
Total Network Cost					90 605 900 €

Tabela 5.22: Table with detailed description of capex

Through the formulas mentioned below we can see how all the values of the quantity column were calculated.

$$\begin{aligned}
 OLTs &: 2 \sum_{(i,j):i < j} L_{ij} & Transceivers &: 2 \sum_{(i,j):i < j} W_{ij} & Amplifiers &: \sum_{(i,j):i < j} N_{ij}^R L_{ij} \\
 EXCs &: \sum_n^N N_{EXC,n} & ODU0 &: \sum_{(o,d)}^N D_{od,0} & ODU1 &: \sum_{(o,d)}^N D_{od,1} & ODU2 &: \sum_{(o,d)}^N D_{od,2}
 \end{aligned}$$

$$ODU3 : \sum_{(o,d)}^N D_{od,3} \quad ODU4 : \sum_{(o,d)}^N D_{od,4} \quad Line : \sum_{(i,j)}^N W_{ij}$$

$OXC_s : \sum_n^N N_{OXC,n}$  but as mentioned initially this result is always zero

*Ports:* does not exist for this case then it is equal to zero

Finally let's focus on the routing information. These paths are bidirectional so the path from one node to another is the same path in the opposite direction. In table 5.23 we can see all the routing obtained for all nodes.

Routing		
o	d	Links
1	2	{(1,2)}
1	3	{(1,3)}
1	4	{(1,2),(2,4)}
1	5	{(1,3),(3,5)}
1	6	{(1,3),(3,5),(5,6)}
2	3	{(2,3)}
2	4	{(2,4)}
2	5	{(2,4),(4,5)}
2	6	{(2,4),(4,6)}
3	4	{(3,5),(5,4)}
3	5	{(3,5)}
3	6	{(3,5),(5,6)}
4	5	{(4,5)}
4	6	{(4,6)}
5	6	{(5,6)}

Tabela 5.23: Table with description of routing

### High Traffic Scenario:

In this scenario we have to take into account the traffic calculated in 4.2.3. In a first phase, we will show the various topologies of the network (physical topology, allowed optical topology and resulting optical topology) where in this specific case the three topologies are the same.

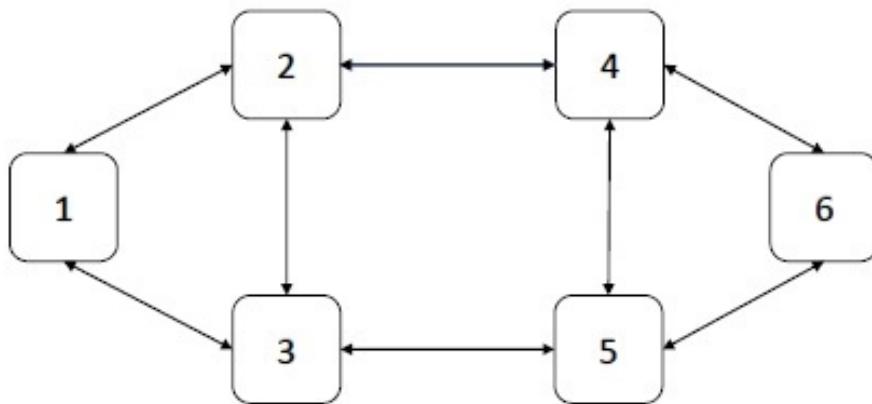


Figura 5.8: Physical, allowed and optical topology of the reference network.

To verify the resulting optical topology we can observe the results indicated below. In table 5.24 we can see the number of optical channels and the number of amplifiers for each link calculated through MatLab.

Information regarding links		
Bidirectional Link	Optical Channels	Amplifiers
Node 1 <-> Node 2	40	4
Node 1 <-> Node 3	39	6
Node 2 <-> Node 3	73	0
Node 2 <-> Node 4	184	6
Node 3 <-> Node 5	95	8
Node 4 <-> Node 5	14	1
Node 4 <-> Node 6	152	7
Node 5 <-> Node 6	134	3

Tabela 5.24: Table with information regarding links

In table 5.25 we can see the number of connections that each node has, the number of line ports and the number of tributary ports for each node.

In each table mentioned below we can see how many ports are connected to a given node and its bit rate (in relation to the line ports) and how many ports are assigned to each different bit rate (in relation to the tributary ports).

Information regarding nodes			
Node	Resulting Nodal Degree	Line Ports	Tributary Ports
1	2	79	2 900
2	3	297	2 300
3	3	207	1 800
4	3	350	2 000
5	3	243	2 400
6	2	286	2 200

Tabela 5.25: Table with information regarding nodes

Through the information obtained previously on the nodes we can now create tables with detailed information about each node.

Detailed description of Node 1		
79 line ports	40 connect to Node 2 39 connect to Node 3	100 Gbtis/s
2 900 tributary ports	1 300 1 300 300	ODU0 ODU1 ODU2

Tabela 5.26: Table with detailed description of node 1

Detailed description of Node 2		
297 line ports	40 connect to Node 1 73 connect to Node 3 184 connect to Node 4	100 Gbtis/s
2 300 tributary ports	1 100 700 200 200 100	ODU0 ODU1 ODU2 ODU3 ODU4

Tabela 5.27: Table with detailed description of node 2

Detailed description of Node 3		
207 line ports	39 connect to Node 1 73 connect to Node 2 95 connect to Node 5	100 Gbtis/s
1 800 tributary ports	700 600 300 200	ODU0 ODU1 ODU2 ODU3

Tabela 5.28: Table with detailed description of node 3

Detailed description of Node 4		
350 line ports	184 connect to Node 2 14 connect to Node 5 152 connect to Node 6	100 Gbtis/s
2 000 tributary ports	700 1 000 300	ODU0 ODU1 ODU2

Tabela 5.29: Table with detailed description of node 4

Detailed description of Node 5		
243 line ports	95 connect to Node 3 14 connect to Node 4 134 connect to Node 6	100 Gbtis/s
2 400 tributary ports	1 400 400 400 100 100	ODU0 ODU1 ODU2 ODU3 ODU4

Tabela 5.30: Table with detailed description of node 5

Detailed description of Node 6		
286 line ports	152 connect to Node 4 134 connect to Node 5	100 Gbtis/s
2 200 tributary ports	800 1 000 100 100 200	ODU0 ODU1 ODU2 ODU3 ODU4

Tabela 5.31: Table with detailed description of node 6

Now through the table 5.32 we can see the result of CAPEX obtained with this ILP model.

CAPEX of the Network					
		Quantity	Unit Price	Cost	Total
Link Cost	OLTs	16	15 000 €	240 000 €	731 520 000 €
	100 Gb/s Transceivers	1 462	5 000 €/Gb/s	731 000 000 €	
	Amplifiers	70	4 000 €	280 000 €	
Node Cost	Electrical	EXCs	6	10 000 €	60 000 €
		ODU0 Ports	6 000	8 €/Gb/s	60 000 €
		ODU1 Ports	5 000	6 €/Gb/s	75 000 €
		ODU2 Ports	1 600	3 €/Gb/s	48 000 €
		ODU3 Ports	600	1.5 €/Gb/s	36 000 €
		ODU4 Ports	400	1 €/Gb/s	40 000 €
		Line Ports	1 462	1 000 €/Gb/s	146 200 000 €
	Optical	OXC	0	20 000 €	0 €
		Ports	0	2 500 €/porto	0 €
Total Network Cost					878 039 000 €

Tabela 5.32: Table with detailed description of capex

Through the formulas mentioned below we can see how all the values of the quantity column were calculated.

$$\begin{aligned}
 OLTs &: 2 \sum_{(i,j):i < j} L_{ij} & Transceivers &: 2 \sum_{(i,j):i < j} W_{ij} & Amplifiers &: \sum_{(i,j):i < j} N_{ij}^R L_{ij} \\
 EXCs &: \sum_n^N N_{EXC,n} & ODU0 &: \sum_{(o,d)}^N D_{od,0} & ODU1 &: \sum_{(o,d)}^N D_{od,1} & ODU2 &: \sum_{(o,d)}^N D_{od,2}
 \end{aligned}$$

$$ODU3 : \sum_{(o,d)}^N D_{od,3} \quad ODU4 : \sum_{(o,d)}^N D_{od,4} \quad Line : \sum_{(i,j)}^N W_{ij}$$

$OXC_s : \sum_n^N N_{OXC,n}$  but as mentioned initially this result is always zero

*Ports:* does not exist for this case then it is equal to zero

Finally let's focus on the routing information. These paths are bidirectional so the path from one node to another is the same path in the opposite direction. In table 5.33 we can see all the routing obtained for all nodes.

Routing		
o	d	Links
1	2	{(1,2)}
1	3	{(1,3)}
1	4	{(1,2),(2,4)}
1	5	{(1,3),(3,5)}
1	6	{(1,3),(3,5),(5,6)}
2	3	{(2,3)}
2	4	{(2,4)}
2	5	{(2,3),(3,5)}
2	6	{(2,4),(4,6)}
3	4	{(3,2),(2,4)}
3	5	{(3,5)}
3	6	{(3,5),(5,6)}
4	5	{(4,5)}
4	6	{(4,6)}
5	6	{(5,6)}

Tabela 5.33: Table with description of routing

### 5.1.2 Opaque with 1+1 Protection

<b>Student Name</b>	:	Tiago Esteves (October 03, 2017 - )
<b>Goal</b>	:	Implement the ILP model for the opaque transport mode with 1 plus 1 protection.

Here, in this case, we must take into account table 5.3, previously mentioned, in order to better understand the objective function.

Before carrying out the description of the objective function we must take into account the following particularity of this mode of transport:

- $N_{OXC,n} = 0, \quad \forall n$
- $N_{EXC,n} = 1, \quad \forall n$  that process traffic

The objective function of following the ILP is a minimization of the CAPEX through the equation 5.1 where in this case for the cost of nodes we only have in consideration the electric cost 5.4 because of the particularity previously mentioned. In this case the value of  $P_{exc,c,n}$  is obtained by equation 5.20 for long-reach and by the equation 5.21 for short-reach.

As previously mentioned, equation 5.20 refers to the number of long-reach ports, that is, the number of line ports of node  $n$  is calculated.

$$P_{exc,-1,n} = \sum_{j=1}^N w_{nj} \quad (5.20)$$

- $P_{exc,-1,n} \rightarrow$  Number of long-reach ports of the electrical switch, i.e. number of line ports
- $w_{nj} \rightarrow$  Number of optical channels between node  $n$  and node  $j$

As previously mentioned, equation 5.12 refers to the number of sort-reach ports, that is, the number of tributary ports with bit-rate  $c$  in node  $n$  is calculated.

$$P_{exc,c,n} = \sum_{d=1}^N D_{nd,c} \quad (5.21)$$

- $P_{exc,c,n} \rightarrow$  Number of sort-reach ports of the electrical switch
- $D_{nd,c} \rightarrow$  client demands between nodes  $n$  and  $d$  with bit rate  $c$

In this case there is the following particularity:

- When  $n=j$  the value of client demands is always zero, i.e.,  $D_{nn,c} = 0$

The objective function, to be minimized, is the expression 5.6.

*subject to*

$$\sum_{j \setminus \{o\}} f_{ij}^{od} = 2 \quad \forall(o, d) : o < d, \forall i : i = o \quad (5.22)$$

This constraint are equal to the constraint 5.7 assuming that Z variable has the value of 2 (work and protection).

$$\sum_{j \setminus \{o\}} f_{ij}^{od} = \sum_{j \setminus \{d\}} f_{ji}^{od} \quad \forall(o, d) : o < d, \forall i : i \neq o, d \quad (5.23)$$

This constraint are equal to the constraint 5.8.

$$\sum_{j \setminus \{d\}} f_{ji}^{od} = 2 \quad \forall(o, d) : o < d, \forall i : i = d \quad (5.24)$$

This constraint are equal to the constraint 5.9 assuming that Z variable has the value of 2 (work and protection).

$$\sum_{(o,d):o < d} (f_{ij}^{od} + f_{ji}^{od}) + \sum_{c \in C} (B(c) D_{odc} \leq 100 W_{ij} G_{ij}) \quad \forall(i, j) : i < j \quad (5.25)$$

This restriction is considered grooming constraint, so it means the total client traffic flows can not be greater than the capacity of optical channels on all links.

$$W_{ij} \leq K_{ij} L_{ij} \quad \forall(i, j) : i < j \quad (5.26)$$

This restriction concerns the capacity of the optical channels which must be less or equal to the maximum number of optical channels. For any situation the maximum number of optical channels supported by each transmission system is 80, i.e.,  $K_{ij} = 80$ .

$$\sum_{(o,d)} (f_{ij}^{od} + f_{ji}^{od}) \leq K_{ij} L_{ij} \quad \forall(i, j) \quad (5.27)$$

This restriction answers capacity constraint problem. Then, total flows must be less or equal to the capacity of network links.

$$L_{ij}, f_{ij}^{od}, f_{ji}^{od} \in \{0, 1\} \quad \forall(i, j) : i < j, \forall(o, d) : o < d \quad (5.28)$$

The number of flows per demand in this case can be zero if there are no traffic demands or one if considering working or protection traffic, in relation to the use of the link, can be zero if it is not being used or one if is being used.

$$W_{ij} \in \mathbb{N} \quad \forall(i, j) : i < j \quad (5.29)$$

The last constraint is just needed to ensure the number optical of channels is a positive integer values greater than zero.

### Result description

To perform the calculations using the implementation of the models described in previous subsection it is necessary to use the MATLAB once more.

We already have all the necessary to obtain the CAPEX value for the reference network 6.1. As described in the subsection of network traffic 6.1, we have three values of network traffic (low, medium and high traffic) so we have to obtain three different CAPEX. The value of the CAPEX of the network will be calculated based on the costs of the equipment present in the table 5.2.

#### Low Traffic Scenario:

In this scenario we have to take into account the traffic calculated in 6.1. In a first phase we will show the three topologies of the network, the first one already knew physical topology, the second the allowed optical topology and finally the resulting optical topology.

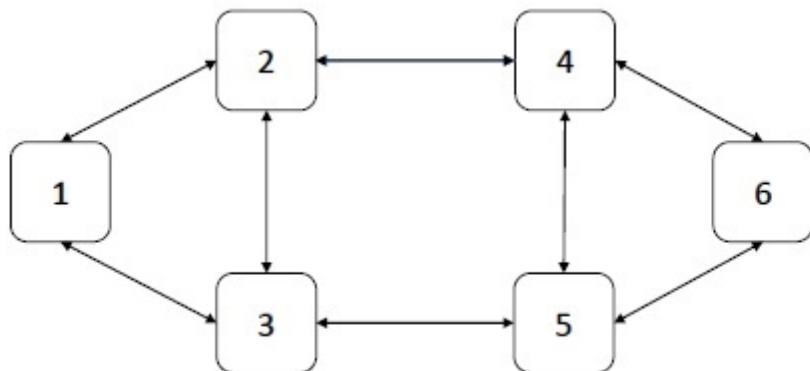


Figura 5.9: Physical topology of the reference network.

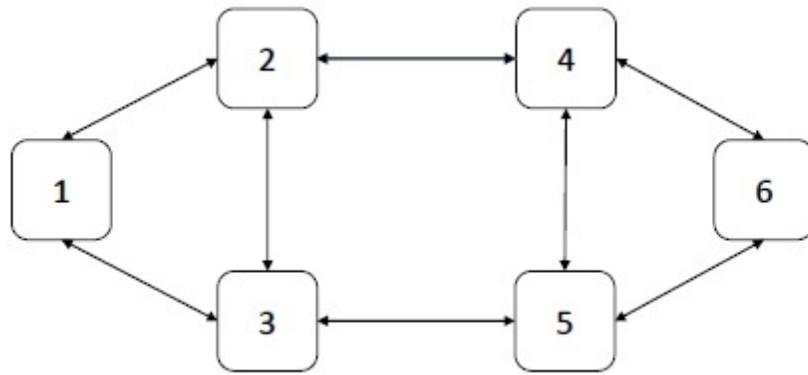


Figura 5.10: Allowed topology of the reference network.

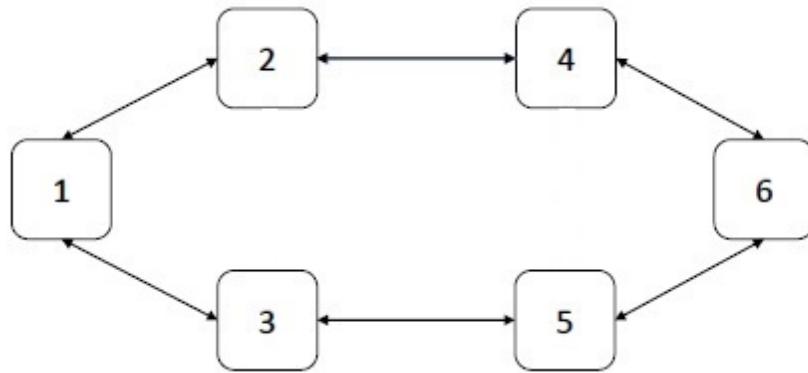


Figura 5.11: Optical topology of the reference network.

To verify the resulting optical topology we can observe the results indicated below. In table 5.34 we can see the number of optical channels and the number of amplifiers for each link calculated through MatLab.

Information regarding links		
Bidirectional Link	Optical Channels	Amplifiers
Node 1 <-> Node 2	5	4
Node 1 <-> Node 3	5	6
Node 2 <-> Node 3	0	0
Node 2 <-> Node 4	5	6
Node 3 <-> Node 5	5	8
Node 4 <-> Node 5	0	1
Node 4 <-> Node 6	5	7
Node 5 <-> Node 6	5	3

Tabela 5.34: Table with information regarding links

In table 5.35 we can see the number of connections that each node has, the number of line ports and the number of tributary ports for each node.

Information regarding nodes			
Node	Resulting Nodal Degree	Line Ports	Tributary Ports
1	2	10	29
2	2	10	23
3	2	10	18
4	2	10	20
5	2	10	24
6	2	10	22

Tabela 5.35: Table with information regarding nodes

Through the information obtained previously on the nodes we can now create tables with detailed information about each node.

In each table mentioned below we can see how many ports are connected to a given node and its bit rate (in relation to the line ports) and how many ports are assigned to each different bit rate (in relation to the tributary ports).

Detailed description of Node 1			
10 line ports	5 connect to Node 2 5 connect to Node 3	100 Gbits/s	
29 tributary ports	13 13 3	ODU0 ODU1 ODU2	

Tabela 5.36: Table with detailed description of node 1

Detailed description of Node 2			
10 line ports	5 connect to Node 1 5 connect to Node 4	100 Gbits/s	
23 tributary ports	11 7 2 2 1	ODU0 ODU1 ODU2 ODU3 ODU4	

Tabela 5.37: Table with detailed description of node 2

Detailed description of Node 3		
10 line ports	5 connect to Node 1 5 connect to Node 5	100 Gbits/s
18 tributary ports	7 6 3 2	ODU0 ODU1 ODU2 ODU3

Tabela 5.38: Table with detailed description of node 3

Detailed description of Node 4		
10 line ports	5 connect to Node 2 5 connect to Node 6	100 Gbits/s
20 tributary ports	7 10 3	ODU0 ODU1 ODU2

Tabela 5.39: Table with detailed description of node 4

Detailed description of Node 5		
10 line ports	5 connect to Node 3 5 connect to Node 6	100 Gbits/s
24 tributary ports	14 4 4 1 1	ODU0 ODU1 ODU2 ODU3 ODU4

Tabela 5.40: Table with detailed description of node 5

Detailed description of Node 6		
10 line ports	5 connect to Node 4 52 connect to Node 5	100 Gbits/s
22 tributary ports	8 10 1 1 2	ODU0 ODU1 ODU2 ODU3 ODU4

Tabela 5.41: Table with detailed description of node 6

Now through the table 5.42 we can see the result of CAPEX obtained with this ILP model.

CAPEX of the Network					
		Quantity	Unit Price	Cost	Total
Link Cost	OLTs	12	15 000 €	180 000 €	30 452 000 €
	100 Gb/s Transceivers	60	5 000 €/Gb/s	30 000 000 €	
	Amplifiers	68	4 000 €	272 000 €	
Node Cost	Electrical	EXCs	6	10 000 €	6 062 590 €
		ODU0 Ports	60	8 €/Gb/s	
		ODU1 Ports	50	6 €/Gb/s	
		ODU2 Ports	16	3 €/Gb/s	
		ODU3 Ports	6	1.5 €/Gb/s	
		ODU4 Ports	4	1 €/Gb/s	
	Optical	Line Ports	60	1 000 €/Gb/s	6 000 000 €
		OXCs	0	20 000 €	0 €
		Ports	0	2 500 €/porto	0 €
Total Network Cost					36 514 590 €

Tabela 5.42: Table with detailed description of capex

Through the formulas mentioned below we can see how all the values of the quantity column were calculated.

$$\begin{aligned}
 OLTs &: 2 \sum_{(i,j):i < j} L_{ij} & Transceivers &: 2 \sum_{(i,j):i < j} W_{ij} & Amplifiers &: \sum_{(i,j):i < j} N_{ij}^R L_{ij} \\
 EXCs &: \sum_n^N N_{EXC,n} & ODU0 &: \sum_{(o,d)}^N D_{od,0} & ODU1 &: \sum_{(o,d)}^N D_{od,1} & ODU2 &: \sum_{(o,d)}^N D_{od,2} \\
 ODU3 &: \sum_{(o,d)}^N D_{od,3} & ODU4 &: \sum_{(o,d)}^N D_{od,4} & Line &: \sum_{(i,j)}^N W_{ij}
 \end{aligned}$$

$$OXCs : \sum_n^N N_{OXC,n} \text{ but as mentioned initially this result is always zero}$$

Ports: does not exist for this case then it is equal to zero

Finally let's focus on the routing information. These paths are bidirectional so the path from one node to another is the same path in the opposite direction. In table 5.43 we can see all the routing obtained for all nodes.

Routing		
$o$	$d$	Links
1	2	$\{(1,2)\}$ $\{(1,3),(3,5),(5,6),(6,4),(4,2)\}$
1	3	$\{(1,3)\}$ $\{(1,2),(2,4),(4,6),(6,5),(5,3)\}$
1	4	$\{(1,2),(2,4)\}$ $\{(1,3),(3,5),(5,6),(6,4)\}$
1	5	$\{(1,3),(3,5)\}$ $\{(1,2),(2,4),(4,6),(6,5)\}$
1	6	$\{(1,2),(2,4),(4,6)\}$ $\{(1,3),(3,5),(5,6)\}$
2	3	$\{(2,1),(1,3)\}$ $\{(2,4),(4,6),(6,5),(5,3)\}$
2	4	$\{(2,4)\}$ $\{(2,1),(1,3),(3,5),(5,6),(6,4)\}$
2	5	$\{(2,4),(4,6),(6,5)\}$ $\{(2,1),(1,3),(3,5)\}$
2	6	$\{(2,4),(4,6)\}$ $\{(2,1),(1,3),(3,5),(5,6)\}$
3	4	$\{(3,1),(1,2),(2,4)\}$ $\{(3,5),(5,6),(6,4)\}$
3	5	$\{(3,5)\}$ $\{(3,1),(1,2),(2,4),(4,6),(6,5)\}$
3	6	$\{(3,5),(5,6)\}$ $\{(3,1),(1,2),(2,4),(4,6)\}$
4	5	$\{(4,6),(6,5)\}$ $\{(4,2),(2,1),(1,3),(3,5)\}$
4	6	$\{(4,6)\}$ $\{(4,2),(2,1),(1,3),(3,5),(5,6)\}$
5	6	$\{(5,6)\}$ $\{(5,3),(3,1),(1,2),(2,4),(4,6)\}$

Tabela 5.43: Table with description of routing

**Medium Traffic Scenario:**

In this scenario we have to take into account the traffic calculated in 4.2.2. In a first phase, we will show the various topologies of the network (physical topology, allowed optical topology and resulting optical topology) where in this specific case the three topologies are the same.

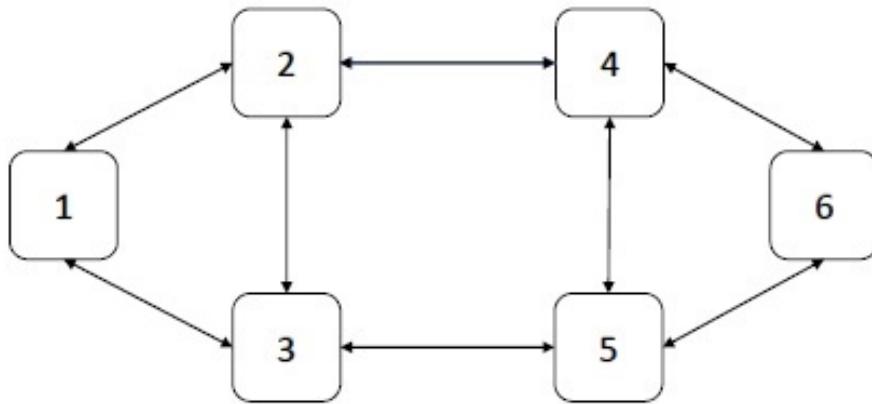


Figura 5.12: Physical, allowed and optical topology of the reference network.

To verify the resulting optical topology we can observe the results indicated below. In table 5.44 we can see the number of optical channels and the number of amplifiers for each link calculated through MatLab.

Information regarding links		
Bidirectional Link	Optical Channels	Amplifiers
Node 1 <-> Node 2	12	4
Node 1 <-> Node 3	12	6
Node 2 <-> Node 3	33	0
Node 2 <-> Node 4	28	6
Node 3 <-> Node 5	28	8
Node 4 <-> Node 5	26	1
Node 4 <-> Node 6	30	7
Node 5 <-> Node 6	30	3

Tabela 5.44: Table with information regarding links

In table 5.45 we can see the number of connections that each node has, the number of line ports and the number of tributary ports for each node.

Information regarding nodes			
Node	Connections	Line Ports	Tributary Ports
1	2	24	290
2	3	73	230
3	3	73	180
4	3	84	200
5	3	84	240
6	2	60	220

Tabela 5.45: Table with information regarding nodes

Through the information obtained previously on the nodes we can now create tables with detailed information about each node. In each table mentioned below we can see how many ports are connected to a given node and its bit rate (in relation to the line ports) and how many ports are assigned to each different bit rate (in relation to the tributary ports).

Detailed description of Node 1		
24 line ports	12 connect to Node 2 12 connect to Node 3	100 Gbtis/s
290 tributary ports	130 130 30	ODU0 ODU1 ODU2

Tabela 5.46: Table with detailed description of node 1

Detailed description of Node 2		
73 line ports	12 connect to Node 1 33 connect to Node 3 28 connect to Node 4	100 Gbtis/s
230 tributary ports	110 70 20 20 10	ODU0 ODU1 ODU2 ODU3 ODU4

Tabela 5.47: Table with detailed description of node 2

Detailed description of Node 3		
73 line ports	12 connect to Node 1 33 connect to Node 2 28 connect to Node 5	100 Gbtis/s
180 tributary ports	70 60 30 20	ODU0 ODU1 ODU2 ODU3

Tabela 5.48: Table with detailed description of node 3

Detailed description of Node 4		
84 line ports	28 connect to Node 2 26 connect to Node 5 30 connect to Node 6	100 Gbtis/s
200 tributary ports	70 100 30	ODU0 ODU1 ODU2

Tabela 5.49: Table with detailed description of node 4

Detailed description of Node 5		
84 line ports	28 connect to Node 3 26 connect to Node 4 30 connect to Node 6	100 Gbtis/s
240 tributary ports	140 40 40 10 10	ODU0 ODU1 ODU2 ODU3 ODU4

Tabela 5.50: Table with detailed description of node 5

Detailed description of Node 6		
60 line ports	30 connect to Node 4 30 connect to Node 5	100 Gbtis/s
220 tributary ports	80 100 10 10 20	ODU0 ODU1 ODU2 ODU3 ODU4

Tabela 5.51: Table with detailed description of node 6

Now through the table 5.52 we can see the result of CAPEX obtained with this ILP model.

CAPEX of the Network					
		Quantity	Unit Price	Cost	Total
Link Cost	OLTs	16	15 000 €	240 000 €	199 520 000 €
	100 Gb/s Transceivers	398	5 000 €/Gb/s	199 000 000 €	
	Amplifiers	70	4 000 €	280 000 €	
Node Cost	Electrical	EXCs	6	10 000 €	39 885 900 €
		ODU0 Ports	600	8 €/Gb/s	
		ODU1 Ports	500	6 €/Gb/s	
		ODU2 Ports	160	3 €/Gb/s	
		ODU3 Ports	60	1.5 €/Gb/s	
		ODU4 Ports	40	1 €/Gb/s	
		Line Ports	398	1 000 €/Gb/s	
	Optical	OXCs	0	20 000 €	
		Ports	0	2 500 €/porto	
Total Network Cost					239 405 900 €

Tabela 5.52: Table with detailed description of capex

Through the formulas mentioned below we can see how all the values of the quantity column were calculated.

$$\begin{aligned}
 OLTs &: 2 \sum_{(i,j):i < j} L_{ij} & Transceivers &: 2 \sum_{(i,j):i < j} W_{ij} & Amplifiers &: \sum_{(i,j):i < j} N_{ij}^R L_{ij} \\
 EXCs &: \sum_n^N N_{EXC,n} & ODU0 &: \sum_{(o,d)}^N D_{od,0} & ODU1 &: \sum_{(o,d)}^N D_{od,1} & ODU2 &: \sum_{(o,d)}^N D_{od,2} \\
 ODU3 &: \sum_{(o,d)}^N D_{od,3} & ODU4 &: \sum_{(o,d)}^N D_{od,4} & Line &: \sum_{(i,j)}^N W_{ij}
 \end{aligned}$$

$OXC_s : \sum_n^N N_{OXC,n}$  but as mentioned initially this result is always zero

*Ports:* does not exist for this case then it is equal to zero

Finally let's focus on the routing information. In table 5.53 we can see all the routing obtained for all nodes.

Routing		
o	d	Links
1	2	{(1,2)} {(1,3),(3,2)}
1	3	{(1,3)} {(1,2),(2,3)}
1	4	{(1,2),(2,4)} {(1,3),(3,5),(5,4)}
1	5	{(1,3),(3,5)} {(1,2),(2,4),(4,5)}
1	6	{(1,2),(2,4),(4,6)} {(1,3),(3,5),(5,6)}
2	3	{(2,3)} {(2,1),(1,3)}
2	4	{(2,4)} {(2,3),(3,5),(5,4)}
2	5	{(2,4),(4,5)} {(2,3),(3,5)}
2	6	{(2,4),(4,6)} {(2,3),(3,5),(5,6)}
3	4	{(3,2),(2,4)} {(3,5),(5,4)}
3	5	{(3,5)} {(3,2),(2,4),(4,5)}
3	6	{(3,5),(5,6)} {(3,2),(2,4),(4,6)}
4	5	{(4,5)} {(4,6),(6,5)}
4	6	{(4,6)} {(4,5),(5,6)}
5	6	{(5,6)} {(5,4),(4,6)}

Tabela 5.53: Table with description of routing

### High Traffic Scenario:

In this scenario we have to take into account the traffic calculated in 4.2.3. In a first phase, we will show the various topologies of the network (physical topology, allowed optical topology and resulting optical topology) where in this specific case the three topologies are the same.

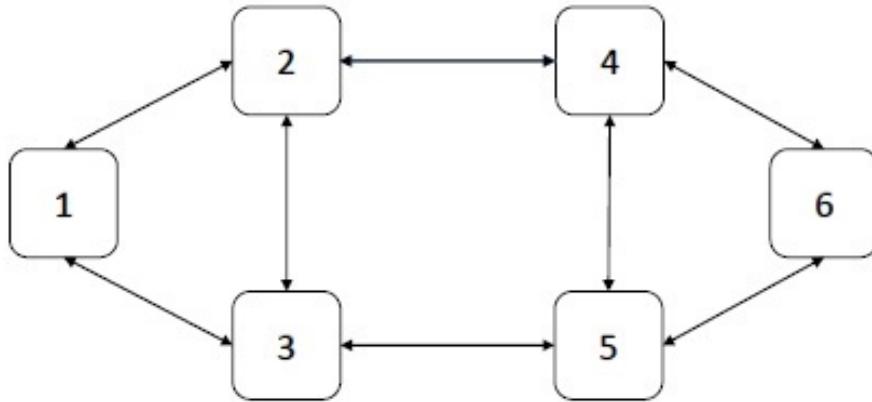


Figura 5.13: Physical, allowed and optical topology of the reference network.

To verify the resulting optical topology we can observe the results indicated below. In table 5.54 we can see the number of optical channels and the number of amplifiers for each link calculated through MatLab.

Information regarding links		
Bidirectional Link	Optical Channels	Amplifiers
Node 1 <-> Node 2	119	4
Node 1 <-> Node 3	119	6
Node 2 <-> Node 3	325	0
Node 2 <-> Node 4	279	6
Node 3 <-> Node 5	279	8
Node 4 <-> Node 5	258	1
Node 4 <-> Node 6	299	7
Node 5 <-> Node 6	299	3

Tabela 5.54: Table with information regarding links

In table 5.55 we can see the number of connections that each node has, the number of line ports and the number of tributary ports for each node.

Information regarding nodes			
Node	Connections	Line Ports	Tributary Ports
1	2	238	2 900
2	3	723	2 300
3	3	723	1 800
4	3	836	2 000
5	3	836	2 400
6	2	598	2 200

Tabela 5.55: Table with information regarding nodes

In table 5.55 we can see the number of connections that each node has, the number of line ports and the number of tributary ports for each node.

In each table mentioned below we can see how many ports are connected to a given node and its bit rate (in relation to the line ports) and how many ports are assigned to each different bit rate (in relation to the tributary ports).

Detailed description of Node 1		
238 line ports	119 connect to Node 2 119 connect to Node 3	100 Gbtis/s
2 900 tributary ports	1 300 1 300 300	ODU0 ODU1 ODU2

Tabela 5.56: Table with detailed description of node 1

Detailed description of Node 2		
723 line ports	119 connect to Node 1 325 connect to Node 3 279 connect to Node 4	100 Gbtis/s
2 300 tributary ports	1 100 700 200 200 100	ODU0 ODU1 ODU2 ODU3 ODU4

Tabela 5.57: Table with detailed description of node 2

Detailed description of Node 3		
723 line ports	119 connect to Node 1 325 connect to Node 2 279 connect to Node 5	100 Gbtis/s
1 800 tributary ports	700 600 300 200	ODU0 ODU1 ODU2 ODU3

Tabela 5.58: Table with detailed description of node 3

Detailed description of Node 4		
836 line ports	279 connect to Node 2 258 connect to Node 5 299 connect to Node 6	100 Gbtis/s
2 000 tributary ports	700 1 000 300	ODU0 ODU1 ODU2

Tabela 5.59: Table with detailed description of node 4

Detailed description of Node 5		
836 line ports	279 connect to Node 3 258 connect to Node 4 299 connect to Node 6	100 Gbtis/s
2 400 tributary ports	1 400 400 400 100 100	ODU0 ODU1 ODU2 ODU3 ODU4

Tabela 5.60: Table with detailed description of node 5

Detailed description of Node 6		
598 line ports	299 connect to Node 4 299 connect to Node 5	100 Gbtis/s
2 200 tributary ports	800 1 000 100 100 200	ODU0 ODU1 ODU2 ODU3 ODU4

Tabela 5.61: Table with detailed description of node 6

Now through the table 5.62 we can see the result of CAPEX obtained with this ILP model.

CAPEX of the Network					
		Quantity	Unit Price	Cost	Total
Link Cost	OLTs	16	15 000 €	240 000 €	1 977 520 000 €
	100 Gb/s Transceivers	3 954	5 000 €/Gb/s	19 770 000 000 €	
	Amplifiers	70	4 000 €	280 000 €	
Node Cost	Electrical	EXCs	6	10 000 €	60 000 €
		ODU0 Ports	6 000	8 €/Gb/s	60 000 €
		ODU1 Ports	5 000	6 €/Gb/s	75 000 €
		ODU2 Ports	1 600	3 €/Gb/s	48 000 €
		ODU3 Ports	600	1.5 €/Gb/s	36 000 €
		ODU4 Ports	400	1 €/Gb/s	40 000 €
		Line Ports	3 954	1 000 €/Gb/s	395 400 000 €
	Optical	OXC	0	20 000 €	0 €
Total Network Cost					2 373 239 000 €

Tabela 5.62: Table with detailed description of capex

Through the formulas mentioned below we can see how all the values of the quantity column were calculated.

$$\begin{aligned}
 OLTs &: 2 \sum_{(i,j):i < j} L_{ij} & Transceivers &: 2 \sum_{(i,j):i < j} W_{ij} & Amplifiers &: \sum_{(i,j):i < j} N_{ij}^R L_{ij} \\
 EXCs &: \sum_n^N N_{EXC,n} & ODU0 &: \sum_{(o,d)}^N D_{od,0} & ODU1 &: \sum_{(o,d)}^N D_{od,1} & ODU2 &: \sum_{(o,d)}^N D_{od,2} \\
 ODU3 &: \sum_{(o,d)}^N D_{od,3} & ODU4 &: \sum_{(o,d)}^N D_{od,4} & Line &: \sum_{(i,j)}^N W_{ij}
 \end{aligned}$$

$OXC_s : \sum_n^N N_{OXC,n}$  but as mentioned initially this result is always zero

*Ports:* does not exist for this case then it is equal to zero

Finally let's focus on the routing information. These paths are bidirectional so the path from one node to another is the same path in the opposite direction. In table 5.63 we can see all the routing obtained for all nodes.

Routing		
o	d	Links
1	2	{(1,2)} {(1,3),(3,2)}
1	3	{(1,3)} {(1,2),(2,3)}
1	4	{(1,2),(2,4)} {(1,3),(3,5),(5,4)}
1	5	{(1,3),(3,5)} {(1,2),(2,4),(4,5)}
1	6	{(1,2),(2,4),(4,6)} {(1,3),(3,5),(5,6)}
2	3	{(2,3)} {(2,1),(1,3)}
2	4	{(2,4)} {(2,3),(3,5),(5,4)}
2	5	{(2,4),(4,5)} {(2,3),(3,5)}
2	6	{(2,4),(4,6)} {(2,3),(3,5),(5,6)}
3	4	{(3,2),(2,4)} {(3,5),(5,4)}
3	5	{(3,5)} {(3,2),(2,4),(4,5)}
3	6	{(3,5),(5,6)} {(3,2),(2,4),(4,6)}
4	5	{(4,5)} {(4,6),(6,5)}
4	6	{(4,6)} {(4,5),(5,6)}
5	6	{(5,6)} {(5,4),(4,6)}

Tabela 5.63: Table with description of routing

### 5.1.3 Transparent without Survivability

<b>Student Name</b>	:	Tiago Esteves (October 03, 2017 - )
<b>Goal</b>	:	Implement the ILP model for the transparent transport mode without survivability.

#### Model description

First, for a better understanding of the functions and variables used in the ILP, a table 5.64 will be created with all indexes, inputs and variables and with their respective description.

Description of notation used in the objective function	
$i$	index for start node of a physical link
$j$	index for end node of a physical link
$o$	index for node that is origin of a demand
$d$	index for node that is destination of a demand
$(i,j)$	physical link between the nodes $i$ and $j$
$(o,d)$	demand between the nodes $o$ and $d$
$f_{ij}^{od}$	Number of 100 Gbit/s optical channels (number of flows) between the link $i$ and $j$ for all demand pairs between $o$ and $d$
$fp_{ij}^{od}$	Number of 100 Gbit/s optical channels (number of flows with protection) between the link $i$ and $j$ for all demand pairs between $o$ and $d$
$L_{ij}$	binary variable indicating if link between the nodes $i$ and $j$ is used
$\lambda_{od}$	number of optical channels between the nodes $o$ and $d$
$G$	Network topology in form of adjacency matrix

Tabela 5.64: Table with description of variables

Before carrying out the description of the objective function we must take into account the following particularity of this mode of transport:

- $N_{OXC,n} = 1, \quad \forall n$  that process traffic
- $N_{EXC,n} = 1, \quad \forall n$  that process traffic

The objective function of following the ILP is a minimization of the CAPEX through the equation 5.1 where in this case for the cost of nodes we have in consideration the electric cost 5.4 and the optical cost 5.5. In this case the value of  $P_{exc,c,n}$  is obtained by equation 5.30 and the value of  $P_{oxc,n}$  is obtained by equation 5.31.

The equation 5.30 refers to the number of sort-reach ports, that is, the number of tributary ports with bit-rate  $c$  in node  $n$  is calculated.

$$P_{exc,c,n} = 2 \sum_{d=1}^N D_{nd,c} \quad (5.30)$$

- $P_{exc,c,n}$  → Number of ports of the electrical switch
- $D_{nj,c}$  → client demands between nodes  $n$  and  $d$  with bit rate  $c$

In this case there is the following particularity:

- When  $n=j$  the value of client demands is always zero, i.e.,  $D_{nn,c} = 0$

The equation 5.31 refers to the number of line ports and the number of adding ports. So this number are calculated for all the nodes.

$$P_{oxc,n} = \sum_{j=1}^N f_{nj} + \sum_{j=1}^N \lambda_{nj} \quad (5.31)$$

- $P_{oxc,n}$  → Number of ports of the optical switch
- $f_{nj}$  → Number of 100 Gbit/s optical channels between node  $n$  and node  $j$  (number of line ports)
- $\lambda_{nj}$  → Number of optical channels between node  $n$  and node  $j$  (number of adding ports)

The objective function, to be minimized, is the expression 5.6.

