#### Rotman

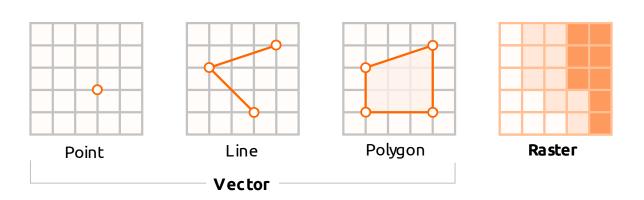
#### INTRO TO DATA VISUALIZATION

Part II Plotting Maps with GeoPandas & Matplotlib



## Spatial Data

- A spatial dataset is a combination of...
  - location data and spatial dimensions (the where)
  - attribute data (the what)
- Two most common forms of spatial data
  - Vector
  - Raster



Source/Ref: Introduction to (Q)GIS by Jeff Allen

#### Vector Data

 Use geographic coordinates, or a series of coordinates, to create points, lines, and polygons representing real-world features

- Two most common vector data format
  - GeoJSON
  - Shapefile
    - Shape (.shp) contains feature geometry
    - Shape index (.shx): facilitates fast search
    - Attribute (.dbf): contains attributes for each shape

```
An example of GeoJSON file.
```

```
{
  "type": "Feature",
  "geometry": {
    "type": "Point",
    "coordinates": [125.6, 10.1]
  },
  "properties": {
    "name": "Dinagat Islands"
  }
}
```

Source/Ref: Introduction to (Q)GIS by Jeff Allen

#### Raster Data

Represents space as a continuous grid with equal cell sizes

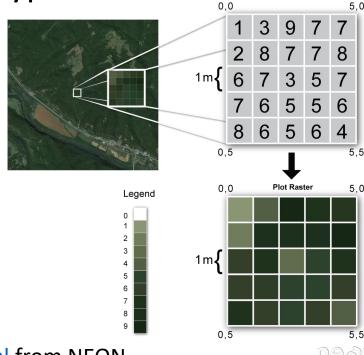
Each cell contains a value pertaining to the type of feature it

represents

Quantitative value (e.g., elevation)

• Categorical value (e.g., type of land use)

- Examples of raster data
  - digital elevation models (DEMs)
  - satellite imagery



## Coordinate Reference System (CRS)

Any geo-spatial dataset comes with a CRS

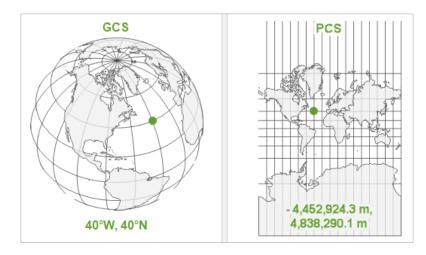
Without CRS, one cannot plot and process geospatial data correctly

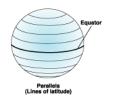
 CRS is "a framework used to precisely measure locations on the surface of Earth as coordinates." (wikipedia)

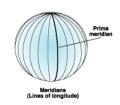
- CRS is a COMPLEX topic
  - Let's attempt to understand some BASICS.

## Two Main Types of CRS

- Geographic Coordinate Systems (GCS)
  - Round
  - Records locations in angular units (e.g., degrees)
    - Latitude: degrees north or south of equator
    - Longitude: degrees west or east of a prime meridian
  - Many different model the Earth surface -> Many CRS
    - e.g. World Geodetic System 1984 (WGS84)
- Projected Coordinate Systems (PCS)
  - Flat
  - Records locations in linear units (e.g., meters)
  - Many ways to project -> Many PCS
    - e.g., Universal Transverse Mercator (UTM)















