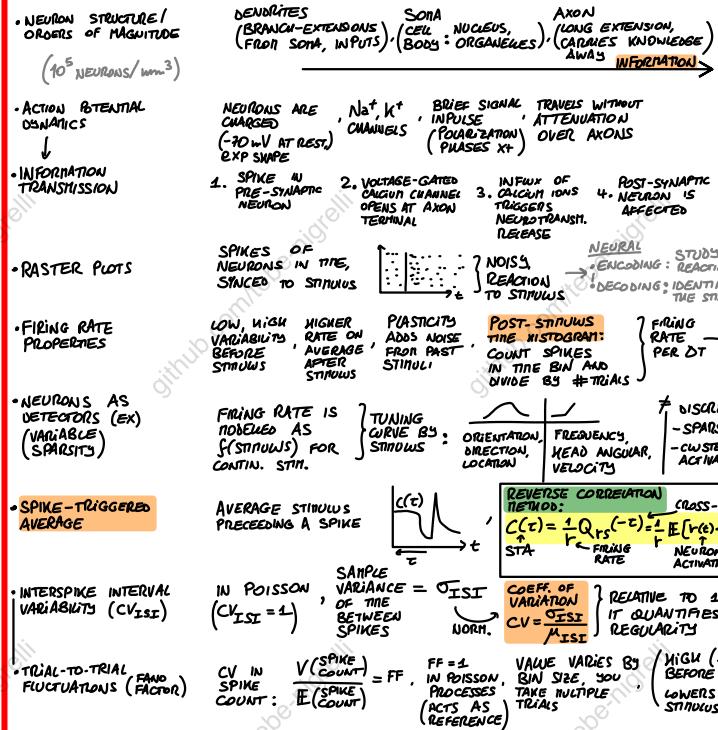


002 / CH1



INTUITION ON CONVOLUTION

THE INTEGRAL OF THE PRODUCT OF FUNCTIONS IS AN INNER PRODUCT OVER FUNCTIONS.
 $(f * g)(y) = \int f(x)g(y-x)dx$

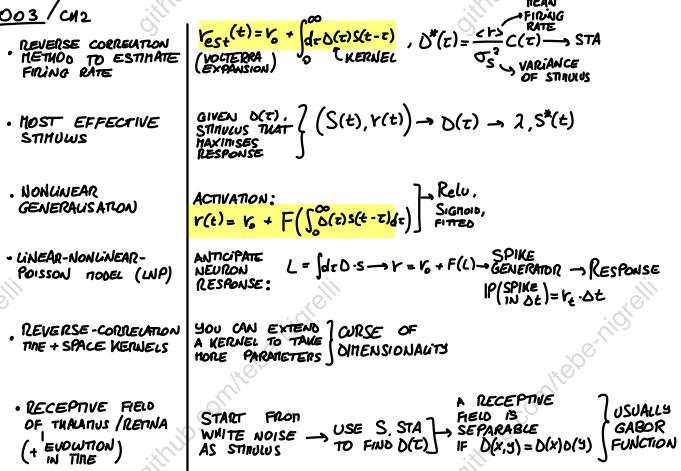
$(f * g)(y)$ IS OBTAINED BY WEIGHING SOME NEIGHBOURHOOD OF $g(y)$ BY f . IT IS THE DIFFERENTIAL UNIT OF A WEIGHTED SUM

$g(x)$ IS THE "KERNEL". IT GIVES A WEIGHING TO THE VALUE $g(y-x)$, AKA THE VALUE OF g AT x dist FROM y .

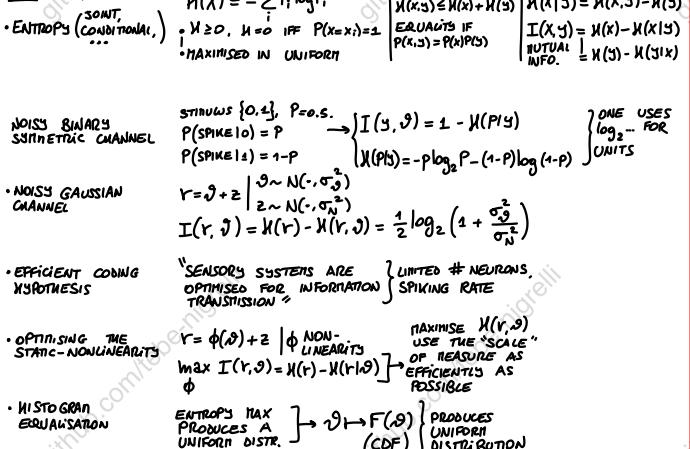
g CAN BE SEEN AS AN INFINITE VECTOR OF VALUES. $g(I(x,y))$ HAS $I(x,y) = y-x$ IF WHAT MATTERS ARE THE VALUES BEFORE y .