*subject to*

$$100\lambda_{od} \geq \sum_{c \in C} B(c) D_{odc} \quad \forall(o, d) : o < d \quad (5.32)$$

This restriction is considered grooming constraint and for this model the grooming can be done before routing since the traffic is aggregated just for demands between the same nodes, thus not depending on the routes.

$$\sum_{j \setminus \{o\}} f_{ij}^{od} = \lambda_{od} \quad \forall(o, d) : o < d, \forall i : i = o \quad (5.33)$$

This constraint are equal to the constraint 5.7 assuming that Z variable has the value of number of optical channels between this demand for all bidirectional links.

$$\sum_{j \setminus \{o\}} f_{ij}^{od} = \sum_{j \setminus \{d\}} f_{ji}^{od} \quad \forall (o, d) : o < d, \forall i : i \neq o, d \quad (5.34)$$

This constraint are equal to the constraint 5.8.

$$\sum_{j \setminus \{d\}} f_{ji}^{od} = \lambda_{od} \quad \forall (o, d) : o < d, \forall i : i = d \quad (5.35)$$

This constraint are equal to the constraint 5.9 assuming that Z variable has the value of number of optical channels between this demand for all bidirectional links.

$$\sum_{(o,d):o < d} (f_{ij}^{od} + f_{ji}^{od}) \leq 80G_{ij} \quad \forall (i, j) : i < j \quad (5.36)$$

This restriction answers capacity constraint problem. Then, total flows must be less or equal to the capacity of network links.

$$f_{ij}^{od}, f_{ji}^{od}, \lambda_{od} \in \mathbb{N} \quad \forall (i, j) : i < j, \forall (o, d) : o < d \quad (5.37)$$

Last constraint define the total number of flows and the number of optical channels must be a counting number.

### Result description

To perform the calculations using the implementation of the models described previously it is necessary to use a mathematical software tool. For this we will use MATLAB which is ideal for dealing with linear programming problems and can call the LPsolve through an external interface.

We already have all the necessary to obtain the CAPEX value for the reference network 6.1. As described in the subsection of network traffic 6.1, we have three values of network traffic (low, medium and high traffic) so we have to obtain three different CAPEX. The value of the CAPEX of the network will be calculated based on the costs of the equipment present in the table 5.2.

**Low Traffic Scenario:**

**Medium Traffic Scenario:**

**High Traffic Scenario:**

### 5.1.4 Transparent with 1+1 Protection

<b>Student Name</b>	:	Tiago Esteves (October 03, 2017 - )
<b>Goal</b>	:	Implement the ILP model for the transparent transport mode with 1 plus 1 protection.

Here, in this case, we must take into account table 5.64, previously mentioned, in order to better understand the objective function.

The objective function of following the ILP is a minimization of the sum of two equations: the cost of the links 5.2 and cost of the nodes 5.3 where in this case we have in consideration the electric cost and the optical cost. In this case the value of  $P_{exc,c,n}$  is obtained by equation 5.30 and the value of  $P_{oxc,n}$  is obtained by equation 5.31.

Objective Function :

minimize

$$\sum_{(i,j)}^N L_{ij} (2\gamma_0^{OLT} + 2\gamma_1^{OLT} \tau W_{ij} + N_{ij}^R c^R) + \sum_{n=1}^N N_{exc,n} (\gamma_{e0} + \sum_{c=-1}^4 \gamma_{e1,c} 2T_1) + \sum_{n=1}^N N_{oxc,n} (\gamma_{o0} + \gamma_{o1} (f_{ij}^{od} + W_{ij})) \quad (5.38)$$

subject to

$$100\lambda_{od} \geq \sum_{c \in C} B(c) D_{odc} \quad \forall (o, d) : o < d \quad (5.39)$$

$$\sum_{j \setminus \{o\}} f_{ij}^{od} = \lambda_{od} \quad \forall (o, d) : o < d, \forall i : i = o \quad (5.40)$$

$$\sum_{j \setminus \{o\}} f_{ij}^{od} = \sum_{j \setminus \{d\}} f_{ji}^{od} \quad \forall (o, d) : o < d, \forall i : i \neq o, d \quad (5.41)$$

$$\sum_{j \setminus \{d\}} f_{ji}^{od} = \lambda_{od} \quad \forall (o, d) : o < d, \forall i : i = d \quad (5.42)$$

$$\sum_{j \setminus \{o\}} fp_{ij}^{od} = \lambda_{od} \quad \forall (o, d) : o < d, \forall i : i = o \quad (5.43)$$

$$\sum_{j \setminus \{o\}} fp_{ij}^{od} = \sum_{j \setminus \{d\}} fp_{ji}^{od} \quad \forall (o, d) : o < d, \forall i : i \neq o, d \quad (5.44)$$

$$\sum_{j \setminus \{d\}} fp_{ji}^{od} = \lambda_{od} \quad \forall (o, d) : o < d, \forall i : i = d \quad (5.45)$$

$$\sum_{(o,d):o < d} \left( f_{ij}^{od} + fp_{ij}^{od} \right) \leq \lambda_{od} \quad \forall (o, d), (i, j) \quad (5.46)$$

$$\sum_{(o,d):o < d} \left( f_{ij}^{od} + f_{ji}^{od} + fp_{ij}^{od} + fp_{ji}^{od} \right) \lambda_{od} \leq 80G_{ij}L_{ij} \quad \forall (i, j) : i < j \quad (5.47)$$

$$f_{ij}^{od}, f_{ji}^{od}, fp_{ij}^{od}, fp_{ji}^{od}, \lambda_{od} \in \mathbb{N} \quad \forall (i, j) : i < j, \forall (o, d) : o < d \quad (5.48)$$

$$L_{i,j} \in \{0, 1\} \quad \forall (i, j) \quad (5.49)$$

The objective function, to be minimized, is the expression 5.38. The flow conservation is performed by equations 5.40, 5.41 and 5.42 and by equations 5.43, 5.44 and 5.45 for the protection case. The constraints 5.40 and 5.43 ensures that, for all demand pairs (o,d), is equal to number of optical channels between this demand for all bidirectional links (i,j) when j is not equal to the origin of the demand. Equation 5.42 and 5.45 is based on the same idea of 5.40, however applied in reverse direction. Assuming bidirectional traffic, so the number of flows in both directions of the link is the same 5.41 and 5.44. The inequality 5.47 answers capacity constraint problem. Then, total flows times the traffic of the demands must be less or equal to the capacity of network links. The grooming of this model can be done before routing since the traffic is aggregated just for demands between the same nodes, thus not depending on the routes. Last constraint define the total number of flows must be zero if there is no demand, or two for a demand with traffic protection, and the number of optical channels must be a counting number.

### 5.1.5 Translucent without Survivability

<b>Student Name</b>	:	Tiago Esteves (October 03, 2017 - )
<b>Goal</b>	:	Implement the ILP model for the translucent transport mode without survivability.

First, for a better understanding of the functions and variables used in the ILP, a table 5.65 will be created with all the variables and their description.

Description of notation used in the objective function	
$i$	index for start node of a physical link
$j$	index for end node of a physical link
$o$	index for node that is origin of a demand
$d$	index for node that is destination of a demand
$(i,j)$	physical link between the nodes $i$ and $j$
$(o,d)$	demand between the nodes $o$ and $d$
$c$	Client traffic Type ( 1 to 5 )
$L_{ij}^{od}$	Number of ODU-o low speed signals from node $o$ to node $d$ employing lightpath $(i,j)$
$f_{ij}^{od}$	Number of 100 Gbit/s optical channels (number of flows) between the link $i$ and $j$ for all demand pairs between $o$ and $d$
$\lambda_{od}$	Number of lightpath channels between the nodes $o$ and $d$
$B$	Client signals granularities (1.25, 2.5, 10, 40, 100)
$D_{od}$	Client traffic demands between the nodes $o$ and $d$
$G$	Network topology in form of adjacency matrix

Tabela 5.65: Table with description of variables

The objective function of following the ILP is a minimization of the sum of two equations: the cost of the links 5.2 and cost of the nodes 5.3 where in this case we have in consideration the electric cost and the optical cost. In this case the value of  $P_{exc,c,n}$  is obtained by equation 5.50 and the value of  $P_{oxc,n}$  is obtained by equation 5.51.

$$P_{exc,c,n} = 2\tau W \quad (5.50)$$

- $P_{exc,c,n} \rightarrow$  Number of ports of the electrical switch
- $\tau \rightarrow$  Traffic per port assuming 100Gbits/s
- $W \rightarrow$  Total number of optical channels

$$P_{oxc,n} = P_{ADD} + P_{LINE} \quad (5.51)$$

- $P_{oxc,n} \rightarrow$  Number of ports of the optical switch
- $P_{ADD} \rightarrow$  Number of adding ports
- $P_{LINE} \rightarrow$  Number of line ports

Objective Function :

*minimize*

$$\sum_{(i,j)}^N L_{ij} (2\gamma_0^{OLT} + 2\gamma_1^{OLT} \tau W_{ij} + N_{ij}^R c^R) + \sum_{n=1}^N N_{exc,n} (\gamma_{e0} + \sum_{c=-1}^4 \gamma_{e1,c} 2\tau W + \sum_{n=1}^N N_{oxc,n} (\gamma_{o0} + \gamma_{o1} (f_{ij}^{od} + W_{ij}))) \quad (5.52)$$

*subject to*

The objective function, to be minimized, is the expression ??.....

### 5.1.6 Translucent with 1+1 Protection

**Student Name** : Tiago Esteves (October 03, 2017 - )  
**Goal** : Implement the ILP model for the translucent transport mode with 1 plus 1 protection.

Here, in this case, we must take into account table 5.65, previously mentioned, in order to better understand the objective function.

The objective function of following the ILP is a minimization of the sum of two equations: the cost of the links 5.2 and cost of the nodes 5.3 where in this case we have in consideration the electric cost and the optical cost. In this case the value of  $P_{exc,c,n}$  is obtained by equation 5.50 and the value of  $P_{oxc,n}$  is obtained by equation 5.51.

Objective Function:

minimize

$$\sum_{(i,j)}^N L_{ij} (2\gamma_0^{OLT} + 2\gamma_1^{OLT} \tau W_{ij} + N_{ij}^R c^R) + \sum_{n=1}^N N_{exc,n} (\gamma_{e0} + \sum_{c=-1}^4 \gamma_{e1,c} 2\tau W) + \sum_{n=1}^N N_{oxc,n} (\gamma_{o0} + \gamma_{o1} (f_{ij}^{od} + W_{ij})) \quad (5.53)$$

subject to

$$\sum_{j \setminus \{o\}} L_{ij}^{od} = D_{odc} \quad \forall (o, d) : o < d \quad (5.54)$$

$$\sum_{j \setminus \{o\}} L_{ij}^{od} = \sum_{j \setminus \{d\}} L_{ji}^{od} \quad \forall (o, d) : o < d, \forall i : i \neq o, d \quad (5.55)$$

$$\sum_{j \setminus \{d\}} L_{ji}^{od} = D_{odc} \quad \forall (o, d) : o < d \quad (5.56)$$

$$\sum_{(o,d):o < d} (B(c) \times L_{ij}^{od}) \leq 100W_{ij} \quad \forall (i, j) \quad (5.57)$$

$$L_{ij}^{od} \geq 0; \quad \forall (i, j), \forall (o, d) : o < d \quad (5.58)$$

$$\sum_{j \setminus \{o\}} f_{ij}^{od} = \lambda_{od} \quad \forall (o, d) : o < d \quad (5.59)$$

$$\sum_{j \setminus \{o\}} f_{ij}^{od} = \sum_{j \setminus \{d\}} f_{ji}^{od} \quad \forall (o, d) : o < d, \forall i : i \neq o, d \quad (5.60)$$

$$\sum_{j \setminus \{d\}} f_{ji}^{od} = \lambda_{od} \quad \forall (o, d) : o < d \quad (5.61)$$

$$\sum_{(o,d):o < d} (f_{ij}^{od} + f_{ji}^{od}) \leq 80G_{ij} \quad \forall (i, j) : i < j \quad (5.62)$$

$$f_{ij}^{od} \geq 0 \quad \forall (i, j) \forall (o, d) \quad (5.63)$$

The objective function, to be minimized, is the expression 5.53.....

## **Capítulo 6**

## **Heuristic Models**

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Heuristic algorithms are used in this report with an objective to minimize the total CAPEX of the network. It is important to have these comparison results with the linear programming ones, because these formulations are faster than the optimal methods and can generate also a near optimal solution. Another advantage of the heuristic approach is that heuristic solutions leads to good performances in practical network scenarios when we present a sufficiently feasible solution, instead of an optimal solution.

In order to get the total network cost for the reference network, the CAPEX is calculated by routing and grooming heuristic algorithms implemented in Java and it is considered that all network equipment is bidirectional. These algorithms are tested in a network design software called Net2Plan.

This chapter consists in demonstrating how the matrices are created, how the heuristic algorithms work and analyzing the results. It is divided in six subsections and the results differ into three different transport modes: opaque (link-by-link grooming method), transparent (single-hop grooming method) and translucent (multi-hop grooming method). Each one of these transport methods are also distinguished and compared by the possibility of being without survivability or with 1+1 protection and for the cases of low, medium and high traffic in the network.

## 6.1 CAPEX

<b>Student Name</b>	:	Tiago Esteves (October 03, 2017 - )
<b>Goal</b>	:	Implement of the heuristic model to obtain the best possible CAPEX of a given network.

The total CAPEX of a network, as it was already described in 5.1, is the sum between two differentiated costs. Firstly, the link cost depends on the link length, which has integrated components such as the OLT, transponders and amplifiers and the node cost depends on the traffic intensity by each node. The optical node cost is 0 because all the ports in the network are electrical.

In order to get the results for the heuristic approach, several algorithms are used which try to obtain the most near optimal solution for the six cases detailed in this chapter. The first step is to create the ODU matrices in the Net2Plan network design software as it is described below.

### Creation of traffic matrices

Accordingly to the reference network in and to the ODUs defined in for the low, medium and high traffic scenario, we can create the traffic matrices with a constant traffic pattern. As all the network components are bidirectional, the amount of traffic that passes to all node pairs must be the same.

The next step is to choose the number of nodes, number of matrices and the constant value. For the network of reference it is used 6 nodes, 5 matrices and the constant has value 0. After inserted the values in each ODU matrix it is possible to save them and create now a network topological design.

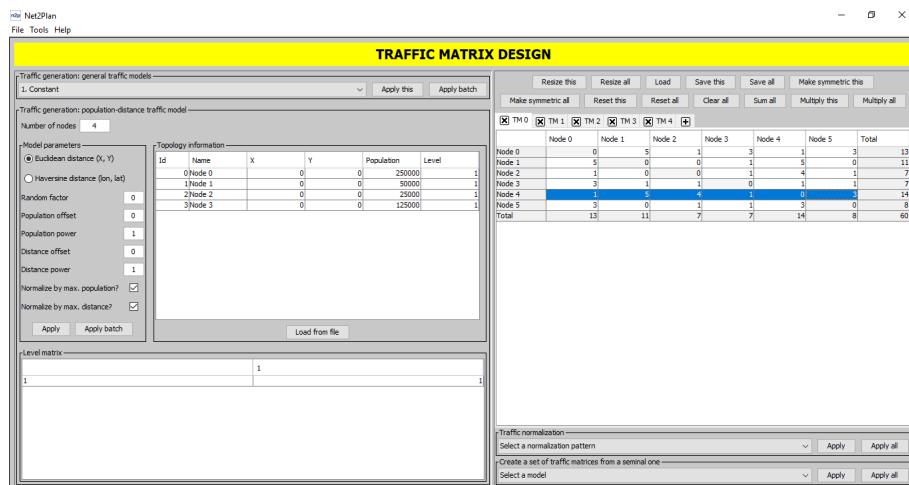


Figura 6.1: Traffic matrix design using Net2Plan.

### Creation of a network topological design

To create the network topological design that was defined before in it is needed to add the 6 nodes that were chosen and link them with bidirectional links as it is shown in the picture below.

It is known that each node represents an end-node which has a certain number of transmitters and receivers for a communication. These nodes are connected by optical fibers that support a fixed number of wavelengths.

On the right side of the network design it is shown all the attributes of the network. However, some arguments are not set yet, like the capacity and the traffic demands that passes in each link, so now it is necessary to use routing and grooming algorithms in order to simulate the heuristic algorithms in this reference network.

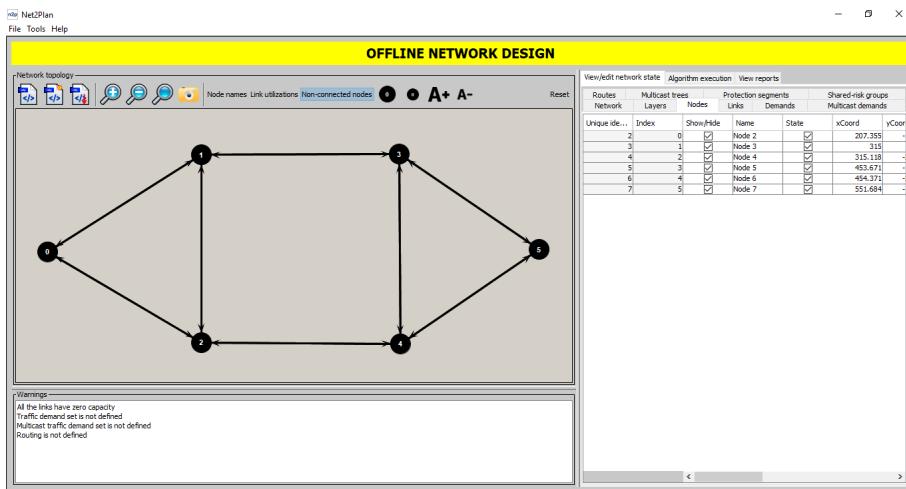


Figura 6.2: Network topological design using Net2Plan.

### Join Traffic Matrices Algorithm

The first algorithm used is the "Join Traffic Matrices" algorithm and it joins the traffic demands of the ODU traffic matrices into a file. This file will be used later for loading the traffic demands to the network topological design on Net2Plan. This algorithm aggregates the traffic matrices from ODU0 to ODU4. If it is used a network with multiple matrices and, respectively, multiple traffic demands it is possible to join each of them and save it.

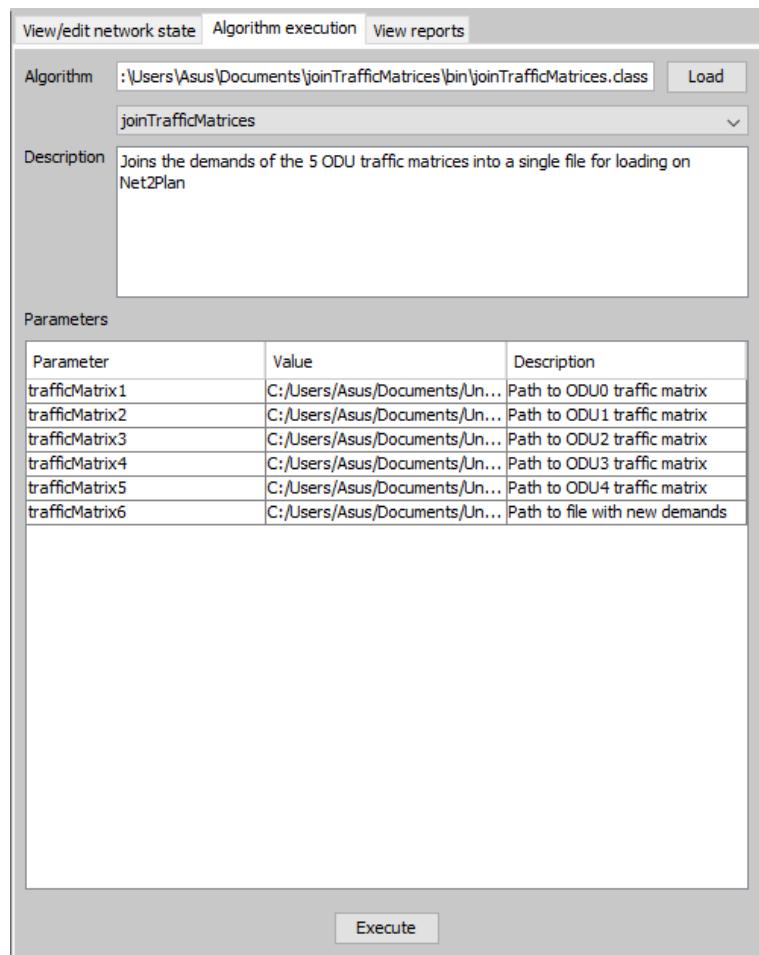


Figura 6.3: Join traffic matrices algorithm using Net2Plan.

### Logical Topology Algorithm

The "Logical Topology" algorithm is the second one used and it is based on the transport mode that is used in the network and it creates the logical topology on another layer. The logical topology value is introduced by the user and it can be one of the three transport modes available. If the transport mode chosen is opaque there is no need of having a second layer because the logical layer is the same as the physical one and if the transport mode is transparent or translucent it is needed to add a new logical layer. One advantage of this algorithm is that all the traffic demands are copied to the new layer and all the arguments remains the same depending on the previous layer, not interfering with the network topology.

It is also needed to add by the user the capacity that is used in each wavelength from all origin nodes to all destination nodes and the length of the links with values of the distance matrix represented in and expressed in km.

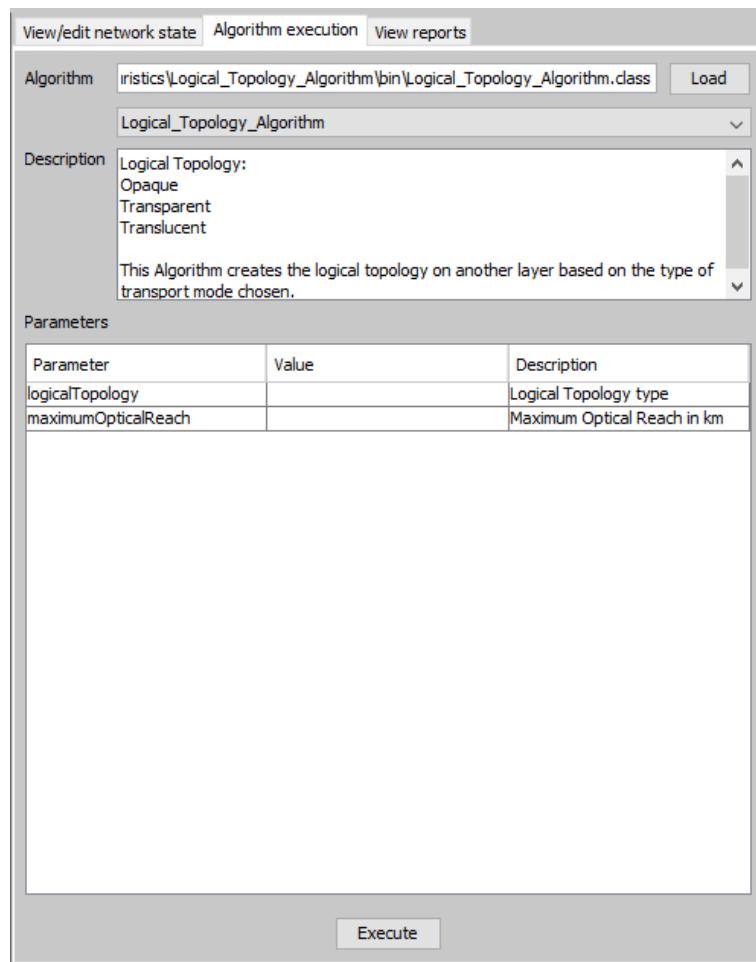


Figura 6.4: Logical topology algorithm using Net2Plan.

### Grooming Algorithm

The "Grooming" algorithm is a shortest-path heuristic algorithm that creates routes and protection paths based on hops or km, accordingly to the pre-defined logical topology. The goal of this grooming algorithm is to minimize the number of links for each path between all node pairs and this will lead to the reduction of the number of wavelengths to serve a set of connections and, consequently, to a lower cost of nodes and lower CAPEX.

The approach of the routing algorithm is to route all the traffic demands using the "Dijkstra" algorithm and uses the shortest number of hops to reach the destination node. The shortest path between two nodes is the one that includes connections whose sum of weights is the least possible. Routing through the shortest path consists in routing sequentially each element of a traffic matrix to the shortest path in the network. The routing is done in the logical and physical topologies of the network. In addition, the route from node o to d should be the opposite direction of node d to o as there could be different routes with the shortest path that are not using the same path. It is assumed that links are bidirectional and the

traffic demands are given between pairs of nodes and a network topology. In this case, each wavelength will be served by two wavelength paths. If the number of used wavelengths is minimum, the number of used fibers will be also minimum, which minimizes the CAPEX.

The 1+1 protection scheme (dedicated path protection) assumes that each link has a dedicated protection communication channel. For this scenario, it is necessary to assign different wavelengths to the primary and protection paths. It is chosen the best path based on the shortest or disjointed path, for without survivability or with 1+1 protection, respectively. The optimization objective is to minimize the number of assigned wavelengths and network components.

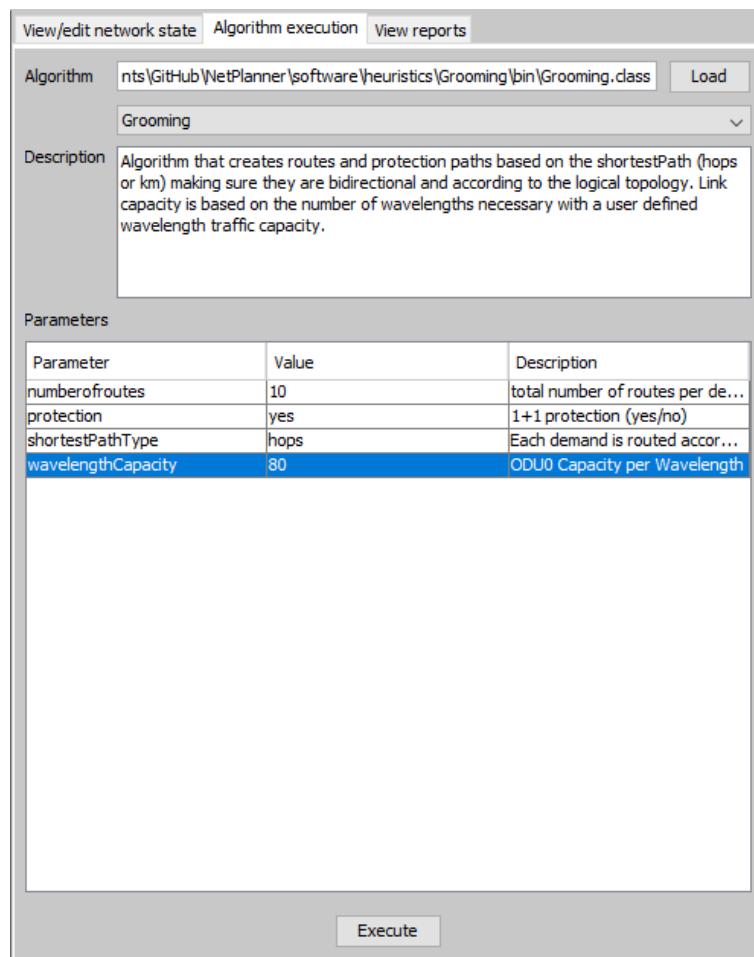


Figura 6.5: Grooming algorithm using Net2Plan.

### 6.1.1 Opaque without Survivability

<b>Student Name</b>	:	Tiago Esteves (October 03, 2017 - )
<b>Goal</b>	:	Implement the Heuristic model for the opaque transport mode without survivability.

#### Model description

In the opaque transport mode (link-by-link approach), the lightpath entering any intermediate node is necessarily terminated, i.e., there are performed OEO (optical-electrical-optical) conversions at every intermediate node since the origin to the destination node. These conversions are used for every wavelength at every node.

Contrary to the opaque with dedicated 1+1 protection technique, the opaque without survivability technique does not have a backup path, so if there is a network failure it is more likely to suffer large data losses, which consequently leads to higher network costs. However, the CAPEX will be significantly lower, because that not includes a secondary path that would increase several network elements.

For this model, after the creation of the matrices and the network topology, it is necessary to apply the routing and grooming algorithms created. For the "Logical Topology" algorithm, the user must insert "Opaque" in the "logicalTopology" value and for the "Grooming" algorithm, the user must insert "no" in the parameter value "protection".

At the end, the "Cost Report" algorithm will be applied to obtain the best CAPEX result for the network in question.

#### Result description

We already have all the necessary formulas to obtain the CAPEX value for the reference network 6.1. As described in the subsection of network traffic 6.1, we have three values of network traffic (low, medium and high traffic), so we have to obtain three different CAPEX.

##### Low Traffic Scenario:

Following all the steps mentioned in the previous subsection and using all the data referring to this scenario, the obtained result can be consulted in the following table:

Category		Quantity	Unit Price	Cost	Total
Link Cost	OLT	12	15.000	180.000	9.404.000
	Transponders	18	5.000	9.000.000	
	Amplifiers	56	4.000	224.000	
Node Cost	EXC	PLine	18	1.000	1.800.000
		PTrib ODU0	60	8	600
		PTrib ODU1	50	6	750
		PTrib ODU2	16	3	480
		PTrib ODU3	6	1.5	360
		PTrib ODU4	4	1	400
	OXC		0	20.000	0
	POXC		0	2.500	0
Total Network Cost					11.206.590

Tabela 6.1: Network Cost for Low Traffic Scenario.

**Medium Traffic Scenario:**

Following all the steps mentioned in the previous subsection and using all the data referring to this scenario, the obtained result can be consulted in the following table:

Category		Quantity	Unit Price	Cost	Total
Link Cost	OLT	12	15.000	180.000	59.404.000
	Transponders	118	5.000	59.000.000	
	Amplifiers	56	4.000	224.000	
Node Cost	EXC	PLine	118	1.000	11.800.000
		PTrib ODU0	60	8	600
		PTrib ODU1	50	6	750
		PTrib ODU2	16	3	480
		PTrib ODU3	6	1.5	360
		PTrib ODU4	4	1	400
	OXC		0	20.000	0
	POXC		0	2.500	0
Total Network Cost					71.206.590

Tabela 6.2: Network Cost for Medium Traffic Scenario.

**High Traffic Scenario:**

Following all the steps mentioned in the previous subsection and using all the data referring to this scenario, the obtained result can be consulted in the following table:

Category		Quantity	Unit Price	Cost	Total
Link Cost	OLT	12	15.000	180.000	578.404.000
	Transponders	1.156	5.000	578.000.000	
	Amplifiers	56	4.000	224.000	
Node Cost	EXC	PLine	1.156	1.000	115.600.000
		PTrib ODU0	60	8	600
		PTrib ODU1	50	6	750
		PTrib ODU2	16	3	480
		PTrib ODU3	6	1.5	360
		PTrib ODU4	4	1	400
	OXC		0	20.000	0
	POXC		0	2.500	0
Total Network Cost					694.006.590

Tabela 6.3: Network Cost for High Traffic Scenario.

### 6.1.2 Opaque with 1+1 Protection

<b>Student Name</b>	:	Tiago Esteves (October 03, 2017 - )
<b>Goal</b>	:	Implement the heuristic model for the opaque transport mode with 1 plus 1 protection.

#### Model description

The impact of failure in WDM (Wavelength Division Multiplexing) networks is caused by extremely high volume of traffic carried. In a high speed network like the WDM, a failure of a network element may cause failure of various optical channels that leads to large data and revenue losses, which can interrupt communication services.

In this protection scheme, the primary and backup path carry the traffic end-to-end, i.e., there is a need to have a backup path (the unaffected path) in case of a network failure. Then, the receiver will decide which one of the two incoming traffic it is going to pick, if the primary or the backup path.

Although it is the fastest protection scheme, it is also the most expensive, because it normally uses more than the double of the capacity for the primary path. This happens because the backup path is typically longer than the primary.

For this protection model, after the creation of the matrices and the network topology, it is necessary to apply the routing and grooming algorithms created. For the "Logical Topology"algorithm, the user must insert "Opaque" in the "logicalTopology" value and for the "Grooming"algorithm, the user must insert "yes" in the parameter value "protection".

At the end, the "Cost Report" algorithm will be applied to obtain the best CAPEX result for the network in question.

#### Result description

We already have all the necessary formulas to obtain the CAPEX value for the reference network 6.1. As described in the subsection of network traffic 6.1, we have three values of network traffic (low, medium and high traffic), so we have to obtain three different CAPEX.

##### Low Traffic Scenario:

Following all the steps mentioned in the previous subsection and using all the data referring to this scenario, the obtained result can be consulted in the following table:

Category		Quantity	Unit Price	Cost	Total
Link Cost	OLT	16	15.000	240.000	15.520.000
	Transponders	30	5.000	150.000.000	
	Amplifiers	70	4.000	280.000	
Node Cost	PLine	30	1.000	3.000.000	3.002.590
	PTrib ODU0	60	8	600	
	PTrib ODU1	50	6	750	
	PTrib ODU2	16	3	480	
	PTrib ODU3	6	1.5	360	
	PTrib ODU4	4	1	400	
	OXC	0	20.000	0	
	POXC	0	2.500	0	
Total Network Cost					18.522.590

Tabela 6.4: Network Cost for Low Traffic Scenario.

#### Medium Traffic Scenario:

Following all the steps mentioned in the previous subsection and using all the data referring to this scenario, the obtained result can be consulted in the following table:

Category		Quantity	Unit Price	Cost	Total
Link Cost	OLT	16	15.000	240.000	128.520.000
	Transponders	256	5.000	128.000.000	
	Amplifiers	70	4.000	280.000	
Node Cost	PLine	256	1.000	25.600.000	25.602.590
	PTrib ODU0	60	8	600	
	PTrib ODU1	50	6	750	
	PTrib ODU2	16	3	480	
	PTrib ODU3	6	1.5	360	
	PTrib ODU4	4	1	400	
	OXC	0	20.000	0	
	POXC	0	2.500	0	
Total Network Cost					154.122.590

Tabela 6.5: Network Cost for Medium Traffic Scenario.

#### High Traffic Scenario:

Following all the steps mentioned in the previous subsection and using all the data referring to this scenario, the obtained result can be consulted in the following table:

Category		Quantity	Unit Price	Cost	Total
Link Cost	OLT	16	15.000	240.000	1.239.520.000
	Transponders	2.478	5.000	1.239.000.000	
	Amplifiers	70	4.000	280.000	
Node Cost	EXC	PLine	2.478	1.000	247.800.000
		PTrib ODU0	60	8	600
		PTrib ODU1	50	6	750
		PTrib ODU2	16	3	480
		PTrib ODU3	6	1.5	360
		PTrib ODU4	4	1	400
	OXC		0	20.000	0
	POXC		0	2.500	0
Total Network Cost					1.487.322.590

Tabela 6.6: Network Cost for High Traffic Scenario.

### 6.1.3 Transparent without Survivability

<b>Student Name</b>	:	Tiago Esteves (October 03, 2017 - )
<b>Goal</b>	:	Implement the heuristic model for the transparent transport mode without survivability.

**Model description**

**Result description**

### 6.1.4 Transparent with 1+1 Protection

<b>Student Name</b>	:	Tiago Esteves (October 03, 2017 - )
<b>Goal</b>	:	Implement the heuristic model for the transparent transport mode with 1 plus 1 protection.

**Model description**

**Result description**

### 6.1.5 Translucent without Survivability

<b>Student Name</b>	:	Tiago Esteves (October 03, 2017 - )
<b>Goal</b>	:	Implement the heuristic model for the translucent transport mode without survivability.

**Model description**

**Result description**

**6.1.6 Translucent with 1+1 Protection**

<b>Student Name</b>	:	Tiago Esteves (October 03, 2017 - )
<b>Goal</b>	:	Implement the heuristic model for the translucent transport mode with 1 plus 1 protection.

**Model description**

**Result description**

## **Capítulo 7**

### **Analytical Models**

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The focus of the current section is to propose and describe a model for the analytical calculation of the network CAPEX, based on the three modes of transport (opaque, transparent and translucent) without survivability and protection.

In the section 7.1, it is described how the CAPEX is calculated in a general way. In the following subsections it is proposed in detail the restrictions of the three previously mentioned models without survivability and with protection as well as a detailed report of the results obtained for each case.

## 7.1 CAPEX

<b>Student Name</b>	:	Tiago Esteves (October 03, 2017 - )
<b>Goal</b>	:	Implement of the analytical model to obtain the best possible CAPEX of a given network.

The cost of a telecommunications network can be divided into CAPEX and OPEX. CAPEX is the amount of money needed to set up and install a particular network. OPEX is the amount of money needed to run this network as well as its maintenance and operation over time. In this section we will only focus on CAPEX, that is, the costs of installing a particular network. As we know the telecommunications networks are made up of links and nodes, so it is possible to define the CAPEX as being the sum of the cost of links and cost of nodes. This can be said that the value of CAPEX is given by the equation 7.1.

$$C_C = C_L + C_N \quad (7.1)$$

- $C_C \rightarrow$  CAPEX cost
- $C_L \rightarrow$  Link cost
- $C_N \rightarrow$  Node cost

For this calculation first let's focus on the cost of the links. Where to calculate the cost of the Links we will use the equation 7.2.

$$C_L = (2 \times L \times \gamma_0^{OLT}) + (2 \times L \times \gamma_1^{OLT} \times \tau \times \langle w \rangle) + (N^R \times c^R) \quad (7.2)$$

- $C_L \rightarrow$  Links cost
- $\gamma_0^{OLT} \rightarrow$  OLT cost in euros
- $L \rightarrow$  Number of unidirectional links
- $\gamma_1^{OLT} \rightarrow$  Transponder cost in euros
- $\langle w \rangle \rightarrow$  Average number of optical channels
- $\tau \rightarrow$  Traffic per port
- $N^R \rightarrow$  Total number of optical amplifiers
- $c^R \rightarrow$  Optical amplifiers cost in euros

Looking at the equation 7.2 we can see that we already have practically all the values of the variables used. Assuming that  $\tau$  is 100 Gbits/s is thus only missing the number of optical amplifiers and the number of optical channels where they can be calculated by equation 7.3 and 7.4 respectively.

$$N^R = \sum_{l=1}^L \left( \left\lceil \frac{len_l}{span} \right\rceil - 1 \right) \quad (7.3)$$

- $N^R \rightarrow$  Total number of regenerators/amplifiers
- $len_l \rightarrow$  Length of link l
- $span \rightarrow$  Distance between amplifiers

$$\langle w \rangle = \left( \frac{\lceil D \times \langle h \rangle \rceil}{L} \right) \times (1 + \langle k \rangle) \quad (7.4)$$

- $\langle w \rangle \rightarrow$  Average number of optical channels
- $D \rightarrow$  Number of bidirectional demands
- $L \rightarrow$  Number of Links
- $\langle k \rangle \rightarrow$  Survivability coefficient

where:

$$D = \left( \frac{1}{2} \right) \times (1 + \xi) \times \left( \frac{T_1}{\tau} \right) \quad (7.5)$$

- $D \rightarrow$  Number of bidirectional demands
- $\xi \rightarrow$  Coefficient
- $T_1 \rightarrow$  Total unidirectional traffic
- $\tau \rightarrow$  Traffic per port

The next step is to take into account the cost of the nodes, but for this we must first know how a node is constituted. The nodes have an electrical part and an optical part so we can conclude that the cost of the nodes is given by the sum of these two parts thus obtaining the equation 7.6.

$$C_N = C_{EXC} + C_{OXC} \quad (7.6)$$

To know the electric cost of the nodes that is given by equation 7.7.

$$C_{exc} = N \times (\gamma_{e0} + (\gamma_{e1} \times \tau \times \langle P_{exc} \rangle)) \quad (7.7)$$

- $C_{exc}$  → Electrical ports cost
- $N$  → Number of nodes
- $\gamma_{e0}$  → EXC cost in euros
- $\gamma_{e1}$  → EXC port cost in euros
- $\tau$  → Traffic per port
- $\langle P_{exc} \rangle$  → Average number of ports of the electrical switch

In relation to the optical part to know the optical cost of the nodes that is given by equation 7.8.

$$C_{oxc} = N \times (\gamma_{o0} + (\gamma_{o1} \times \langle P_{oxc} \rangle)) \quad (7.8)$$

- $C_{oxc}$  → Optical ports cost
- $N$  → Number of nodes
- $\gamma_{o0}$  → OXC cost in euros
- $\gamma_{o1}$  → OXC port cost in euros
- $\langle P_{oxc} \rangle$  → Average number of ports of the optical switch

We have to take into account that the calculated value for the variable  $\langle P_{exc} \rangle$  and  $\langle P_{oxc} \rangle$  will depend on the mode of transport used (opaque, transparent or translucent) but later on it will be explained how these values are calculated for each specific transport mode. Finally, for this we will also have to take into account the cost of the equipment used that can be consulted in table 7.1.

Equipment	Cost
OLT without transponders	15000 €
Transponder	5000 €/Gb
Optical Amplifier	4000 €
EXC	10000 €
OXC	20000 €
EXC Port	1000 €/Gb/s
OXC Port	2500 €/porto

Tabela 7.1: Table with costs

### 7.1.1 Opaque without Survivability

<b>Student Name</b>	:	Tiago Esteves (October 03, 2017 - )
<b>Goal</b>	:	Implement the analytical model for the opaque transport mode without survivability.

#### Model description

Before carrying out the detailed description we must take into account the following peculiarities of this mode of transport:

- $C_{oxc} = 0$
- $\xi = 1$
- $\langle k \rangle = 0$

The first particularity exists because in this mode of transport there is no optical cost, in the case of the second we are assuming that the coefficient has value 1 and finally in the last particularity we are assuming that the survivability coefficient is zero because it is without survivability.

Finally looking at the equation 7.7 we can see that we already have practically all the values with the exception of the number of ports the electrical switch that can be calculated through the equation 7.9.

$$\langle P_{exc} \rangle = \langle d \rangle \times [1 + (1 + \langle k \rangle) \times \langle h \rangle] \quad (7.9)$$

- $\langle P_{exc} \rangle \rightarrow$  Average number of ports of the electrical switch
- $\langle d \rangle \rightarrow$  Average number of demands
- $\langle k \rangle \rightarrow$  Survivability coefficient
- $\langle h \rangle \rightarrow$  Average number of hops

Where:

$$\langle d \rangle = \frac{2 \times D}{N} \quad (7.10)$$

#### Result description

We already have all the necessary formulas to obtain the CAPEX value for the reference network 6.1. As described in the subsection of network traffic 6.1, we have three values of network traffic (low, medium and high traffic) so we have to obtain three different CAPEX.