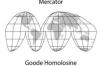










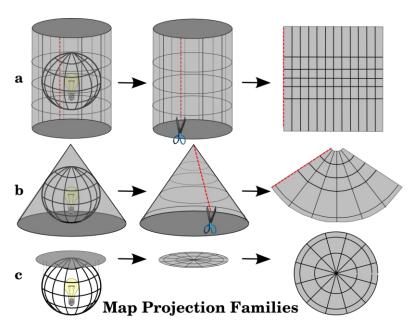




Source/Ref: 1) CRS Wikipedia; 2) GCS vs PCS

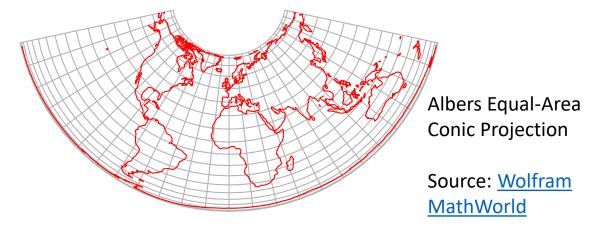
### Projections

- MANY different projections
  - Three main families, but there are more
  - Within each family, there are many projections



Source: QGIS Doc

- A projection can preserve one or more properties below but never all
  - Direction
  - Distance
  - Area
  - Shape



Source/Ref: 1) List of map projections wiki; 2) Map projection wiki

## Components of CRS

- Coordinate system
  - E.g., longitude & latitude, x & y, etc.
- Datum: binds abstract coordinate system to real space on the Earth
  - Datum usually consists of
    - an estimate of the shape of the Earth (usually an ellipsoid)
    - one or more anchor points for which the measurement is documented
  - Examples of dataum
    - Global datum: WGS84, North American Datum (NAD83)
    - Local datum: NAD27 (A local datum aligns its ellipsoid to closely fit the earth's surface in a particular area)
- Projection (if it is a PRS)

Source/Ref: CRS wiki

## CRS is a "Stack" of Dependent Specifications

| EPSG<br>Code | Name                                   | Ellipsoid      | Horizontal<br>Datum       | CS Type                   | Projection   | Origin                                 | Axes  | Unit of<br>Measure   |
|--------------|--|----------------|---------------------------|---------------------------|--|--|---|----------------------|
| 4326₺        | GCS WGS 84                             | GRS 80         | WGS 84                    | ellipsoidal<br>(lat, lon) | N/A  | equator/<br>prime<br>meridian          | equator,<br>prime<br>meridian                     | degree of arc        |
| 26717 년      | UTM Zone 17N<br>NAD 27                 | Clarke<br>1866 | NAD 27                    | cartesian<br>(x,y)        | Transverse Mercator:<br>central meridian<br>81°W, scaled 0.9996                                | 500 km<br>west of<br>(81°W, 0°N)       | equator,<br>81°W<br>meridian                      | meter                |
| 6576 ₺       | SPCS Tennessee Zone NAD 83 (2011) ftUS | GRS 80         | NAD 83<br>(2011<br>epoch) | cartesian<br>(x,y)        | Lambert Conformal<br>Conic: center 86°W,<br>34°20'N, standard<br>parallels 35°15'N,<br>36°25'N | 600 km grid<br>west of<br>center point | grid east at<br>center point,<br>86°W<br>meridian | US<br>survey<br>foot |

Source/Ref: CRS wiki

# GIS (Geographic Information Systems)

 GIS are tools to analyze, manipulate, and visualize spatial information on a computer

- Many GIS tools
  - QGIS, ArcGIS, MapBox, etc.

- We will only focus on visualization with <u>GeoPandas</u>'s plot() function
  - GeoPandas's plot() is a method on GeoSeries or GeoDataFrame
  - GeoPandas's plot() builds on Matplotlib

Source/Ref: Introduction to (Q)GIS by Jeff Allen

### Geopandas - 1

Make working with geospatial data in Python easier

- Extends <u>pandas</u> to allow spatial operations on geometric types
  - Geometric operations built on <a href="mailto:shapely">shapely</a>
  - File access built on <u>fiona</u>
  - Plotting built on <u>matplotlib</u>

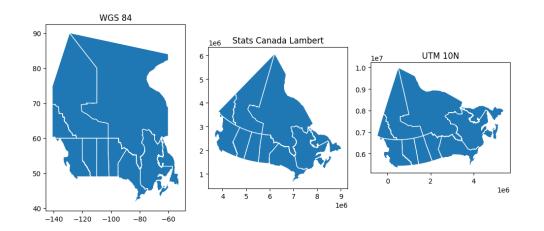


## Geopandas - 2

- Load dataset containing geometry info
- Manage Coordinate Reference System (CRS)
  - Store CRS info
  - translate between CRSs
- Geospatial operations
  - Calculate areas bounded by polygons
  - Spatial join
  - Spatial aggregation
  - Many more

