Report Lab 4

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Dijkstra and Floy

Code

```
def f(x): return 4 * x - 1.8 * (x ** 2) + 1.2 * (x ** 3) - 0.3 * (x ** 4)
4 # derivative of f(x) is g(x)
5 def g(x): return 4 - 3.6 * x + 3.6 * (x ** 2) - 1.2 * (x ** 3)
8 \text{ def } dg(x): return -3.6 + 7.2 * x - 3.6 * (x ** 2)
10
def newton(f, df, x_initial, e_s, max_iter):
12
   i = 0
   e_a = 100
13
   x0 = x_{initial}
14
    global x
   print("%10s %10s %10s" % ("Iteration", "x", "err"))
16
   while i < max_iter and abs(e_a) > e_s:
     i = i + 1
18
      x = x0 - (f(x0) / df(x0))
      e_a = (x - x0) / x
20
     x = 0x
21
      print("%10d %10f %10f" % (i, x, e_a))
22
    return x
24
optimal_point = newton(g, dg, 0, 0.01, 100)
28 print("Optimal point is %f." % optimal_point)
30 print("Optimal value is %f" % f(optimal_point))
```

Running

```
Iteration x
                         err
        1 1.111111
                    1.000000
        2 64.074074 0.982659
        3 43.049578 -0.488379
        4 29.033492 -0.482756
        5 19.689984 -0.474531
        6 13.462216 -0.462611
        7
          9.313152 -0.445506
           6.553356 -0.421127
          4.727457 -0.386233
       10
           3.540951 -0.335081
       11
           2.814433 -0.258140
       12
           2.445873 -0.150686
       13
           2.335960 -0.047053
       14
           2.326421 -0.004100
Optimal point is 2.326421.
Optimal value is 5.885340
```

2

Code

```
1 import sympy as sp
3 X, Y = sp.symbols('X, Y', real=True)
5 f = (X - 3) ** 2 + (Y - 2) ** 2
8 def steepest_descent(function, x_i, y_i, Es, max_iter, true_x, true_y):
    global x_res, y_res
    i = 0
10
   err_x = 100
11
    err_y = 100
12
13
   x0, y0 = x_i, y_i
14
15
    H = sp.Symbol('H', real=True)
16
    dfdx = sp.diff(f, X)
17
    dfdy = sp.diff(f, Y)
18
19
    print("%10s %10s %10s %10s %10s" % ("Iteration", "x", "y", "errX", "errY"))
20
    while i < max_iter and (abs(err_x) > Es or abs(err_y) > Es):
22
     i = i + 1
23
24
      x = x0 + dfdx.subs([(X, x0), (Y, y0)]) * H
```

```
y = y0 + dfdy.subs([(X, x0), (Y, y0)]) * H
26
      g = f.subs([(X, x), (Y, y)])
28
29
      dg = sp.diff(g, H)
30
      if sp.solve(dg, H):
31
        h = sp.solve(dg, H)[0]
      x_res = x.subs(H, h)
34
      y_res = y.subs(H, h)
35
36
      err_x = (true_x - x_res) / true_x
37
      err_y = (true_y - y_res) / true_y
38
      x0, y0 = x_res, y_res
      print("%10d %10f %10f %10f %10f" % (i, x_res, y_res, err_x, err_y))
41
    return f.subs([(X, x_res), (Y, y_res)])
42
43
print("Optimal value of f(x) is: %f" % steepest_descent(f, 1, 1, 0.01, 100, 3, 2))
```

Running

Analysis and Comparation

Although both of the 2 methods can help us find the optimal points and values of a function, there are some differences:

• Newton method

This method is originally a root-finding method.

Here we just use Newton method to find the root of the derivative function, which is also the optimal point.

 \Rightarrow Therefore, this method is simple in its principle but it is not the best method for optimization.

This can be proved by looking at the 1^{st} problem: a simple 4^{th} degree single variable non-linear function but it requires up to 14 iterations to find out the optimal value.

• Steepest descent method

This method, from the result in problem 2, is unarguably faster than Newton method with only 1 iteration needed.

This is due to it being designed to solve optimization problems at first.

However, the main disadvantage of this method that I encounter while applying it is the complexity in its principles.

The first step of finding out the gradient is simple, but the fact that we have to recalculate the value of the gradient in every iteration makes it tedious.

The second step of find out the optimal point in the gradient direction, on the other hand, is a whole root-finding problem of the function's derivative. Thus, it can be very tedious in cases when it is hard

to find the derivatives or when the derivative function is hard to solve.

⇒ Therefore, this method is faster, better for optimization but is much more complex and tedious.

Conclusion

Newton method is much simpler, thus, it should be prioritized in hand-on calculation with no help from computer.

Reversely, steepest descent method should be prioritized as an algorithm in optimization programs because the computer can help us do all the tedious jobs and we can benefit from the advantages of the method.