**Low Traffic Scenario:**

In this scenario we have to take into account the traffic calculated in 6.1.

Using equation 7.5:

$$D = \frac{1}{2} * (1 + 1) * \left(\frac{1000}{100}\right) \quad D = 10$$

Replacing in equation 7.4:

$$\langle w \rangle = \left(\frac{10*1.533}{8}\right) * (1 + 0) \quad \langle w \rangle = 2$$

Using equation 7.3:

$$N^R = \left(\frac{460}{100}-1\right) + \left(\frac{640}{100}-1\right) + \left(\frac{75}{100}-1\right) + \left(\frac{684}{100}-1\right) + \left(\frac{890}{100}-1\right) + \left(\frac{103}{100}-1\right) + \left(\frac{761}{100}-1\right) + \left(\frac{361}{100}-1\right)$$

$$N^R = 35$$

Finally, replacing all in equation 7.2 the Link Cost is:

$$C_L = (2 * 8 * 15\,000) + (2 * 8 * 5\,000 * 100 * 2) + (33 * 4\,000)$$

$$C_L = \mathbf{16\,380\,000 \text{ €}}$$

In relation to the cost of the nodes we first use the equation 7.10:

$$\langle d \rangle = \frac{2*10}{6} \quad \langle d \rangle = 3.333$$

Replacing in equation 7.9:

$$\langle P_{exc} \rangle = 3.333 * [1 + (1 + 0) * 1.533] \quad \langle P_{exc} \rangle = 8.4425$$

Finally, replacing all in equation 7.7 the Node Cost is:

$$C_N = C_{exc} = 6 * (10\,000 + (1\,000 * 100 * 8.4425))$$

$$C_N = \mathbf{5\,125\,500 \text{ €}}$$

The CAPEX is:

$$CAPEX = 16\,380\,000 + 5\,125\,500$$

$$CAPEX = \mathbf{21\,505\,500 \text{ €}}$$

### Medium Traffic Scenario

In this scenario we have to take into account the traffic calculated in 4.2.2.

Using equation 7.5:

$$D = \frac{1}{2} * (1 + 1) * \left(\frac{10000}{100}\right) \quad D = 100$$

replacing in equation 7.4:

$$\langle w \rangle = \left(\frac{100*1.533}{8}\right) * (1 + 0) \quad \langle w \rangle = 20$$

Using equation 7.3:

$$N^R = \left(\frac{460}{100}-1\right) + \left(\frac{640}{100}-1\right) + \left(\frac{75}{100}-1\right) + \left(\frac{684}{100}-1\right) + \left(\frac{890}{100}-1\right) + \left(\frac{103}{100}-1\right) + \left(\frac{761}{100}-1\right) + \left(\frac{361}{100}-1\right)$$

$$N^R = 35$$

Finally, replacing all in equation 7.2 the Link Cost is:

$$C_L = (2 * 8 * 15\,000) + (2 * 8 * 5\,000 * 100 * 20) + (35 * 4\,000)$$

$$C_L = \mathbf{160\,380\,000 \text{ €}}$$

In relation to the cost of the nodes we first use the equation 7.10:

$$\langle d \rangle = \frac{2*100}{6} \quad \langle d \rangle = 33.333$$

Replacing in equation 7.9:

$$\langle P_{exc} \rangle = 33.333 * [1 + (1 + 0) * 1.533] \quad \langle P_{exc} \rangle = 84.4325$$

Finally, replacing all in equation 7.7 the Node Cost is:

$$C_N = C_{exc} = 6 * (10\,000 + (1\,000 * 100 * 84.4325))$$

$$C_N = \mathbf{50\,719\,500 \text{ €}}$$

The CAPEX is:

$$CAPEX = 160\,380\,000 + 50\,719\,500$$

$$CAPEX = \mathbf{211\,099\,500 \text{ €}}$$

### High Traffic Scenario

In this scenario we have to take into account the traffic calculated in 4.2.3.

Using equation 7.5:

$$D = \frac{1}{2} * (1 + 1) * \left(\frac{100000}{100}\right) \quad D = 1000$$

replacing in equation 7.4:

$$\langle w \rangle = \left(\frac{1000 * 1.533}{8}\right) * (1 + 0) \quad \langle w \rangle = 192$$

Using equation 7.3:

$$N^R = \left(\frac{460}{100} - 1\right) + \left(\frac{640}{100} - 1\right) + \left(\frac{75}{100} - 1\right) + \left(\frac{684}{100} - 1\right) + \left(\frac{890}{100} - 1\right) + \left(\frac{103}{100} - 1\right) + \left(\frac{761}{100} - 1\right) + \left(\frac{361}{100} - 1\right)$$

$$N^R = 35$$

Finally, replacing all in equation 7.2 the Link Cost is:

$$C_L = (2 * 8 * 15000) + (2 * 8 * 5000 * 100 * 192) + (35 * 4000)$$

$$C_L = 1\,536\,380\,000 \text{ €}$$

In relation to the cost of the nodes we first use the equation 7.10:

$$\langle d \rangle = \frac{2 * 1000}{6} \quad \langle d \rangle = 333.333$$

Replacing in equation 7.9:

$$\langle P_{exc} \rangle = 333.333 * [1 + (1 + 0) * 1.533] \quad \langle P_{exc} \rangle = 844.3325$$

Finally, replacing all in equation 7.7 the Node Cost is:

$$C_N = C_{exc} = 6 * (10000 + (1000 * 100 * 844.3325))$$

$$C_N = 506\,659\,500 \text{ €}$$

The CAPEX is:

$$CAPEX = 1\,536\,380\,000 + 506\,659\,500$$

$$CAPEX = 2\,043\,039\,500 \text{ €}$$

### 7.1.2 Opaque with 1+1 Protection

<b>Student Name</b>	:	Tiago Esteves (October 03, 2017 - )
<b>Goal</b>	:	Implement the analytical model for the opaque transport mode with 1 plus 1 protection.

### 7.1.3 Transparent without Survivability

<b>Student Name</b>	:	Tiago Esteves (October 03, 2017 - )
<b>Goal</b>	:	Implement the analytical model for the transparent transport mode without survivability.

### 7.1.4 Transparent with 1+1 Protection

<b>Student Name</b>	:	Tiago Esteves (October 03, 2017 - )
<b>Goal</b>	:	Implement the analytical model for the transparent transport mode with 1 plus 1 protection.

### 7.1.5 Translucent without Survivability

<b>Student Name</b>	:	Tiago Esteves (October 03, 2017 - )
<b>Goal</b>	:	Implement the analytical model for the translucent transport mode without survivability.

### 7.1.6 Translucent with 1+1 Protection

<b>Student Name</b>	:	Tiago Esteves (October 03, 2017 - )
<b>Goal</b>	:	Implement the analytical model for the translucent transport mode with 1 plus 1 protection.

## **Capítulo 8**

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## **Comparative Analysis**

## 8.1 Opaque without Survivability

**Student Name** : Tiago Esteves (October 03, 2017 - )  
**Goal** : Comparative analysis of the results of the models used for the opaque transport mode without survivability.

In this section we will compare the CAPEX values obtained for the three scenarios in the three types of dimensioning. For a better analysis of the results will be created the table 8.1 (scenario 1), the table 8.2 (scenario 2) and the table 8.3 (scenario 3) with the different values obtained.

### Low traffic scenario:

	Analytical	ILP	Heuristic
Link Cost	16 372 000 €	11 372 000 €	12 004 000 €
Node Cost	5 125 500 €	3 260 000 €	4 360 000 €
CAPEX	<b>21 497 500 €</b>	<b>14 632 000 €</b>	<b>16 364 000 €</b>

Tabela 8.1: Table with different value of CAPEX

Looking at the previous table we can make some comparisons between the several different models of dimensioning and finally draw some conclusions.

- We can conclude that in this case the dimensioning using ILP is the best (lowest cost).
- In comparison with the analytical model we can see that there is a difference considered with a 32% error, this value is mainly due to the number of optical channels because in the analytical model more optical channels are calculated and used than those required in the ILP model.
- In comparison with the heuristic model we can see that there is a small difference with a 11% error, much smaller than the previous one.

### Medium traffic scenario:

	Analytical	ILP	Heuristic
Link Cost	72 372 000 €	35 372 000 €	36 004 000 €
Node Cost	21 337 200 €	11 260 000 €	12 260 000 €
CAPEX	<b>93 709 200 €</b>	<b>46 632 000 €</b>	<b>48 264 000 €</b>

Tabela 8.2: Table with different value of CAPEX

Looking at the previous table we can make some comparisons between the several different models of dimensioning and finally draw some conclusions.

- We can conclude that in this case the dimensioning using ILP is the best (lowest cost).
- In comparison with the analytical model we can see that there is a difference considered with a 50% error.
- In comparison with the heuristic model we can see that there is a smaller difference with a 3% error.

#### **High traffic scenario:**

	Analytical	ILP	Heuristic
Link Cost	160 372 000 €	75 372 000 €	76 504 000 €
Node Cost	50 719 500 €	25 060 000 €	25 960 000 €
CAPEX	<b>211 091 500 €</b>	<b>100 432 000 €</b>	<b>102 464 000 €</b>

Tabela 8.3: Table with different value of CAPEX

Looking at the previous table we can make some comparisons between the several different models of dimensioning and finally draw some conclusions.

- We can conclude that in this case the dimensioning using ILP is the best (lowest cost).
- In comparison with the analytical model we can see that there is a difference considered with a 66% error.
- In comparison with the heuristic model we can see that there is a smaller difference with a 2% error.

## 8.2 Opaque with 1+1 Protection

<b>Student Name</b>	:	Tiago Esteves (October 03, 2017 - )
<b>Goal</b>	:	Comparative analysis of the results of the models used for the opaque transport mode with 1 plus 1 protection.

### 8.3 Transparent without Survivability

<b>Student Name</b>	:	Tiago Esteves (October 03, 2017 - )
<b>Goal</b>	:	Comparative analysis of the results of the models used for the transparent transport mode without survivability.

## 8.4 Transparent with 1+1 Protection

<b>Student Name</b>	:	Tiago Esteves (October 03, 2017 - )
<b>Goal</b>	:	Comparative analysis of the results of the models used for the transparent transport mode with 1 plus 1 protection.

## 8.5 Translucent without Survivability

**Student Name** : Tiago Esteves (October 03, 2017 - )

**Goal** : Comparative analysis of the results of the models used for the translucent transport mode without survivability.

## 8.6 Translucent with 1+1 Protection

<b>Student Name</b>	:	Tiago Esteves (October 03, 2017 - )
<b>Goal</b>	:	Comparative analysis of the results of the models used for the translucent transport mode with 1 plus 1 protection.

## **Capítulo 9**

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## **Case Studies**

## 9.1 Opaque without Survivability - European Optical Network

In this case study we focus on the opaque case without survivability for the realistic network. The opaque transport mode performs OEO (optical-electric-optical) conversions on each intermediate node from the source to the destination node. One advantage of this mode of transport is that it eliminates accumulation of physical impairments, and allows optimum grooming by performing grooming at each node.

### 9.1.1 Physical Network Topology

**Student Name :** Tiago Esteves (October 03, 2017 - )

The real network chosen for this work is the EON (European Optical Network).



Figura 9.1: Physical topology of the realistic network.

In this real case we have take into consideration the table 9.1 because it is through it that we can see the values of the variables associated with this network.

Constant	Description	Value
N	Number of nodes	19
L	Number of bidirectional links	37
$\langle \delta \rangle$	Node out-degree	3.89
$\langle \text{len} \rangle$	Mean link length (km)	753.76
$\langle h \rangle$	Mean number of hops for working paths	2.3
$\langle h' \rangle$	Mean number of hops for backup paths	3.2

Tabela 9.1: Table of realistic network values

Through the previous figure we can see how nodes are organized geographically and the distance matrix created on the next page is constructed based on real distances between them. For a better understanding of the distances matrix the table 9.2 was created to assign to each city a number of a node in the network.

City	Node
Oslo	1
Stockholm	2
Moscow	3
Copenhagen	4
Berlin	5
Prague	6
Vienna	7
Zagreb	8
Athens	9
Rome	10
Milan	11
Zurich	12
Brussels	13
Amesterdan	14
London	15
Dublin	16
Paris	17
Madrid	18
Lisbon	19

Tabela 9.2: Table of city and respective node

The values indicated in the distance matrix, referred to below, are expressed in kilometers (Km). For this network we must also create matrices of ODU's to determine the total traffic used in each scenario but in this case only the matrices for low traffic are elucidated.

$$Dist = \begin{pmatrix} 0 & 417 & 0 & 484 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 417 & 0 & 1228 & 523 & 811 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1228 & 0 & 0 & 1611 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 484 & 523 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 811 & 1611 & 0 & 0 & 281 & 524 & 0 & 0 & 0 & 0 & 843 & 0 & 0 & 577 & 933 & 0 \\ 0 & 0 & 0 & 0 & 0 & 281 & 0 & 251 & 0 & 0 & 0 & 646 & 527 & 0 & 712 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 524 & 251 & 0 & 268 & 0 & 0 & 0 & 0 & 0 & 622 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 268 & 0 & 1081 & 518 & 530 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1081 & 0 & 1052 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 518 & 1052 & 0 & 477 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 843 & 646 & 0 & 530 & 0 & 477 & 0 & 219 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 646 & 0 & 0 & 0 & 219 & 0 & 493 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 493 & 0 & 173 & 321 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 622 & 577 & 712 & 0 & 0 & 0 & 0 & 173 & 0 & 358 & 0 & 0 \\ 1155 & 0 & 0 & 0 & 933 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 321 & 358 & 0 & 464 & 344 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 464 & 0 & 782 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 640 & 488 & 264 & 0 & 344 & 782 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1054 & 0 & 503 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1587 & 0 & 0 & 503 \end{pmatrix}$$





$$ODU4 = \begin{bmatrix} 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 \end{bmatrix}$$

In the traffic matrices each ODU, referred previously, has its respective value being that the ODU0 corresponds to 1.25 Gbits/s, ODU1 to 2.5 Gbits/s, ODU2 to 10 Gbits/s, ODU3 to 40 Gbits/s and finally the ODU4 corresponds to 100 Gbits/s. As we can see these matrices are bidirectional because they are symmetric matrices and as such the traffic sent in one direction must be the same traffic sent in the opposite direction.

Through these ODU's we can calculate total network traffic for the low traffic scenario:

$$T_1^0 = 240 \times 1.25 = 300 \text{ Gbits/s} \quad T_1^1 = 200 \times 2.5 = 500 \text{ Gbits/s} \quad T_1^2 = 64 \times 10 = 640 \text{ Gbits/s}$$

$$T_1^3 = 24 \times 40 = 960 \text{ Gbits/s} \quad T_1^4 = 16 \times 100 = 1600 \text{ Gbits/s}$$

$$T_1 = 300 + 500 + 640 + 960 + 1600 = 4000 \text{ Gbits/s} \quad T = 4000 / 2 = 2 \text{ Tbits/s}$$

Where the variable  $T_1^x$  represents the unidirectional traffic of the ODUx, for example,  $T_1^0$  represents the unidirectional traffic of the ODU0 and  $T_1^4$  represents the unidirectional traffic of the ODU4. The variable  $T_1$  represents the total of unidirectional traffic that is injected into the network and finally the variable  $T$  represents the total of bidirectional traffic.

Again, we can thus conclude that the total traffic for the two scenarios is as follows:

- Low Traffic: **2 TBits/s**
- High Traffic: **20 TBits/s**

### 9.1.2 Dimensioning using Analytical Model

**Student Name :** Tiago Esteves (October 03, 2017 - )

In this section we will do the dimensioning of the network mentioned in the previous subsection to calculate the value of your CAPEX, for this we will use the analytical formulations so as to obtain the best solution but for this we will also have to take into account the cost of the equipment used that can be consulted in table ???. The formulas and calculations needed for the CAPEX of the network are the same as in the previous case (reference network) and therefore only the results obtained will be presented.

As described in the subsection of the network topology we have two values of network traffic, low traffic and high traffic, soon we will get two different CAPEX. Finally we have to take into account that as it is the opaque transport mode, the value of  $\xi$  is 1 and because it is without survivability, the value of  $\langle k \rangle$  is 0. Then we can rewrite the equations.

#### Scenario 1: Realistic Network Low Traffic

Using equation 7.5:

$$D = \frac{1}{2} * (1 + 1) * \left(\frac{4000}{100}\right) \quad D = 40$$

Replacing in equation 7.4:

$$\langle w \rangle = \left(\frac{40*2.3}{37}\right) * (1 + 0) \quad \langle w \rangle = 3$$

Using equation 7.3:

$$N^R \leq L * \langle N^R \rangle$$

$$\langle N^R \rangle = \frac{\text{len}}{\text{span}} - 1$$

$$\langle N^R \rangle = \frac{753.76}{100} - 1$$

$$N^R = 259$$

Finally, replacing all in equation 7.2 the Link Cost is:

$$C_L = (2 * 37 * 15000) + (2 * 37 * 5000 * 100 * 3) + (259 * 4000)$$

$$C_L = 113\,146\,000 \text{ €}$$

In relation to the cost of the nodes we first use the equation 7.10:

$$\langle d \rangle = \frac{2*40}{19} \quad \langle d \rangle = 4.21$$

Replacing in equation 7.9:

$$P_{exc} = 4.21 * [1 + (1 + 0) * 2.3] \quad P_{exc} = 13.893$$

Finally, replacing all in equation 7.7 the Node Cost is:

$$C_N = C_{exc} = 19 * (10000 + (1000 * 100 * 13.893))$$

$$C_N = \mathbf{26\ 589\ 700\ €}$$

The CAPEX is:

$$CAPEX = 113\ 146\ 000 + 26\ 589\ 700$$

$$CAPEX = \mathbf{139\ 732\ 700\ €}$$

### Scenario 2: Reference Network High Traffic

Using equation 7.5:

$$D = \frac{1}{2} * (1 + 1) * \left(\frac{40000}{100}\right) \quad D = 400$$

replacing in equation 7.4:

$$\langle w \rangle = \left(\frac{400*2.3}{37}\right) * (1 + 0) \quad \langle w \rangle = 25$$

Finally, replacing all in equation 7.2 the Link Cost is:

$$C_L = (2 * 37 * 15000) + (2 * 37 * 5000 * 100 * 25) + (259 * 4000)$$

$$C_L = \mathbf{927\ 146\ 000\ €}$$

In relation to the cost of the nodes we first use the equation 7.10:

$$\langle d \rangle = \frac{2*400}{19} \quad \langle d \rangle = 42.105$$

Replacing in equation 7.9:

$$P_{exc} = 42.105 * [1 + (1 + 0) * 2.3] \quad P_{exc} = 138.9465$$

Finally, replacing all in equation 7.7 the Node Cost is:

$$C_N = C_{exc} = 19 * (10000 + (1000 * 100 * 138.9465))$$

$$C_N = 246\,188\,350 \text{ €}$$

The CAPEX is:

$$CAPEX = 927\,146\,000 + 246\,188\,350$$

$$CAPEX = 1\,191\,334\,350 \text{ €}$$

### 9.1.3 Dimensioning using ILP

**Student Name :** Tiago Esteves (October 03, 2017 - )

In this section we will do the dimensioning of the network mentioned in the previous section to calculate the value of your CAPEX. The initial subsection is the same as the subsection of the previous case so in this case it will be omitted presenting only the subsection of the results.

#### Scenario 1: Realistic Network Low Traffic

This real network consists of many nodes and with many links between them as such the lpssolve takes immense time to get an optimal solution. Therefore, in this two cases, the execution time was defined as being two days (48 hours) and after that time presented the best solution. In this scenario we used the table 9.1 and in the table 9.3 we can see the values calculated through MatLab and using the values indicated in table ?? we can finally calculate the CAPEX value.

Using equation ?? :

$$C_L = (2 * 15\,000 * 37) + (2 * 5\,000 * 100 * ) + ( * 4\,000)$$

$$C_L = \text{€}$$

Using equation ?? :

$$C_{exc} = (19 * 10\,000) + 1\,000 * (4\,000 + (2 * * 100))$$

$$C_N = C_{exc} = \text{€}$$

$$CAPEX = + = \text{€}$$

Number of optical channels	Value
in link (1,2)	
in link (1,4)	
in link (1,15)	
in link (2,3)	
in link (2,4)	
in link (2,5)	
in link (3,5)	
in link (4,14)	
in link (5,6)	
in link (5,7)	
in link (5,11)	
in link (5,14)	
in link (5,15)	
in link (6,7)	
in link (6,11)	
in link (6,12)	
in link (6,14)	
in link (7,8)	
in link (8,9)	
in link (8,10)	
in link (8,11)	
in link (9,10)	
in link (10,11)	
in link (11,12)	
in link (11,17)	
in link (12,13)	
in link (12,17)	
in link (13,14)	
in link (13,15)	
in link (13,17)	
in link (14,15)	
in link (15,16)	
in link (15,17)	
in link (15,19)	
in link (16,17)	
in link (17,18)	
in link (18,19)	

Tabela 9.3: Table with results

**Scenario 2: Realistic Network High Traffic**

In this scenario we used again the table 9.1 and in the table 9.4 we can see the values calculated through MatLab and using the values indicated in table ?? we can finally calculate the CAPEX value.

Using equation ?? :

$$C_L = (2 * 15\,000 * 37) + (2 * 5\,000 * 100) + (24 * 4\,000)$$
$$C_L = \text{€}$$

Using equation ?? :

$$C_{exc} = (19 * 10\,000) + 1\,000 * (40\,000 + (2 * 100))$$
$$C_N = C_{exc} = \text{€}$$

$$CAPEX = + = \text{€}$$

#### 9.1.4 Dimensioning using Heuristics

##### Heuristics Results

#### 9.1.5 Comparative Analysis

Number of optical channels	Value
in link (1,2)	
in link (1,4)	
in link (1,15)	
in link (2,3)	
in link (2,4)	
in link (2,5)	
in link (3,5)	
in link (4,14)	
in link (5,6)	
in link (5,7)	
in link (5,11)	
in link (5,14)	
in link (5,15)	
in link (6,7)	
in link (6,11)	
in link (6,12)	
in link (6,14)	
in link (7,8)	
in link (8,9)	
in link (8,10)	
in link (8,11)	
in link (9,10)	
in link (10,11)	
in link (11,12)	
in link (11,17)	
in link (12,13)	
in link (12,17)	
in link (13,14)	
in link (13,15)	
in link (13,17)	
in link (14,15)	
in link (15,16)	
in link (15,17)	
in link (15,19)	
in link (16,17)	
in link (17,18)	
in link (18,19)	

Tabela 9.4: Table with results

## 9.2 Opaque with 1+1 Protection - European Optical Network

In this case study we focus on the opaque case with 1+1 protection for the realistic network.

### 9.2.1 Physical Network Topology

**Student Name :** Tiago Esteves (October 03, 2017 - )

The real network chosen for this work is the EON (European Optical Network).



Figura 9.2: Physical topology of the realistic network.

Since the realistic network used in this case has already been mentioned previously in section 9.1 we can assume that the table 9.1 is the same and the table 9.2 where each city contains a number of a node in the network also is the same.

The distance matrix constructed based on real distances between cities and the matrices of ODU's are also the same. Finally, the total traffic for the two scenarios are:

Low Traffic: 2 TBits/s; High Traffic: 20 TBits/s;

### 9.2.2 Dimensioning using ILP

**Student Name :** Tiago Esteves (October 03, 2017 - )

The initial subsection is the same as the subsection of the previous case so in this case it will be omitted presenting only the subsection of the results. In this section we will do the dimensioning of the network mentioned in the previous section to calculate the value of your CAPEX, for this we will use the ILP model describe in section 5.1.2. This real network consists of many nodes and with many links between them as such the lp\_solve takes immense time to get an optimal solution. Therefore, in this case, the execution time was defined as being two days (48 hours) and after that time presented the best solution.

### Scenario 1: Realistic Network Low Traffic

In this scenario we used the table 9.1 and in the table 9.5 we can see the values calculated through MatLab and using the values indicated in table ?? we can finally calculate the CAPEX value.

Using equation ?? :

$$C_L = (2 * 15\ 000 * 37) + (2 * 5\ 000 * 100 * 111) + (24 * 4\ 000)$$

$$C_L = \mathbf{112\ 206\ 000\ €}$$

Using equation ?? :

$$C_{exc} = (19 * 10\ 000) + 1\ 000 * (4\ 000 + (2 * 111 * 100))$$

$$C_N = C_{exc} = \mathbf{26\ 390\ 000\ €}$$

$$CAPEX = 112\ 206\ 000 + 26\ 390\ 000 = \mathbf{138\ 596\ 000\ €}$$

### Scenario 2: Realistic Network High Traffic

In this scenario we used again the table 9.1 and in the table 9.6 we can see the values calculated through MatLab and using the values indicated in table ?? we can finally calculate the CAPEX value.

Using equation ?? :

$$C_L = (2 * 15\ 000 * 37) + (2 * 5\ 000 * 100 * 1538) + (24 * 4\ 000)$$

$$C_L = \mathbf{1\ 539\ 206\ 000\ €}$$

Using equation ?? :

$$C_{exc} = (19 * 10\ 000) + 1\ 000 * (40\ 000 + (2 * 100 * 1538))$$

$$C_N = C_{exc} = \mathbf{347\ 790\ 000\ €}$$

$$CAPEX = 1\ 539\ 206\ 000 + 347\ 790\ 000 = \mathbf{1\ 886\ 996\ 000\ €}$$

Number of optical channels	Value
in link (1,2)	4
in link (1,4)	4
in link (1,15)	2
in link (2,3)	3
in link (2,4)	5
in link (2,5)	5
in link (3,5)	3
in link (4,14)	2
in link (5,6)	3
in link (5,7)	6
in link (5,11)	3
in link (5,14)	1
in link (5,15)	4
in link (6,7)	3
in link (6,11)	2
in link (6,12)	1
in link (6,14)	2
in link (7,8)	4
in link (8,9)	2
in link (8,10)	2
in link (8,11)	3
in link (9,10)	2
in link (10,11)	2
in link (11,12)	1
in link (11,17)	4
in link (12,13)	2
in link (12,17)	2
in link (13,14)	1
in link (13,15)	1
in link (13,17)	2
in link (14,15)	1
in link (15,16)	2
in link (15,17)	4
in link (15,19)	7
in link (16,17)	2
in link (17,18)	7
in link (18,19)	7

Tabela 9.5: Table with results

Number of optical channels	Value
in link (1,2)	80
in link (1,4)	80
in link (1,15)	80
in link (2,3)	50
in link (2,4)	49
in link (2,5)	69
in link (3,5)	32
in link (4,14)	15
in link (5,6)	80
in link (5,7)	80
in link (5,11)	45
in link (5,14)	24
in link (5,15)	27
in link (6,7)	80
in link (6,11)	80
in link (6,12)	55
in link (6,14)	39
in link (7,8)	45
in link (8,9)	20
in link (8,10)	28
in link (8,11)	36
in link (9,10)	20
in link (10,11)	13
in link (11,12)	8
in link (11,17)	35
in link (12,13)	19
in link (12,17)	28
in link (13,14)	27
in link (13,15)	3
in link (13,17)	6
in link (14,15)	41
in link (15,16)	17
in link (15,17)	18
in link (15,19)	64
in link (16,17)	17
in link (17,18)	64
in link (18,19)	64

Tabela 9.6: Table with results

### **9.2.3 Dimensioning using Heuristics**

**Heuristics Results**

### **9.2.4 Comparative Analysis**

## **Capítulo 10**

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## **Appendices**

## 10.1 Net2Plan Guide

This first section will describe how to install Net2Plan and some of the solvers.

### Net2Plan Download and Installation

In the software folder (NetPlanner/software/net2plan) there is a stable version of all required installers or programs.

Before downloading Net2Plan, the first step is verifying if the computer has the necessary Java Runtime Environment. The Java Runtime Environment is necessary as Net2Plan was coded in Java. Version 8 or later is recommended. In the software folder you can find an installer for the Java SE Runtime Environment 8 Update 151, file JavaSetup8u151.exe. The latest available version can be found in the Java website at <https://java.com/en/download/>.

Having installed the Java Environment it is now possible to run Net2Plan. It is possible to run Net2Plan (version 0.4.2) directly from the folder NetPlanner/software/net2plan-0.4.2. There is also available a zip file from which the program can be extracted. The program can be started just double clicking on the file Net2Plan.jar. The latest available version can be found in the Net2Plan website at <http://net2plan.com/download.php>.



Figura 10.1: Net2Plan v0.4.2. opening menu.

### Net2Plan Options and Installing Solvers

To access the main Net2Plan options click "File → Options". In this window the global parameters for simulations can be changed if needed. For example, an important option to note in this tab is the parameter "defaultRunnableCodePath", whose value should be

the path to the jar file containing NetPlanner algorithms. As will be explained further on, Net2Plan is an open source tool and as such, new algorithms can be implemented and the default path can be changed to the path where those will be available instead of loading them manually each time Net2Plan is opened. The remaining parameters are related to solver options, which are the default external solvers used and also the path in which the ".dll", ".so", ".dylib" files of each solver are available. By default there is no path for each solver but in this case it was already changed to where the solvers were installed.

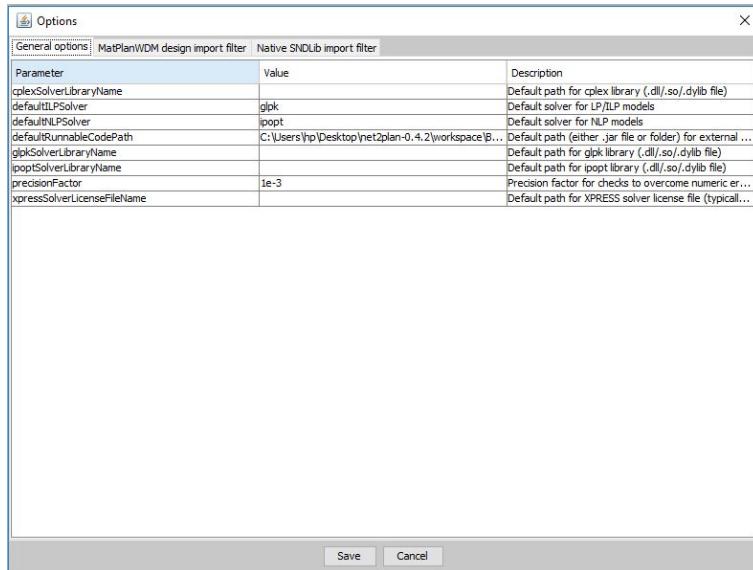


Figura 10.2: Net2Plan v0.4.2. general options.

These external solvers are not extracted along with Net2Plan and as such, need to be downloaded if needed for the algorithms to be used.

## Net2Plan Tools

This section will describe in some detail the tools presented in Net2Plan as a network planner, most notably how to created a traffic matrix, design a network and some of the simulation options available.

### Creating Traffic Matrices

To start creating a traffic matrix in Net2Plan go to "Tools → Traffic matrix design" or press *Alt + 2*. The traffic matrix menu is shown on Figure 10.3.

On the top left side a traffic pattern can be chosen for one matrix or several if used the "Apply batch" option.

- "Constant" has two parameters the number of nodes and a constant value. This creates an uniform matrix with the number of nodes chosen and traffic equal to the value selected.

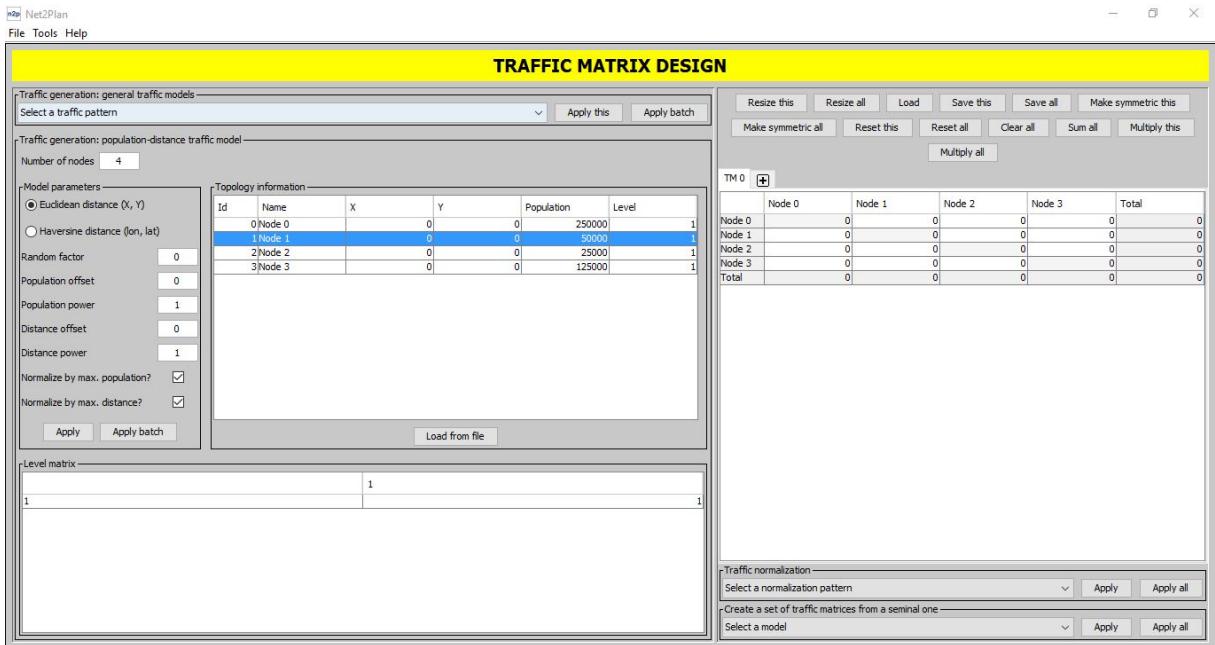


Figura 10.3: Net2Plan Traffic Matrix Design

- "Uniform (0,10)" has the number of nodes and the option of being symmetric as the parameters. The matrix then has the number of nodes introduced and an amount of traffic chosen randomly between 0 and 10 which can be symmetric or not depending on the choice done.
- "Uniform (0,100)" is very similar to the other uniform option whereas in this case the traffic values are chosen randomly between 0 and 100.
- "50% Uniform (0,100) & 50% Uniform (0,10)" and "25% Uniform (0,100) & 75% Uniform (0,10)" are as expected a mixture of the previous two options.
- "Gravity model" in this option a number of nodes is chosen as well as the amount of traffic both generated and received by each node. The sum of the traffic generated by all the nodes needs to be equal to the sum of the traffic received by them.

Below the traffic pattern options, an existing model can be loaded and additional parameters defined such as Population and Node Level.

On the right side a traffic matrix can be created manually by defining the number of nodes on "resize this" and the amount of traffic can be typed on each demand. The other options above the matrix are self explanatory, for example, "multiply this" multiplies all the traffic by a constant number chosen. A point to note is that most options has an "all" choice as it is possible to have more than one matrix created.

Below the matrix part are two further options available for the matrices, the first one is the option to select a normalization pattern such as "Total normalization" where a total number of traffic can be chosen for the network and the demands are adapted to it

accordingly. The other option is to create a set of matrices based on the designed one.

Figure 10.4 shows how to create batch of matrices with constant traffic.

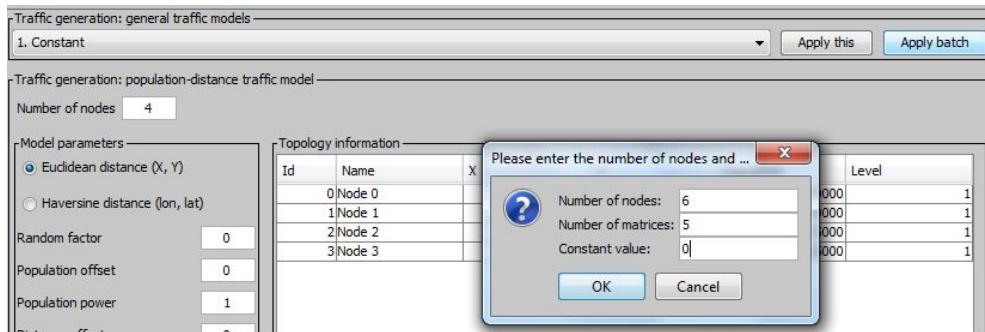


Figura 10.4: Net2Plan example on creating a batch of matrices

Using this option, 5 traffic matrices for a 6 node network were created all with a constant value of 1 as can be seen on figure 10.5 that shows the first matrix of the batch.

	Node 0	Node 1	Node 2	Node 3	Node 4	Node 5	Total
Node 0	0	1	1	1	1	1	5
Node 1	1	0	1	1	1	1	5
Node 2	1	1	0	1	1	1	5
Node 3	1	1	1	0	1	1	5
Node 4	1	1	1	1	0	1	5
Node 5	1	1	1	1	1	0	5
Total	5	5	5	5	5	5	30

Figura 10.5: Net2Plan Traffic Matrix Example

This example demonstrates how several different types of traffic can be introduced for a network by creating different matrices for each. These can then be saved individually and will further on be used as traffic matrices for ODU's 0 through 4.

### Creating the Network topologies

To start with the Network creation tools in Net2Plan go to "Tools → Offline network design" or press *Alt + 1*. The network design menu is shown on Figure 10.6.

On the left side, the network topology part has the option to load an existing design and demand set or a new one can be created. To start creating a new network, first nodes have to be introduced by right clicking on the grey area and choosing "Add node here". Links between nodes are created by holding a click on the origin node and dragging until the destination node, holding shift before releasing the click creates 2 links, one in each direction. Another option to create links is to right click on an existing node and choosing the desired create a link option. Nodes can be moved by holding control and dragging them into the desired position.

Below the network topology is the "Warnings" box where the parts missing from having a functional network are displayed. For example if the nodes and links where already created

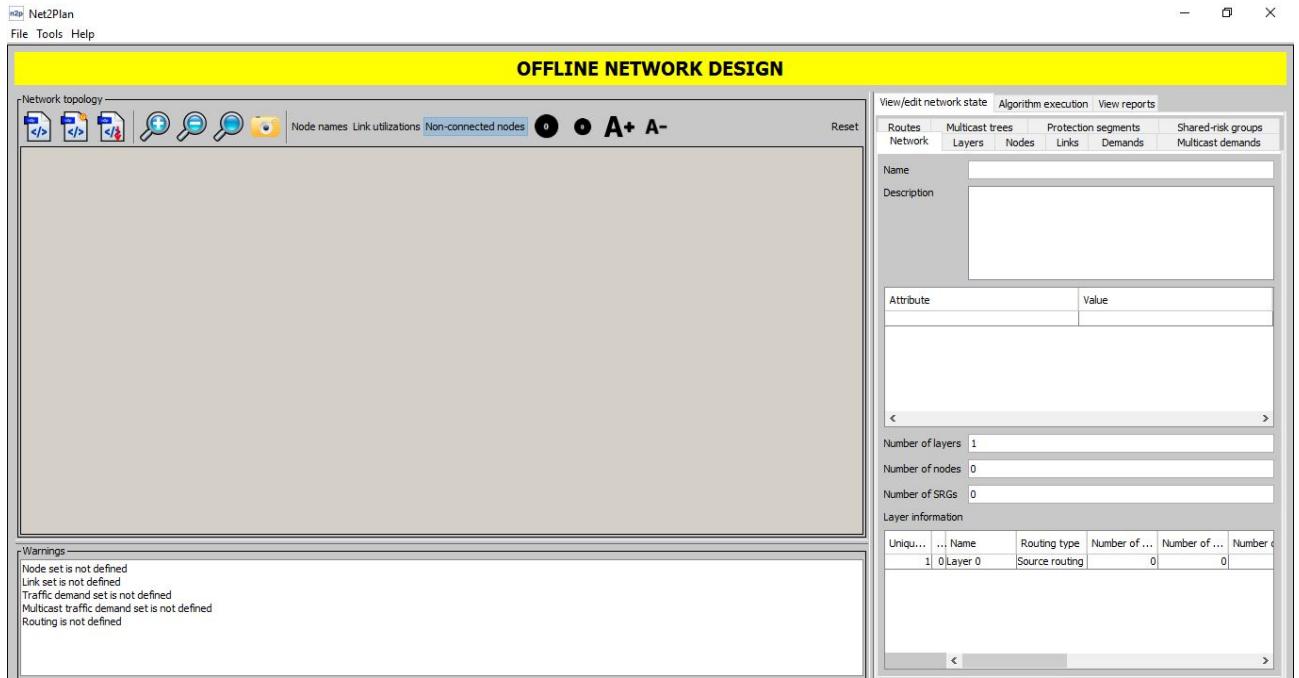


Figura 10.6: Net2Plan Offline Network Design

it should say "traffic demand set is not defined" and "Routing is not defined" as these were still not introduced.

The whole right side of the network design menu are the parameters separated into various tabs which will be explored further on in this document. Besides these tabs, there is also the tab for Algorithm execution where the network is modified based on built algorithms, for example a routing algorithm and the View reports tab where information on the network can be displayed from built in reports.

Figure 10.7 demonstrates an example of the 6 node and 16 links network created using the tools explained above. As can be seen on the image at the warning tab, this network still has several steps left to become a fully functional network. The link capacity will be defined based on the routing algorithm chosen and the demand set will be loaded based on the matrices created.

