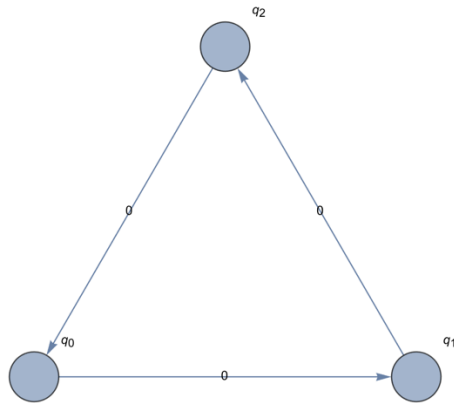
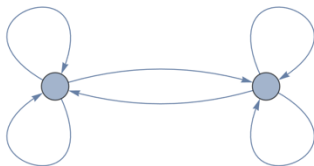


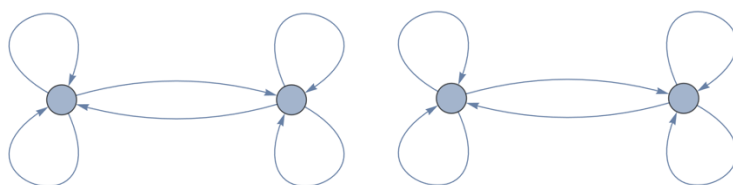
The motivation behind our project comes from the fact that biological organisms can be viewed as computers executing specific algorithms. Genetic regulatory networks, specifically, can be thought of as computational objects called finite state machines, or automata in short. An automata describes a dynamical system with a finite number of states and events. For example,



This is a very simple automaton with 3 states  $q_1$ ,  $q_2$ , and  $q_3$ . There is one event, labelled 0 (zero), which tells us how the states transform. Take the following automata (called the **flip-flop** automata).

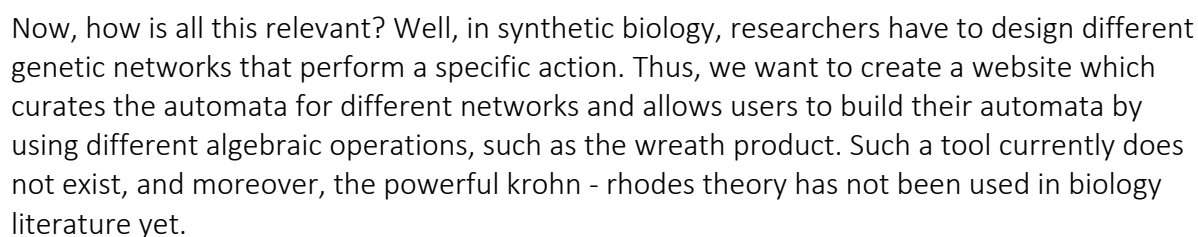
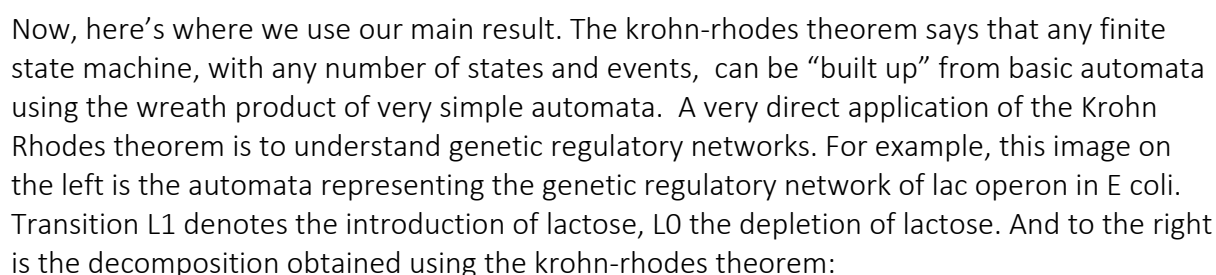


Now, we can define an algebraic operation called the direct product which takes 2 automata and “runs them simultaneously” , separately from each other



This is another automata. This way, we have built a new automata from 2 small automata. In a sense, that’s what an algebraic structure broadly is – it contains a set of elements, and an operation between them. We can define another operation called the wreath product of 2 automata. This is essentially a generalisation of the direct product, but includes a flow of information between them (so their computations can be related, unlike in the direct product case).

This is the wreath product of the **flip-flop** automata with itself:



We are currently in the process of implementing the decomposition of complicated in the backend website (*the code for the decomposition has already been implemented in a computer algebra software called GAP. The package is called SGP DEC*).