```
int main() {
  return 0;
}
```

In the previous tutorial, we have written the $bare\ minimum\ PROGRAM\ in\ C-Language\ (the code above)$

When the micro-controller is Powered-Up, the CPU will execute all the instruction codes within the main() function body within the curly bracket {} pair. Ideally we must put whatever instruction code that we want the CPU to perform, before the "return 0;" instruction code.

Once the CPU executes the "return" code, function ends

When the main() function ends, our PROGRAM is "dead" and our micro-controller does not have any more instruction codes to run, it is now "brain dead". We do not want that to happen. We want to "live forever"

"SUPER LOOP"

Arduino IDE|Save PROGRAM as: **c_super_loop** Enter codes below and upload.

```
int main() {
  while(1)
  {
    // The codes within the "while" curly bracket { } pair
    // will be repeated forever
  }
  return 0; // our main() function will never reach here
}
```

In this PROGRAM, the "return 0;" instruction code inside our main() function will never be executed by the CPU. Meaning our main() function will never end, our PROGRAM 'lives forever"

The "instruction codes" within the "while loop" body section will be repeated forever because of the "while(1)" code

The forever "while loop" in the main() function is known as "SUPER LOOP"

In Regular Computers/Smartphone type of micro-controllers, we keep the CPU alive by using an "Operating System PROGRAM". In smaller micro-controllers we use "SUPER LOOP" or another technique called "RTOS - Real Time Operating System", where the "RTOS" allows us to run "multiple SUPER LOOP" inside PROGRAM. However, we will need more memory and processing power to use the RTOS. We will just stick to "SUPER LOOP" for now, "SUPER LOOP" is good enough for most PROGRAM used in micro-controllers

C-Language: programmers comment line "//"

The text after the "//" Symbol in our C-Language PROGRAM are "programmers comment line". They will not be included in the final PROGRAM. We put them in our PROGRAM Source Code to explain things

```
ATMEGA328/Arduino Uno - c_language "while loop"
https://github.com/teaksoon/lmaewapm
C-Language: while loop
There are 3 Parts in the "while loop"
Part1: "while" Keyword
Part2:condition - within a bracket ( ) pair
Part3:body - "instruction codes" within a curly bracket { } pair
                         Part2:condition
                          - placed within the bracket ( ) pair
                         - value of 0 or NOT 0
                         - can be variable name or constant name which
                         contains value of 0 or NOT 0
                         - can be an "expression" of a logic operation
                         resulting in value of 0 or NOT 0
                         - can be a function returning a value of 0 or NOT 0
             Part1: "while" Keyword
                      while (condition)
Part3: body
contains
"instruction codes"
- within a curly
bracket { } pair
"while loop" Starts with "condition evaluation:"
- when the condition is 0, "instruction codes" within the body will NOT be
executed. The PROGRAM continues with the "instruction codes" after the body
closing curly bracket "}"
- when the condition is NOT 0, "instruction codes" within the body will be
executed. After the last line of "instruction codes" in the body, PROGRAM
will run the "condition evaluation:" again, just like before
Example:
while(1) {
```

```
// This will run forever, condition has a fixed value 1, which is NOT 0
int cond value = 1;
while(cond value) {
  // This will run forever, as long as "cond_value" variable does not turn 0
int cond_value = 1;
while(cond_val == 1) {
  // This will run forever, as long as the logic "cond_value == 1" is true
  // true = 1, false = 0
int get_value() {return 1;}
while( get value() ) {
  // This will run forever, as long as get_value() does not return 0
 We can forced an immediate "exit from while loop" by coding break;
- We can forced an immediate "condition evaluation:" by coding continue;
```

https://github.com/teaksoon/lmaewapm

```
Step 1/3:
```

Start with a skeleton "while loop" with a default condition

while(0){}

Step 2/3:

We want to make a "SUPER LOOP", we need to repeat running the "instuction codes" in the "while loop" body "forever". We put a **non 0** for the "while loop" **condition** and make sure that condition will never change

while (1) { }

At this point, we already have a functional "while loop" for the main() function "SUPER LOOP"