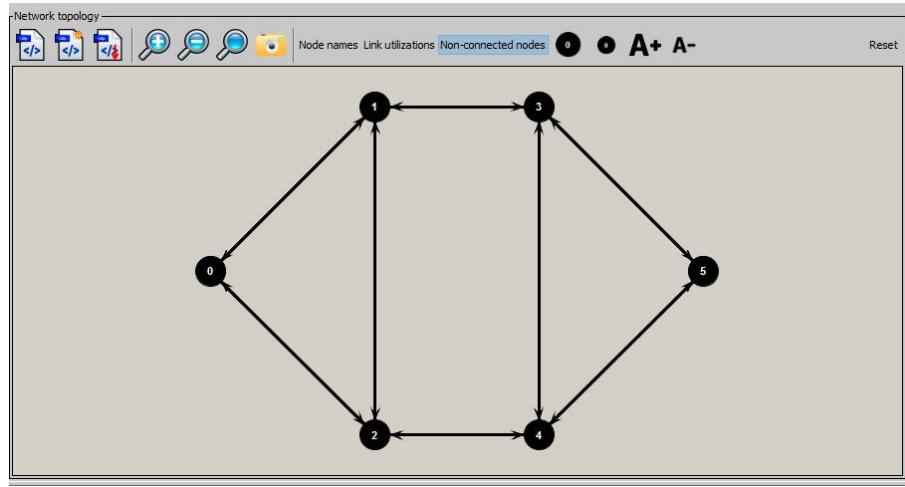


Figura 10.7: Net2Plan Network Example

The links and nodes parameters created for the network can be visualized and modified as seen on Figures 10.8(a) and 10.8(b) displaying the tabs for each case.

View/edit network state					
Routes		Multicast trees		Protection segments	
Network	Layers	Nodes	Links	Demands	Shared-risk groups
Unique ide...	Index	Show/Hide	Name	State	xCoord
2	0	<input checked="" type="checkbox"/>	Node 0	<input checked="" type="checkbox"/>	
3	1	<input checked="" type="checkbox"/>	Node 1	<input checked="" type="checkbox"/>	
4	2	<input checked="" type="checkbox"/>	Node 2	<input checked="" type="checkbox"/>	
5	3	<input checked="" type="checkbox"/>	Node 3	<input checked="" type="checkbox"/>	
6	4	<input checked="" type="checkbox"/>	Node 4	<input checked="" type="checkbox"/>	
7	5	<input checked="" type="checkbox"/>	Node 5	<input checked="" type="checkbox"/>	

(a) a

View/edit network state					
Routes		Multicast trees		Protection segments	
Network	Layers	Nodes	Links	Demands	Shared-risk groups
Unique ide...	Index	Show/Hide	Origin node	Destinatio...	State
8	0	<input checked="" type="checkbox"/>	0 (Node 0)	1 (Node 1)	<input checked="" type="checkbox"/>
9	1	<input checked="" type="checkbox"/>	1 (Node 1)	0 (Node 0)	<input checked="" type="checkbox"/>
10	2	<input checked="" type="checkbox"/>	0 (Node 0)	2 (Node 2)	<input checked="" type="checkbox"/>
11	3	<input checked="" type="checkbox"/>	2 (Node 2)	0 (Node 0)	<input checked="" type="checkbox"/>
12	4	<input checked="" type="checkbox"/>	1 (Node 1)	2 (Node 2)	<input checked="" type="checkbox"/>
13	5	<input checked="" type="checkbox"/>	2 (Node 2)	1 (Node 1)	<input checked="" type="checkbox"/>
14	6	<input checked="" type="checkbox"/>	1 (Node 1)	3 (Node 3)	<input checked="" type="checkbox"/>
15	7	<input checked="" type="checkbox"/>	3 (Node 3)	1 (Node 1)	<input checked="" type="checkbox"/>
16	8	<input checked="" type="checkbox"/>	2 (Node 2)	4 (Node 4)	<input checked="" type="checkbox"/>
17	9	<input checked="" type="checkbox"/>	4 (Node 4)	2 (Node 2)	<input checked="" type="checkbox"/>
18	10	<input checked="" type="checkbox"/>	3 (Node 3)	4 (Node 4)	<input checked="" type="checkbox"/>
19	11	<input checked="" type="checkbox"/>	4 (Node 4)	3 (Node 3)	<input checked="" type="checkbox"/>
20	12	<input checked="" type="checkbox"/>	3 (Node 3)	5 (Node 5)	<input checked="" type="checkbox"/>
21	13	<input checked="" type="checkbox"/>	5 (Node 5)	3 (Node 3)	<input checked="" type="checkbox"/>
22	14	<input checked="" type="checkbox"/>	4 (Node 4)	5 (Node 5)	<input checked="" type="checkbox"/>
23	15	<input checked="" type="checkbox"/>	5 (Node 5)	4 (Node 4)	<input checked="" type="checkbox"/>

(b) b

Figura 10.8: Network a) Nodes tab ; b) Links tab

On the Nodes tab most of the parameters are still 0 as there is no traffic on the network but there are three parameters that can be changed here. A node name can be set and both x and y coordinates can be defined as a more thorough alternative to define the node position.

On the links tab, again most is at 0 at this moment while the parameters that can be manually set are the link capacity, at 0 until defined and the link length which was set to the same value in every link.

Having the basic physical topology created, the next step is to load the demand set into the network. In the case where there are multiple traffic matrices an algorithm was developed to aggregate these in order for it to be possible to load all demands. For traffic matrices with ODU signals, an algorithm called "joinTrafficMatrices" can aggregate the different ODUs and convert them to ODU0 in order to have all the traffic in the same units. Besides converting the different ones to ODU0 it also creates an attribute in each demand indicating the type of signal before converting. This attribute can be seen on the demands tab after loading the resulting demand list. Figure 10.9 shows the algorithm to be used.

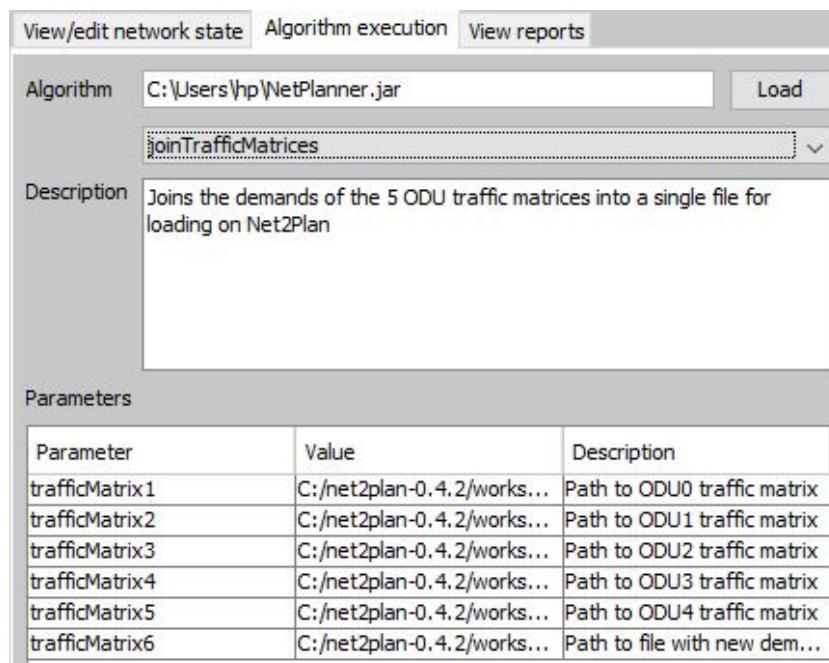


Figura 10.9: joinTrafficMatrices Algorithm

As can be seen on Figure 10.9 there are 6 user defined parameters, the first five are the paths for the traffic matrices to be aggregated in order, as said in the description. The last parameter is the resulting demand list that can then be loaded into the network.

The paths are by default defined considering Net2Plan is on C: and the matrices are in the default directory where they are saved. Lastly, the name of the files are in order ODU0.n2p through ODU4.n2p. All the path and file names can be changed to where the matrices are saved taking into account that just the order of the ODUs needs to be kept due to the conversion to ODU0 units.

To load the resulting demands into the created network the second icon on top of the network topology called "Load a demand traffic set" is used. After this, the warning tab changes from "Traffic demand set not defined" to "Traffic losses: Not all the traffic is being carried". This new warning indicates that the demand are in the network but as the routes have not yet been defined the traffic is not being transported.

In the demands tab, all the traffic that was created will be displayed in order of ODU type. For this case as all matrices were unitary and uniform, there are thirty demands with offered traffic 1 which is the ODU0 matrix and then consecutively groups of 30 demands (6 nodes) with offered traffic based on the ODU type (5 matrices). For example, an ODU1 is equivalent to two ODU0 so these demands have 2 in offered traffic and an attribute called ODU with value 1.

Before going into the network routing, the network transport mode needs to be defined by creating a logical topology. An algorithm was developed that creates a new layer consisting on this topology depending on the transport mode chosen. This algorithm can be seen on Figure 10.10.

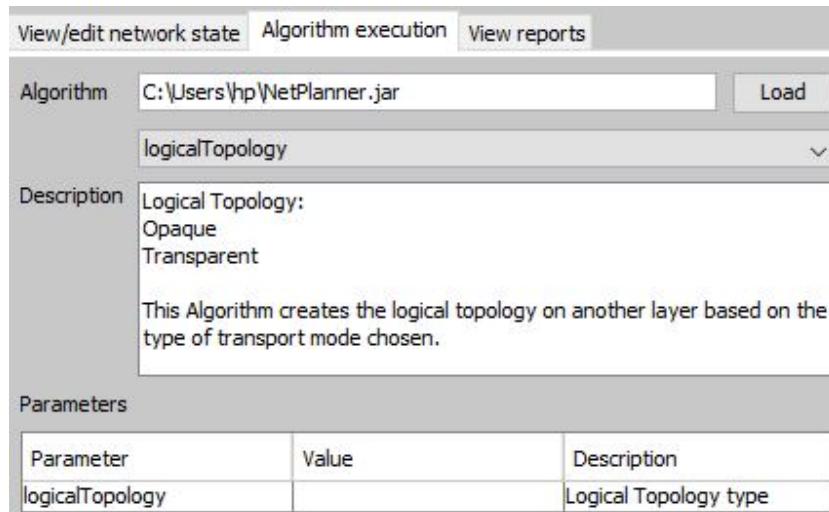


Figura 10.10: Net2Plan Logical Topology Algorithm

There are two user defined parameters on this algorithm. The "logicalTopology" parameter defines the type of transport mode, Opaque or Transparent.

Besides creating this new Layer, the algorithm also copies the demands to that layer and defines the logical links based on the length of the physical ones. Figures 10.11(a), 10.11(b) demonstrate the resulting logical topologies for each transport mode.

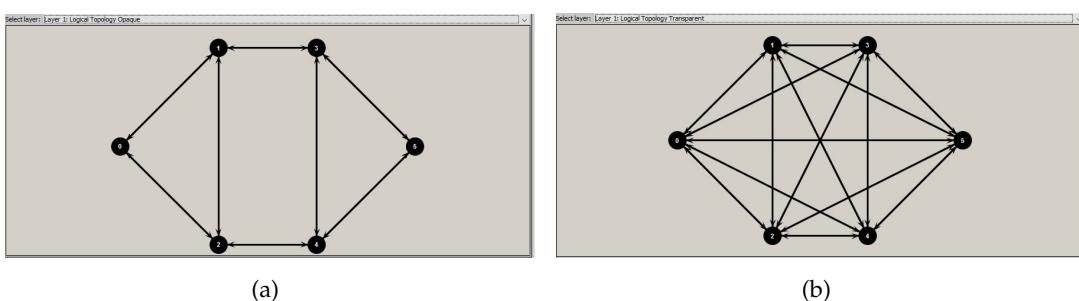


Figura 10.11: Logical Topology: a) Opaque; b) Transparent;

As can be seen on the logical topologies, for an Opaque transport mode the traffic goes through an OEO conversion at every node and as such the logical topology is the same as the physical one.

In the Transparent mode, there are no regeneration in intermediate nodes and as such the logical topology shows that the traffic between nodes flows directly without grooming with signals from another source.

## Routing and Grooming

In this section, different routing and grooming options will be discussed for both a network without protection and using a 1+1 protection scheme (dedicated path protection).

The routing will be done based on a shortest path algorithm where the routes for each demand are created based one either the shortest number of hops needed to reach the destination node or by shortest distance in km. The option can be chosen as a user defined parameter on the algorithm as can be seen on Figure 10.12. This algorithm does the routing in both the logical and physical topologies based on the transport mode chosen and makes sure routes are bidirectional meaning the route from node  $o$  to  $d$  should be the opposite direction of node  $d$  to  $o$  as there could be different routes with the shortest path that are not using the same path.

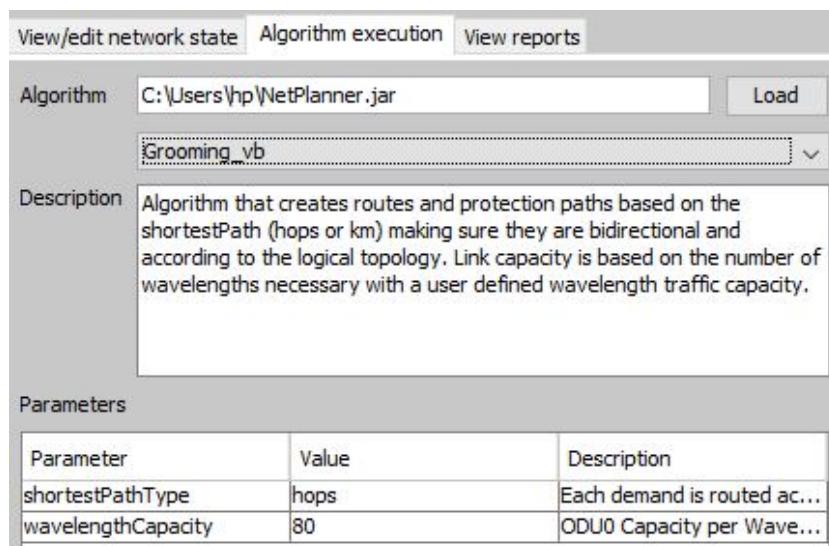


Figura 10.12: Net2Plan Grooming shortest Path Algorithm

Besides the metric through which the shortest path is calculated, the other available parameter defines the amount of ODU0s each wavelength is capable of carrying. By default it is set for 80 ODU0s as it is equal to an ODU4 or 100 Gbit/s.

The protection segments similarly to the routes have their own tab where information on their path, route it protects and such can be observed.

## Reports

As looking separately at each tab to obtain information for different parts of the network is a slow process and does not show some important metrics, Net2Plan allows for the creation of reports where in a similar way to algorithms they can be adjusted to display the information needed, these can also be seen in html format for an easier read. In this section, the report developed will be demonstrated.

A very important aspect in network planning that is not present natively in Net2Plan is a Network Cost report. To fulfil this gap, a report was created to obtain the network Capex based on user defined equipment costs present on Table 10.1.

Equipment	Costs
OLT	15000€
Transponder	5000€/GB
Optical Amplifier	4000€
EXC	10000€
OXC	20000€
EXC Port	1000€/GB/s
OXC Port	2500€/port

Tabela 10.1: Equipment Costs

These Equipment costs are introduced into a report as user defined parameters as can be seen on Figure 10.13.

Besides the equipment costs, this report also has the parameter "span". The value of this variable is used to calculate the number of optical amplifiers needed in the network using Equation 10.1.

$$N^R = \sum_{l=1}^L \left( \left\lceil \frac{len_l}{span} \right\rceil - 1 \right) \quad (10.1)$$

The other parameters of this equation being:

- $N^R$  → Total number of regenerators/amplifiers
- $len_l$  → Length of link l
- $span$  → Distance between amplifiers

By running the report three main categories are presented to the user.

The first category displayed by the report is the Detailed per-link description. In here the number of optical channels or wavelengths is displayed for each link based on the grooming algorithm used. The numbers displayed are based on the physical topology and represent all the wavelengths that will be needed to transport the network traffic. Using this information it is possible to obtain the average and total number of optical channels on the network.

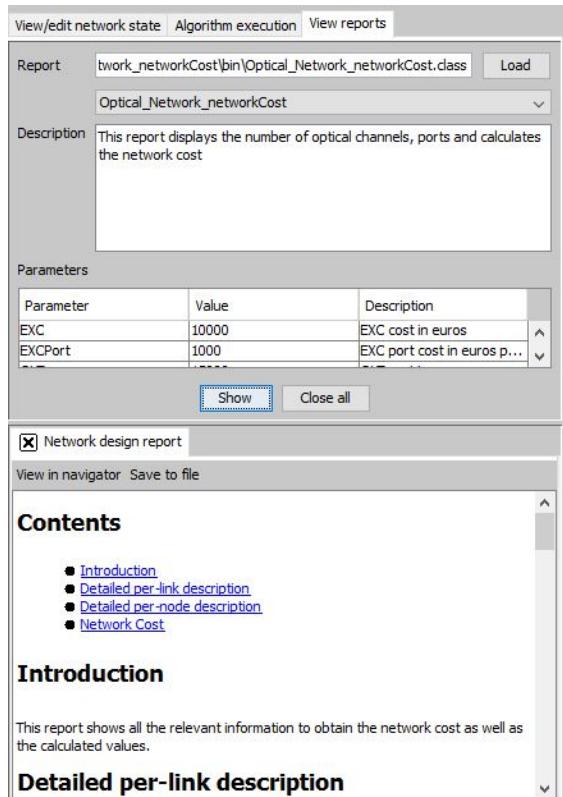


Figura 10.13: Network Cost Report

Besides the number of wavelengths, this section also indicates the amount of amplifiers necessary in each link.

The second category is the Detailed per-node description. This section displays a table indicating how many ports are needed of each type for every node. The number of tributary ports obtained in each node is the sum of all traffic originating from that node or ending on it depending if its the input or output ports divided by the amount of traffic each optical channel can carry. This number also depends on the links through which traffic will be routed, for example, if 40 ODU0s are transmitted into 2 separate links only one wavelength could carry it but as they are going through different routes then 2 wavelengths will be used resulting in also a need for 2 tributary ports.

The number of line ports is obtained by adding the total amount of optical channels in the links that use that specific node as origin or destination.

Finally the total number of ports is as expected the sum of all the tributary ports with the line ones. With this information the average and the total number of ports in the network can be obtained which will later be used in calculating the network cost.

Having the node and link information available, the network cost can then be calculated as displayed on the third category of the report. The Node electrical cost is obtained with Equation 10.2 for a Transparent Network.

$$C_{exc} = (\gamma_{e0} \times N) + (\gamma_{e1} \times \tau \times 2 \times P_{TRIB}) \quad (10.2)$$

- $C_{exc}$  → Electrical Ports Cost
- $\gamma_{e0}$  → EXC cost in Euros
- $N$  → Number of Nodes
- $\gamma_{e1}$  → EXC port cost in Euros per GB/s
- $\tau$  → Traffic supported by optical channel
- $P_{TRIB}$  → Number of tributary ports

The cost values can be obtained from Table 10.1, the number of nodes is a known value when designing a network, the traffic supported by optical channel is defined by the grooming algorithm or by dividing the link capacity by its amount of optical channels and the number of tributary ports was obtained on the previous section of the report.

For an Opaque network, the electrical nodes cost is similar as displayed in Equation 10.3.

$$C_{exc} = (\gamma_{e0} \times N) + (\gamma_{e1} \times \tau (P_{LINE} + P_{TRIB})) \quad (10.3)$$

The node optical cost on the other hand, can be calculated for a Transparent network using Equation 10.4.

$$C_{oxc} = (\gamma_{o0} \times N) + \gamma_{o1} \times (P_{LINE} + P_{TRIB}) \quad (10.4)$$

- $C_{oxc}$  → Optical Ports Cost
- $\gamma_{o0}$  → OXC cost in Euros
- $N$  → Number of Nodes
- $\gamma_{o1}$  → OXC port cost in Euros
- $P_{TRIB}$  → Number of tributary ports
- $P_{LINE}$  → Number of line ports

As for the electrical ports, the cost values were previously defined in Table 10.1 and as such, only the number of ports is needed. These value were obtained on the second part of the report (Detailed per-Node description).

For an Opaque network, the node optical cost is 0 as the ports are all electrical.

The Node Total Cost is as expected the sum of both the optical and electrical node costs.

The rest of the network cost is from the links. This cost is obtained with Equation 10.5.

$$C_L = (\gamma_0^{OLT} \times L) + (\gamma_1^{OLT} \times \tau \times W) + (N^R \times c^R) \quad (10.5)$$

- $C_L \rightarrow$  Links Cost
- $\gamma_0^{OLT} \rightarrow$  OLT cost in Euros
- $L \rightarrow$  Number of unidirectional Links
- $\gamma_1^{OLT} \rightarrow$  Transponder cost in Euros
- $\tau \rightarrow$  Traffic per port
- $W \rightarrow$  Total number of optical channels
- $N^R \rightarrow$  Total number of optical amplifiers
- $c^R \rightarrow$  Optical amplifiers cost in Euros

As in previous equations, the costs are all available in Table 10.1. The total number of optical channels can be obtained by summing the wavelengths in each link on the Detailed per-Link description section. The number of optical amplifiers was calculated previously with Equation 10.1.

The middle part of the equation:  $\gamma_1^{OLT} \times \tau \times W$  refers to the Transponders cost while the rest is the "Fiber" and the "OLT" cost. Lastly the total network cost can be obtained by adding the Links cost with the Nodes cost.

## Results

This section will display the results obtained using the algorithms and reports previously explained for a network with an Opaque transport mode and for one with Transparent.

### Opaque with 1+1 protection

The results will be displayed only in the logical topology as in an opaque network it is the same as the physical one. Using the algorithm presented on figure 10.12 the routes and protection segments are created as well as the grooming.

There is not a second algorithm type for wavelengths reduction due to the fact that, that algorithm chooses the best path based on the shortest or disjointed path which in this case both need to be used one for work and one for protection. As such, is difficult to reduce in any instance the shortest path because of the algorithm performance.

The traffic matrix for the reference 6 node network, used for demonstration is shown below.

$$\begin{bmatrix} 0 & 17 & 17 & 15 & 1 & 13 \\ 17 & 0 & 32 & 7 & 15 & 114 \\ 17 & 32 & 0 & 11 & 46 & 1 \\ 15 & 7 & 11 & 0 & 11 & 7 \\ 1 & 15 & 46 & 11 & 0 & 93 \\ 13 & 114 & 1 & 7 & 93 & 0 \end{bmatrix}$$

Figura 10.14

The amount of traffic that needs to be reserved in each link is as was to be expected a lot higher due to the need to reserve double the amount and in more links. The same happens in terms of wavelengths.

The number of wavelengths can again be seen on the links section of the "networkCost" report as well as the amplifiers needed on Figure 10.15.

### Detailed per-link description

Node Pair	Wavelengths forward	Wavelengths backward	Amplifiers forward	Amplifiers backward
Node 0 «-> Node 1	10	10	1	1
Node 0 «-> Node 2	10	10	1	1
Node 1 «-> Node 2	14	14	1	1
Node 1 «-> Node 3	14	14	1	1
Node 2 «-> Node 4	14	14	1	1
Node 3 «-> Node 4	14	14	1	1
Node 3 «-> Node 5	10	10	1	1
Node 4 «-> Node 5	10	10	1	1

Figura 10.15: Links for Opaque Network with 1+1 Protection

The conclusions to take from these results are the same as was previously discussed as

the number of amplifiers does not change and the wavelengths are the ones shown on the line matrices.

As for the nodes in the network Figure 10.16 shows the ports needed.

### Detailed per-node description

Name	Trib ports in	Trib ports out	Line Ports in	Line Ports out	Total Ports in	Total Ports out
Node 0	9	9	20	20	29	29
Node 1	9	9	38	38	47	47
Node 2	9	9	38	38	47	47
Node 3	10	10	38	38	48	48
Node 4	10	10	38	38	48	48
Node 5	9	9	20	20	29	29
Total	56	56	192	192	248	248

Figura 10.16: Nodes for Opaque Network with 1+1 Protection

Again, the difference for the case without protection is only on the number of line ports as this value is based on the number of wavelengths going in or out of that node.

Comparing the number of ports obtained here with the network with a transparent transport mode, the amount is lower for the opaque network due to the reduced number of wavelengths required to route the traffic.

Lastly the total network cost is on Figure 10.17.

### Network Cost

Category		Cost	Total
Link Cost	OLT	240,000	96,304,000
	Transponders	96,000,000	
	Amplifiers	64,000	
Node Cost	Electrical	24,860,000	24,860,000
	Optical	0	
<b>Total Network Cost</b>			<b>121,164,000</b>

Figura 10.17: Network Cost for Opaque Network with 1+1 Protection

The increase in cost is as described on the transparent network just based on the additional number of wavelengths required which translates in also more trunk ports needed. As noted above in the amount of ports, the cost is also lower in this instance when compared to the transparent network due to the cheaper cost in transponders and optical ports.

### **Transparent with 1+1 protection**

For a network with a transparent transport mode, the routing as was explained before, is done using a shortest path algorithm since there are no traffic grooming between different node pairs. For this instance as there is also a 1+1 protection scheme in place, the algorithm needs to not only create the routes but also a protection segment for each route. This segment is the shortest disjoint path of the route created.

Comparing the results obtained here with the previous example, it can be seen that the amount of traffic and wavelengths is significantly higher. It is in both cases, double the amount of before since the same quantity needs to be reserved for protection.

The conclusions that can be taken from the physical topology are as explained before, the huge number of wavelengths is related to the needed for double the amount of traffic where this extra will go through even more links.

For the logical topology the Average second shortest path number of hops is 1 since as for the shortest path, it is considered that there are always direct links between nodes in a transparent network. As for the physical topology, this value is not so obvious as it has to be calculated based on the second shortest path between each node pair.

These differences for the transparent network with protection segments can also be seen on the information provided in the "networkCost" report. Figure 10.18 shows the results for the links in the physical topology.

### **Detailed per-link description**

Node Pair	Wavelengths forward	Wavelengths backward	Amplifiers forward	Amplifiers backward
Node 0 «-> Node 1	12	12	1	1
Node 0 «-> Node 2	12	12	1	1
Node 1 «-> Node 2	18	18	1	1
Node 1 «-> Node 3	18	18	1	1
Node 2 «-> Node 4	18	18	1	1
Node 3 «-> Node 4	18	18	1	1
Node 3 «-> Node 5	12	12	1	1
Node 4 «-> Node 5	12	12	1	1

Figura 10.18: Links for Transparent Network with 1+1 Protection

It can be seen that as expected the number of amplifiers is the same due to the link lengths remaining constant but the number of wavelengths are higher due to having a grooming

scheme worst with this topology.

The results in terms of ports per node are shown below.

### Detailed per-node description

Name	Trib ports in	Trib ports out	Line Ports in	Line Ports out	Total Ports in	Total Ports out
Node 0	10	10	24	24	34	34
Node 1	10	10	48	48	58	58
Node 2	10	10	48	48	58	58
Node 3	10	10	48	48	58	58
Node 4	10	10	48	48	58	58
Node 5	10	10	24	24	34	34
Total	60	60	240	240	300	300

Figura 10.19: Nodes for Transparent Network with 1+1 Protection

The number of tributary ports remain the same but the number of line ports increase based on the higher number of wavelengths needed in the network.

Lastly, the total network cost is shown on Figure 10.20.

### Network Cost

Category		Cost	Total
Link Cost	OLT	240,000	120,304,000
	Transponders	120,000,000	
	Amplifiers	64,000	
Node Cost	Electrical	12,060,000	12,930,000
	Optical	870,000	
<b>Total Network Cost</b>			<b>133,234,000</b>

Figura 10.20: Network Cost for Transparent Network with 1+1 Protection

The results obtained for the network Cost confirm those obtained in the previous categories in this report. The OLT and amplifiers cost does not change as the number of links and amplifiers remains the same. Similarly, the electrical ports cost is also the same as the amount of ADD/DROP ports remains the same.

The differences are in the Transponders cost in the links and the Optical cost in the nodes. These as expected, cost more based on the increased number of them needed in the network to have a 1+1 protection scheme in a transparent transport mode network.

## Simulations

To access the Simulations window go to "Tools → Online Simulation" or press *Alt + 3*. The simulations menu is very similar to the one available for network design with the notable difference that in this instance the network needs to have already been saved with every definition done as all the tabs described earlier are only available here for viewing.

Using the already built network with the demand set introduced as well as routing and protection segments, an example of a Time-varying simulation is demonstrated. The main parameters to be chosen on this simulation are the "Event generator" and the "Provisioning algorithm", displayed on Figures 10.21(a) and 10.21(b).

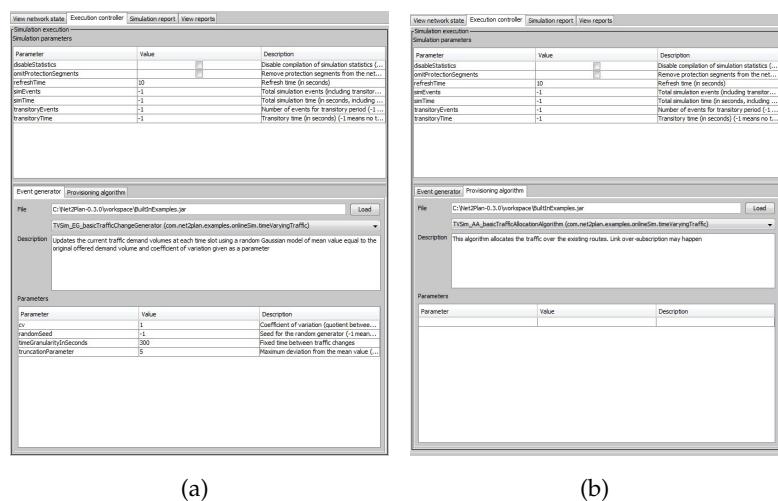


Figura 10.21: a) Net2Plan Event generator ; b) Net2Plan Provisioning algorithm

The Event generator shown creates a time varying simulation by updating the network traffic based on the chosen parameters while the allocation algorithm in this case only allocates this traffic into the available routes. Besides these options it is also possible to change the main simulation parameters which are displayed on the top half.

Having defined all the simulation parameters and the other necessary options, the simulation can be started by just pressing "run" below the network topology at the lower left side. The "simulation controller" will update automatically based on the time defined at the simulation parameters or it can be paused for an update on the results.

## Implementing new algorithms on Net2Plan

This section will demonstrate some of the possibilities provided by Net2Plan as an open source tool. By creating new algorithms or reports it is possible to adapt this program for most necessities in terms of network planning.

There are already several built-in algorithms present in Net2Plan but as it is impossible to have an algorithm built for every specific necessity it is possible for each user to build new ones or modify existing ones to fulfil what needs to be done.

As everything in Net2Plan was built in Java, the program "Eclipse" that can be downloaded from <https://eclipse.org/downloads/> was chosen as the best option for coding. All the .java files from the available algorithms in Net2Plan can be downloaded from its website and introduced into "Eclipse" to create a class.

When opening Eclipse, the first choice is to define the work directory in which all the projects will be created. Having defined the workspace, Figure 10.22 demonstrates the window for creating new projects in Eclipse, this can be accessed by going into "File → New → Java Project". In this window, only the name needs to be defined and then finish.

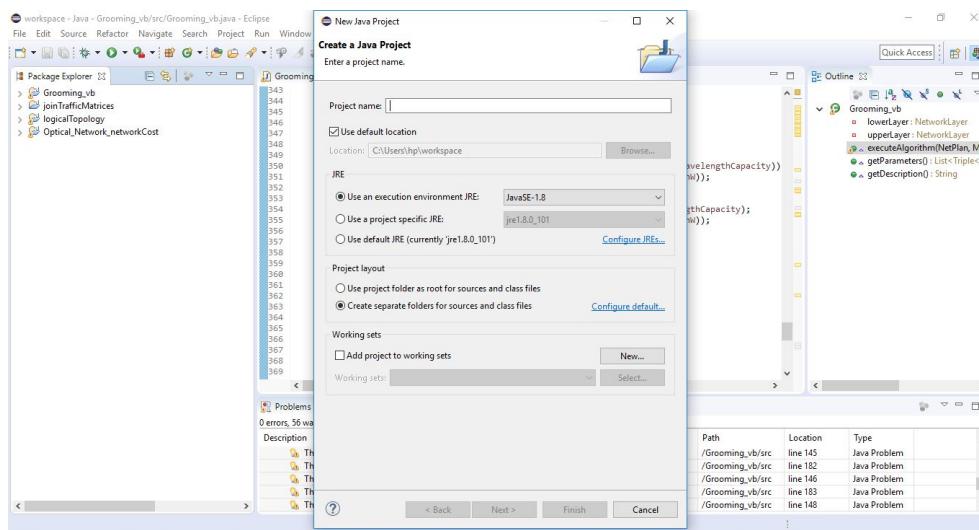


Figura 10.22: Eclipse new project

Having created a new project, a "src" directory should be available where the .java should be located. As a starting point, an existing algorithm should be used as a template and then modified to do its necessary purpose. Figure 10.23 shows a newly created project called "logicalTopology".

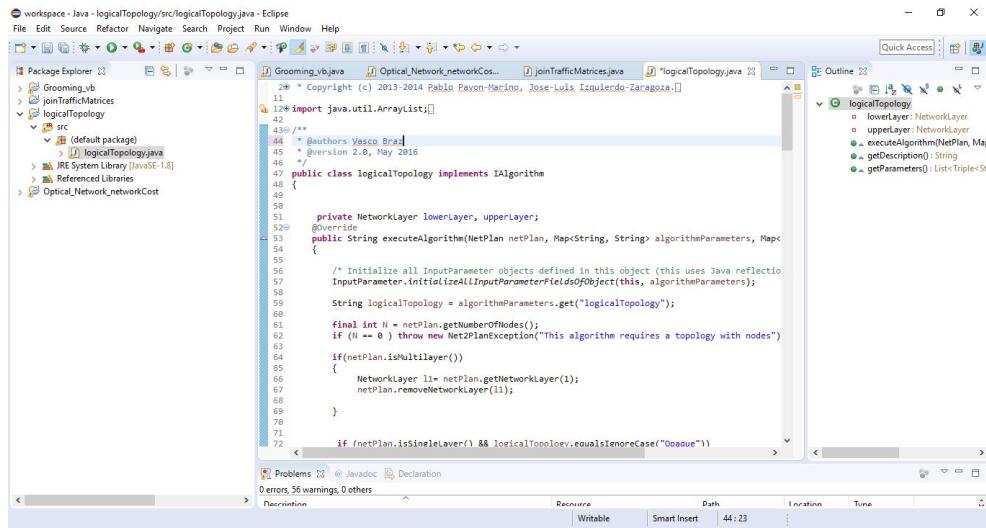


Figura 10.23: Eclipse new project with source file

To add the library files to a project, right click on it and choose "Build Path → Configure Build Path ...". On the window that appears, press "Add External Jars..." and include all the files in the Net2Plan "lib" directory as shown on Figures 10.24(a) and 10.24(b).

To further illustrate how these modifications to algorithms work, the project created above using an existing code as a template was modified to create a new algorithm which creates the logical topology of a network in another layer.

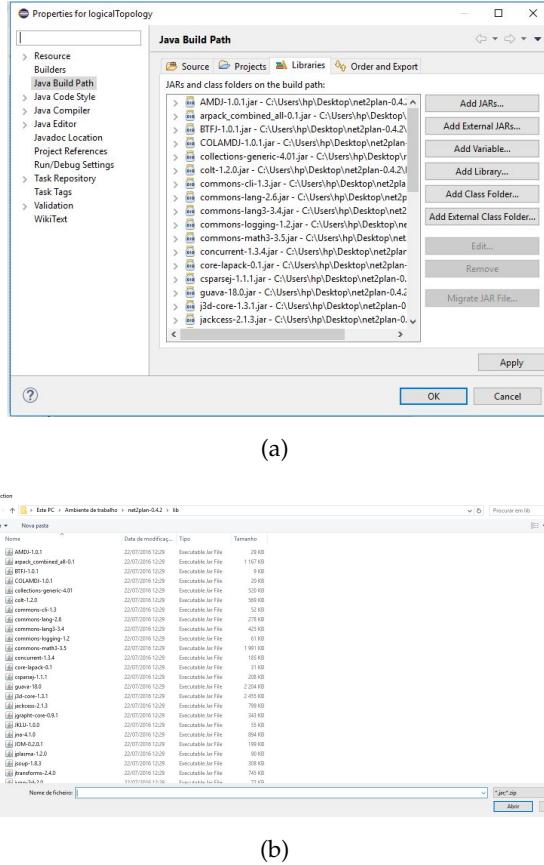


Figura 10.24: a) Eclipse Java Configure Build Path ; b) Net2Plan library files

The code created is shown on Figure 10.22. By saving this project on Eclipse a .class file is created on the bin directory of the project which can be loaded on Net2Plan. On the "Algorithm execution" tab at the "Offline network design", the "BuiltInExamples.jar" is loaded as the default location for algorithms and as it is a .jar file all the available ones that came with Net2Plan are integrated into it. To get the newly created algorithm available, press "Load" and find the .class file created in Eclipse as shown on Figure 10.25.

As was said before and can be seen on the "Description", this algorithm creates the network logical topology as was explained on section 10.1.

Algorithms developed on Eclipse can be exported into a .jar file so on Net2Plan this file can be loaded and all the algorithms developed are shown in a list in the same manner as the ones that came with the Net2Plan installation. The export option can be accessed by going into File → Export, and the menu are shown in Figures 10.26(a) and 10.26(b).

By default only the .class files are exported along with the necessary libraries so that the algorithms can be loaded on Net2Plan. There is however an option to also export the .java files so that if needed the ones who will use the code also have access to it if they need to change it.

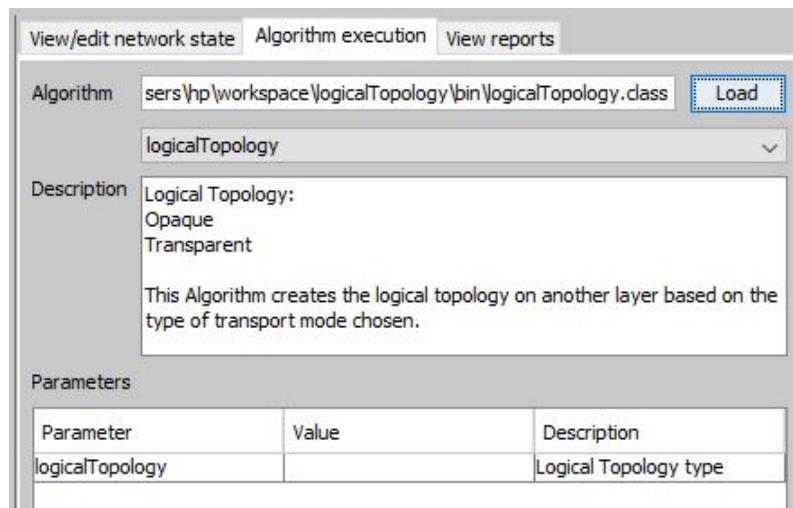


Figura 10.25: Net2Plan new algorithm

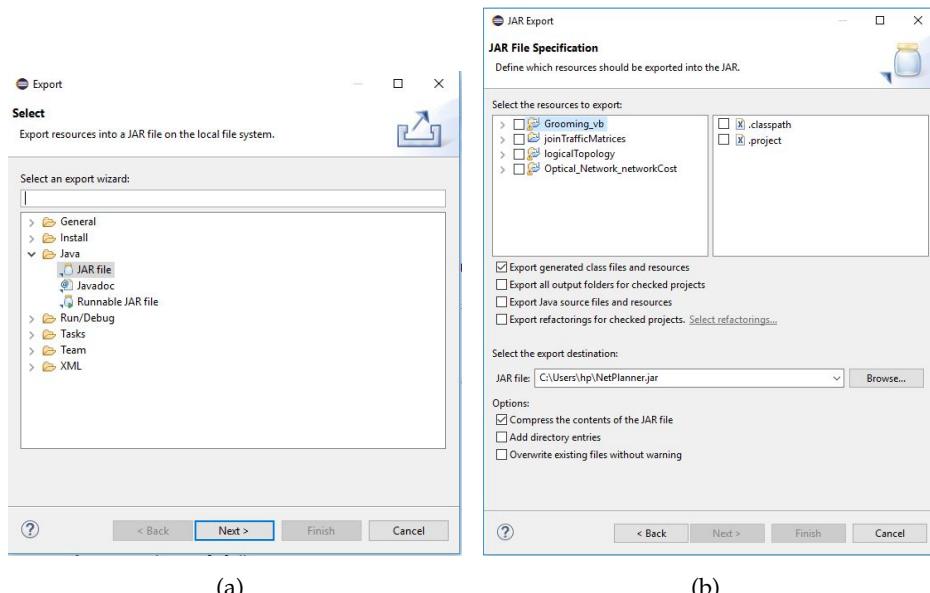


Figura 10.26: a) Eclipse export ; b) Projects to export into a .jar file

## Developing new Reports

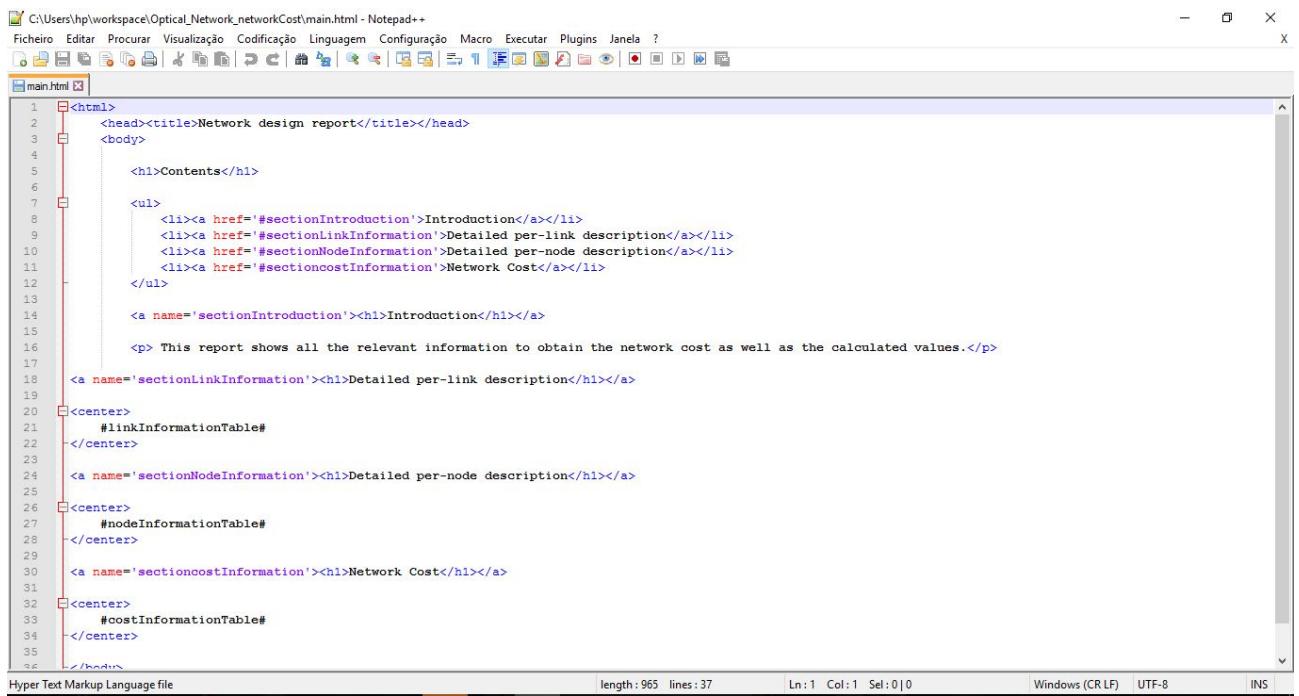
Similarly to the way algorithms can be modified or new ones created, also reports can be done using almost the same steps. For the following examples, the "Optical\_Network\_networkcost" is being used as a basis for modifying or creating new reports.