Plot

|    | PRENAME                   | PREABBR | LANDAREA     | geometry                                       |
|----|---------------------------|---------|--------------|--|
| 0  | Newfoundland and Labrador | N.L.    | 3.581704e+05 | POLYGON ((7644464.869 2980078.217, 7648864.423 |
| 1  | Prince Edward Island      | P.E.I.  | 5.681179e+03 | POLYGON ((8427184.671 1638777.314, 8427169.677 |
| 2  | Nova Scotia               | N.S.    | 5.282471e+04 | MULTIPOLYGON (((8693947.526 1494906.237, 86935 |
| 3  | New Brunswick             | N.B.    | 7.124850e+04 | POLYGON ((8188457.820 1707919.583, 8188444.194 |
| 4  | Quebec                    | Que.    | 1.298600e+06 | MULTIPOLYGON (((8396476.571 1754341.151, 83956 |
| 5  | Ontario                   | Ont.    | 8.924118e+05 | POLYGON ((6378273.940 2296884.400, 6378455.637 |
| 6  | Manitoba                  | Man.    | 5.403102e+05 | POLYGON ((6039718.643 2636909.880, 6039717.720 |
| 7  | Saskatchewan              | Sask.   | 5.770604e+05 | POLYGON ((5248633.914 2767057.263, 5249285.640 |
| 8  | Alberta                   | Alta.   | 6.346583e+05 | POLYGON ((5228304.177 2767597.891, 5228098.463 |
| 9  | British Columbia          | B.C.    | 9.206866e+05 | POLYGON ((4018904.414 3410247.271, 4019429.869 |
| 10 | Yukon                     | Y.T.    | 4.723454e+05 | POLYGON ((4561932.471 4312865.174, 4564007.580 |
| 11 | Northwest Territories     | N.W.T.  | 1.127712e+06 | POLYGON ((5689672.257 4324508.314, 5685498.029 |
| 12 | Nunavut                   | Nvt.    | 1.836994e+06 | POLYGON ((7297737.369 3983558.454, 7316653.440 |

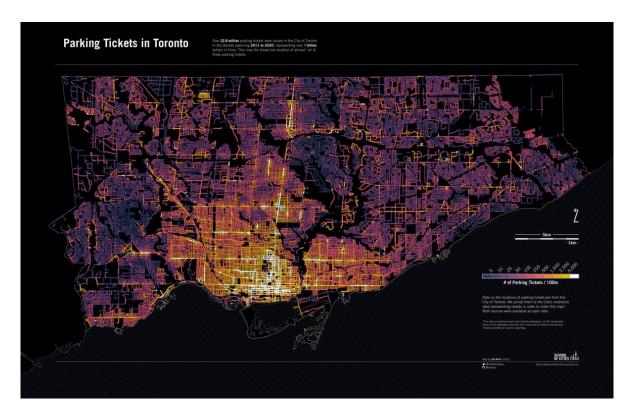


## Walk-through — Toronto Parking Ticket

 Reproduce (almost) Jeff Alan's <u>Toronto Parking</u> <u>Tickets</u> Visualization

 I believe Jeff's plot is done using QGIS and Inkscape

We will use GeoPandas with Matplotlib

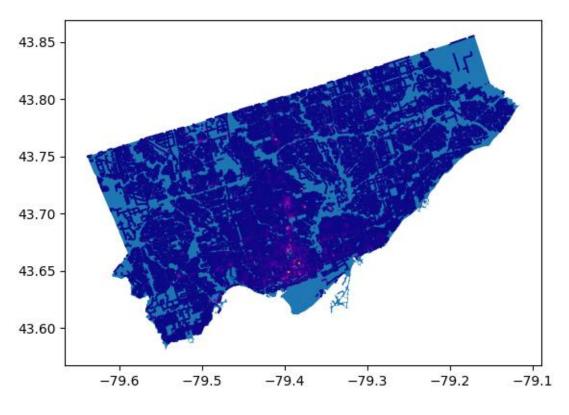


Parking Tickets in Toronto by Jeff Alan

Ref: 1) <a href="https://schoolofcities.github.io/parking-tickets-toronto/">https://schoolofcities.github.io/parking-tickets-toronto/</a>

