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FREEDOM KL25Z

Revisions & Change Log			
Rev	Description	Date	Approved
X1	Initial Draft	04/10/12	M. NORMAN
A	Release to production	05/03/12	M. NORMAN
B	Prototype redefinition.  KL25 XTAL capacitors C16 & C19 changed from 10pF DNP to 22pF populated. Defined A5 signal from K20 MCU	05/09/12	M. NORMAN
C	Prototype release.  Fixed J10 orientation according to Arduino R3 specification	05/21/12	M. NORMAN
CX1	Prototype Re-spin.  Changed two pin headers to DNP bottom-shorting headers. Added support to AT45DB161D-S or AT45DB161E-SSHD SPI Flash Memory. Added 2pin header (J11) for on-board MCU programming isolation. Redefined KL25 power netnames. Changed USB connectors part numbers J5 and J7 Changed KL25 XTAL 1M resistor (R25) to DNP. Changed X-FREEDOM-KL25Z board name to FRDM-KL25Z	06/29/12	M. NORMAN
D	Pilot release.  Changed 2pin header (J11) location for on-board MCU SWD CLK isolation. Changed to DNP non-production BOM parts BT1, J1, J2, J3, J4, J6, J9, J10, TP6, U5, J8 Removed OpenSDA leverage hint voltage legend	07/10/12	M. NORMAN
DX1	Production Re-spin.  Fixing V. drop in ADC by changing SH1 for R77 & R80, and 3.0V zenner (D9) also changed BAT54C rectifiers (D1, D2, D5) for MBR120VLSFT1G diodes (D6, D7, D8, D10, D11, D12, D13 to enhance VF curve and current capability. Added J20 header to bypass D12 vdrop. Changed J4 and J3 to no bottom-shorting headers and added R73 & R74 0-ohm instead, along with R81 for current measuring Added USB host functionality without electrical protection by placing J21 and R82 options. Updated KL25 symbol TPM to FTM function misnaming	01/22/13	M. NORMAN
E	Production Re-spin release.  Adding 5V buck-boost VR support by 1x3 pin header J22 and C26-29 10uF capacitors	01/30/13	M. NORMAN



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ICAP Classification: FCP: FLK: PUB: X

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Approved: MICHAEL NORMAN

Size C     Document Number SCH-27556 | PDF: SPF-27556     Rev E

Date: Thursday, January 31, 2013

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- The diagram illustrates the OpenSDA development board architecture. It features two main microcontrollers: the Kinetis K-Series K20DX128VFM5 and the Kinetis L-Series KL25Z128VLK4 80 LQFP. The K20 is connected to the K25 via UART, SPI, GPIO, SWD, and RESET lines. The K20 is also connected to a Mini-B USB port and a 10-pin Debug header. The K25 is connected to a Mini-B USB port, a 10-pin Debug header, and an Inertial Sensor via I2C and GPIO. The board includes a 3.3V LDO, a CR2032 battery, and a 3.3V LDO. The board is labeled 'OpenSDA' and 'Touch Pad - Slider'.

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ICAP Classification:      FCP:      FIUO:      PUB: X				
Drawing Title: <div style="text-align: center; font-size: 1.2em; font-weight: bold;">FRDM-KL25Z</div>				
Page Title: <div style="text-align: center; font-size: 1.2em; font-weight: bold;">BLOCK DIAGRAM</div>				
Size C	Document Number SCH-27556   PDF: SPF-27556			Rev E
Date:	Wednesday, January 30, 2013	Sheet	2 of	5