An important point to note as the main difference as to when modifying algorithms, is that in this case not only are the Net2Plan libraries needed but also the extra files summoned by the report. These files can be found opening the "BuiltInExamples.jar" file in the Net2Plan

directory on the corresponding report.

For the report being used there is an .html file called "main" which is where the information to be displayed in html form is described as well as several image files that are displayed in the report. As such, if the modifications to be done in the reports are to be shown in html format the "main.html" file needs to be modified in order to adapt to these changes.

The tables themselves are created in eclipse as Java code but the html file needs to be opened for example with "Notepad++" to change some its code as the tables are being appended into the html. Figure 10.27 shows the modified html that is used in the Optical\_Network\_networkcost.



```

C:\Users\hp\workspace\Optical_Network_networkCost\main.html - Notepad++
Ficheiro Editar Procurar Visualização Codificação Linguagem Configuração Macro Executar Plugins Janela ?
File Edit Find View Encoding Language Configuration Macro Execute Plugins Window ?
main.html [x]
1 <html>
2   <head><title>Network design report</title></head>
3   <body>
4     <h1>Contents</h1>
5     <ul>
6       <li><a href="#sectionIntroduction">Introduction</a></li>
7       <li><a href="#sectionLinkInformation">Detailed per-link description</a></li>
8       <li><a href="#sectionNodeInformation">Detailed per-node description</a></li>
9       <li><a href="#sectioncostInformation">Network Cost</a></li>
10    </ul>
11
12    <a name='sectionIntroduction'><h1>Introduction</h1></a>
13
14    <p> This report shows all the relevant information to obtain the network cost as well as the calculated values.</p>
15
16    <a name='sectionLinkInformation'><h1>Detailed per-link description</h1></a>
17
18    <center>
19      #linkInformationTable#
20    </center>
21
22    <a name='sectionNodeInformation'><h1>Detailed per-node description</h1></a>
23
24    <center>
25      #nodeInformationTable#
26    </center>
27
28    <a name='sectioncostInformation'><h1>Network Cost</h1></a>
29
30    <center>
31      #costInformationTable#
32    </center>
33
34  </h1>
35 </body>
36 </html>

```

Hyper Text Markup Language file length : 965 lines : 37 Ln : 1 Col : 1 Sel : 0 | 0 Windows (CR LF) UTF-8 INS

Figura 10.27: html file for Network Cost report

As can be seen, this is a simple example of an html file since there are only hyper links created to link the contents index to the tables. Other options could be added as for example, hyper links to each of the network costs with the formula describing its calculations by adding the necessary information in this file. These extra options are present on more complex reports such as the "Report\_networkDesign" where the images used are equations showcasing how some of the calculations are done.

## 10.2 Installing LPSOLVE for using in MatLab

<b>Student Name</b>	:	Tiago Esteves (November 28, 2017 - December 05, 2017)
<b>Goal</b>	:	Help other to install lpsolve for using in MatLab.

In this section will describe how to install lpsolve and how it can be used through matlab. For this it is necessary to follow the following steps:

1. Install lpsolve in your computer
2. Install lpsolve matlab extensions
3. Install the library

### **Step 1:**

The first thing to do is to install lpsolve using the execute file "lp-solve-5.5.2.5-IDE-Setup" that can be found in GitHub through this link <https://github.com/netxpto/NetPlanner/tree/Develop/software/lpsolve>. The installation is quite simple and contains few steps for its execution.

In case there is any doubt or question you can always use the lpsolve reference guide in link: <http://lpsolve.sourceforge.net/5.5/>

### **Step 2:**

In this step it is necessary to go to GitHub again and download with the name "lp-solve-5.5.2.0-MATLAB-exe-win64" in link <https://github.com/netxpto/NetPlanner/tree/Develop/software/lpsolve> and extract all the files. Then you need to put the **mxlpsolve.mexw64** and **mxlpsolve.m** files in the same folder as the .m files. In case there is any doubt or question you can always use this guide for help: [there is any doubt or question you can always use the lpsolve reference guide in link:](#)

### **Step 3:**

Finally, once again in GitHub through the link <https://github.com/netxpto/NetPlanner/tree/Develop/software/lpsolve> we can find the last folder to get the necessary library, thus downloading the folder "lp-solve-5.5.2.0-dev-win64" and then include in the Windows PATH environment.

## **Capítulo 11**

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## **Master Dissertations**

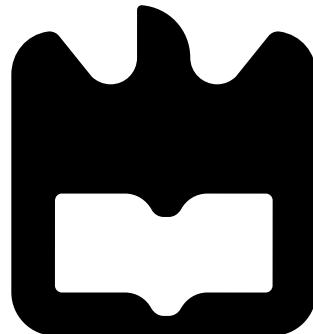
- Vasco Braz, Dimensioning and Optimization of Node Architecture in Optical Transport Networks, University of Aveiro, 2016



**Vasco Rafael Brites  
dos Santos Braz**

**Dimensionamento e Optimização da Arquitetura  
dos Nós em Redes de Trasporte Óticas**

**Dimensioning and Optimization of Node  
Architecture in Optical Transport Networks**







**Vasco Rafael Brites  
dos Santos Braz**

**Dimensionamento e Optimização da Arquitetura  
dos Nós em Redes de Trasporte Óticas**

**Dimensioning and Optimization of Node  
Architecture in Optical Transport Networks**

“Anyone who has never made a mistake has never tried anything new.”

— Albert Einstein





**Vasco Rafael Brites  
dos Santos Braz**

**Dimensionamento e Optimização da Arquitetura  
dos Nós em Redes de Trasporte Óticas**

**Dimensioning and Optimization of Node  
Architecture in Optical Transport Networks**

Dissertação apresentada à Universidade de Aveiro para cumprimento dos requisitos necessários à obtenção do grau de Mestre em Engenharia Eletrónica e Telecomunicações, realizada sob a orientação científica do Dr. Armando Humberto Moreira Nolasco Pinto, Professor Associado do Departamento de Eletrónica, Telecomunicações e Informática da Universidade de Aveiro, coorientação empresarial do Dr. Rui Manuel Dias Morais, doutorado em Engenharia Eletrotécnica pela Universidade de Aveiro, coordenador de atividades de investigação em optimização de redes na Coriant Portugal.



## **o júri / the jury**

presidente / president

**Mário José Neves de Lima**

Professor Auxiliar da Universidade de Aveiro

vogais / examiners committee

**Maria do Carmo Raposo de Medeiros**

Professora Associada da Universidade de Coimbra

**Armando Humberto Moreira Nolasco Pinto**

Professor Associado da Universidade de Aveiro



**agradecimentos /  
acknowledgements**

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Queria agradecer especialmente à minha mãe que tanto fez por este momento.



## **Resumo**

Nesta dissertação é apresentada uma introdução às redes de transporte óticas multicamada. Foram caracterizados os dois elementos principais da rede: nós e ligações. Ao nível das ligações foi feita uma abordagem baseada nos seus elementos físicos principais. Ao nível dos nós foram tidos em consideração o tráfego de cliente (baixo débito) e o tráfego de linha (alto débito), bem como os componentes necessários para os transportar. A forma como o tráfego de cliente é agregado e o encaminhamento do mesmo na rede, exigem a elaboração de uma arquitetura que minimize os recursos necessários. A necessidade de otimizar este processo de dimensionamento da rede levou à construção e validação de métodos de agregação de tráfego e encaminhamento baseados em topologias lógicas da rede. Assim, proponho nesta dissertação algoritmos de agregação e encaminhamento aplicados a um software livre, previamente validados por modelos de programação linear baseados em restrições e funções objectivo adequadas à topologia pretendida. A apresentação detalhada dos resultados considerando o CAPEX, bem como a sua análise são considerados na dissertação. Por fim, são apresentadas conclusões e sugerido o trabalho científico que ainda pode ser realizado neste âmbito.



## **Abstract**

In this dissertation an introduction is presented to the multilayer optical transport networks. The two main elements of the network were characterized: nodes and links. Regarding the connections it was made a shallower approach based on its key physical elements. In terms of nodes client traffic (low bandwidth) and the line traffic (high bandwidth) were considered as well as the components necessary to carry them. The way the client traffic is aggregated and its forwarding in the same network requires an architecture which makes use of the minimum resources. The need of optimizing this network design process led to the construction and validation of traffic aggregation methods and routing based on logical network topologies. I therefore propose in this dissertation routing and grooming algorithms applied to a open source software, previously validated by linear programming models based on constraints and objective functions suitable to the desired topology. A detailed presentation of the results considering the CAPEX and its analysis are also taken into account. Finally, conclusions are presented and the scientific work that can still be done in this area is suggested.



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# List of Acronyms

API	application user interface
EDFA	erbium doped fiber amplifier
EXC	electrical cross connect
CAPEX	capital expenditures
IDE	integrated development interface
ILP	integer linear programming
ITU-T	international telecommunication union - telecommunication standardization
IP	Internet protocol
MPLS-TP	multi protocol label switching - transport profile
M2M	machine-to-machine
OTN	optical transport network
OEO	optica-electrical-optical
OPEX	operational expenditures
OXC	optical cross connect
OTN	optical transport network
TCO	total cost of ownership
SDH	synchronous digital hierarchy
WAM	wide area network
WDM	wavelength division multiplexing



# Chapter 1

## Introduction

Systems based on Machine-to-Machine (M2M) communication, Voice over Internet Protocol (VOIP) services, online gaming and data storage are considered penetration services. These services have led to an overhead on existing networks caused by a huge number of users [4][5][6]. As it increases the amount of traffic and the transmission rates required, telecommunication agents involved are undergoing a pressure to develop the network technology in their processes, in order to increase the bandwidth.[7]

Technological development has allowed lower prices for network components, however, these prices are similar to the major operators. The costs with the setup of the infrastructure, CAPEX, compromises physical network components, buildings where they are installed and software needed for network operation and management. Currently, almost all traffic is transported through optical networks, so the operators are very interested in reducing the cost per transported bit as much as possible without compromising the quality of service. At the same time, there are entities concerned about the ecological footprint because of the uncontrolled increase in energy reserved for telecommunications. Therefore, it is inevitable to create or enhance methods and equipment compatible with networks already realized. So, to lead the market competition, those operators are making an effort to optimize their networks, using the minimum resources with the minimum power consumption. Hence, the outcome of reducing power consumption is the diminish of operational costs (OPEX) and a crucial step to save the planet. The result of summing capital expenditures and operational expenditures is the total cost of ownership (TCO).[8]

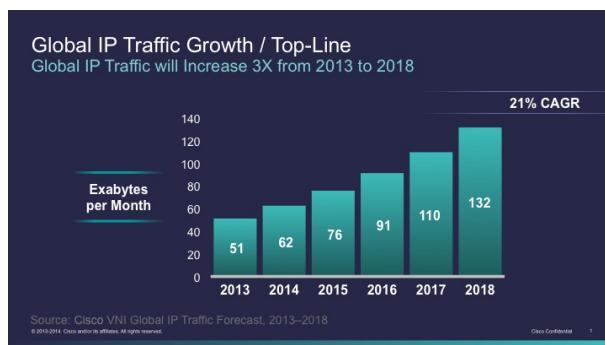


Figure 1.1: Cisco forecast for ip traffic growth [1]

## 1.1 Motivation

Scientific researchers in the academic and business scope are joining efforts to improve network planning processes. In an optical network there are inevitable problems that occur such as, excessive traffic in one certain node or link and physical damage that may happen in the components of the network, this type of problems can block the flow of traffic and cause a huge loss of information if the network is not properly designed. The consequences of a failure of a single fiber can be catastrophic and may affect the medical emergency number, banking operations, or many other important services, that's why the study of protection and survivability methods are so crucial. In this context the operators are obliged to invest in more equipment and new strategies that ensure the protection and survivability of the network [9].

Nonetheless, it would be extremely difficult to make a fast and scalable planning to an optical network by hand, so it is used a network planning tool which is purposeful for systems vendors and network operators. It is used in the various stages of the telecommunications business, in the budgeting stage a planning tool offers a cost-efficient solution has a enormous benefit in a competing environment. However, the needs of people in terms of telecommunications are constantly changing, so in the operation stage, the planning tool can be used to re-optimize the available resources, making possible additional cost savings to network operators. Many companies as Coriant, Cisco and Ericson operating in the telecommunications area, developed their own optical network planners [2]. However, it is evident that these tools are not publicly available to perform comparative studies of the obtained solutions for corporative reasons.

Therefore, in this dissertation, it is used an open source software (Net2Plan) as a platform to achieve a heuristic solution. Heuristic algorithms tend to be relatively fast, scalable, and suitable for huge networks. The optimal solutions can be obtained through ILP models. However, scalability limitations may arise depending on the computational resources available and the network scale. Nevertheless, the type of solutions obtained and the models themselves can give an insight in key and structural aspects of the problem and are crucial to verify the quality of heuristic algorithms. These dimensioning tools, process input parameters and generate outputs regarding optical network constraints, in order to obtain a solution focused on cost efficiency.

## 1.2 Objectives

This dissertation emerges from the collaboration between University of Aveiro, Instituto de Telecomunicações Aveiro, and Coriant Portugal due to the interest of network operators in saving some resources inherent to the planning and operation of their networks and also contribute with knowledge to the scientific community of optical networks. To achieve the main objectives of this dissertation, the following steps should be fulfilled:

1. Develop ILP models for opaque and transparent networks using dedicated path protection.
2. Get a solution for optical networks with protection dimensioning through heuristic algorithms applied in Net2Plan (open source platform).
3. Compare and validate heuristics based results with the ILP based results.
4. Apply heuristic method to a realistic network.

### 1.3 Thesis outline

This dissertation is organized in 6 chapters. Chapter 2 is a state-of-art of optical networks topological design, dimensioning and dedicated protection. The basic concepts and fundamentals are defined as well as the physical and logical topology. In terms of physical topology, basic optical network elements are described in that chapter. The relation between logical topology and transport modes is presented in detail. Chapter 3 starts by a reference network dimensioning problem analysis and an integer linear programming approach. It begins with a problem definition, and the set of variables and inputs used. Hence, the remaining of the chapter is devoted to propose dimensioning models for optical networks based on opaque and transparent transport modes and the consequent results. In Chapter 4, a heuristic approach is suggested and described. Thus, an open source software was chosen to implement this solution to be accessible to students and modifiable for educational purposes. An overview of the software used to create the algorithms on the platform used (Net2Plan). The pseudo code behind the routing and grooming is also contained in this chapter. The solution obtained through integer linear programming is considered the optimal solution and served to evaluate the quality of the solution based on heuristics. The optical channels needed for a specified client traffic matrix as a function of the algorithms runtime or as a function of different client traffic type are some of the results presented on the results chapter. The results of this two approaches are in Chapter 5. In this chapter and after validating the heuristics, they are applied to a real network and the results will be analyzed. The last step is the conclusions 6 and suggestions for future research directions.

## Chapter 2

# Network Design and Dimensioning

Internet is becoming one of the most powerful platforms allowing entertainment and productivity. Some services, as cloud storage or online social networks, have been implemented over Internet and they require a suitable network design for huge traffic requirements and must be able to deal, efficiently, with time-varying traffic [10]. Thus, it is mandatory to perform the best arrangement for physical resources, in order to simplify future improvements and ensure a reliable and efficient network. So, it is necessary to consider an overview of this chapter, starting from the optical reference network approach and the definition of main elements (links and nodes). As described on section 2.1.3, node mapping and links connecting them are considered physical topology.

Optical links establish the connection between two adjacent nodes, ensuring the transmission of optical signals between them. Nodes can perform six main functions: encapsulation; electrical switching; deterministic or statistical multiplexing (grooming); wavelength assignment; optical switching; and optical multiplexing. This chapter is more focused on grooming tasks. Up to now, the majority of the functions performed at the nodes are only capable of being carried out in the electrical domain. However, an optical signal may suffer optical-electrical-optical (OEO) conversions in intermediate nodes. The consequence of this clear optical channels inside a wide area network(WAN) is a virtual topology as known as optical or logical topology 2.1.4. According to all-optical fragments in a single lightpath, three transport modes will emerge: opaque, transparent and translucent.

In section 2.2, each transport mode is detailed, clarified and exemplified. An efficient topological network design makes optical networks more and more robust and reliable, but not infallible. An alternative for network working paths should be considered, regarding the limit of failure recovery time established by standardized protocols. Throughout the dissertation, only dedicated protection implementation strategies are considered 2.3. Thus, considering protection schemes and working paths for each traffic demand, it is possible to suggest an approach for node dimensioning, including optical and electrical components and support structures. The consequence of a well designed network is the minimization of node components and, as a result, lower capital expenditures (CAPEX) [11].

## 2.1 Optical Networks

Optical technologies are widely used in telecommunication networks, and currently they constitute the central physical network elements in most parts of the world, thanks to their high speed, large capacity, and other attractive characteristics. Optical networks can be classified as core, metro and access networks. The backbone infrastructure of telecommunication networks are core networks, which interconnects large cities (as network nodes), and spans nationwide, continental, and even intercontinental distances connected by links.

### 2.1.1 Links Arquitecture

Links are basically the connection between two adjacent nodes. In transport networks links are physical point-to-point connections ensured by transmission systems. The transmission system starts and ends in adjacent nodes, i.e. in directly connected nodes. Signals are transmitted through a pair of fibers required bidirectional communication.

Optical signal is sent through optical fiber and this propagation causes signal deterioration and produce linear and non-linear effects. Loss coefficient imposed by optical fibers is a physical parameter described on each different fiber datasheet. In order to compensate attenuation, transmission systems contain optical amplifiers spaced by an expected distance (span) enough to increase signal power to allow a reliable signal detection at the receivers.

In figure 2.1 each colored line corresponds to an optical channel which is associated a wavelength. The WDM signal requires WDM transmission systems in the ends of the link.

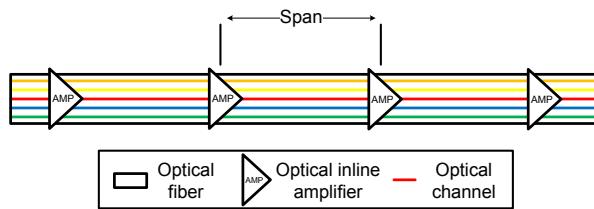


Figure 2.1: Bidirectional transmission system architecture: optical fiber and inline optical amplifiers [2]

Depending on the bandwidth used, WDM signals suffer different attenuation. Although, all channels are simultaneously amplified. An amplifier acts over the band selected, for example, EDFA (Erbium Doped Fiber Amplifier) is the most deployed fiber amplifier as its amplification window coincides with the third transmission window (1530nm –1570nm) of silica-based optical fiber [12].

## 2.1.2 Nodes Arquitecture

The more significant operations that the optical signal goes through in the network occur in nodes. Node operations require a lot of hardware (e.g. processors, modules, control modules, short-reach and long-reach transceivers), therefore nodes are generally considered the most expensive element of an optical transport network. In optical networks, nodes are composed of three essential structures: modules, shelves and rack. The modules can contain multiple ports. Shelves are the place where different modules are assembled and these shelves are contained within a larger structure, capable of providing sufficient power for each shelf. In high-capacity multilayer transport nodes, depending on network operation requirements in optical and electrical layer, different type of modules are used. Modules comprise electrical and optical components in order to perform well-defined functionalities as encapsulation, grooming and wavelength assignment. Connection between modules are established through front panel and backplane. Usually, front panel connections are mainly ensured by transceivers located in the ports. Depending on the optical signal travel distance, long-reach or short-reach transmitters must be used [13].

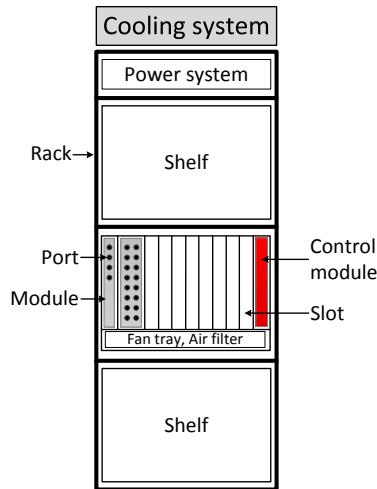


Figure 2.2: Node schematic: port, module, slot, shelf and rack [2]

### 2.1.2.1 Grooming

Traffic grooming refers to techniques used to combine low-speed traffic streams onto high-speed wavelengths in order to minimize the networkwide cost in terms of line terminating equipment and/or electronic switching. Network planners need to define which mixture of client signals should be aggregated as well as in which node will be grooming capable components, in order to improve the dimensioning of a multilayer node. Dimensioning models are closely related to the grooming operation as it determines the number of ports and wavelengths required. These models rely on ILP or heuristics, which require complete information about the network topology and traffic demands. In order to minimize the number of wavelengths used and, consequently, power consumption, network planners started with the aggregation of SDH/SONET traffic. The optimization of multi-layer networks has been focused on the two layer IP-over-WDM, or the three layer IP-over-OTN-over-WDM architectures. All optimization models of this dissertation are focused on OTN technology defined

in ITU-T recommendation G.709 however the approaches and models are flexible to support other technologies such as SDH/SONET or Ethernet. The set of all client bit rates is denoted by  $C = \{c : c \in \{1.25, 2.5, 10, 40, 100\}\}$  corresponding to an ODU1, ODU2, ODU3 and ODU4, these lower bit rate client signals, defined in Gbps, are then groomed to form a higher bit rate line signal,  $l$ . The set of line bit rates, defined in Gbps, will be denoted by  $L = \{l : l \in \{2.5, 10, 40, 100\}\}$ , corresponding to an OTU1, OTU2, OTU3 and OTU4, respectively. According to the ITU-T recommendation G.709, a single higher bit rate signal can be composed by a mix of different lower bit rate signals, then various lower bit rate signals, with different bit rates can be groomed into a single higher bit rate signal [14, 2].

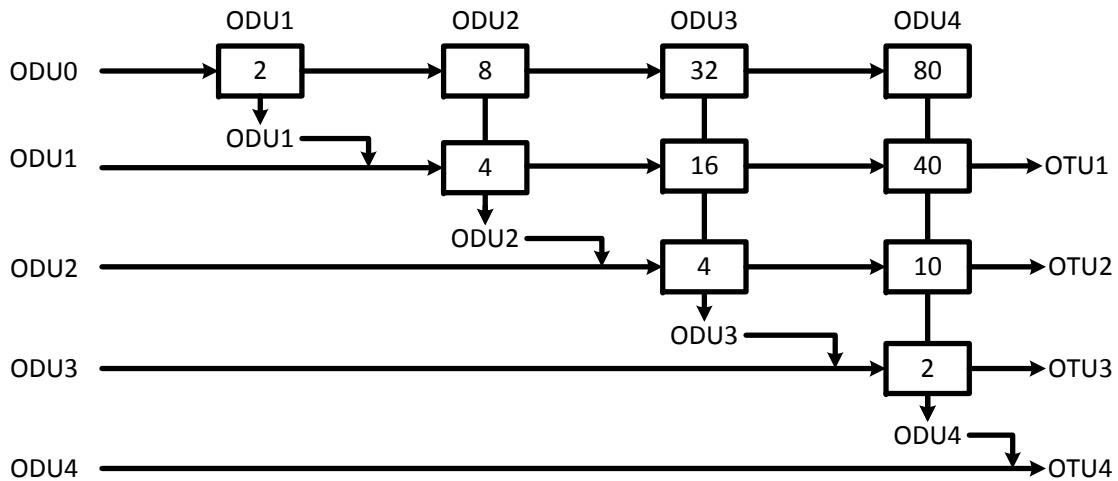


Figure 2.3: Grooming of OTN Signals [2]

As depicted in figure 2.3, the grooming of eight ODU0 client signals result in an OTU2 line signal. However, two ODU0 client signals mixed with three ODU1 is another possibility to form an OTU2 signal. The same reasoning is extensible to 100 Gbps line signals (OTU4) which are the line signals used in optimization models proposed in the next chapters.

### 2.1.2.2 Switching

In transport networks, currently, encapsulation, electrical switching and electrical grooming are usually realized using OTN. Regarding the original protocol, client traffic is encapsulated into ODU (optical data units) to be groomed and switched. The OTN technology is defined as circuit switching and depending on the layer where the switching occurs, two main types of switching were defined: electrical and optical.

**2.1.2.2.1 Electrical Switching** The use of circuit switched networks can introduce a waste of bandwidth due to the constant bit rate imposed by the OTN technology when the network becomes more and more packet dominated. Then, the Internet Engineering Task Force (IETF) defined the multi-protocol label switching - transport profile (MPLS-TP) as a customization of MPLS, in order to allow the possibility of packet switching transport networks. The MPLS-TP technology distinguishes the units of data through labels which are

manipulated to provide an efficient bandwidth utilization. Then, there are different configurations for an electrical switch, but in general electrical switches are capable of receiving the traffic from an input interface, processing the traffic and switching to the appropriate output interface. The transparent transport mode does not perform switching in electrical domain. Then, the figure 2.4 shows an electrical switching capable node [15].

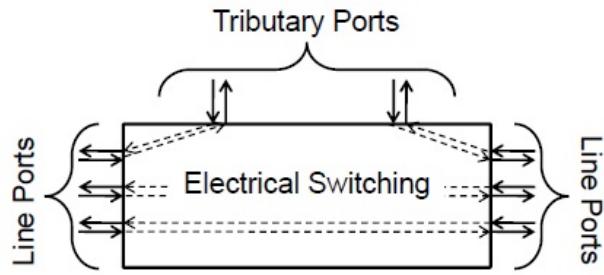


Figure 2.4: Scheme of a node for opaque transport mode network

Tributary ports are add/drop ports. Add ports are responsible for inserting traffic in the node from the access network and, inversely, the drop ports are used to extract traffic from the node. The line ports are used to make the connection between a node and the links of the core network through a higher bit rate signal (line signal).

**2.1.2.2.2 Optical Switching** In transparent and translucent networks, the optical layer has an important role in terms of switching. If a wavelength reaches a node in a transparent or translucent network, it can be switched to electrical domain to drop traffic information or can be correctly routed to the appropriate output port. In opaque networks there is no optical switching and the electrical layer is only used for wavelength multiplexing to perform WDM signals [16].

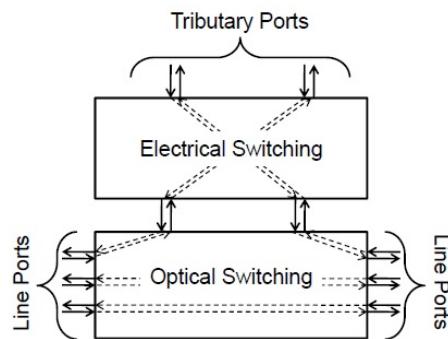


Figure 2.5: Scheme of a node using electrical and optical switching

### 2.1.3 Physical Topology

Physical topology can be seen as a layout of a real optical network, the placement of an optical network components, i.e., nodes disposition and connection conceded by links. Hence, an optical network simulation can be advantageous to analyse this approach. Thus, can be helpful to consider a simple six node core optical network connected by links, so physical topology design:

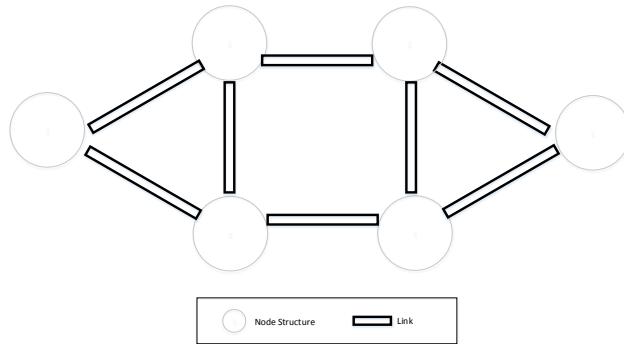


Figure 2.6: Nodes position and connection established by links located according to the real optical network

As depicted in Figure 4.4, the main elements are nodes and links. In this specific case study the number of nodes ( $N$ ) and the number of links ( $L$ ) are 6 and 8 respectively. The degree of a node ( $\delta_i$ ) is given by the number of direct connection it has to other nodes.

#### 2.1.4 Logical Topology

Optical or logical topology for networks is an approach that defines how components are connected. In the case of optical networks, logical topology is associated with the optical path segments in a single lightpath. Thus, each node may be optical directly connected to each other, or only optical connected to adjacent nodes or optical connected to suitable nodes. Therefore, these shorter optical paths along the route imposed by logical topology lead to a situation of three transport modes: Opaque, Transparent and Translucent. During this dissertation the focus will be on opaque and transparent models.

## 2.2 Transport modes

Although the logical topologies of optical networks share the same physical links, the traffic is carried differently. Depending on the number of conversions from an optical signal to the electric domain different transport modes will appear.

### 2.2.1 Opaque

Opaque transport mode performs OEO(optical-electrical-optical) conversions at every intermediate node since origin to destination node. Thus, signal can be regenerated to provide signal quality conceded by electronic signal processing. In terms of topology, logical and physical topologies are the same, so each traffic route in logical topology corresponds to the link-by-link path imposed by optical fibers between each intermediate nodes until destination [17].

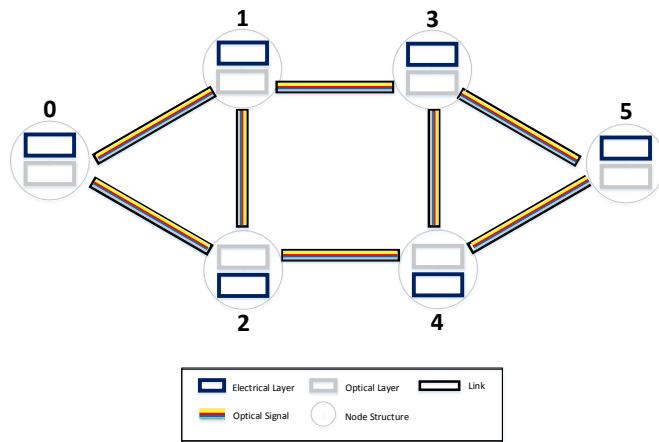


Figure 2.7: Opaque transport mode with a link-by-link grooming scheme

As a deduction, at all consecutive nodes until egress node, line signal was subjected to OEO conversions. An advantage of this transport mode is that it eliminates accumulation of physical impairments and allows full flexibility in terms of switching and grooming. Thus, it can improve capacity utilization of optical channels by providing traffic grooming at every node.

### 2.2.2 Transparent

In transparent transport mode, the information travels in a defined route through optical channels between origin and destination nodes(i.e. lightpaths) always in optical domain, and consequently physical topology and logical topology are different 2.8. Generally this procedure includes the conservation of the same wavelength on all the links which compose the route, as known as, wavelength continuity constraint. Grooming at intermediate nodes is not possible due to all-optical path applied end-to-end. Grooming scheme is single-hop because only client signals with the same destination and origin can be groomed in the same wavelength. Thus, figure 2.8 elucidate what is the optical topology for transparent transport mode from physical topology considered above [18].

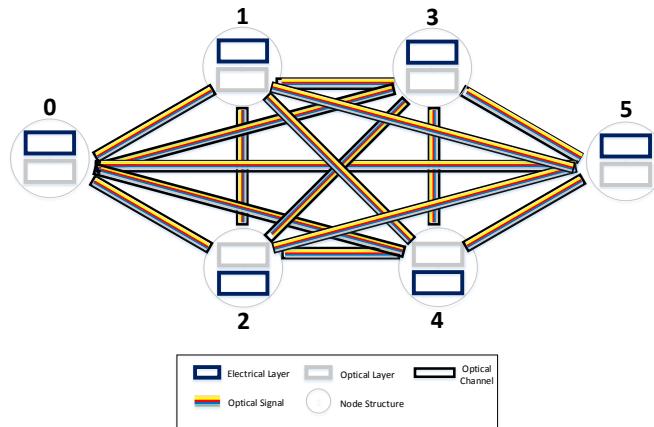


Figure 2.8: Logical topology for previous physical topology with each node connected to each other (Transparent Transport Mode)

Multicolor lines,obviously, assume the role of the optical signal. An advantage of this transport mode is the possibility for transportation of express traffic. Nevertheless, the quality of the optical signals degrade as they traverse the optical components along the route limiting the maximum optical reach of the signal. Another disadvantage is that the capacity utilization of optical channels is worse than in the opaque transport mode due to the grooming only in client signals with the same end-points.

### 2.2.3 Translucent

Translucent transport mode is a combination of previous transport modes. Thus, for the same physical topology there are several logical topologies. Within a single traffic route, the optical signal can cross some nodes regardless OEO conversions. However, to recover signal from all optical impairments and to optimize traffic grooming OEO conversions are needed. So, for a defined route there is some all-optical segments separated by regeneration, switching and grooming capable nodes. Then, using the same physical topology design as used in previous transport modes, figure 2.9 shows two possible examples of logical topologies.

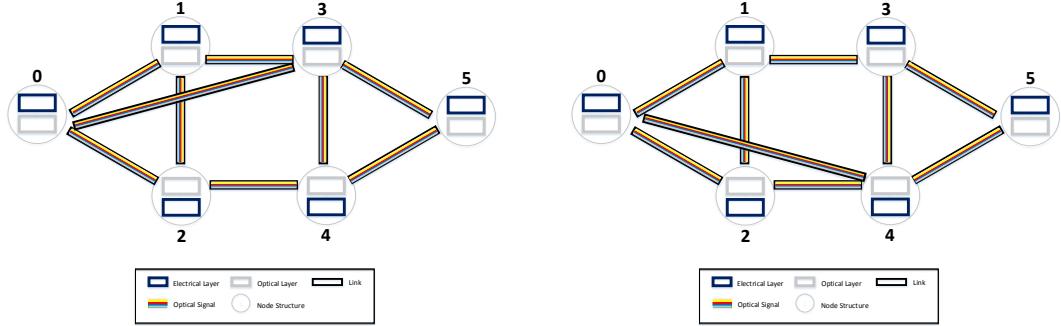


Figure 2.9: Translucent logical topologies

In translucent transport mode a multi-hop grooming scheme is employed, so different source and destination nodes can share the same lightpath until reach some intermediate node common to both. Thus, in all network nodes, lightpaths carrying local or client traffic that need to be switched a different to a different lightpath are sent to electrical domain, while through traffic lightpaths are kept in optical domain.

Transport mode	Opaque	Transparent	Translucent
<b>Grooming</b>			
Link-by-link	✓		
Single-Hop		✓	
Multi-Hop			✓
<b>Intermediate nodes</b>			
Electrical Switching	✓		✓
Optical switching		✓	✓
Grooming	✓		✓
Wavelength assignment	✓		✓
WDM multiplexing	✓	✓	✓
<b>End nodes</b>			
Encapsulation	✓	✓	✓
Electrical switching	✓	✓	✓
Grooming	✓	✓	✓
Wavelength assignment	✓	✓	✓
WDM multiplexing	✓	✓	✓

Table 2.1: Transport mode comparation

## 2.3 Network Survivability

Dedicated or shared protection are two main types of survivability applied for protection at any layer. Shared protection requires less spare capacity, employing protection reserved capacity for multiple working paths. A network planned for shared protection are feasible if the working paths that share the protection capacity have no links or intermediate nodes in common. This process is typically more vulnerable to multiple failures and slower to recover from a failure .

In dedicated protection backup resources are needed even before the failure occurrence. Depending on backup paths state, there will be two categories of dedicated path protection. In 1+1 mode, the backup path available is active, so both independent paths are transmitting at the same time and the choice of which is the best is the responsibility of the destination node. In opposition, the 1:1 dedicated protection activates the backup path, just in case of a failure on the primary path. After network restore, routes involved on previous failure may return to primary path (revertive mode) or proceed in backup path (non-revertive mode). In the following chapters will be proposed ways to implement dedicated path protection [19, 20].

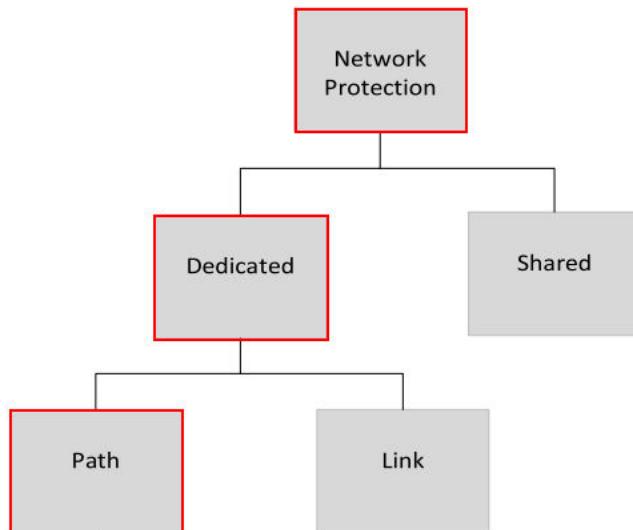


Figure 2.10: Network protection scheme

## 2.4 Chapter summary

In terms of optical networking design, there are two basic concepts, physical and logical topologies. The physical topology is the physical component of the network and how they are arranged, while the logical topology is how they work in terms of connection between the elements. Different types of logical topology in the same physical topology may have advantages or disadvantages desired by the network designer.

Logical topologies are related to how the optical signal is propagated. The signal can cross the nodes without being converted to the electrical domain (transparent), thus saving on the electrical components, and still be converted to the electrical domain and aggregate with other signals that cross the same next link, optimizing the bandwidth of the optical channels and saving on the optical components. It can even be a mixture of the other two topologies combining the advantages of both. In network planning it is extremely important to consider protecting traffic from failures. The protection can be shared, thus saving on the resources assigned for protection, or can be dedicated by assigning the resources before the failure occurs, preventing any failure in nodes or links of the working path. Then, based on the characteristics necessary for the network, different logical topologies may be more useful.



## Chapter 3

# Integer Linear Programming Models

Study of problems in which it is intended to minimize or maximize a function subject to a set of constraints is called optimization. Optimization models have a specific number of variables and constraints dependent on the problem to be solved. In telecommunications, ILP models are used to design networks describing real components and their capacities through a set of linear equations and inequalities. Despite the quality of the solutions obtained through the ILP models, depending on the number of variables and computational resources, the results of the ILP models can take days, months or even years [21]. The focus of the current chapter is to propose and describe two optimization models, based on opaque and transparent transport mode with protection. In section 3.1, is described a reference network protection topological design problem, including the definition of variables and inputs of the model and problem description. In section 3.2.1, it is proposed in detail the constraints of the opaque model with dedicated path protection as well as the objective function of the dimensioning problem. In accordance, the next section 3.2.2 is where the model of opaque transport mode will take place. In section 3.3, it is a brief approach to how an ILP model can be implemented through the LPsolve package. In section 3.4, will be the results of the models considering homogeneous and heterogeneous traffic while varying the number of demands. Then, the last section 3.5 contains a succinct summary of the chapter with the most important concepts.

### 3.1 Network protection topological design problem

The development of an ILP model requires first the definition of the inputs, outputs and variables of the problem in a mathematical representation. Then, let's consider a network consisting of a set of nodes,  $V = \{1, \dots, n\}$ , and a set of bidirectional links connecting nodes,  $L = \{\{i,j\} : i, j \in V, i < j\}$ . Network node connections are in the form of an adjacency matrix called  $G_{i,j}$ . The client traffic demands from each origin node to the destination are also in matrix form:  $D_{od} = \{[o, d] : o, d \in V, o < d\}$ . For each type of client traffic, it must be created a bidirectional demand matrix  $D_{od}$ . The result of the sum of this matrices is a 3-dimensional matrix  $D_{cod}$ , depending on client traffic type in Gb/s,  $c = \{1.25, 2.5, 10, 40, 100\}$ . Thereby, it will be considered the reference network below as an example of a smaller network where ILP approach will be tested.

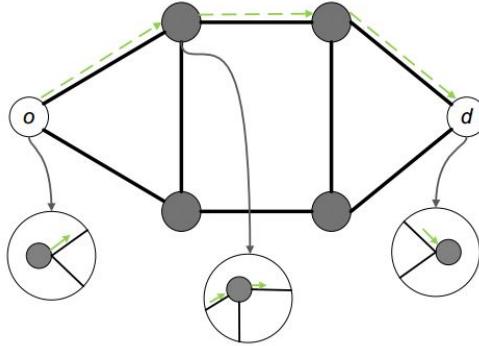


Figure 3.1: Traffic demand path from node "o" to node "d"

The traffic demands go through one or more links to reach their destination and it is assumed that the path between node  $o$  and  $d$  is the same as the path between node  $d$  and  $o$ . Therefore, considering dedicated path protection, the integer variable  $f_{ij}^{od}$  indicates how many flows starting at  $o$  and ending in  $d$  cross the link  $(i, j)$ . Thus, to be consistent,  $f_{ji}^{od}$  indicates if the link  $(i, j)$  is used in the reverse direction between nodes  $(o, d)$ . A demand of traffic requires a reserved capacity in each transmission system depending on the type of client traffic ( $c$ ). For instance, if there are four traffic demands at 40 Gb/s, so a bandwidth of 160 Gb/s will have to be reserved. Otherwise, in this dissertation will be considered line ports capable of transmitting at 100Gb/s. Each optical signal is composed by several optical channels and each optical channel has a corresponding wavelength. Then, variable  $W_{ij}$  is an integer variable indicating the number of 100 Gb/s optical channels between nodes  $i$  and  $j$ . Consequently, almost the same model may be applied for transparent transport mode, but this time using optical channels ( $W_{od}$ ) between end nodes instead of using optical channels link-by-link along the path. It is important to highlight that to reduce the computing time will be used bidirectional traffic matrices, i.e.,  $D_{cod} = D_{cod}^T$ .