2) <a href="https://github.com/schoolofcities/parking-tickets-toronto/tree/main">https://github.com/schoolofcities/parking-tickets-toronto/tree/main</a>

# Walk-through – Our Implementation

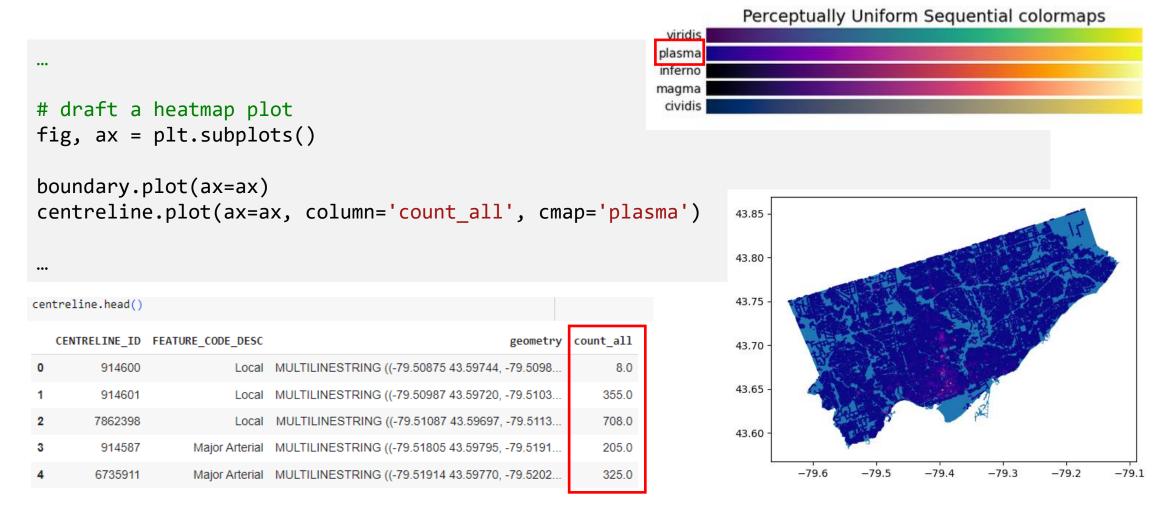


the default plot from Geopandas/Matplotlib



the refined plot

#### Default Plot



Ref: 1) <a href="https://geopandas.org/en/stable/docs/reference/api/geopandas.GeoDataFrame.plot.html">https://geopandas.org/en/stable/docs/reference/api/geopandas.GeoDataFrame.plot.html</a>

2) <a href="https://matplotlib.org/stable/users/explain/colors/colormaps.html">https://matplotlib.org/stable/users/explain/colors/colormaps.html</a>

#### Refine 1. Better Orientation

```
# rotate centreline
                                                                   930000
# turn EPSG:4326 to EPSG:3347 first to avoid shape
# distortion after rotation
                                                                   925000
cline 3347 = centreline.to crs(epsg=3347)
                                                                              7.21
                                                                                      7.22
                                                                                              7.23
# rotate with respect to the centroid of all centrelines
cline_3347_rotated = cline_3347.rotate(-28, origin=cline_3347.unary union.centroid)
    .rename("geometry 3347 rotate")
# combine the original centreline GeoDataFrame with the rotated GeoSeries
centreline rotated = centreline.join(cline 3347 rotated)
# rotate boundary
# turn EPSG:4326 to EPSG:3347 first to avoid shape distortion after rotation
# rotate with respect to the centroid of all centrelines to match centreline rotation centroid
boundary rotated = boundary.to crs(epsg=3347).rotate(-28, origin=cline 3347.unary union.centroid)
```

