THOMAS DUDZIK

EDUCATION

Massachusetts Institute of Technology (MIT)

Cambridge, MA

M.Eng in Electrical Engineering & Computer Science – 5.0/5.0 GPA

Class of 2020

S.B. in Computer Science & Engineering and in Mathematics (double major) – 4.9/5.0 GPA

Class of 2019

Current

Honor Societies: Eta Kappa Nu, Tau Beta Pi

Relevant Coursework: • Advanced Algorithms • Linear Algebra • Machine Learning • Computer Vision • OS Engineering

• Probability • Theoretical Statistics • Stochastic Processes • Bayesian Inference • Information Theory

EXPERIENCE

Crypto HFT Firm Remote

Engineer (Partner)

Quantitative research and development for crypto spot & derivatives trading across all major CeFi and DeFi exchanges.

Vatic Labs New York, NY

Quantitative Developer

Sep. 2020 – Jan. 2021

Performed statistical analysis and high-performance software engineering for high-frequency trading.

Zoox Foster City, CA

Software Engineering Intern – Perception Team

Summer 2019

Developed and patented a novel computer vision approach for classifying and understanding dynamic environments. Implemented a semi-supervised convolutional network for monocular depth estimation aboard autonomous vehicles.

J.P. Morgan

New York, NY

Markets Analyst Intern – FX E-Trading

Summer 2018

Improved price discovery algorithm for G10 FX forwards via statistical lead/lag analysis of broker time-series data. Developed a chatbot to identify broker quotes indicating live price updates using NLP and machine learning techniques.

Blockstream Mountain View, CA

Software Engineering Intern – Core Infrastructure Team

Summer 2017

Developed an entirely new blockchain format focused on scalability, user privacy, and fungibility.

Implemented the protocol as an open-source Bitcoin sidechain, decreasing disk and network usage by tens of gigabytes.

Philips Cambridge, MA

Software Engineering Intern – Acute Care Solutions (ACS) Team

Summer 2016

Prototyped various reinforcement and deep learning algorithms for use in behavior change applications/healthcare.

Researched machine learning methods to better adapt to individuals for improved efficacy and user engagement.

RESEARCH

MIT Biomimetic Robotics Lab

Cambridge, MA

Graduate Researcher – Sangbae Kim's Lab

Fall 2019 - Spring 2020

Developed a vision-based mapping and planning framework for the MIT Mini-Cheetah robotic platform.

Published a paper to IROS2020 as first author titled "Robust Autonomous Navigation of a Small-Scale Quadruped Robot in Real-World Environments."

NASA Biologic Analog Science Associated with Lava Terrains (BASALT)

Cambridge, MA

Undergraduate Researcher – MIT Man Vehicle Lab

Spring 2016

Optimized features for the SEXTANT API to allow for planning of efficient extravehicular traverses. Integrated resource-based path-optimization into the widely-utilized xGDS software using Python.

SKILLS & INTERESTS

Python • Rust • TypeScript • C/C++ • Machine Learning • HFT • Web3/Solidity/MEV

English • Polish • Spanish • Rubik's Cubes • Cycling • Alto Saxophone • MIT Bitcoin Club