	<b>Opaque</b>	<b>Transparent</b>
<b>Inputs</b>	$G_{i,j}$ $D_{cod}$	$G_{ij}$ $d$
<b>Variables</b>	$f_{ij}^{od}$ $f_{ji}^{od}$ $W_{ij}$	$t_{ij}^{od}$ $W_{od}$

Table 3.1: Inputs and variables of opaque and transparent transport modes

## 3.2 ILP models

Integer linear program approaches proposed below, follow the standard form. All decision variable values that satisfy the set of constraints are called admissible solutions, in the cases that the solutions set is finite and the decision variables are restricted to integer values, it is called Integer Linear Programming. The optimal solution to the problem will be the values of an admissible solution(s) that obtain the higher or lower objective function value. The main goal is then to determine the non-negative values of the decision variables, such that all the linear equations or inequalities are satisfied and the value of the objective function is maximized or minimized. The objective function is introduced by the keyword "*minimize*" or "*maximize*", and the set of the constraints are introduced by the expression "*subject to*". Therefore, in order to solve the optimization models, it is required a software as MATLAB to effect a solution. There are also optimization software packages such as IBM ILOG CPLEX Optimization Studio, GLPK or Gurobi Optimizer to simplify the optimization problem description. In this dissertation, LPsolve was the package used to solve optimization problems. Then, ILP models proposed along this dissertation will be described using this structure [22].

### 3.2.1 Opaque with 1+1 Protection

The objective function of following ILP is a minimization of the sum of two variables: total number of flows crossing link  $(i, j)$  for all demand pairs  $(o, d)$  and total number of optical channels in each link  $(i, j)$ .

$$\text{minimize} \quad \sum_{(i,j)} \sum_{(o,d)} f_{ij}^{od} + \sum_{(i,j)} W_{ij} \quad (3.1)$$

*subject to*

$$\sum_{j \setminus \{o\}} f_{ij}^{od} = 2 \quad \forall (o, d) : o < d, \forall i : i = o \quad (3.2)$$

$$\sum_{j \setminus \{o\}} f_{ij}^{od} = \sum_{j \setminus \{d\}} f_{ji}^{od} \quad \forall (o, d) : o < d, \forall i : i \neq o, d \quad (3.3)$$

$$\sum_{j \setminus \{d\}} f_{ji}^{od} = 2 \quad \forall (o, d) : o < d, \forall i : i = d \quad (3.4)$$

$$\sum_{(o,d):o < d} (f_{ij}^{od} + f_{ji}^{od}) + \sum_{c \in C} (B(c)D_{cod}) \leq 100W_{ij}G_{ij} \quad \forall (i, j) : i < j \quad (3.5)$$

$$W_{ij} \leq 80 \quad \forall (i, j) : i < j \quad (3.6)$$

$$f_{ij}^{od}, f_{ji}^{od} \in \{0, 2\} \quad \forall (i, j) : i < j, \forall (o, d) : o < d \quad (3.7)$$

$$W_{ij} \in \mathbb{N} \quad \forall (i, j) : i < j \quad (3.8)$$

The objective function, to be minimized, is the expression(3.1). The flow conservation constraints are (3.2), (3.3) and (3.4). First constraint ensures that, for all demand pairs  $(o,d)$ , it routes two flows of traffic for all bidirectional links  $(i,j)$  when "j" is not equal to the origin of the demand. Equation (3.4) is based on the same idea of (3.1), however applied in reverse direction. Assuming bidirectional traffic, so the number of flows in both directions of the link is the same (3.3). The inequality (3.5) is considered grooming constraint, so it means the total client traffic flows can not be greater than the capacity of optical channels on all links. Another important constraint (3.6) is the capacity of the optical channels which must be less or equal to 100 Gb/s or 80 ODU0. The number of flows per demand can be zero if there are no traffic demands or two if considering working and protection traffic (3.7). The last constraint is just needed to ensure the number optical of channels is a positive integer values greater than zero.

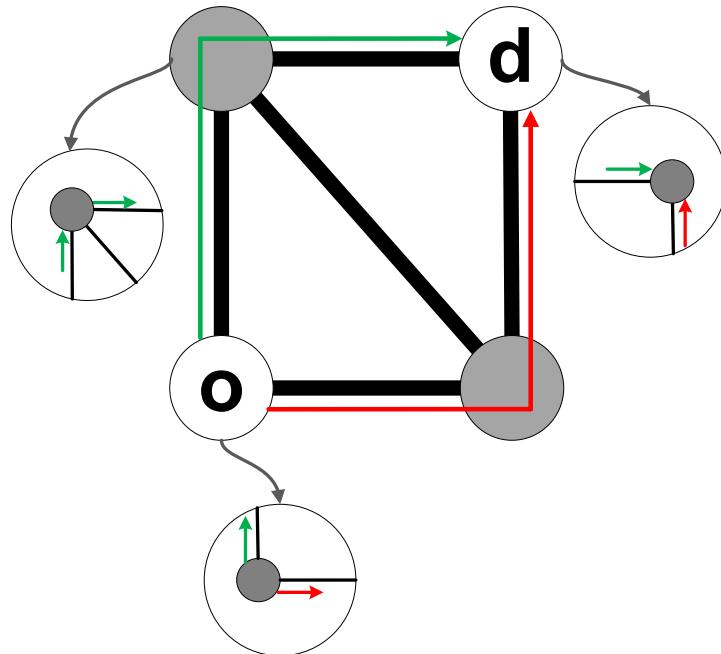


Figure 3.2: Example of two nodes in a network sending traffic through disjoint links

Constraints (3.2) and (3.4), was proposed to ensure that the flow used for protection should be different from working path. Figure 3.2 shows a signal being sent by disjoint paths as supposed in dedicated path protection. From client point of view, there is just a single flow from the origin to the destination, but as shown in the detailed view of the figure above, it's possible to verify that there is a flow arriving and another starting at each intermediate node.

### 3.2.2 Transparent with 1+1 Protection

The optimization model suggested for transparent transport mode with dedicated path protection intends to minimize the total number of flows crossing link  $(i, j)$  for all demand pairs  $(o, d)$ . The mathematical model described below also minimizes the total number of optical channels between each demand end nodes  $W_{od}$ , instead of minimizing the number of optical link-by-link channels as in the previous model.

$$\text{minimize} \quad \sum_{(i,j)} \sum_{(o,d)} f_{ij}^{od} + \sum_{(o,d)} W_{od} \quad (3.9)$$

subject to

$$\sum_{j \setminus \{o\}} f_{ij}^{od} = 2 \quad \forall (o, d) : o < d, \forall i : i = o \quad (3.10)$$

$$\sum_{j \setminus \{o\}} f_{ij}^{od} = \sum_{j \setminus \{d\}} f_{ji}^{od} \quad \forall (o, d) : o < d, \forall i : i \neq o, d \quad (3.11)$$

$$\sum_{j \setminus \{d\}} f_{ji}^{od} = 2 \quad \forall (o, d) : o < d, \forall i : i = d \quad (3.12)$$

$$\sum_{(o,d):o < d} (f_{ij}^{od} + f_{ji}^{od}) x W_{od} \leq 80 G_{ij} \quad \forall (i, j) : i < j \quad (3.13)$$

$$f_{ij}^{od}, f_{ji}^{od} \in \{0, 2\} \quad \forall (i, j) : i < j, \forall (o, d) : o < d \quad (3.14)$$

$$W_{od} \in \mathbb{N} \quad \forall (o, d) : o < d \quad (3.15)$$

The objective function, to be minimized, is the expression(3.9). The flow conservation is performed by equations (3.10), (3.11) and (3.12) and share the same mathematical description of opaque model. The inequality (3.13) answers capacity constraint problem. Then, total flows times the traffic of the demands must be less or equal to the capacity of network links. The grooming of this model can be done before routing since the traffic is aggregated just for demands between the same nodes, thus not depending on the routes. Last two constraints define the total number of flows must be zero if there is no demand, or two for a demand with traffic protection, and the number of optical channels must be a counting number.

### 3.3 LPSolve and Matlab implementation

Implementation of the models described in section 3.2 requires the use of mathematical software tools. Software chosen was MATLAB, since it is ideally suited to handle linear programming problems. The use of this powerful software allows declaration and definition of variables and constraints in an iterative and simplified procedure. Variables are written and stored into vector or matrices sorted by indices known by the developer and dependent on the network size. This computing resource can call LPsolve through an external interface or MEX-function. LPsolve is used to resolve linear programming problems when declared according to a specific structure, in this case, achieved through MATLAB. LPsolve is an optimization software package that reuses other free software components to make an integrated development environment (IDE). The use of this IDE allows solving ILPs in a user-friendly graphical interface, thus making it easier to debug problems. The control of LPsolve is provided by mxlpsolve driver which is allowed to operate with data sent through an application programming interface (API).

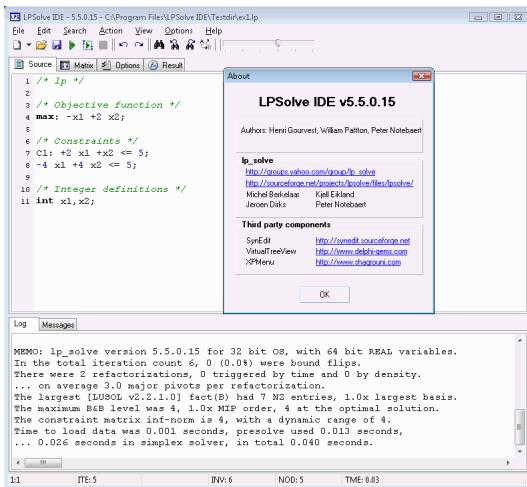


Figure 3.3: LPsolve integrated development interface

Optimization models presented in section 3.2.1 and 3.2.2 should be written on programming format imposed by mxlpsolve driver, then the following steps have to be followed [23]:

1. Create and initialize the new model with total number of variables.
2. Set the coefficients of the objective function.
3. Add the constraint vector with the coefficients and independent terms.
4. Set variable types.
5. Write ILP to an .lp file
6. Solve the model
7. Returns the value of the objective function
8. Returns the value of the variables

The first step is to declare the model and send the total number of problem variables to the solver. Thereafter, it is needed to send the objective function coefficients using the appropriate API function. Then, the driver is called iteratively sending as arguments the name of the function to add a constraint, the correct indexes of the variables vector, the corresponding equality or inequality and the independent terms. It makes it possible to define all constraints of the problem. Regarding problem description, the last step is to set variables type according to the mathematical model. Hence, in order to simplify the visualization, it is advisable to write the model to a file that can be opened in LPsolve IDE. Finally, it is necessary to instruct the solver to resolve the problem and to return the results.

### 3.4 ILP results

The presentation and analysis of the results of the model 3.2.1 and 3.2.2 are consummated during this section. The models will be tested with homogeneous and heterogeneous traffic, changing the number of demands or fluctuating the client traffic type (lower to higher bandwidth). The results for opaque and transparent models are shown using, respectively, blue and green bars. All results were obtained considering the reference network. The model was not applied to a real network because the execution time would be protracted.

Then, starting with homogeneous client traffic from the lowest to the highest bandwidth, the following results were obtained:

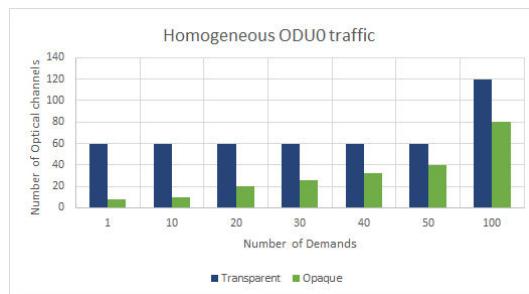


Figure 3.4: ILP solution for ODU0 client traffic

Considering a low number of demands the result of transparent model is exaggeratedly high. When there is only one traffic demand, sixty optical channels are required, since the network has six nodes and there is a demand from each node to the other five and the same number of demands for protection.

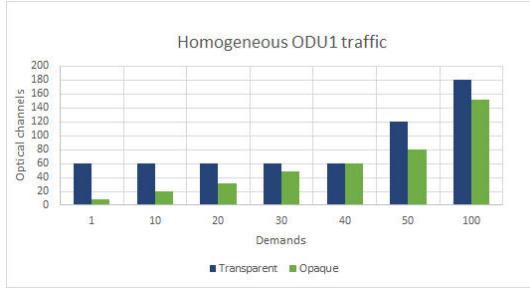


Figure 3.5: ILP solution for ODU1 client traffic

The analysis of results for ODU0 (1.25 Gb/s) client traffic is almost the same as for ODU1 traffic (2.5 Gb/s). A result to be highlighted is the number of optical channels for 40 demands of traffic. If there are 40 demands at 2.5Gb/s, then it performs 100Gb/s which is the capacity of each optical channel. So, traffic aggregation is impossible because all optical channels are completely occupied.

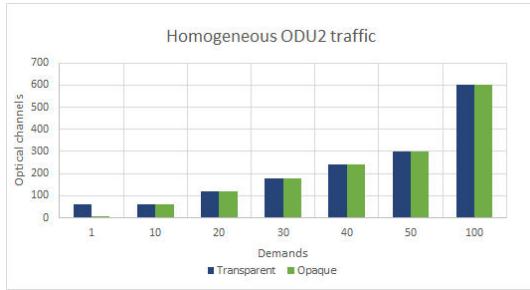


Figure 3.6: ILP solution for ODU2 client traffic

Both ILP models has approximately the same performance. As expected, the results sending one demand of traffic ODU2 (10Gb/s) are much better using opaque transport mode. When the number of demands is a multiple of 10, traffic between each node pair is a multiple of 100 (optical channel capacity), so link-by-link grooming has the same result as grooming only in end nodes.

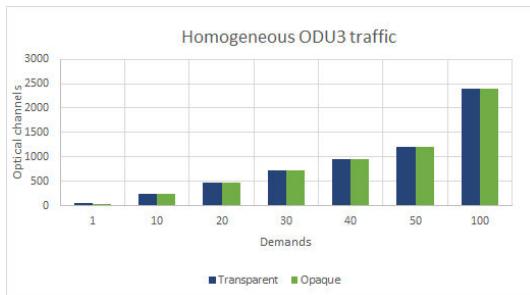


Figure 3.7: ILP solution for ODU3 client traffic

Figure 3.7 shows the behaviour of the algorithm for ODU3 (40Gb/s) traffic. The reasons why opaque and transparent models have practically the same results are mentioned above. It is important to note that 100 demands of ODU3 traffic are approximately 4Tb/s of traffic. When the number of optical channels required in a network is the same for both models, transparent is cheaper than opaque since some electrical components are not needed at intermediate nodes and the propagation of optical signals are faster. Wilfully, results for demands at 100Gb/s (ODU4) are not necessary since the demands has the same bandwidth as optical channels capacity, then there is no traffic aggregation.

After analysing and detailing the results for each client traffic and changing the number of demands, it is necessary to see the results from another point of view.

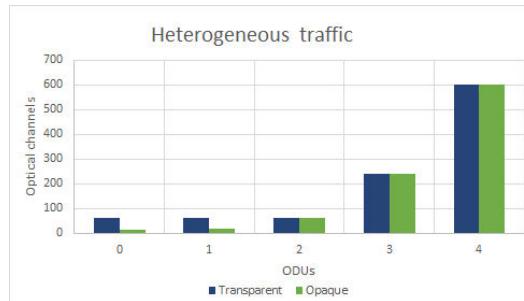


Figure 3.8: ILP solution changing client traffic type

Then, setting number of demands constant and changing the type of traffic, the number of optical channels has a big leap for client traffic based on demands of ODU3 and ODU4 traffic. Transparent model has 8 times more optical channels for signals with the lowest bandwidth.

### 3.5 Chapter Summary

In sum, this chapter was dedicated to the introduction of linear programming concept. In order to understand the meaning of mathematical models, all models used were described in the first section. The description of proposed integer linear problems in mathematical form as well as the use of optimization packages and their specific syntax are essential for the developer. Finally, the results prove the efficiency of opaque model for lower bandwidth traffic and a small difference when client traffic has higher bandwidth. In cases where the number of optical channels is lower, it will be beneficial to use an opaque network, however when the number of optical channels is similar to the transparent network, transparent network is cheaper and the signals take less time to reach their destinations.



## Chapter 4

# Heuristics

Heuristic approaches are techniques for solving a problem, faster than optimal methods and able to find an acceptable solution. Heuristics can be applied in several problems and are widely used in computer science and telecommunication networks [24, 25]. There are some commonly used heuristics such as genetic algorithm or simulated annealing. When networks are too large, the ILP models can be very slow to obtain the solution. In this chapter, algorithms are proposed based on heuristics and their implementation in a networks design software. The software was chosen for being open source and, consequently, easy to employ in academic projects. The grooming and routing algorithms presented in this chapter involve a graphical user interface developed for Net2Plan tool. Thus, section 4.1 is an overview of the routing algorithm, starting by trying to find the protection and work paths used by grooming algorithm. Aggregation algorithm is proposed in section 4.2. Routing and grooming algorithms are the core of the code behind the graphical user interface and focus in all the steps required for an offline simulation. In section 4.3 there is a description of how the program works, the developers involved in the program and a brief approach to the interface from creating traffic matrices and network topology (inputs) until obtaining the number of necessary ports of the designed network. Concerning publication of the results, node features and most expensive components are depicted on the last subsection. In section 4.4, the algorithms proposed in previous sections are tested and compared with those of the previous chapter. Finally, the last section is a brief summary of the principal terms to retain.

## 4.1 Heuristic routing

Regarding the heuristic approach, an algorithm for routing and grooming was implemented, which will be explained in three steps. The pseudo code will be shown in a flowchart using rounded rectangle shapes to symbolize the beginning and the end of the program, the parallelogram shape indicates a point where there is input to or output from the program, the diamond shape symbolizing a decision point, the rectangle shape indicating the assignment of a value to a variable, constant or parameter, and the hexagon shows the beginning of a repetition.

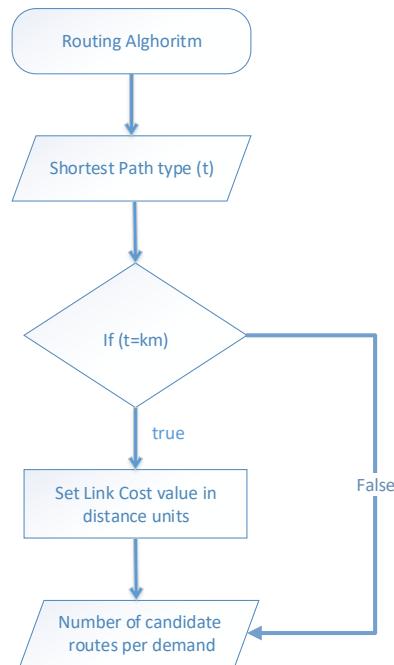


Figure 4.1: Heuristic routing algorithm code flow

Routing algorithm begins with the definition of the input parameter. The variable "t" is an input variable, which is defined by the user. The previous variable can assume two possible values: "hops" or "km". If the units of distance are the number kilometres, then it is necessary to assign a virtual cost to the links that will be used, in order to decrease the computing time of the algorithm used to find the shortest path. Through the Dijkstra algorithm the paths sorted by distance units are added to a list and ordered by node pair. The number of candidate routes per node pair depends on the user, and can be defined through graphical interface setting the corresponding variable. The performance of the algorithm can be compromised if the number of routes or the network topology is too large.

Once the list of candidate routes has been filled, it is necessary to find the primary and protection paths for each demand. So, for each demand will run the code below.

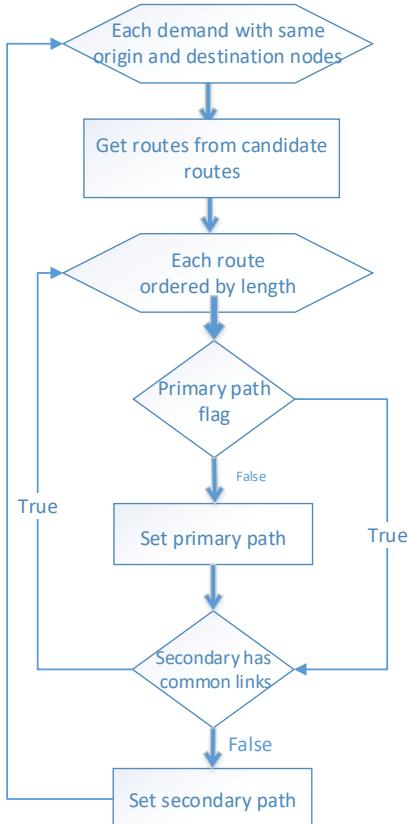


Figure 4.2: Heuristic routing algorithm code flow

The second step of routing algorithm begins with the search of candidate routes for the demand. The routes are analysed one by one, starting from the smallest to the largest. Then, the first (shortest) is the primary path and this must be set if the flag is disabled. If the primary path flag is enabled, the program flow jumps to the decision point to verify if the route does not have links in common with the first path. Then, if it is verified, the protection path is the current route. On the other hand, if the route has at least a common link, the next step is to try another route. The routing ends when the protection path of the last demand was found.

## 4.2 Heuristic grooming

After traffic routing decision, the consequent step is traffic aggregation. The algorithm begins by getting the routes (primary and protection path) already saved for each node pair. The input parameter of this algorithm is the type of grooming desired, which is represented in the flowchart as " $g$ ".

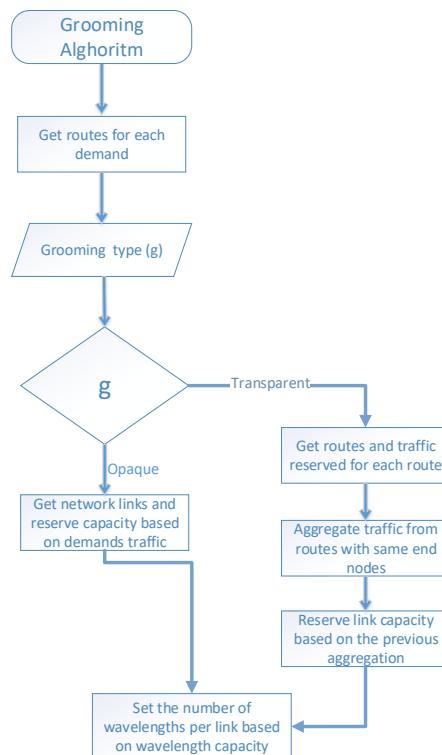


Figure 4.3: Heuristic grooming algorithm code flow

The consequence of the proposed type of grooming is the branch of flowchart. In Opaque form, the procedure starts by obtaining all links and the capacity based on traffic per demand. The sum of traffic that crosses the same link gives the information of carried traffic. After traffic aggregation, dividing the total carried traffic by the wavelength capacity it is possible to get the number of wavelengths (line ports) in each node. Although, if logical topology is Transparent the plan of action is different. The branch starts by getting reserved traffic capacity in each path. Then, using routes from different demands with common end nodes it aggregates the traffic of these routes. After this step, knowing the links that constitute the path, it is reserved the capacity required in each link. In order to know the number of wavelengths, the reserved traffic capacity in each link needs to be divided by wavelength

capacity as in the previous grooming type. Obviously, these flowcharts are simplified schemes which express as much as possible the complexity of hundreds of lines of code.

### 4.3 Net2Plan Aproach

The Net2Plan tool began in 2011, with the aim of being used as a material for educational in Universidad Politcnica de Cartagena. At this time, there are already many simulators available for network planning as, for example, SIMTON, OPNET, NIST Merlin or TONetS [2]. Up to now, the lastest version of Net2Plan tool is version 0.4.0. All algoritms were developed in JAVA language, and the specific algoritms presented in this dissertation were developed using Eclipse for JAVA developers IDE. The first step to start the simulation is the creation of traffic matrices.

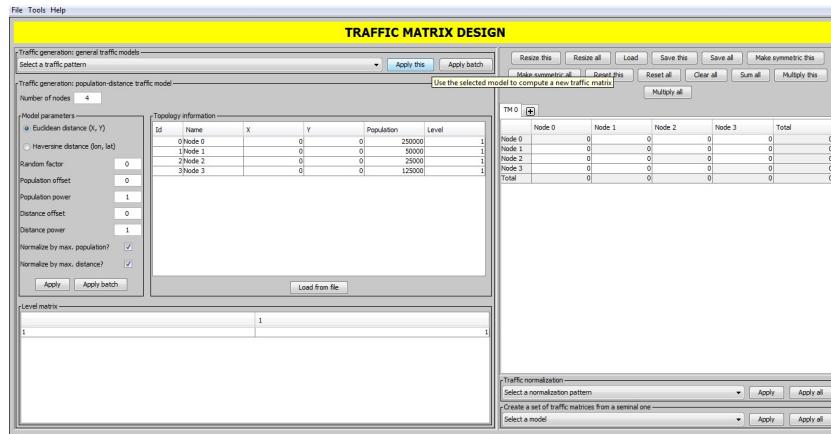


Figure 4.4: Net2Plan user interface for traffic matrices creation

The matrices created can be defined as a matrix with constant traffic, so the amount of traffic between all node pairs are the same. Another possibility is to choose randomly the traffic for each demand and there is also an option to choose automatically the number of nodes and the traffic amount, or define them manually as parameters. The results presented in this dissertation are obtained defining matrices manually to ensure that the ILPS and heuristics have the same inputs. After the matrices creation for each type of client bit rate (ODU0, ODU1...) is needed a network topological design.

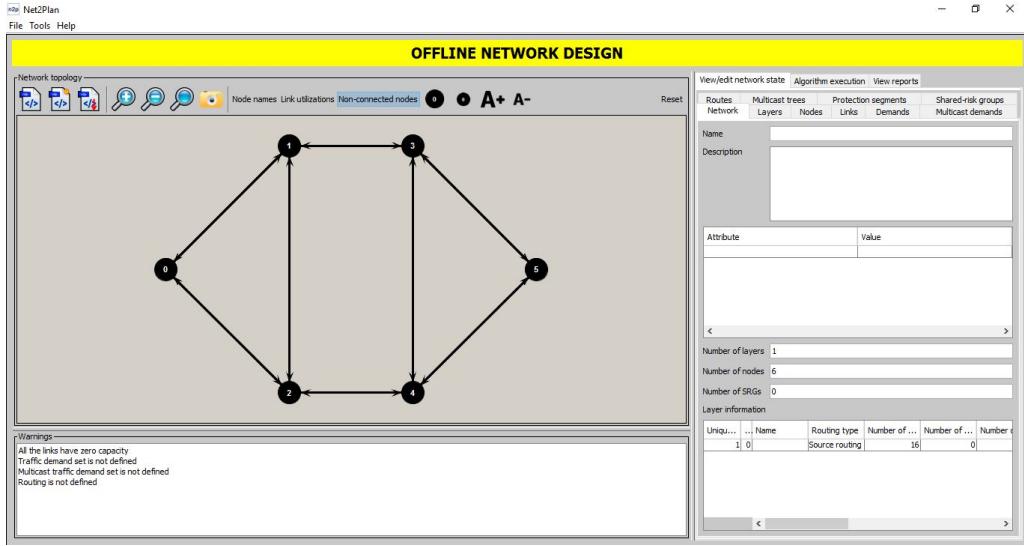


Figure 4.5: Net2Plan user interface for reference network topological design

In figure 5.2 it is shown how the real network suggested in chapter 3 is designed in Net2Plan. Each black narrow symbolizes a bidirectional link. Once created the design of the network and the traffic matrices defined all inputs are set. Thus, the network is ready for routing and grooming.

#### 4.3.1 Join Traffic Matrices Alghoritm

Having the basic physical topology created, the next step is to load the demand set into the network. In the case where there are multiple traffic matrices an algorithm was developed to aggregate these, in order for it to be possible to load all demands. In order to deal with different client traffic in OTN units, it was developed the "*joinTrafficMatrices*" algorithm to convert all traffic matrices to ODU0. Besides converting the different ones to ODU0 it also creates an attribute in each demand indicating the type of signal before converting.

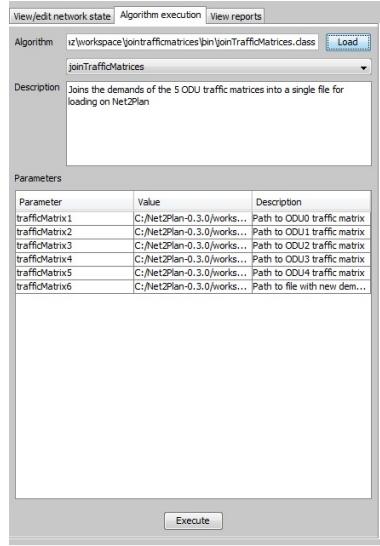


Figure 4.6: Net2Plan join traffic matrices alghoritm input parameters

As shown in figure 4.6 above, using five different paths for the client traffic matrices in ODU0, ODU1, ODU2, ODU3 and ODU4 as inputs and the last path to save the resultant demand set, is possible to create a matrix with total traffic regarding the original client traffic type. Thus, to set all network design inputs is just needed to load the demand traffic set to the network topology previously designed.

#### 4.3.2 Logical Topology Alghoritm

The "*logicalTopology*" algorithm accepts only one input parameter and it creates a new layer depending on the transport mode chosen. This step is needed before network routing and grooming, because these two operations depend on the logical topology of the network. Besides creating this new Layer, the algorithm also copies the demands to that layer and defines the logical links based on the length of the physical ones.

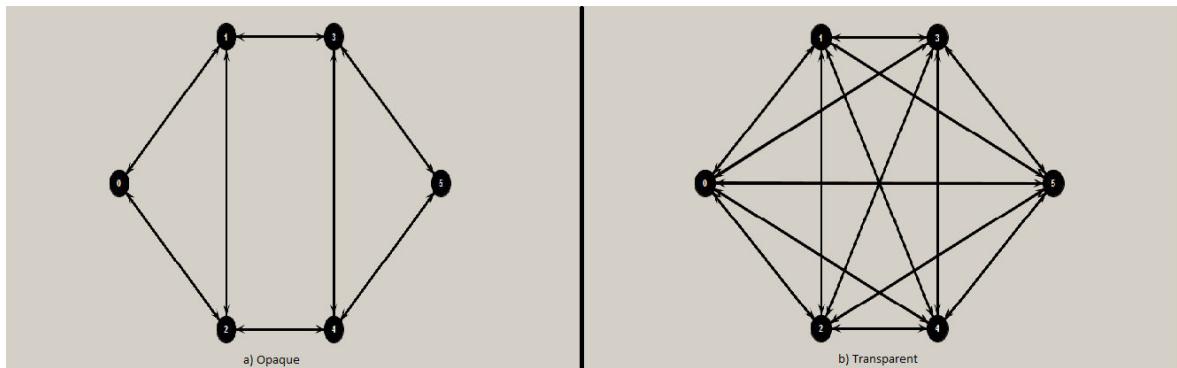


Figure 4.7: Net2Plan logical topology for reference network physical topology based on a) Opaque transport mode b)Transparent transport mode

As depicted in figure 5.3, an Opaque transport mode the traffic goes through an OEO

conversion at every node and as such the logical topology is the same as the physical one. In the Transparent mode, there are no regeneration in intermediate nodes, so the logical topology shows that the traffic between nodes flows directly without grooming with signals from another source. Thus, in optical layer, for opaque transport mode the topology of the network are equal to the physic one and for transparent transport mode is a full mesh network topology.

#### 4.3.3 Grooming and Routing Alghoritm

In this section, it is presented an algorithm to perform grooming an routing with dedicated path protection scheme. This algorithms are based on reducing the number of wavelengths needed for the network to carry all traffic. One way to minimize the number of wavelengths is minimizing the number of links for each path between all node pairs. The consequence of the reduction of the number of links is to decrease the number of necessary transmission systems leading to a lower cost of nodes.

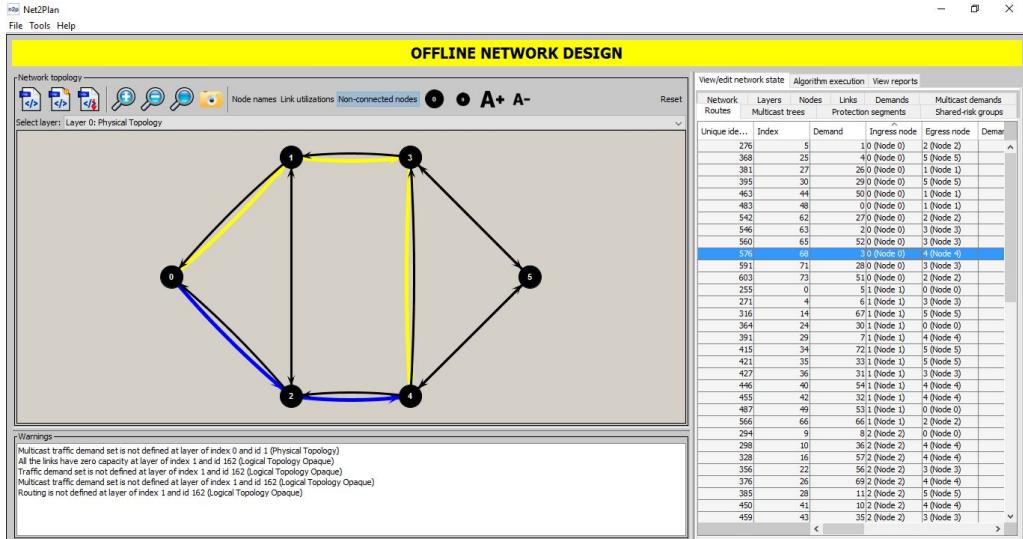


Figure 4.8: Net2Plan route using *grooming dedicated* alghoritm

Thus, this approach is done based on a shortest path algorithm where the routes for each demand are created based on the shortest number of hops needed to reach the destination node. The protection path for each demand, as shown in figure 4.8, is created using the same methodology, so the protection path is the second shortest loop disjoint path. The routes are made through the use of existing classes in Net2Plan, and the shortest path is computed using Dijkstra algorithm. The blue lines symbolize the working path and the protection segments are depicted in yellow. Grooming is different for the modes described above. Although, it is implemented in the same physical topology , i.e. the first layer in the program. The inputs, defined by network designer, of this algorithm are the number of routes computed per demand in order to find two disjoint shortest loopless paths and the wavelength capacity for each transmission system in ODU0.

#### 4.3.4 Reports

The display of results was also a concern in the development of algorithms, a report was created in HTML language that can be written to a file or open through web browsers. The *networkCost* algorithm, which has as inputs the elements with higher cost. The most expensive elements are optical ports and equipments (OLT, OXC and OXC ports, Transponders and amplifiers) and electrical ports and equipments (EXCs, EXC ports).

The number of optical channels is already calculated for each link in subsection 4.3.3 and, consequently, the number of transmission systems. Thus, in order to make a characterization of the links is required the number of optical amplifiers. The result, for instance, of link information in Net2Plan report for the reference network is:

Node Pair	Wavelengths forward	Wavelengths backward	Amplifiers forward	Amplifiers backward
Node 0 -> Node 1	2	2	5	5
Node 1 -> Node 0	2	2	5	5
Node 0 -> Node 2	2	2	5	5
Node 2 -> Node 0	2	2	5	5
Node 1 -> Node 2	4	4	3	3
Node 2 -> Node 1	4	4	3	3
Node 1 -> Node 3	3	3	3	3
Node 3 -> Node 1	3	3	3	3
Node 2 -> Node 4	3	3	3	3
Node 4 -> Node 2	3	3	3	3
Node 3 -> Node 4	3	3	3	3
Node 4 -> Node 3	3	3	3	3
Node 3 -> Node 5	3	3	5	5
Node 5 -> Node 3	3	3	5	5
Node 4 -> Node 5	3	3	5	5
Node 5 -> Node 4	3	3	5	5

Figure 4.9: Reference network link information using random traffic matrices

More information can be obtained on the reporting algorithms that will be detailed in next chapter.

## 4.4 Heuristic results validation

Heuristics are approximate results so their results when not compared to a solution taken as correct may be misleading. Thus, the algorithms were tested using the same inputs as ILP models and the results are presented through line graphs and compared with previously obtained bar graphs. The blue line is relative to the results for transparent transport mode and the yellow line for the opaque transport mode.

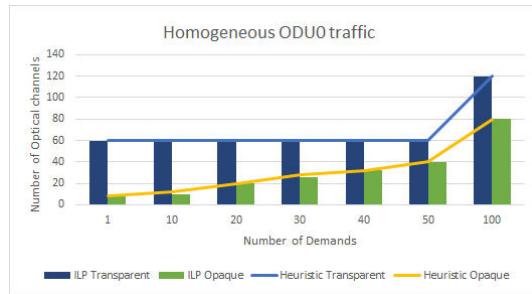


Figure 4.10: Heuristic solution for ODU0 client traffic

The figure above shows that even when grooming is done for small amounts of low-bandwidth traffic, the results are close. In the results of transparent transport mode, the line has exactly the same points as the graph which means that the traffic was aggregated through the same method. On the other hand, for opaque transport mode the results are slightly different, but as the number of demands increases the relative error suffers a huge decrease.

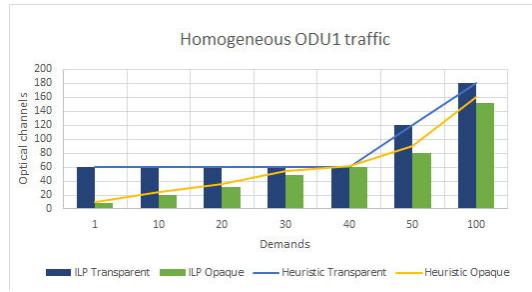


Figure 4.11: Heuristic solution for ODU1 client traffic

From the results for ODU1 traffic the same considerations are correct. Then, the comparative results are the same for transparent model and have small differences for opaque. The results for 40 demands are the same for all models and transport modes, because 40 demands requires 100Gb/s of bandwidth which is the total capacity of each optical channel, then there is no possible traffic aggregation.

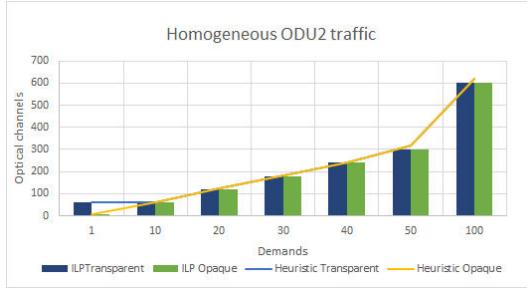


Figure 4.12: Heuristic solution for ODU2 client traffic

When demands at 10Gb/s are used the differences between ilps and heuristics are minimal and they are only visible when the number of demands is not a multiple of 10. When one demand is sent the opaque model is much more advantageous in terms of grooming for both approaches.

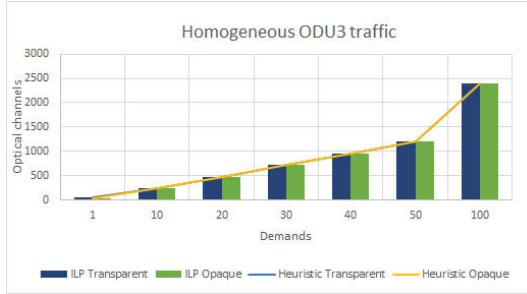


Figure 4.13: Heuristic solution for ODU3 client traffic

Traffic at 40Gb/s (ODU3) is high bandwidth traffic, therefore the aggregation in channels in 100Gb/s can not be done in different ways, so the results are approximately the same for both transport modes and methods. Sending 100 demands of traffic, it has 2500 optical channels which is a huge number and a consequence of the flow of 4Tb/s between each node pair.

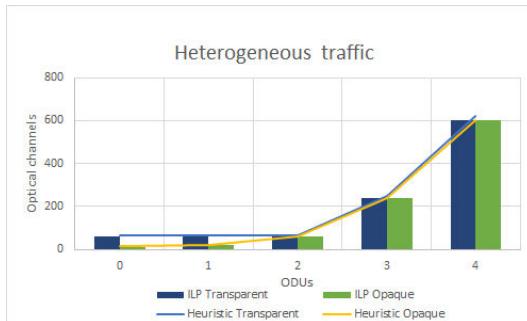


Figure 4.14: Heuristic comparative results for heterogeneous traffic

The last validation results were obtained applying heuristic methods in sex node reference network and changing client traffic type. Relative error between ILP solution and heuristic is less than 0.1. The number of optical channels for high bandwidth traffic is accordingly high.

## 4.5 Chapter Summary

In sum, the implementation of heuristics involves not only the creation of the algorithms but also their implementation in an open source software with graphical user interface called Net2Plan. This customized software has four algorithms developed in the context of this dissertation. The first is used for conversion of traffic matrices. The visualization of the network logical topology is performed by the second algorithm proposed. Routing and grooming algorithm is the core of the program. The code flow and graphical user interface of this algorithm can be seen in this chapter. The last customization made on net2plan concerns the presentation of results that is done in the reports section. Then, regarding the validation of the heuristic methods, in the last section is shown the comparative results between ILPs and Heuristics. The results of heuristics are in line with ILP results for homogeneous and heterogeneous traffic and using the six node reference network.