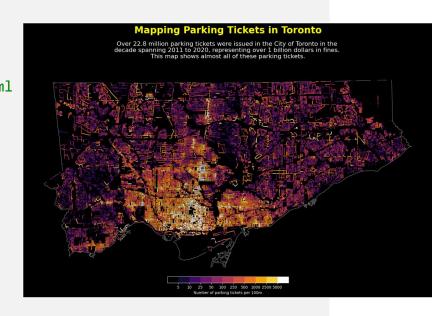
945000

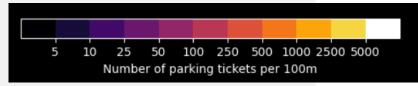
935000

7.24

## Refine 2. Colormap on Discrete Intervals

```
# Generate a colormap index based on discrete intervals
# https://matplotlib.org/stable/api/ as gen/matplotlib.colors.Colormap.html
# https://matplotlib.org/stable/api/ as gen/matplotlib.colors.BoundaryNorm.html
cmap = plt.colormaps['inferno'].with extremes(over="white")
bounds = [5, 10, 25, 50, 100, 250, 500, 1000, 2500, 5000]
norm = BoundaryNorm(bounds, cmap.N, extend='both')
# plot centreline heatmap
centreline rotated.plot(ax=ax, column='count all',
                        cmap=cmap,
                        norm=norm,
                        markersize=0.5,
                        legend=True,
                        legend kwds={
                            'shrink': 0.3,
                            'orientation': 'horizontal',
                            'pad': 0,
                            'anchor': (0.5, 1),
                            'extendfrac': 'auto',
                            'extendrect': True,
                            'label': 'Number of parking tickets per 100m'})
```





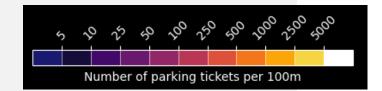
Ref: 1) Discrete and extended colorbar with continuous colorscale

2) In general, you can use mapclassify to auto-generate classification schemes for choropleth maps.

#### Refine 3. Better Colorbar

```
# plot coloarbar legend separately so as to customize its look
cbar = fig.colorbar(ScalarMappable(norm=norm, cmap=cmap),
                    ax=ax,
                    orientation='horizontal',
                    shrink=0.3,
                    pad = -0.02,
                    anchor=(0.5, 1),
                    extendfrac='auto',
                    extendrect=True,
                    drawedges=True,
                    label='Number of parking tickets per 100m')
cbar.ax.tick params('x',
                    bottom=False, labelbottom=False,
                    top=True, labeltop=True,
                    labelrotation=45)
```





## Refine 4. Map Scale, North Arrow, & Notes

```
# add scalebar
# https://geopandas.org/en/stable/gallery/matplotlib scalebar.html
scale = ScaleBar(dx=1,
                  location='lower right',
                  color='grey',
                  box alpha=0,
                  width fraction=0.005,
                  border pad=5)
= ax.add artist(scale)
                                                                             Note: This is an attempt to reproduce Jeff Allan's Toronto
                                                                             Parking Tickets Map using Matplotlib. Find the original plot
                                                                             at https://schoolofcities.github.io/parking-tickets-toronto/.
# add north arrow
# https://matplotlib.org/stable/users/explain/text/annotations.html
                                                                             Data source and data processing code can be found therein.
                                                                                                                                              5 km
= ax.annotate("N",
                 xy=(0.91, 0.25), xycoords='figure fraction',
                 xytext=(0.9, 0.19), textcoords='figure fraction',
                 ha='center',
                 color='gray',
                 arrowprops=dict(arrowstyle="fancy", color="gray"))
# add notes
= ax.text(0.6, 0.11,
             ("Note: This is an attempt to reproduce Jeff Allan's Toronto \nParking Tickets Map using Matplotlib."
              "Find the original plot \nat https://schoolofcities.github.io/parking-tickets-toronto/.\n\n"
             "Data source and data processing code can be found therein."),
            transform=ax.transAxes,
            wrap=True,
            fontsize=8,
            horizontalalignment='left',
            bbox=dict(boxstyle='square', pad=1, facecolor='black', edgecolor='black'))
```