

EVAClass.EVA_robot.Object_EVA

```
graph LR; A[EVAClass.EVA_robot.Object_EVA] --> B[sim.simxGetObjectPosition]; A --> C[sim.simxReadProximitySensor];
```

The diagram illustrates a class object, `EVAClass.EVA_robot.Object_EVA`, which is represented in a grey box on the left. Two blue arrows originate from the right side of this box and point to two separate white boxes on the right. The top white box contains the text `sim.simxGetObjectPosition`, and the bottom white box contains the text `sim.simxReadProximitySensor`. This visualizes the object's interaction with the simulation environment through these specific methods.

sim.simxGetObjectPosition

sim.simxReadProximitySensor