# Chapter 5

## Case Study

A network dimensioning software is used in the design of real networks. The cost of a network depends on the network size and capacity, but this huge investment from network stakeholders re-enforces the importance of network planning. There are networks created for research purposes and installed in the field. Then, to get results from a real network, it will be studied a network from United States known as NFSNET. The first section of this chapter is a network characterization in terms of physical network elements regarding their geographic location and the traffic matrix generated. In section 5.2 is presented an approach for network cost, considering the cost of links and the cost of nodes. This section has the equations used as the basis of network cost reports in Net2Plan. This equations perform network cost using as input the most expensive network components cost defined by the designer. In section 5.3, the results in terms of tributary and line ports and network cost of opaque transport mode are shown. The results of the transparent transport mode for the same matrix of traffic are described in the next section (5.4). The chapter ends, as in previous chapters, with a brief overview of all important information and results of the chapter.

## 5.1 NSFNET

After validating the quality of the algorithms implemented in Net2Plan, let's consider a realistic network. NSFNET refers to a program sponsored by National Science Foundation to support and foment advanced networking among United States research and education institutions. The way the nodes are geographically arranged can be seen from the figure 5.1.

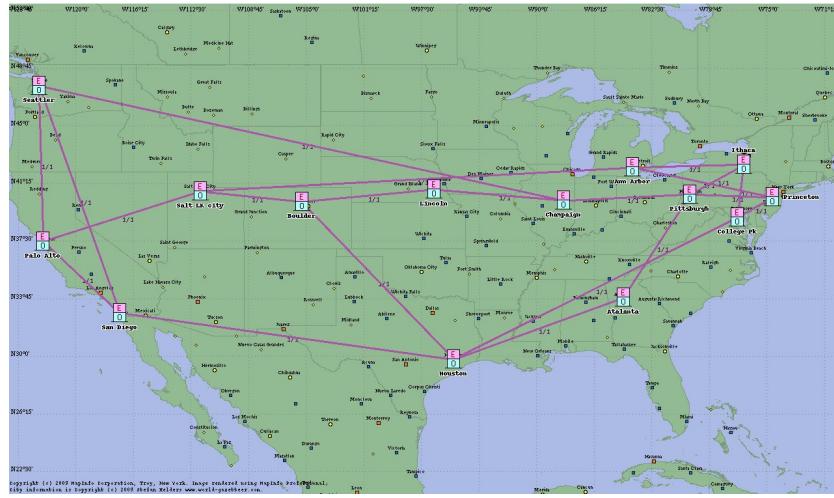


Figure 5.1: NSF Network topology [3].

The network represented above is composed of fourteen nodes and twenty one bidirectional links. The result of dividing the number of links per node by the number of nodes is the average degree of the nodes in this network. All nodes have less than four and more than two links, so major nodal degree is 4 and minor is 2. Then, there are no isolated nodes (node with only one connection) and it's important because the dedicated path protections requires disjoint paths, so each node must have at least two links. The maximum number of connections per node is also important because the larger it is, the fewer will be the number of hops suffered by each demand from the origin to the destination. Obviously, the number of links per node could be higher, but it would compromise the price to be paid for the network.

Constant	Description	Value
N	Number of Nodes	14
E	Number of Bidirectional Links	21
$\langle \delta \rangle$	Node out-degree (max,min, avg)	4,2,3.0
$\langle h \rangle$	Mean Number of Hops,for Working Paths	2.14
$\langle h' \rangle$	Mean Number of Hops,for Backup Paths	3.60
$\langle s \rangle$	Mean Link Length (km)	1086

To begin the analysis of traffic routing and aggregation it is necessary to consider the matrix of demands (D):

$$D = \begin{bmatrix} 0 & 12 & 34 & 15 & 12 & 54 & 12 & 12 & 43 & 12 & 12 & 23 & 12 & 11 \\ 12 & 0 & 60 & 12 & 35 & 12 & 23 & 20 & 12 & 36 & 12 & 23 & 33 & 13 \\ 34 & 60 & 0 & 15 & 12 & 12 & 12 & 18 & 14 & 12 & 21 & 23 & 12 & 12 \\ 15 & 12 & 15 & 0 & 21 & 18 & 12 & 12 & 43 & 12 & 12 & 23 & 12 & 11 \\ 12 & 35 & 12 & 21 & 0 & 12 & 12 & 12 & 29 & 12 & 12 & 26 & 12 & 15 \\ 54 & 12 & 12 & 18 & 12 & 0 & 42 & 30 & 12 & 12 & 21 & 12 & 30 & 84 \\ 12 & 23 & 12 & 12 & 12 & 42 & 0 & 30 & 48 & 12 & 12 & 14 & 9 & 54 \\ 12 & 20 & 18 & 30 & 12 & 30 & 30 & 0 & 12 & 48 & 12 & 60 & 30 & 72 \\ 43 & 12 & 14 & 25 & 29 & 12 & 48 & 12 & 0 & 12 & 12 & 54 & 12 & 66 \\ 12 & 12 & 21 & 12 & 12 & 21 & 12 & 12 & 12 & 12 & 0 & 12 & 12 & 12 \\ 23 & 23 & 24 & 12 & 26 & 12 & 14 & 60 & 54 & 12 & 12 & 0 & 12 & 12 \\ 12 & 33 & 12 & 19 & 12 & 30 & 9 & 30 & 12 & 36 & 12 & 12 & 0 & 11 \\ 11 & 13 & 12 & 11 & 15 & 84 & 54 & 72 & 66 & 12 & 12 & 12 & 11 & 0 \end{bmatrix}$$

This traffic matrix was generated randomly through Net2Plan. The total amount of traffic in the NFSNET network considering this demands matrix is 5Tb/s. It should be noted that the total number of columns and rows is equal to the number of nodes and the main diagonal of the matrix is composed of zeros since it does not make sense for a node to send traffic to itself. Once traffic has been defined, the next step is to upload the shape of the network to the dimensioning software.

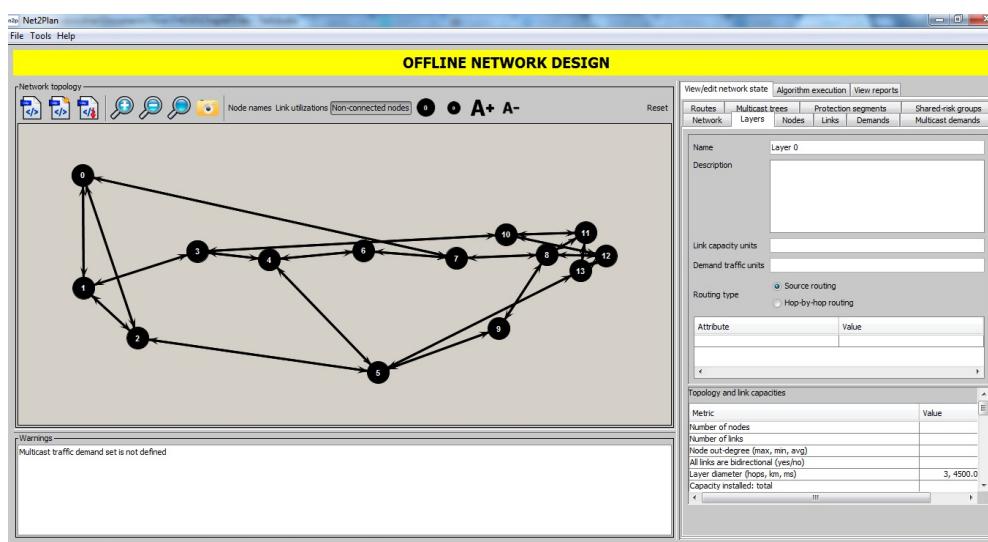


Figure 5.2: Net2Plan user interface for NSFNET topological network design

In the logical layer the network aspect for the Opaque and Transparent topology will be as follows:

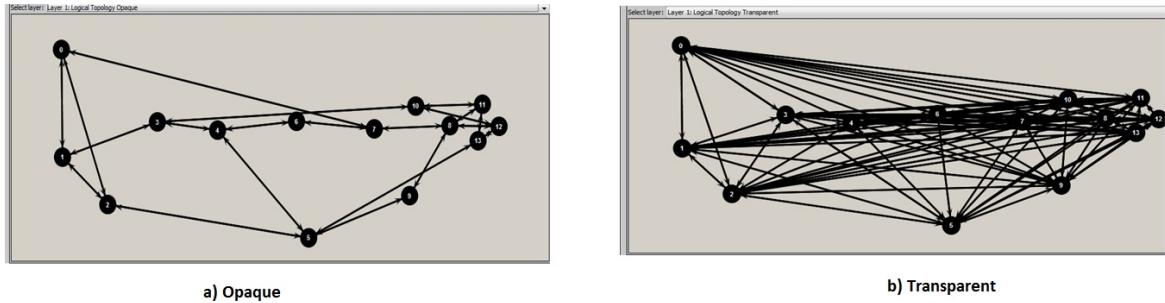


Figure 5.3: Net2Plan logical topology for NSFNET physical topology based on a) Opaque transport mode b)Transparent transport mode

All twenty one network links have the source and destination node attributes corresponding to the cities they belong, for instance, the link between node 0 and 2 has de attribute origin node equals to Seattle and destination San Diego. Obviously, to be consistent all nodes have the length attribute corresponding to the distance in kilometres they cross in the real context. Although there are 182 demands corresponding to traffic requests from each of the fourteen nodes to all the other thirteen, only 91 routes are needed because the path from "o" to "d" is assumed to be the same as "d" to". The computation of the routes obeys the same reasoning.

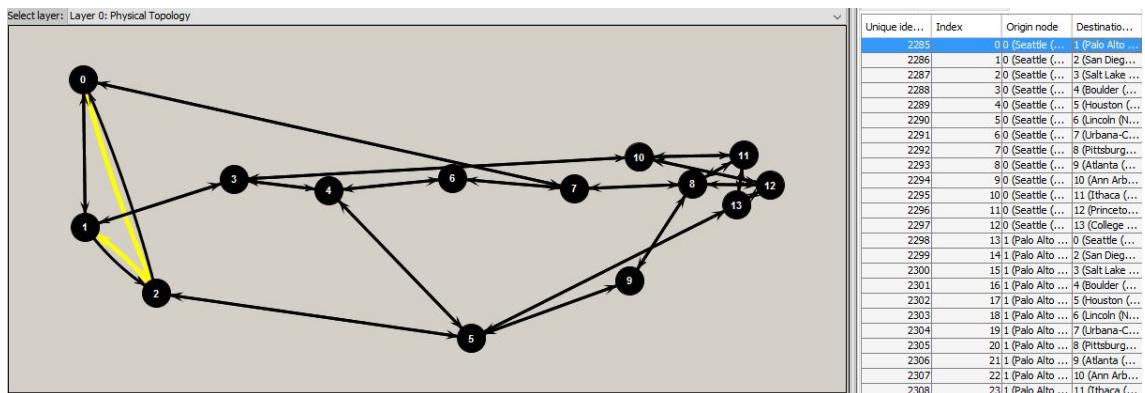


Figure 5.4: Protection traffic route between Seattle and Palo Alto

## 5.2 Network Cost

Regarding network cost, the approach will be based on three major factors: cost of the electrical part of the nodes, cost of the optical part of the nodes and cost of the links. Then, besides the equipment costs, this report also has the parameter *span*. The value of this variable is used to calculate the number of optical amplifiers needed in the network:

$$N^R = \sum_{l=1}^L \left( \left\lceil \frac{len_l}{span} \right\rceil - 1 \right) \quad (5.1)$$

- $N^R \rightarrow$  Total number of regenerators/amplifiers
- $len_l \rightarrow$  Length of link
- $span \rightarrow$  Distance between amplifiers

Thus, the number of regenerators or amplifiers is calculated based on the approximation (5.1). The equation means that the number of regenerators is given the division of the size of each link by the desired spacing between amplifiers minus one. The reason for the subtraction is to prevent the amplifier closer to the destination node from being unnecessary [26].

$$C_L = (\gamma_0^{OLT} \times L) + (\gamma_1^{OLT} \times \tau \times W) + (N^R \times c^R) \quad (5.2)$$

- $C_L \rightarrow$  Links Cost
- $\gamma_0^{OLT} \rightarrow$  OLT cost in Euros
- $L \rightarrow$  Number of unidirectional Links
- $\gamma_1^{OLT} \rightarrow$  Transponder cost in Euros
- $\tau \rightarrow$  Traffic per port
- $W \rightarrow$  Total number of optical channels
- $N^R \rightarrow$  Total number of optical amplifiers
- $c^R \rightarrow$  Optical amplifiers cost in Euros

The cost of links includes the transmission systems (OLT - Optical line termination) for each link plus a parcel depending on the optical channels and bandwidth summing with the number of amplifiers and their cost. After analysing how to calculate the cost of links, will be considered the approximation to the cost of nodes, starting with the electrical layer.

$$C_{exc} = (\gamma_{e0} \times N) + (\gamma_{e1} \times \tau \times 2 \times P_{TRIB}) \quad (5.3)$$

- $C_{exc}$  → Electrical Equipment Cost
- $\gamma_{e0}$  → EXC cost in Euros
- $N$  → Number of Nodes
- $\gamma_{e1}$  → EXC port cost in Euros per Gb/s
- $\tau$  → Traffic supported by optical channel
- $P_{TRIB}$  → Number of tributary ports

The equation (5.3) suggest the price of an electrical node based on the price of the electrical cross connect(electrical switching) for each node. In addition, there is a price that depends on the traffic that arrives at that node and consequently the number of ports. Then, the cost depends on the ports costs per Gb/s, the traffic per optical channel and 2 times the number of tributary ports because it's needed one for input client traffic and one for output at the node point of view. All of this equipment is used in opaque topology.

$$C_{oxc} = (\gamma_{o0} \times N) + \gamma_{o1} \times (P_{LINE} + P_{TRIB}) \quad (5.4)$$

- $C_{oxc}$  → Optical Equipment Cost
- $\gamma_{o0}$  → OXC cost in Euros
- $N$  → Number of Nodes
- $\gamma_{o1}$  → OXC port cost in Euros
- $P_{TRIB}$  → Number of tributary ports
- $P_{LINE}$  → Number of line ports

The equation (5.4) suggest the price of an optical node based on the price of the optical cross connect(optical switching) for each node. In addiction, there is a price depending on the cost of ports times the sum of tributary ports and the ports used to send an optical channel (line ports). Lastly, the price of node components and amplifiers span which will be the inputs of network cost are shown in the image below. It's difficult to know the real prices of network components, so the prices are just an approximation.

Parameter	Value	Description
EXC	10000	EXC cost in euros
EXCPort	1000	EXC port cost in euros per...
OLT	15000	OLT cost in euros
OXC	20000	OXC cost in euros
OXCPort	2500	OXC port cost in euros
Transponder	5000	Transponder cost in euros
opticalAmplifier	4000	Optical amplifier cost in euros
span	100	Separation between regenerators in kilometers

Figure 5.5: Network cost inputs

### 5.3 Opaque topology results

The consequences of the network designing can be seen in Net2Plan reports. As previous chapters the results for opaque transport mode are obtained first. So, using the traffic matrix proposed in the first section, the results in terms of tributary and line ports are:

Name	Trib ports in	Trib ports out	Line Ports in	Line Ports out	Total Ports in	Total Ports out
Seattle (WA)	5	5	21	21	26	26
Palo Alto (CA)	5	5	17	17	22	22
San Diego (CA)	5	5	19	19	24	24
Salt Lake City (UT)	4	4	22	22	26	26
Boulder (CO)	4	4	27	27	31	31
Houston (TX)	6	6	34	34	40	40
Lincoln (NE)	5	5	17	17	22	22
Urbana-Champaign (IL)	6	6	27	27	33	33
Pittsburgh (PA)	6	6	33	33	39	39
Atlanta (GA)	4	4	16	16	20	20
Ann Arbor (MI)	5	5	17	17	22	22
Ithaca (NY)	5	5	16	16	21	21
Princeton (NJ)	4	4	20	20	24	24
College Park (MD)	7	7	20	20	27	27
Total	71	71	306	306	377	377

Figure 5.6: Opaque ports per node

The number of ports per node for opaque transport mode. Tributary ports are the ports used for input traffic in a node from access networks. For instance, Seattle node requires 10 tributary ports because of bidirectional traffic. To send line signals is required line ports, two ports are required per line signal because signals considered are bidirectional also. The table above is given by reports algorithm and is the basis to calculate network cost.

Category		Cost	Total
Link Cost	OLT	630,000	155,278,000
	Transponders	153,000,000	
	Amplifiers	1,648,000	
Node Cost	Electrical	37,840,000	37,840,000
	Optical	0	
Total Network Cost		193,118,000	

Figure 5.7: Opaque cost given by Net2Plan

Figure 5.7 contains the table of the network cost for NFSNET and the input traffic of 5Tb/s. The important information, besides total cost, is the cost of optical switches which is equals to zero. The switching is performed in electrical domain, so the node cost is given by the electrical switching equipments. The number of transponders is proportional to the number of optical channels and the most expensive components. The total network cost in euros is 193,118,000 for the equipments price defined in previous chapter.

## 5.4 Transparent topology results

The results for transparent transport mode in NFSNET are shown in the current section. The number of input and output ports for each node and the network CAPEX given by the network design software are crucial information for network planning. Then, the results for the same traffic matrix are:

Name	Trib ports in	Trib ports out	Line Ports in	Line Ports out	Total Ports in	Total Ports out
Seattle (WA)	13	13	66	66	79	79
Palo Alto (CA)	13	13	64	64	77	77
San Diego (CA)	13	13	63	63	76	76
Salt Lake City (UT)	13	13	88	88	101	101
Boulder (CO)	13	13	96	96	109	109
Houston (TX)	14	14	120	120	134	134
Lincoln (NE)	13	13	53	53	66	66
Urbana-Champaign (IL)	13	13	87	87	100	100
Pittsburgh (PA)	13	13	103	103	116	116
Atlanta (GA)	13	13	53	53	66	66
Ann Arbor (MI)	13	13	68	68	81	81
Ithaca (NY)	13	13	55	55	68	68
Princeton (NJ)	13	13	72	72	85	85
College Park (MD)	14	14	70	70	84	84
Total	184	184	1058	1058	1242	1242

Figure 5.8: Transparent ports per node

An important information is the total number of ports. In opaque transport mode, the total number of ports were 377 and for transparent transport mode are 1242. Obviously, it will affect the cost of the network. The huge number of line ports is related with the grooming. The grooming link-by-link is more efficient than grooming in end nodes. Then, it is important to see the impact of the number of ports on the total cost of the network.

Category		Cost	Total
Link Cost	OLT	630,000	
	Transponders	529,000,000	531,278,000
	Amplifiers	1,648,000	
Node Cost	Electrical	36,940,000	
	Optical	3,385,000	40,325,000
Total Network Cost			571,603,000

Figure 5.9: Transparent cost given by Net2Plan

Unlike the previous model, this transport mode requires optical components in nodes. The total network cost in euros is 571,603,000 and comparing with opaque transport mode which is less than half of this value it shows how grooming is important. The number of transponders is almost five times more, because of the number of optical channels. The number of optical amplifiers for transparent and opaque transport modes is the same, because the physical links as the same length. Transparent transport mode requires less electrical switches than opaque transport mode, but the price to pay for less efficient grooming is great.

## 5.5 Chapter Summary

In summary, heuristic methods are crucial for network planning, since they can be applied in real networks. Despite there are several networks used for researching and academic studies, NFSNET was the option taken for testing in this work. This network from the United States of America has fourteen nodes and twenty one links, making it more generic and useful for testing. Applying both transport modes and the algorithms proposed on previous chapter, it is possible to obtain an estimation of the network ports per node and cost. It is also possible to conclude that, in general, opaque networks are cheaper than transparent networks, but this is not true when the number of optical channels is equal in both transport modes. The signal propagation is faster in transparent transport mode, then depending on the network requirements, the most efficient model may vary.

# Chapter 6

## Conclusions and future directions

### 6.1 Conclusions

Through this dissertation the optical network design problem was studied having dedicated path protection insight. The same physical topology may have several logical topologies, choosing for further study opaque and transparent types. For each logical topology approach an ILP model was developed. These models contain a set of constraints used to minimize or maximize an objective function, in order to find an optimal solution. Both ILP models proposed were implemented using a mathematical software and an open source solver, and both of them were tested in a reference network, with the comparison results being shown and analysed during chapter 3. Having ILP results as optimal solutions for the dimensioning problem, heuristic approaches were then developed to find similar solutions for the same problems.

The main advantage of using heuristics is the save in processing time. Then, in chapter 4, a set of algorithms capable of being implemented in an open source software with graphical user interface was proposed. The results obtained through the algorithms were compared with those obtained by ILP models to verify their quality. The relative error was not considerably high, so the algorithms could be a good solution for the real network design problem. By the end, in chapter 5, the heuristic solution was applied to a real network which is used primarily for academic and research purposes. The results of this test, in a more real environment, revealed some advantages in terms of cost for the opaque network, since grooming is more efficient. However, from the results of the previous chapters, it is known that when the number of channels is equal in both models it is advantageous to choose the transparent model, as it is cheaper to implement and is able to achieve a faster signal transmission. As it can be verified in the results section of the chapter 5, optical network has a huge CAPEX so it is important to invest in the improvement of the dimensioning tools to minimize the required resources.

## 6.2 Future directions

Through this dissertation it was clearly shown the importance of network planning in a world with an increasing number of digital devices requiring faster and infallible interconnections. While data is exponentially growing and its transport means everything, this dissertation gives way to a new exploration work which should be stopped here. There is always space for improvement especially when optimization is involved. Some of the most important topics are presented below:

1. Heuristics and ILP tested in this dissertation with transparent and opaque networks can be applied in the future to different transport types, making it possible to evaluate advantages and disadvantages of choosing translucent transport.
2. Regarding protection methods, there are also several options that should be taken into account affecting directly the network planning. The usage of shared protection or dedicated link protection may also be considered and tested. The combination of transport type and protection type create a whole new range of options which might come up as a better solution for some specific situation.
3. The customization and the inclusion of new features in Net2Plan would ease the testing process and retrieve results quicker.
4. A GIT repository was already created during this dissertation. There the existing code was released, as well as a document, shown in appendices, which explains in detail how to generate algorithms to be used in Net2Plan. Giving continuity to this repository also composes an important part of the future work, ensuring code organization and a well-documented investigation.

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# Appendices

# NetPlanner

University of Aveiro

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# 1 Installing Net2Plan and its main options

This first section will describe how to install Net2Plan and some of the solvers usable by it as well as the main program preferences available.

## 1.1 Net2Plan download and installation

Before downloading Net2Plan, the first step is verifying if the computer has the necessary Java Runtime Environment, it is recommended the latest release (Version 8). This can be download from the java website at <https://java.com/en/download/>. The Java Runtime Environment is necessary as Net2Plan was coded in Java.

Having installed the Java Environment it is now possible to install Net2Plan. The download is available on its website at <http://net2plan.com/download.php>. The files just need to be extracted and the program can be run without an installation by just double clicking on the file "Net2Plan.jar". The latest Net2Plan version available at the time this report was revised is 0.4.2 from July 22nd, 2016



Figure 1: Net2Plan Opening Menu

## 1.2 Net2Plan Options and installing solvers

To access the main Net2Plan options click "File → Options". In this window the global parameters for simulations can be changed if needed. For example, an important option to note in this tab is the parameter "defaultRunnableCodePath", whose value should be the path to the jar file containing NetPlanner algorithms. As will be explained further on, Net2Plan is an open source tool and as such, new algorithms can be implemented and the default path can be changed to the path where those will be available instead of loading them manually each time Net2Plan is opened. The remaining parameters are related to solver options, which are the default external solvers used and also the path in which the ".dll", ".so", ".dylib" files of each solver are available. By default there is no path for each solver but in this case it was already changed to where the solvers were installed.

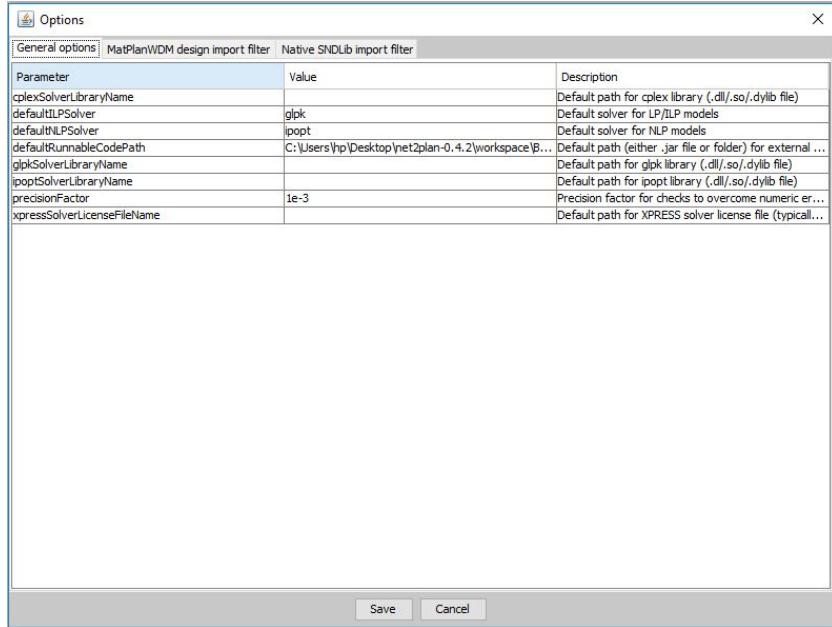


Figure 2: Net2Plan General Options

These external solvers are not extracted along with Net2Plan and as such, need to be downloaded if needed for the algorithms to be used. As "cplex" is a paid application, only the other two solvers will be shown as the process is similar.

The "IPOPT" solver can be downloaded from <http://www.coin-or.org/download/source/Ipopt/>. There are various choices available to download but for this case the *.dll* is the main file needed. An example of an algorithm which uses this solver is shown on Figure 3. Note that the "solverLibraryName" has the path shown earlier on the "Solver options" tab, this would have to be added manually if not introduced into the main options.

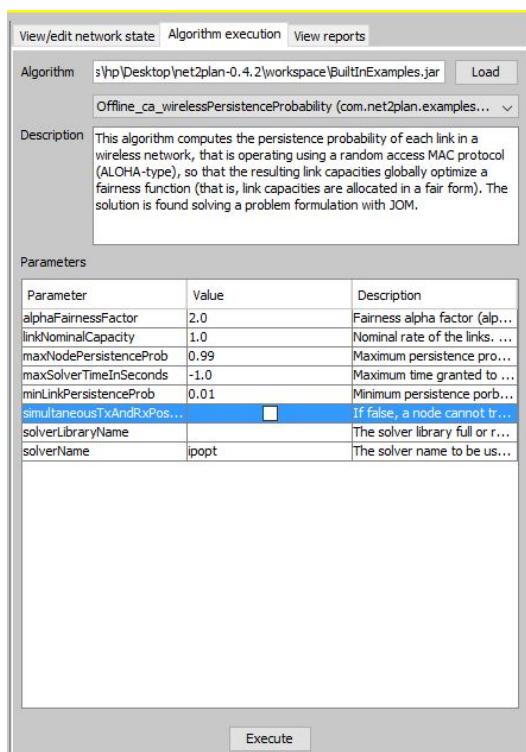


Figure 3: Net2Plan Algorithm with *ipopt* solver

The other free solver also used by some Net2Plan is "glpk", this one can be downloaded from [http://sourceforge.net/projects/winglpk/?source=typ\\_redirect](http://sourceforge.net/projects/winglpk/?source=typ_redirect). An example is shown on Figure 4. Again note the path shows up as in the options.

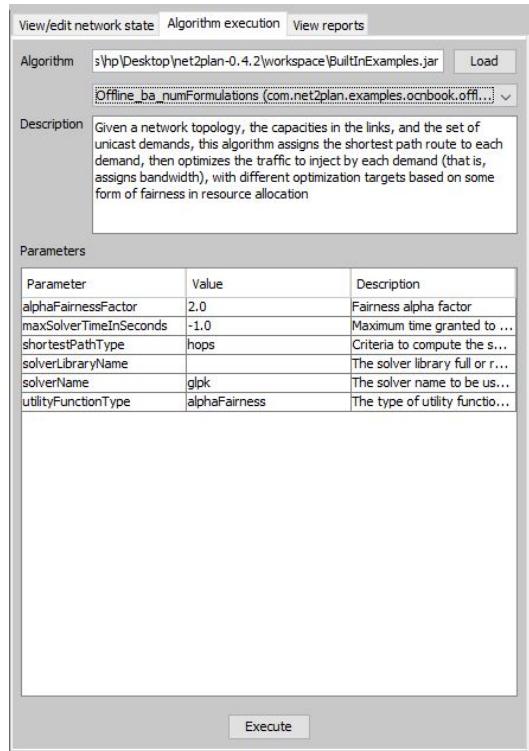


Figure 4: Net2Plan Algorithm with *glpk* solver

## 2 Net2Plan Tools

This section will describe in some detail the tools presented in Net2Plan as a network planner, most notably how to created a traffic matrix, design a network and some of the simulation options available.

### 2.1 Creating Traffic Matrices

To start creating a traffic matrix in Net2Plan go to "Tools → Traffic matrix design" or press *Alt + 2*. The traffic matrix menu is shown on Figure 5.

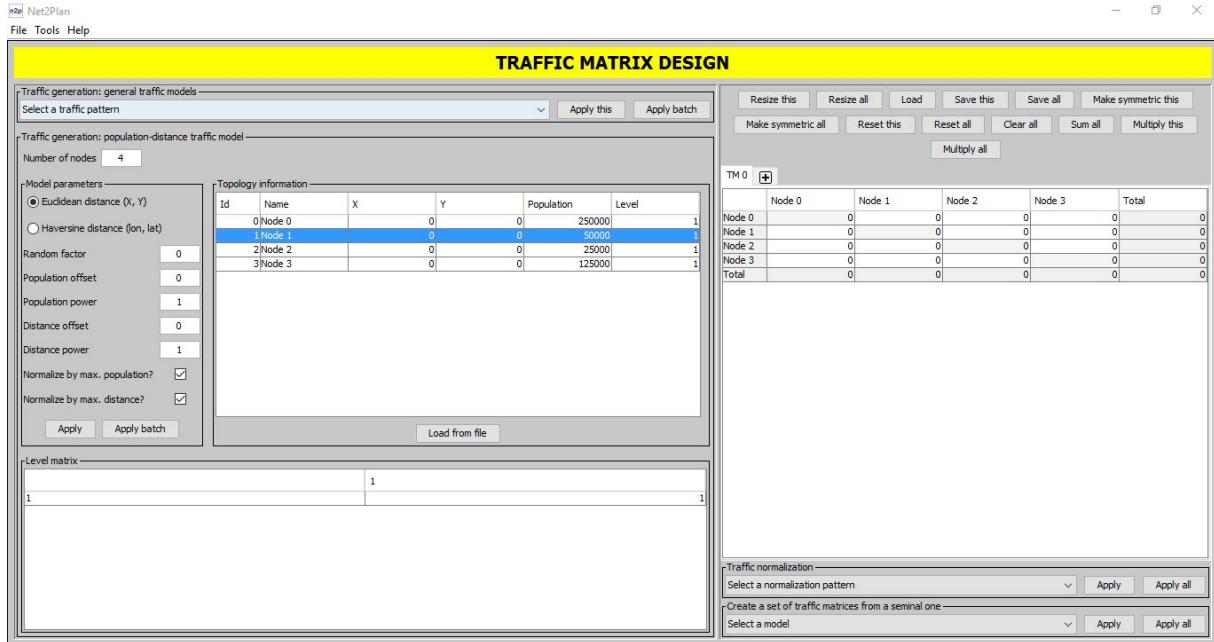


Figure 5: Net2Plan Traffic Matrix Design

On the top left side a traffic pattern can be chosen for one matrix or several if used the "Apply batch" option.

- "Constant" has two parameters the number of nodes and a constant value. This creates an uniform matrix with the number of nodes chosen and traffic equal to the value selected.
- "Uniform (0,10)" has the number of nodes and the option of being symmetric as the parameters. The matrix then has the number of nodes introduced and an amount of traffic chosen randomly between 0 and 10 which can be symmetric or not depending on the choice done.
- "Uniform (0,100)" is very similar to the other uniform option whereas in this case the traffic values are chosen randomly between 0 and 100.
- "50% Uniform (0,100) & 50% Uniform (0,10)" and "25% Uniform (0,100) & 75% Uniform (0,10)" are as expected a mixture of the previous two options.
- "Gravity model" in this option a number of nodes is chosen as well as the amount of traffic both generated and received by each node. The sum of the traffic generated by all the nodes needs to be equal to the sum of the traffic received by them.

Below the traffic pattern options, an existing model can be loaded and additional parameters defined such as Population and Node Level.

On the right side a traffic matrix can be created manually by defining the number of nodes on "resize this" and the amount of traffic can be typed on each demand. The other options above the

matrix are self explanatory, for example, "multiply this" multiplies all the traffic by a constant number chosen. A point to note is that most options has an "all" choice as it is possible to have more then one matrix created.

Below the matrix part are two further options available for the matrices, the first one is the option to select a normalization pattern such as "Total normalization" where a total number of traffic can be chosen for the network and the demands are adapted to it accordingly. The other option is to create a set of matrices based on the designed one.

Figure 6 shows how to create batch of matrices with constant traffic.

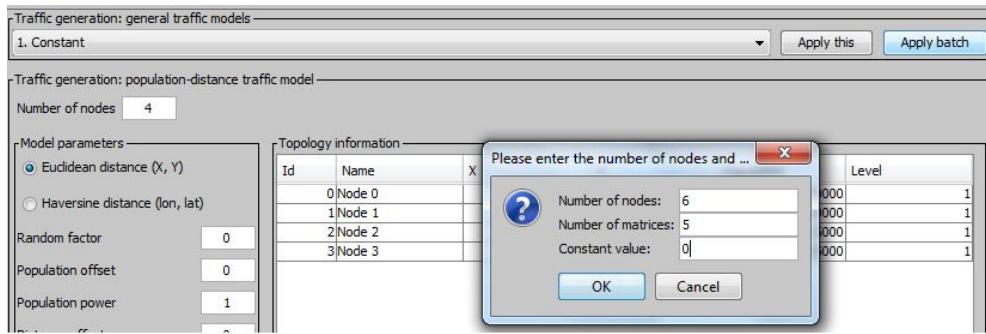


Figure 6: Net2Plan example on creating a batch of matrices

Using this option, 5 traffic matrices for a 6 node network were created all with a constant value of 1 as can be seen on figure 7 that shows the first matrix of the batch.

	Node 0	Node 1	Node 2	Node 3	Node 4	Node 5	Total
Node 0	0	1	1	1	1	1	5
Node 1	1	0	1	1	1	1	5
Node 2	1	1	0	1	1	1	5
Node 3	1	1	1	0	1	1	5
Node 4	1	1	1	1	0	1	5
Node 5	1	1	1	1	1	0	5
Total	5	5	5	5	5	5	30

Figure 7: Net2Plan Traffic Matrix Example

This example demonstrates how several different types of traffic can be introduced for a network by creating different matrices for each. These can then be saved individually and will further on be used as traffic matrices for ODU's 0 through 4.

## 2.2 Creating the Network topologies

To start with the Network creation tools in Net2Plan go to "Tools → Offline network design" or press *Alt + 1*. The network design menu is shown on Figure 8.

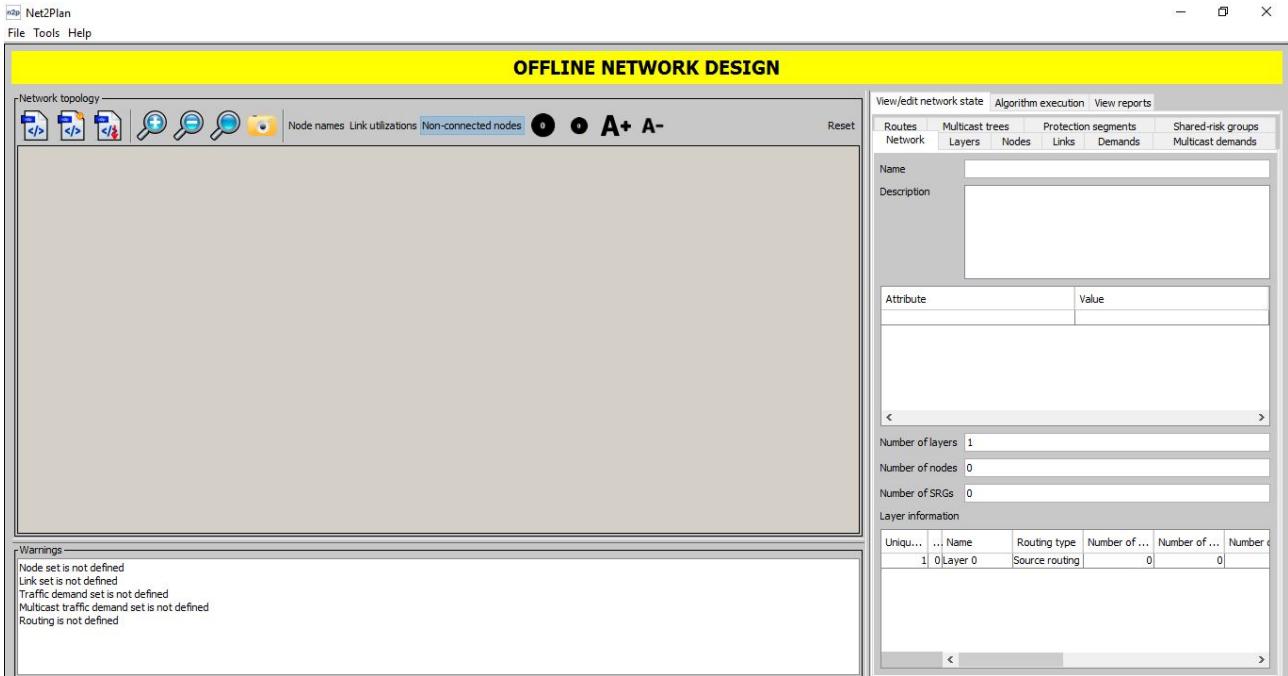


Figure 8: Net2Plan Offline Network Design

On the left side, the network topology part has the option to load an existing design and demand set or a new one can be created. To start creating a new network, first nodes have to be introduced by right clicking on the grey area and choosing "Add node here". Links between nodes are created by holding a click on the origin node and dragging until the destination node, holding shift before releasing the click creates 2 links, one in each direction. Another option to create links is to right click on an existing node and choosing the desired create a link option. Nodes can be moved by holding control and dragging them into the desired position.

Below the network topology is the "Warnings" box where the parts missing from having a functional network are displayed. For example if the nodes and links where already created it should say "traffic demand set is not defined" and "Routing is not defined" as these were still not introduced.

The whole right side of the network design menu are the parameters separated into various tabs which will be explored further on in this document. Besides these tabs, there is also the tab for Algorithm execution where the network is modified based on built algorithms, for example a routing algorithm and the View reports tab where information on the network can be displayed from built in reports.

Figure 9 demonstrates an example of the 6 node and 16 links network created using the tools explained above. As can be seen on the image at the warning tab, this network sill has several steps left to become a fully functional network. The link capacity will be defined based on the routing algorithm chosen and the demand set will be loaded based on the matrices created.

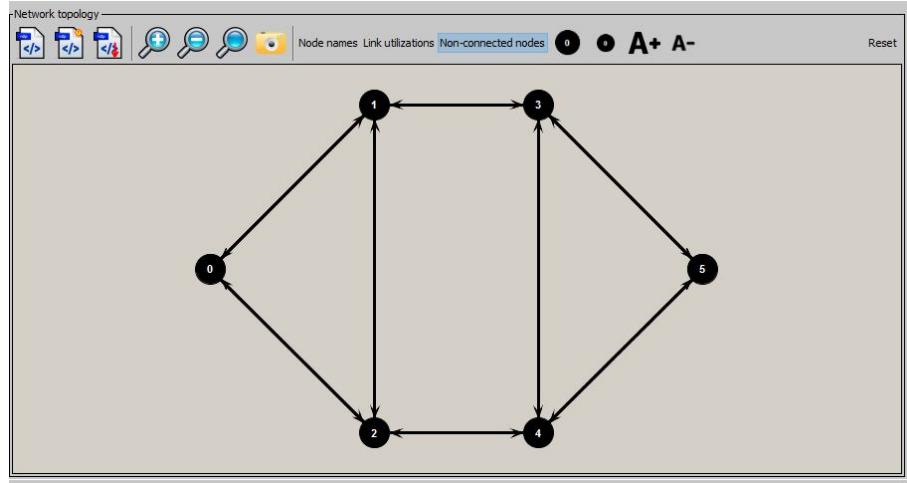


Figure 9: Net2Plan Network Example

The links and nodes parameters created for the network can be visualized and modified as seen on Figures 10(a) and 10(b) displaying the tabs for each case.