* THEORETICAL NEUROSCIENCE: COMPUTATIONAL AND MATHEMATICAL MODELING OF NEURAL SYSTEMS

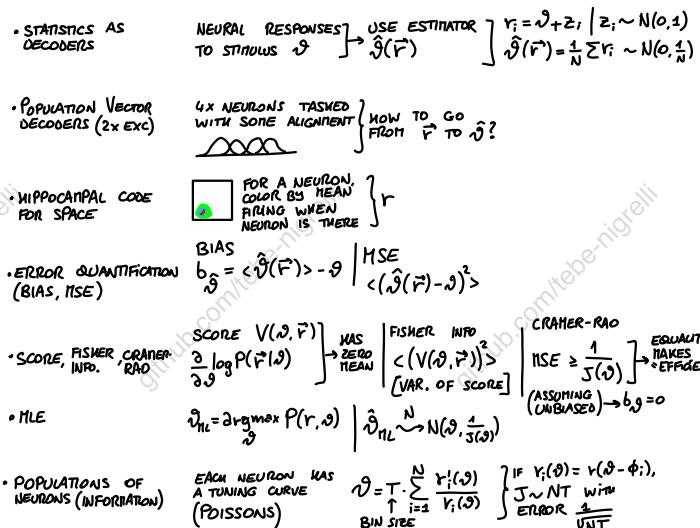
003 / CH2



005 / CH4



004 / CH3



012 / 017

• ANALYSIS OF 1D RNN

$$\tau_r \frac{du(t)}{dt} = -u(t) + F(h + Mu) \quad \left| \begin{array}{l} \text{YOU CAN STUDY A FIXED POINT LOCALLY WITH A LINEAR SYSTEM.} \\ \text{FROM THE TAYLOR EXPANSION} \end{array} \right.$$

WITH $h = Wu$ | $\boxed{\{u \mid u'(t) = 0\}}$

$$\tau_r \frac{du}{dt} = 2u \quad \boxed{| = -1 + M \frac{dF(h)}{dh}} \quad \boxed{|_{u=u_0}}$$

$\lambda > 0 \rightarrow \text{UNSTABLE}$
 $\lambda < 0 \rightarrow \text{ATTRACTOR}$
 $\lambda = 0 \rightarrow \text{FIXED VALUE}$

• 2, N DIM CASES

BUT $u(t)$: $\tau_r \frac{du}{dt} = J\dot{u}$ | J DOES NOT HAVE TO BE SYMMETRIC →

LINEARIZED: $J = \boxed{\lambda_1 \dots \lambda_n}$ | $\lambda_i \in \mathbb{C}$, λ_i NOT ALREADY ↴

$\Im(\lambda_i) = 0$ HAS 1D BEHAVIOR OVER C_μ
1. λ_i DISTINCT → ELSE, OSCILLATION
2. λ_i NOT DISTINCT → BEHAVIOR IS EXP WITH β_m FREE: $\Re(\lambda_i) < 0$ HAS DAMPING, ELSE GROWTH

• HETERO VS. HOM. NETWORKS

2X GROUPS OF NEURONS →

HOM	INHOM
• 2x NEURONS TOTAL	$N \gg 1$
• USED FOR STABILITY ANALYSIS	TESTING OF FIRING RATES

$\tau_r \frac{dv_E}{dt} = -v_E + [I_E + M_{EE}v_E - M_{EI}v_I]_+$
 $\tau_r \frac{dv_I}{dt} = -v_I + [I_I + M_{IE}v_E - M_{II}v_I]_+$

IN BOTH CASES THERE IS A SINGLE EFFECTIVE NEURON

• HOMOGENOUS EXC/INH. POPULATIONS

$$M > 0 \quad \left\{ \begin{array}{l} \tau_r \frac{dv_E}{dt} = -v_E + [I_E + M_{EE}v_E - M_{EI}v_I]_+ \\ \tau_r \frac{dv_I}{dt} = -v_I + [I_I + M_{IE}v_E - M_{II}v_I]_+ \end{array} \right.$$

[...: $\frac{du}{dt}|_{P_0} = 0$]

1. FOR FIXED POINT P . 2. PLOT NULLCLINES WITH P AT INTERSECTION
3. STABLE IF $\Re(\lambda_{\text{LARGEST EIG. VALUE}}) < 0$

STABLE **UNSTABLE**

• INHIBITORY STABILISATION PARADOXES

TWO POPULATIONS MODEL HAS A FIXED POINT IS STABLE IF $\Re(\lambda) > 0$, IT'S POSSIBLE THAT A HIGHER STIMULUS TO INHIBITORY NEURONS LOWERS OVERALL FIRING RATE

$$M = \begin{bmatrix} M_{EE} & M_{EI} \\ M_{IE} & M_{II} \end{bmatrix}, \text{ FOR } \lambda \text{ EIGEN IN THE LINEARIZED SYSTEM}$$

BY FIRING MORE OFTEN, INHIBITORY NEURONS REDUCE THE RATE OF THE NEURONS THAT WERE STIMULATING THEM