Step 3/3:

Lets put something in the "while loop" body, so that we will have something to "see"

```
while(1) {
   PORTB = PORTB ^ (1<<PB5);
   _delay_ms(250);
}</pre>
```

We should be coding the "while loop" inside our bare_minimum main() function directly. We do it seperately here, so that we can see how it is coded, step by step

Below, is our completed "SUPER LOOP" that lives forever (turning LED ON and OFF forever)

Arduino IDE|Save PROGRAM as: c_super_loop_blink Enter codes below and upload.

```
#define F_CPU 16000000UL
#include <avr/delay.h>
#include <avr/io.h>
int main() {
    DDRB = DDRB | (1<<DDB5);
    while(1) {
        PORTB = PORTB ^ (1<<PB5);
        _delay_ms(250);
    }
    return 0;
}</pre>
```

Watch the LED on the Arduino Uno Board

The instruction codes inside the "while loop" body will be repeated forever because the "condition" for the "while loop" is always 1 (non-0)

#define F_CPU 1600000UL #include <avr/delay.h>

The two lines of codes above works together, they are required when we use the _delay_ms() function

#include <avr/io.h>

- The line of code above, is required when we use "DDRB", "DDB5", "PORTB" or "PB5" in our PROGRAM

```
Arduino IDE|Save PROGRAM as: c_super_loop_blink_function
Enter codes below and upload. Watch the LED on the Arduino Uno board
```

```
#define F_CPU 16000000UL
#include <avr/delay.h>
#include <avr/io.h>
int main() {

    setup_run_once(); // move the codes previously here into a function
    while(1) {

    loop_run_forever(); // move the codes previously here into a function
    }
    return 0; // our main() function will never reach here
}

void setup_run_once() {
    DDRB = DDRB | (1<<DDB5);
}

void loop_run_forever() {
    PORTB = PORTB ^ (1<<PB5);
    _delay_ms(250);
}</pre>
```

These are exactly the same

```
Arduino IDE|Save PROGRAM as: c_super_loop_blink_arduino
Enter codes below and upload. Watch the LED on the Arduino Uno board
```

```
void setup() {
   DDRB = DDRB | (1<<DDB5);
}

void loop() {
   PORTB = PORTB ^ (1<<PB5);
   _delay_ms(250);
}</pre>
```

The setup() and loop() functions in our regular Arduino Libaries PROGRAM are actually components of a "SUPER LOOP" BUT where is the main() function?

When we make PROGRAM using the **setup()** and **loop()** with the Arduino IDE Software, **the main() function has already been coded for us.** It is just being hidden from us by the Arduino IDE Software. The main() function is kept in a .cpp file in ther Arduino IDE installation folder:

<install folder>/hardware/arduino/avr/cores/arduino/main.cpp

```
int main(void)
{
  init();
  initVariant();
  #if defined(USBCON)
     USBDevice.attach();
  #endif

> setup();
  for (;;) {
  loop();
   if (serialEventRun) serialEventRun();
  }
  return 0;
}
```

< codes extracted from main.cpp
This main() function is doing
more things than ours</pre>

The hidden main() function provided by the Arduino IDE Software uses the "for loop" instead of the "while loop" in our example, both have the same effects

setup() and loop() function run from the main() function

ATMEGA328/Arduino Uno - Arduino "SUPER LOOP"

https://github.com/teaksoon/lmaewapm

From now onwards, we will be writing our PROGRAM using the C-Language with Arduino Libraries and the Arduino "SUPER LOOP"

We will not see the main() function anymore on our Arduino IDE Software. We will only see and code inside the **setup()** and **loop()** function

This style of coding is very much easier for learning process, as alot of details are already taken care for us by the Arduino Libraries

However, once a while we will still dive into the details, especially when it is something important

When we start writing a new PROGRAM.

We will start from the "bare minimum skeleton" code below, then we expand from there

void setup(){}
void loop(){}