View/edit network state						Algorithm execution		View reports	
Routes		Multicast trees		Protection segments		Shared-risk groups			
Network	Layers	Nodes	Links	Demand	Multicast demands				
Unique ide...	Index	Show/Hide		Origin node	Destinatio...	State			
8	0	<input checked="" type="checkbox"/>		0 (Node 0)	1 (Node 1)	<input checked="" type="checkbox"/>			
9	1	<input checked="" type="checkbox"/>		1 (Node 1)	0 (Node 0)	<input checked="" type="checkbox"/>			
10	2	<input checked="" type="checkbox"/>		0 (Node 0)	2 (Node 2)	<input checked="" type="checkbox"/>			
11	3	<input checked="" type="checkbox"/>		2 (Node 2)	0 (Node 0)	<input checked="" type="checkbox"/>			
12	4	<input checked="" type="checkbox"/>		1 (Node 1)	2 (Node 2)	<input checked="" type="checkbox"/>			
13	5	<input checked="" type="checkbox"/>		2 (Node 2)	1 (Node 1)	<input checked="" type="checkbox"/>			
14	6	<input checked="" type="checkbox"/>		1 (Node 1)	3 (Node 3)	<input checked="" type="checkbox"/>			
15	7	<input checked="" type="checkbox"/>		3 (Node 3)	1 (Node 1)	<input checked="" type="checkbox"/>			
16	8	<input checked="" type="checkbox"/>		2 (Node 2)	4 (Node 4)	<input checked="" type="checkbox"/>			
17	9	<input checked="" type="checkbox"/>		4 (Node 4)	2 (Node 2)	<input checked="" type="checkbox"/>			
18	10	<input checked="" type="checkbox"/>		3 (Node 3)	4 (Node 4)	<input checked="" type="checkbox"/>			
19	11	<input checked="" type="checkbox"/>		4 (Node 4)	3 (Node 3)	<input checked="" type="checkbox"/>			
20	12	<input checked="" type="checkbox"/>		3 (Node 3)	5 (Node 5)	<input checked="" type="checkbox"/>			
21	13	<input checked="" type="checkbox"/>		5 (Node 5)	3 (Node 3)	<input checked="" type="checkbox"/>			
22	14	<input checked="" type="checkbox"/>		4 (Node 4)	5 (Node 5)	<input checked="" type="checkbox"/>			
23	15	<input checked="" type="checkbox"/>		5 (Node 5)	4 (Node 4)	<input checked="" type="checkbox"/>			

(a)

(b)

Figure 10: Network a) Nodes tab ; b) Links tab

On the Nodes tab most of the parameters are still 0 as there is no traffic on the network but there are three parameters that can be changed here. A node name can be set and both x and y coordinates can be defined as a more thorough alternative to define the node position.

On the links tab, again most is at 0 at this moment while the parameters that can be manually set are the link capacity, at 0 until defined and the link length which was set to the same value in every link.

Having the basic physical topology created, the next step is to load the demand set into the network. In the case where there are multiple traffic matrices an algorithm was developed to aggregate these in order for it to be possible to load all demands. For traffic matrices with ODU signals, an algorithm called "joinTrafficMatrices" can aggregate the different ODUs and convert them to ODU0 in order to have all the traffic in the same units. Besides converting the different ones to ODU0 it also creates an attribute in each demand indicating the type of signal before converting. This attribute can be seen on the demands tab after loading the resulting demand list. Figure 11 shows the algorithm to be used.

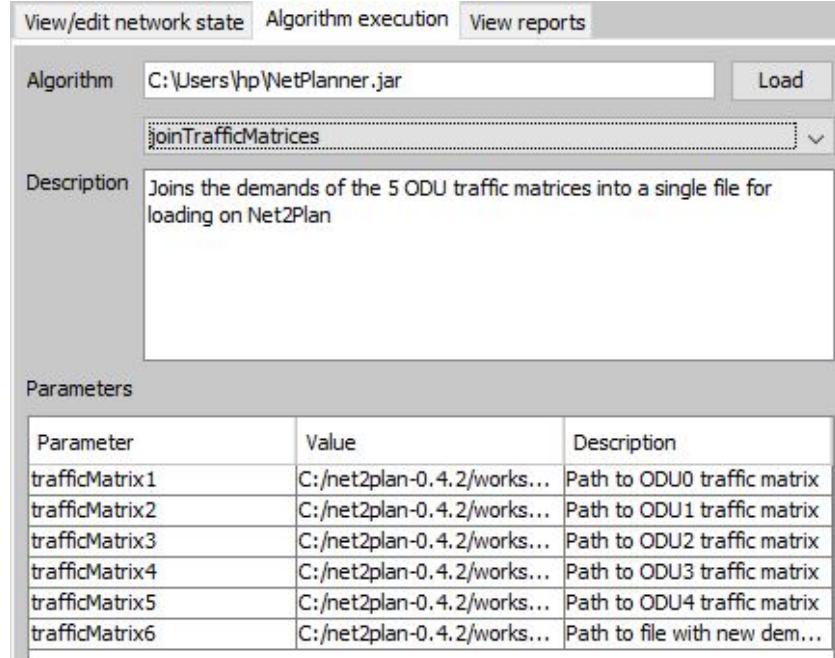


Figure 11: joinTrafficMatrices Algorithm

As can be seen on Figure 11 there are 6 user defined parameters, the first five are the paths for the traffic matrices to be aggregated in order, as said in the description. The last parameter is the resulting demand list that can then be loaded into the network.

The paths are by default defined considering Net2Plan is on C: and the matrices are in the default directory where they are saved. Lastly, the name of the files are in order ODU0.n2p through ODU4.n2p. All the path and file names can be changed to where the matrices are saved taking into account that just the order of the ODUs needs to be kept due to the conversion to ODU0 units.

To load the resulting demands into the created network the second icon on top of the network topology called "Load a demand traffic set" is used. After this, the warning tab changes from "Traffic demand set not defined" to "Traffic losses: Not all the traffic is being carried". This new warning indicates that the demand are in the network but as the routes have not yet been defined the traffic is not being transported.

In the demands tab, all the traffic that was created will be displayed in order of ODU type. For this case as all matrices were unitary and uniform, there are thirty demands with offered traffic 1 which is the ODU0 matrix and then consecutively groups of 30 demands (6 nodes) with offered traffic based on the ODU type (5 matrices). For example, an ODU1 is equivalent to two ODU0 so these demands have 2 in offered traffic and an attribute called ODU with value 1.

Before going into the network routing, the network transport mode needs to be defined by creating a logical topology. An algorithm was developed that creates a new layer consisting on this topology depending on the transport mode chosen. This algorithm can be seen on Figure 12.

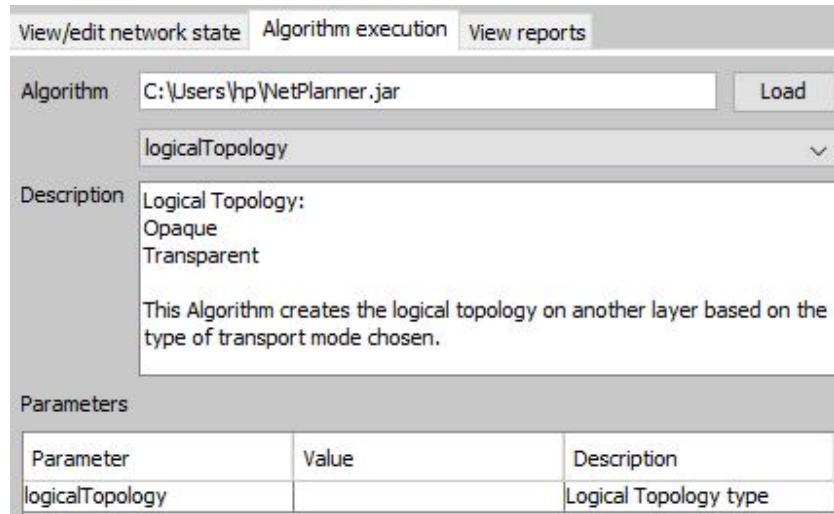


Figure 12: Net2Plan Logical Topology Algorithm

There are two user defined parameters on this algorithm. The "logicalTopology" parameter defines the type of transport mode, Opaque or Transparent.

Besides creating this new Layer, the algorithm also copies the demands to that layer and defines the logical links based on the length of the physical ones. Figures 13(a), 13(b) demonstrate the resulting logical topologies for each transport mode.

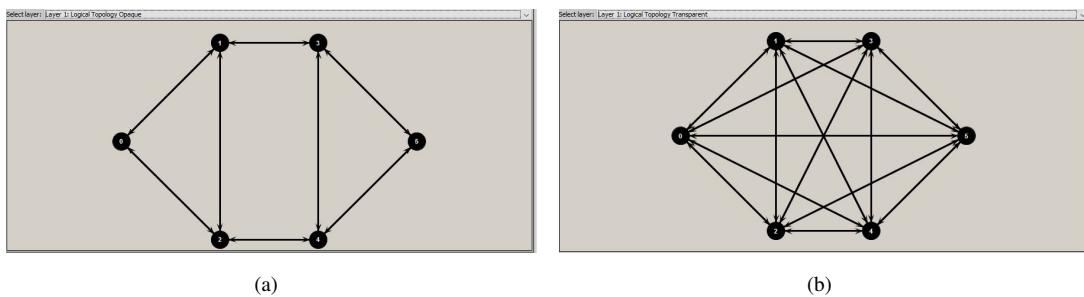


Figure 13: Logical Topology: a) Opaque; b) Transparent;

As can be seen on the logical topologies, for an Opaque transport mode the traffic goes through an OEO conversion at every node and as such the logical topology is the same as the physical one.

In the Transparent mode, there are no regeneration in intermediate nodes and as such the logical topology shows that the traffic between nodes flows directly without grooming with signals from another source.

## 2.3 Routing and Grooming

In this section, different routing and grooming options will be discussed for both a network without protection and using a 1+1 protection scheme (dedicated path protection).

The routing will be done based on a shortest path algorithm where the routes for each demand are created based one either the shortest number of hops needed to reach the destination node or by shortest distance in km. The option can be chosen as a user defined parameter on the algorithm as can be seen on Figure 14. This algorithm does the routing in both the logical and physical topologies based on the transport mode chosen and makes sure routes are bidirectional meaning the route from node  $o$  to  $d$  should be the opposite direction of node  $d$  to  $o$  as there could be different routes with the shortest path that are not using the same path.

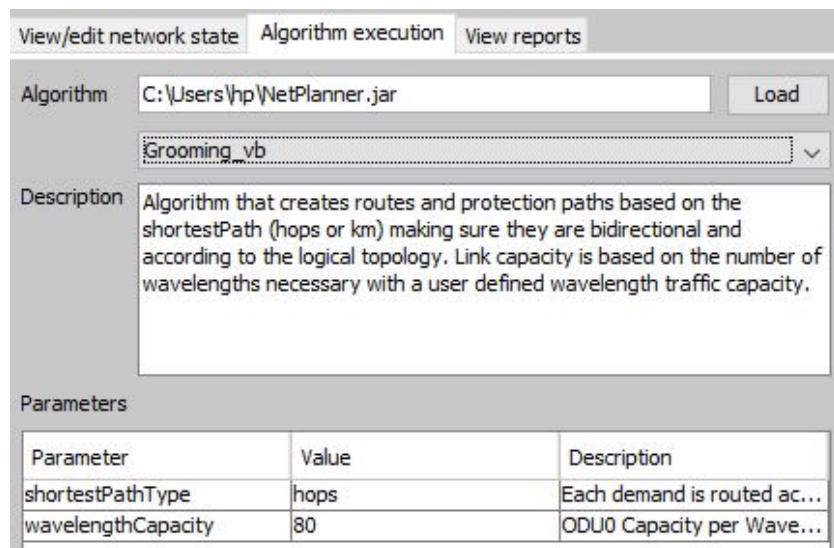


Figure 14: Net2Plan Grooming shortest Path Algorithm

Besides the metric through which the shortest path is calculated, the other available parameter defines the amount of ODU0s each wavelength is capable of carrying. By default it is set for 80 ODU0s as it is equal to an ODU4 or 100 Gbit/s.

The protection segments similarly to the routes have their own tab where information on their path, route it protects and such can be observed.

## 2.4 Reports

As looking separately at each tab to obtain information for different parts of the network is a slow process and does not show some important metrics, Net2Plan allows for the creation of reports where in a similar way to algorithms they can be adjusted to display the information needed, these can also be seen in html format for an easier read. In this section, the report developed will be demonstrated.

A very important aspect in network planning that is not present natively in Net2Plan is a Network Cost report. To fulfil this gap, a report was created to obtain the network Capex based on user defined equipment costs present on Table 1.

Equipment	Costs
OLT	15000€
Transponder	5000€/GB
Optical Amplifier	4000€
EXC	10000€
OXC	20000€
EXC Port	1000€/GB/s
OXC Port	2500€/port

Table 1: Equipment Costs

These Equipment costs are introduced into a report as user defined parameters as can be seen on Figure 15.

The screenshot shows the Net2Plan software interface with the following details:

- Top Bar:** View/edit network state, Algorithm execution, View reports.
- Report Section:**
  - Report: twork\_networkCost\bin\Optical\_Network\_networkCost.class
  - Load button
  - Optical\_Network\_networkCost
  - Description: This report displays the number of optical channels, ports and calculates the network cost
- Parameters Section:**

Parameter	Value	Description
EXC	10000	EXC cost in euros
EXCPort	1000	EXC port cost in euros p...
- Buttons:** Show, Close all.
- Report Status:** Network design report checked.
- View Options:** View in navigator, Save to file.
- Contents:**
  - Introduction
  - Detailed per-link description
  - Detailed per-node description
  - Network Cost
- Introduction Content:** This report shows all the relevant information to obtain the network cost as well as the calculated values.
- Detailed per-link description Content:** (This section is currently collapsed, indicated by a dropdown arrow icon).

Figure 15: Network Cost Report

Besides the equipment costs, this report also has the parameter "span". The value of this variable is used to calculate the number of optical amplifiers needed in the network using Equation 1.

$$N^R = \sum_{l=1}^L \left( \left\lceil \frac{len_l}{span} \right\rceil - 1 \right) \quad (1)$$

The other parameters of this equation being:

- $N^R$  → Total number of regenerators/amplifiers
- $len_l$  → Length of link l
- $span$  → Distance between amplifiers

By running the report three main categories are presented to the user.

The first category displayed by the report is the Detailed per-link description. In here the number of optical channels or wavelengths is displayed for each link based on the grooming algorithm used. The numbers displayed are based on the physical topology and represent all the wavelengths that will be needed to transport the network traffic. Using this information it is possible to obtain the average and total number of optical channels on the network.

Besides the number of wavelengths, this section also indicates the amount of amplifiers necessary in each link.

The second category is the Detailed per-node description. This section displays a table indicating how many ports are needed of each type for every node. The number of tributary ports obtained in each node is the sum of all traffic originating from that node or ending on it depending if its the input or output ports divided by the amount of traffic each optical channel can carry. This number also depends on the links through which traffic will be routed, for example, if 40 ODU0s are transmitted into 2 separate links only one wavelength could carry it but as they are going through different routes then 2 wavelengths will be used resulting in also a need for 2 tributary ports.

The number of line ports is obtained by adding the total amount of optical channels in the links that use that specific node as origin or destination.

Finally the total number of ports is as expected the sum of all the tributary ports with the line ones. With this information the average and the total number of ports in the network can be obtained which will later be used in calculating the network cost.

Having the node and link information available, the network cost can then be calculated as displayed on the third category of the report. The Node electrical cost is obtained with Equation 2 for a Transparent Network.

$$C_{exc} = (\gamma_{e0} \times N) + (\gamma_{e1} \times \tau \times 2 \times P_{TRIB}) \quad (2)$$

- $C_{exc}$  → Electrical Ports Cost
- $\gamma_{e0}$  → EXC cost in Euros
- $N$  → Number of Nodes
- $\gamma_{e1}$  → EXC port cost in Euros per GB/s
- $\tau$  → Traffic supported by optical channel

- $P_{TRIB}$  → Number of tributary ports

The cost values can be obtained from Table 1, the number of nodes is a known value when designing a network, the traffic supported by optical channel is defined by the grooming algorithm or by dividing the link capacity by its amount of optical channels and the number of tributary ports was obtained on the previous section of the report.

For an Opaque network, the electrical nodes cost is similar as displayed in Equation 3.

$$C_{exc} = (\gamma_{e0} \times N) + (\gamma_{e1} \times \tau (P_{LINE} + P_{TRIB})) \quad (3)$$

The node optical cost on the other hand, can be calculated for a Transparent network using Equation 4.

$$C_{oxc} = (\gamma_{o0} \times N) + \gamma_{o1} \times (P_{LINE} + P_{TRIB}) \quad (4)$$

- $C_{oxc}$  → Optical Ports Cost
- $\gamma_{o0}$  → OXC cost in Euros
- $N$  → Number of Nodes
- $\gamma_{o1}$  → OXC port cost in Euros
- $P_{TRIB}$  → Number of tributary ports
- $P_{LINE}$  → Number of line ports

As for the electrical ports, the cost values were previously defined in Table 1 and as such, only the number of ports is needed. These value were obtained on the second part of the report (Detailed per-Node description).

For an Opaque network, the node optical cost is 0 as the ports are all electrical.

The Node Total Cost is as expected the sum of both the optical and electrical node costs.

The rest of the network cost is from the links. This cost is obtained with Equation 5.

$$C_L = (\gamma_0^{OLT} \times L) + (\gamma_1^{OLT} \times \tau \times W) + (N^R \times c^R) \quad (5)$$

- $C_L$  → Links Cost
- $\gamma_0^{OLT}$  → OLT cost in Euros
- $L$  → Number of unidirectional Links
- $\gamma_1^{OLT}$  → Transponder cost in Euros
- $\tau$  → Traffic per port
- $W$  → Total number of optical channels

- $N^R \rightarrow$  Total number of optical amplifiers
- $c^R \rightarrow$  Optical amplifiers cost in Euros

As in previous equations, the costs are all available in Table 1. The total number of optical channels can be obtained by summing the wavelengths in each link on the Detailed per-Link description section. The number of optical amplifiers was calculated previously with Equation 1.

The middle part of the equation:  $\gamma_1^{OLT} \times \tau \times W$  refers to the Transponders cost while the rest is the "Fiber" and the "OLT" cost. Lastly the total network cost can be obtained by adding the Links cost with the Nodes cost.

## 3 Results

This section will display the results obtained using the algorithms and reports previously explained for a network with an Opaque transport mode and for one with Transparent.

### 3.1 Opaque with 1+1 protection

The results will be displayed only in the logical topology as in an opaque network it is the same as the physical one. Using the algorithm presented on figure 14 the routes and protection segments are created as well as the grooming.

There is not a second algorithm type for wavelengths reduction due to the fact that, that algorithm chooses the best path based on the shortest or disjointed path which in this case both need to be used one for work and one for protection. As such, is difficult to reduce in any instance the shortest path because of the algorithm performance.

The traffic matrix for the reference 6 node network, used for demonstration is shown below.

$$\begin{bmatrix} 0 & 17 & 17 & 15 & 1 & 13 \\ 17 & 0 & 32 & 7 & 15 & 114 \\ 17 & 32 & 0 & 11 & 46 & 1 \\ 15 & 7 & 11 & 0 & 11 & 7 \\ 1 & 15 & 46 & 11 & 0 & 93 \\ 13 & 114 & 1 & 7 & 93 & 0 \end{bmatrix}$$

Figure 16:

The amount of traffic that needs to be reserved in each link is as was to be expected a lot higher due to the need to reserve double the amount and in more links. The same happens in terms of wavelengths.

The number of wavelengths can again be seen on the links section of the "networkCost" report as well as the amplifiers needed on Figure 17.

The conclusions to take from these results are the same as was previously discussed as the number of amplifiers does not change and the wavelengths are the ones shown on the line matrices.

As for the nodes in the network Figure 18 shows the ports needed.

### Detailed per-link description

Node Pair	Wavelengths forward	Wavelengths backward	Amplifiers forward	Amplifiers backward
Node 0 «» Node 1	10	10	1	1
Node 0 «» Node 2	10	10	1	1
Node 1 «» Node 2	14	14	1	1
Node 1 «» Node 3	14	14	1	1
Node 2 «» Node 4	14	14	1	1
Node 3 «» Node 4	14	14	1	1
Node 3 «» Node 5	10	10	1	1
Node 4 «» Node 5	10	10	1	1

Figure 17: Links for Opaque Network with 1+1 Protection

### Detailed per-node description

Name	Trib ports in	Trib ports out	Line Ports in	Line Ports out	Total Ports in	Total Ports out
Node 0	9	9	20	20	29	29
Node 1	9	9	38	38	47	47
Node 2	9	9	38	38	47	47
Node 3	10	10	38	38	48	48
Node 4	10	10	38	38	48	48
Node 5	9	9	20	20	29	29
Total	56	56	192	192	248	248

Figure 18: Nodes for Opaque Network with 1+1 Protection

Again, the difference for the case without protection is only on the number of line ports as this value is based on the number of wavelengths going in or out of that node.

Comparing the number of ports obtained here with the network with a transparent transport mode, the amount is lower for the opaque network due to the reduced number of wavelengths required to route the traffic.

Lastly the total network cost is on Figure 19.

## Network Cost

Category		Cost	Total
Link Cost	OLT	240,000	96,304,000
	Transponders	96,000,000	
	Amplifiers	64,000	
Node Cost	Electrical	24,860,000	24,860,000
	Optical	0	
Total Network Cost			121,164,000

Figure 19: Network Cost for Opaque Network with 1+1 Protection

The increase in cost is as described on the transparent network just based on the additional number of wavelengths required which translates in also more trunk ports needed. As noted above in the amount of ports, the cost is also lower in this instance when compared to the transparent network due to the cheaper cost in transponders and optical ports.

### 3.2 Transparent with 1+1 protection

For a network with a transparent transport mode, the routing as was explained before, is done using a shortest path algorithm since there are no traffic grooming between different node pairs. For this instance as there is also a 1+1 protection scheme in place, the algorithm needs to not only create the routes but also a protection segment for each route. This segment is the shortest disjoint path of the route created.

Comparing the results obtained here with the previous example, it can be seen that the amount of traffic and wavelengths is significantly higher. It is in both cases, double the amount of before since the same quantity needs to be reserved for protection.

The conclusions that can be taken from the physical topology are as explained before, the huge number of wavelengths is related to the needed for double the amount of traffic where this extra will go through even more links.

For the logical topology the Average second shortest path number of hops is 1 since as for the shortest path, it is considered that there are always direct links between nodes in a transparent network. As for the physical topology, this value is not so obvious as it has to be calculated based on the second shortest path between each node pair.

These differences for the transparent network with protection segments can also be seen on the information provided in the "networkCost" report. Figure 20 shows the results for the links in the physical topology.

**Detailed per-link description**

Node Pair	Wavelengths forward	Wavelengths backward	Amplifiers forward	Amplifiers backward
Node 0 «» Node 1	12	12	1	1
Node 0 «» Node 2	12	12	1	1
Node 1 «» Node 2	18	18	1	1
Node 1 «» Node 3	18	18	1	1
Node 2 «» Node 4	18	18	1	1
Node 3 «» Node 4	18	18	1	1
Node 3 «» Node 5	12	12	1	1
Node 4 «» Node 5	12	12	1	1

Figure 20: Links for Transparent Network with 1+1 Protection

It can be seen that as expected the number of amplifiers is the same due to the link lengths remaining constant but the number of wavelengths are higher due to having a grooming scheme worst with this topology.

The results in terms of ports per node are shown below.

### Detailed per-node description

Name	Trib ports in	Trib ports out	Line Ports in	Line Ports out	Total Ports in	Total Ports out
Node 0	10	10	24	24	34	34
Node 1	10	10	48	48	58	58
Node 2	10	10	48	48	58	58
Node 3	10	10	48	48	58	58
Node 4	10	10	48	48	58	58
Node 5	10	10	24	24	34	34
Total	60	60	240	240	300	300

Figure 21: Nodes for Transparent Network with 1+1 Protection

The number of tributary ports remain the same but the number of line ports increase based on the higher number of wavelengths needed in the network.

Lastly, the total network cost is shown on Figure 22.

### Network Cost

Category		Cost	Total
Link Cost	OLT	240,000	120,304,000
	Transponders	120,000,000	
	Amplifiers	64,000	
Node Cost	Electrical	12,060,000	12,930,000
	Optical	870,000	
<b>Total Network Cost</b>			<b>133,234,000</b>

Figure 22: Network Cost for Transparent Network with 1+1 Protection

The results obtained for the network Cost confirm those obtained in the previous categories in this report. The OLT and amplifiers cost does not change as the number of links and amplifiers remains the same. Similarly, the electrical ports cost is also the same as the amount of ADD/DROP ports remains the same.

The differences are in the Transponders cost in the links and the Optical cost in the nodes. These as expected, cost more based on the increased number of them needed in the network to have a 1+1 protection scheme in a transparent transport mode network.

## 4 Simulations

To access the Simulations window go to "Tools → Online Simulation" or press *Alt + 3*. The simulations menu is very similar to the one available for network design with the notable difference that in this instance the network needs to have already been saved with every definition done as all the tabs described earlier are only available here for viewing.

Using the already built network with the demand set introduced as well as routing and protection segments, an example of a Time-varying simulation is demonstrated. The main parameters to be chosen on this simulation are the "Event generator" and the "Provisioning algorithm", displayed on Figures 23(a) and 23(b).

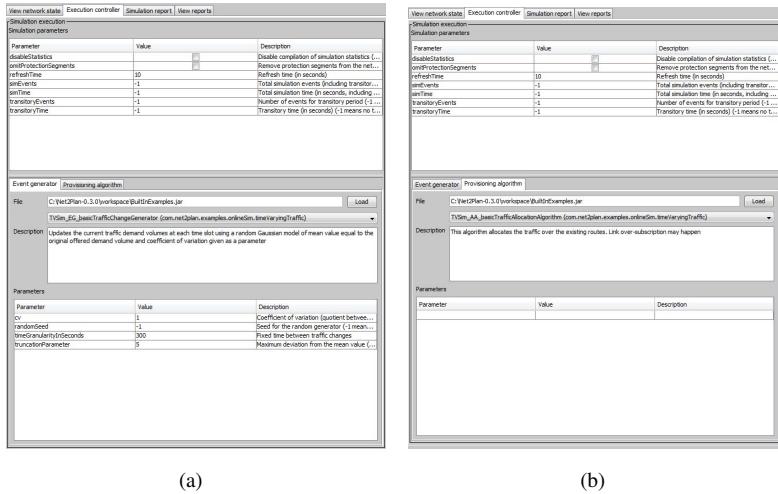


Figure 23: a) Net2Plan Event generator ; b) Net2Plan Provisioning algorithm

The Event generator shown creates a time varying simulation by updating the network traffic based on the chosen parameters while the allocation algorithm in this case only allocates this traffic into the available routes. Besides these options it is also possible to change the main simulation parameters which are displayed on the top half.

Having defined all the simulation parameters and the other necessary options, the simulation can be started by just pressing "run" below the network topology at the lower left side. The "simulation controller" will update automatically based on the time defined at the simulation parameters or it can be paused for an update on the results.

## 5 Implementing new algorithms on Net2Plan

This section will demonstrate some of the possibilities provided by Net2Plan as an open source tool. By creating new algorithms or reports it is possible to adapt this program for most necessities in terms of network planning.

There are already several built-in algorithms present in Net2Plan but as it is impossible to have an algorithm built for every specific necessity it is possible for each user to build new ones or modify existing ones to fulfil what needs to be done.

As everything in Net2Plan was built in Java, the program "Eclipse" that can be downloaded from <https://eclipse.org/downloads/> was chosen as the best option for coding. All the .java files from the available algorithms in Net2Plan can be downloaded from its website and introduced into "Eclipse" to create a class.

When opening Eclipse, the first choice is to define the work directory in which all the projects will be created. Having defined the workspace, Figure 24 demonstrates the window for creating new projects in Eclipse, this can be accessed by going into "File → New → Java Project". In this window, only the name needs to be defined and then finish.

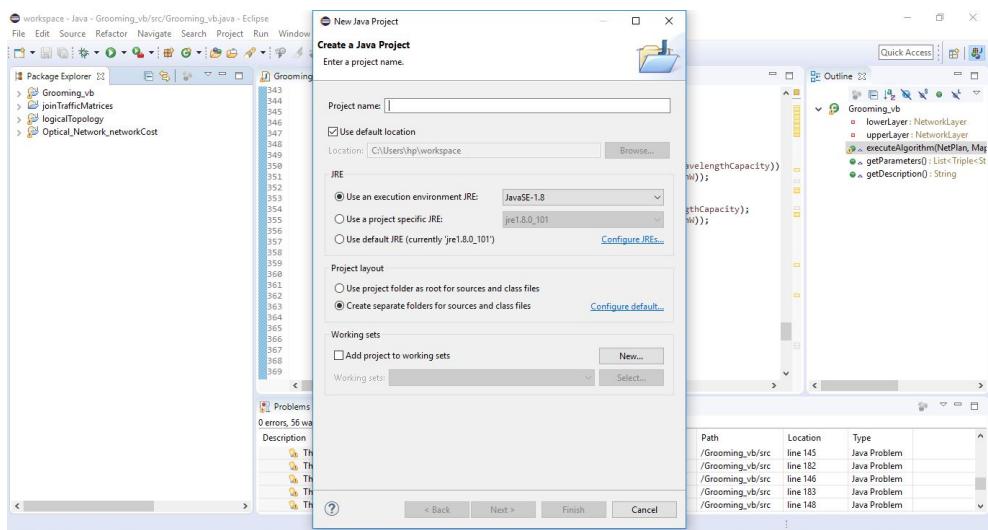


Figure 24: Eclipse new project

Having created a new project, a "src" directory should be available where the .java should be located. As a starting point, an existing algorithm should be used as a template and then modified to do its necessary purpose. Figure 25 shows a newly created project called "logicalTopology".

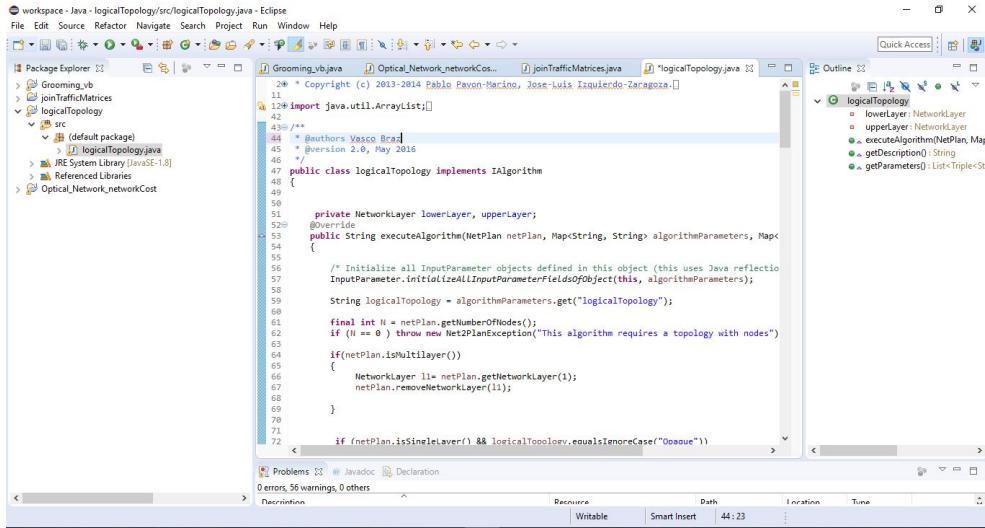


Figure 25: Eclipse new project with source file

To add the library files to a project, right click on it and choose "Build Path → Configure Build Path ..." . On the window that appears, press "Add External Jars..." and include all the files in the Net2Plan "lib" directory as shown on Figures 26(a) and 26(b).

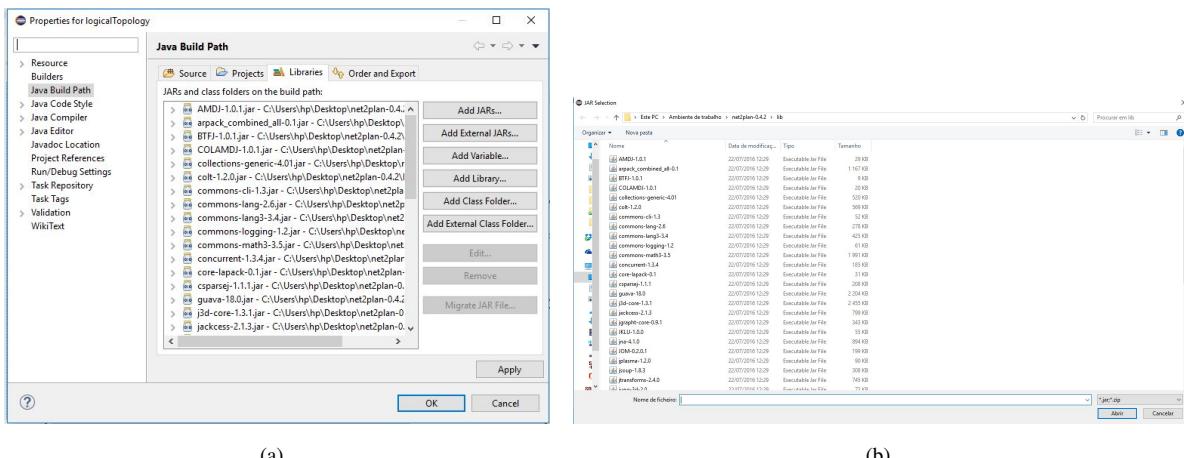


Figure 26: a) Eclipse Java Configure Build Path ; b) Net2Plan library files

To further illustrate how these modifications to algorithms work, the project created above using an existing code as a template was modified to create a new algorithm which creates the logical topology of a network in another layer.

The code created is shown on Figure 24. By saving this project on Eclipse a .class file is created on the bin directory of the project which can be loaded on Net2Plan. On the "Algorithm execution" tab at the "Offline network design", the "BuiltInExamples.jar" is loaded as the default location for algorithms and as it is a .jar file all the available ones that came with Net2Plan are integrated into it. To get the newly created algorithm available, press "Load" and find the .class file created in Eclipse as shown on Figure 27.

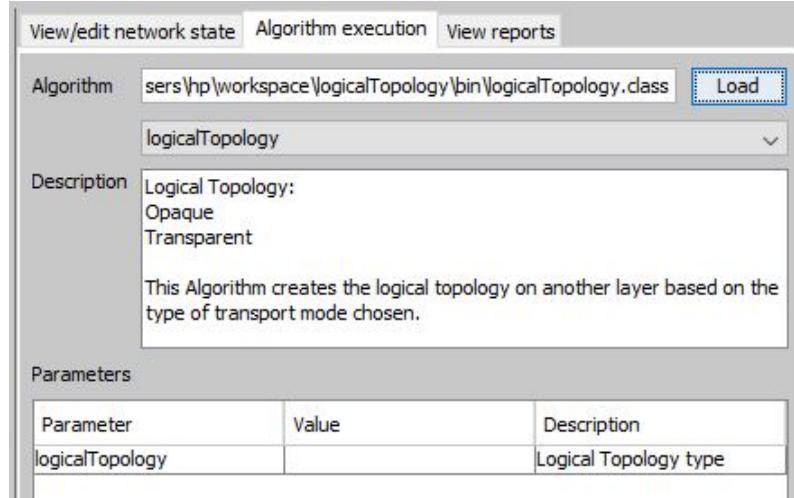


Figure 27: Net2Plan new algorithm

As was said before and can be seen on the "Description", this algorithm creates the network logical topology as was explained on section 2.2.

Algorithms developed on Eclipse can be exported into a .jar file so on Net2Plan this file can be loaded and all the algorithms developed are shown in a list in the same manner as the ones that came with the Net2Plan installation. The export option can be accessed by going into File → Export, and the menu are shown in Figures 28(a) and 28(b).

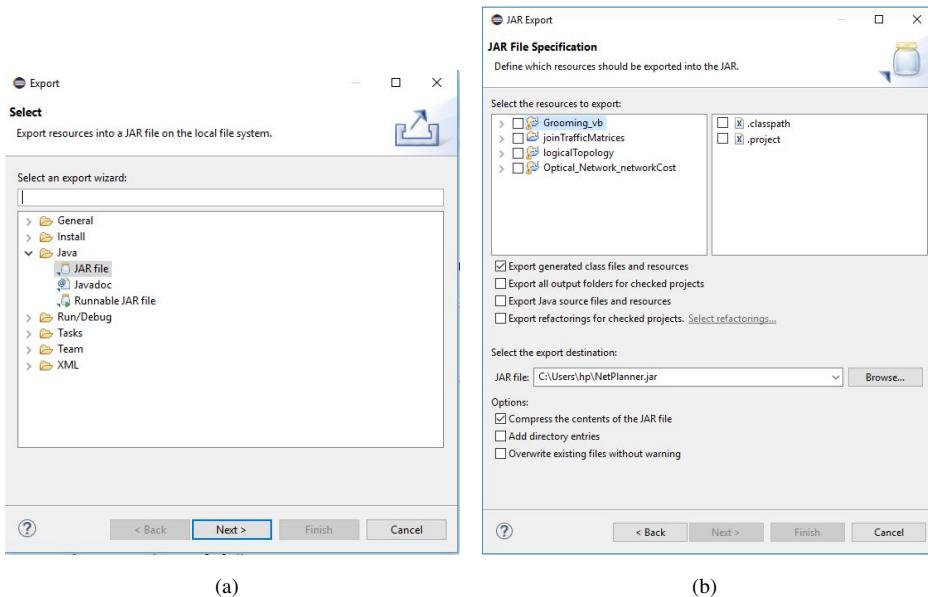


Figure 28: a) Eclipse export ; b) Projects to export into a .jar file

By default only the .class files are exported along with the necessary libraries so that the algorithms can be loaded on Net2Plan. There is however an option to also export the .java files so that if needed the ones who will use the code also have access to it if they need to change it.

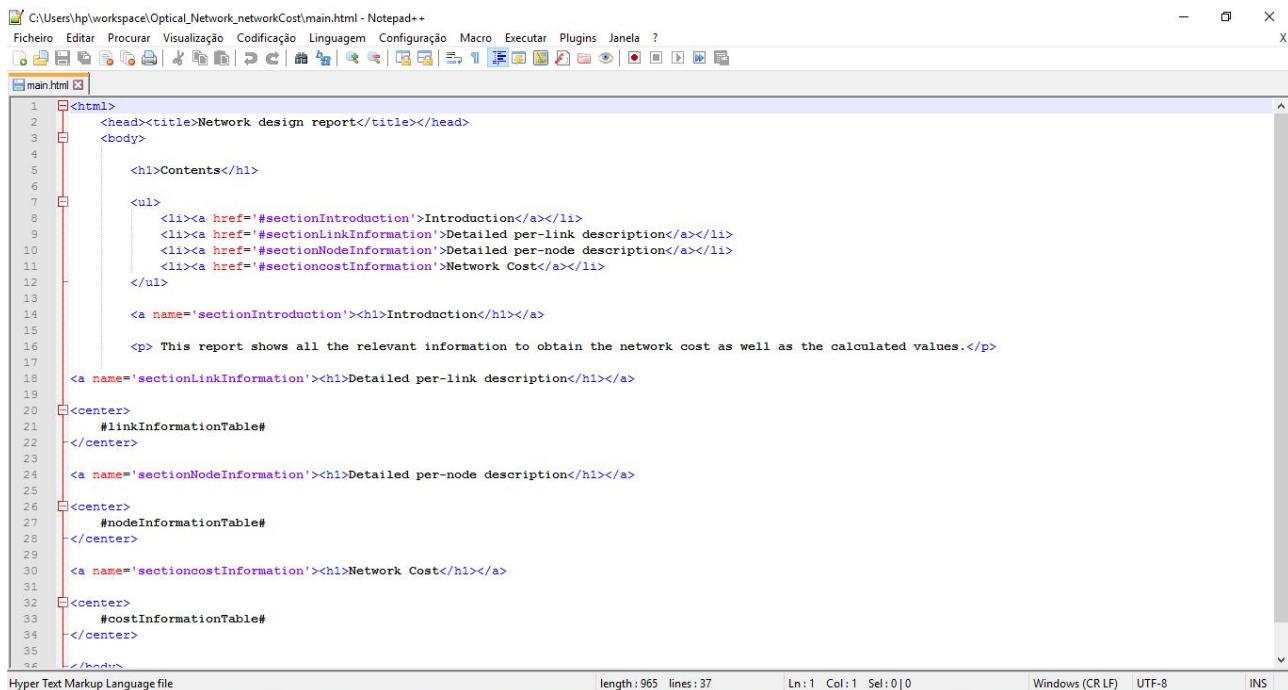
## 6 Developing new Reports

Similarly to the way algorithms can be modified or new ones created, also reports can be done using almost the same steps. For the following examples, the "Optical\_Network\_networkcost" is being used as a basis for modifying or creating new reports.

An important point to note as the main difference as to when modifying algorithms, is that in this case not only are the Net2Plan libraries needed but also the extra files summoned by the report. These files can be found opening the "BuiltInExamples.jar" file in the Net2Plan directory on the corresponding report.

For the report being used there is an .html file called "main" which is where the information to be displayed in html form is described as well as several image files that are displayed in the report. As such, if the modifications to be done in the reports are to be shown in html format the "main.html" file needs to be modified in order to adapt to these changes.

The tables themselves are created in eclipse as Java code but the html file needs to be opened for example with "Notepad++" to change some its code as the tables are being appended into the html. Figure 29 shows the modified html that is used in the Optical\_Network\_networkcost.



The screenshot shows the Notepad++ application window with the file "main.html" open. The code is an HTML document structure:

```
<html>
    <head><title>Network design report</title></head>
    <body>

        <h1>Contents</h1>

        <ul>
            <li><a href="#sectionIntroduction">Introduction</a></li>
            <li><a href="#sectionLinkInformation">Detailed per-link description</a></li>
            <li><a href="#sectionNodeInformation">Detailed per-node description</a></li>
            <li><a href="#sectioncostInformation">Network Cost</a></li>
        </ul>

        <a name='sectionIntroduction'><h1>Introduction</h1></a>

        <p> This report shows all the relevant information to obtain the network cost as well as the calculated values.</p>

        <a name='sectionLinkInformation'><h1>Detailed per-link description</h1></a>

        <center>
            #linkInformationTable#
        </center>

        <a name='sectionNodeInformation'><h1>Detailed per-node description</h1></a>

        <center>
            #nodeInformationTable#
        </center>

        <a name='sectioncostInformation'><h1>Network Cost</h1></a>

        <center>
            #costInformationTable#
        </center>
    </body>
```

The status bar at the bottom indicates: length : 965 lines : 37 Ln : 1 Col : 1 Sel : 0 | 0 Windows (CR LF) | UTF-8 | INS

Figure 29: html file for Network Cost report

As can be seen, this is a simple example of an html file since there are only hyper links created to link the contents index to the tables. Other options could be added as for example, hyper links to each of the network costs with the formula describing its calculations by adding the necessary information in this file. These extra options are present on more complex reports such as the "Report\_networkDesign" where the images used are equations showcasing how some of the calculations are done.

