

ILP
 → NP-HARD (YOU CAN ENCODE 3SAT IN ILP)
 → WEAK DUALITY HOLDS BUT NOT STRONG

TU
 A MATRIX IS TU IFF $\forall e \in \mathbb{Z}^n$
 $\text{DET}(\text{SUBMATRIX}) = 0, 1, -1 \iff P = \{x | Ax \leq b, x \geq 0\}$
 IS INTEGER

TU PRESERVED BY:
 $\begin{pmatrix} A \\ I \end{pmatrix}, \begin{pmatrix} A \\ -I \end{pmatrix}, \begin{pmatrix} -I \\ A^T \end{pmatrix}$ → PROVE DIRECTLY BY EXPANDING USING LAPLACE FORMULA

P IS INTEGER \iff ALL VERTICES POLYHEDRON ARE INTEGER

INCIDENCE MATRIX OF A GRAPH: $A \in \mathbb{R}^{|V| \times |E|}$
 $A_{v,e} = \begin{cases} 1 & v \in e \\ 0 & \text{otherwise} \end{cases} \rightarrow A = \left[\begin{matrix} \text{SUM OVER } v = 2 \end{matrix} \right]_{|V|}$

BIPARTITE = YOU CAN PARTITION VERTICES IN TWO SO NO VERTICES ARE ADJACENT

GRAPH IS BIPARTITE \Rightarrow TU INCIDENCE MATRIX

MATCHING: SELECT EDGES WITHOUT TOUCHING THE SAME VERTEX MORE THAN ONCE
 • SIZE \rightarrow # EDGES USED
 • MAX/MIN \rightarrow ACCOUNTS FOR EDGE WEIGHT
 • PERFECT \rightarrow TOUCHES ALL VERTICES (MAY NOT EXIST)

MAX-CARD. MATCHING: SELECT EDGES ST. EACH VERTEX IS TOUCHED ONCE
 $\max \sum x_e$ (O/1 FOR WHETHER YOU SELECT EDGE x_e)
 $\forall v \in V \sum_{e \in v} x_e \leq 1$ (SELECT ONE OF EDGES PER VERTEX)
 $\forall e \in E \begin{cases} x_e \geq 0 \\ x_e \in \mathbb{Z} \end{cases}$
 PERFECT MATCHING = COVERS ALL VERTICES (NOT ALWAYS POSSIBLE)

DUAL \longleftrightarrow

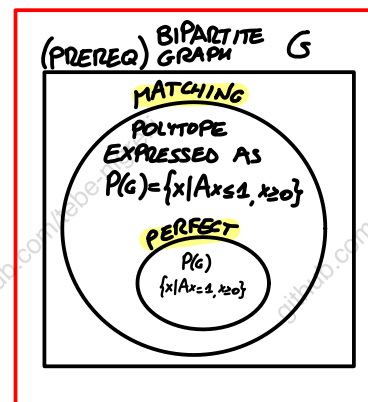
STRONG DUALITY HOLDS IN THIS FOR BIPARTITE GRAPHS
 KÖNIG'S MATCHING THEOREM

MIN CARD. VERTEX COVER: SELECT VERTICES ST. ANY EDGE IS TOUCHED AT LEAST ONCE
 $\min \sum y_v$
 ST. $\forall u, v \in E \quad y_u + y_v \geq 1$ (YOU SELECT AT LEAST/NOT ONE OF TWO)
 $\forall v \in V \quad y_v \geq 0$
 $y_v \in \mathbb{N}$

REPRESENT A SELECTION OF EDGES
 $x^F \in \mathbb{R}^E, F \subseteq E$ (PARTITION OF EDGES)
 $x_e^F = \begin{cases} 1 & \text{if } e \in F \\ 0 & \text{otherwise} \end{cases}$ (THIS IS SOMETHING YOU CAN EVALUATE WITH THE INCIDENCE MATRIX)

→

IN BIPARTITE GRAPHS, MATCHING POLYTOPES HAVE A SHORT EXPRESSION
 MATCHING POLYTOPE = $\text{CONV} \{x^\pi \mid \pi \text{ IS A MATCHING IN } G\}$
 $(G \text{ IS BIPART}) = \{x \in \mathbb{R}^E \mid Ax \leq \underline{1}, x \geq 0\}$
 PERFECT MATCHING = $\text{CONV} \{x^\pi \mid \pi \text{ IS A P. MATCHING IN } G\}$
 $= \{x \in \mathbb{R}^E \mid Ax = \underline{1}, x \geq 0\}$



(BIPARTITE GRAPH ASSUMPTION) \oplus MAX INDEP. SET = THE LP RELAXATION (AKA A^T) HAS INTEGER OPTIMUM

MAX CARD INDEP SET = LARGEST SET OF NON-ADJACENT VERTICES

$$\begin{aligned} \max \sum y_v & \text{ s.t. } A^T y \leq \mathbb{I} \\ y_v & \geq 0 \\ y_v & \in \{0, 1\} \end{aligned}$$

INDEP SET POLYTOPE = $\text{CONV} \{x^I \mid I \subseteq V \text{ is indep. of } G\}$

\oplus
(BIPARTITE GRAPH ASSUMPTION)
=
 $\{y \mid A^T y \leq \mathbb{I}, y \geq 0\}$

(WITHOUT BIPARTITE ASSUMPTION) \rightarrow NO SIMPLE REPRESENTATION

$$P_{\text{MATCH}}(G) \subseteq \{x \in \mathbb{R}^E \mid Ax \leq \mathbb{I}, x \geq 0\}$$

$$P_{\text{INDEP}}(G) \subseteq \{x \in \mathbb{R}^V \mid A^T x \leq \mathbb{I}, x \geq 0\}$$

INCIDENCE MATRIX
DIRECTED GRAPH \Rightarrow TU MATRIX SO INTEGER POLY.
 $M \in \mathbb{R}^{V \times E}$
 $M_{e,v} = \begin{cases} 1 & e \text{ LEAVES } v \\ -1 & e \text{ ENTERS } v \\ 0 & \text{else} \end{cases}$

"FLOW CONFIGURATION"
 $f \in \mathbb{R}^E$

CIRCULATION
 $\forall v \in V$

$$\sum_{e \in \text{in}} f_e = \sum_{e \in \text{out}} f_e$$

(THERE IS FLOW CONSERV.)
 \Updownarrow
 $\Pi f = 0$ (FOR EACH NODE)

\neq FLOW CONSERVATION HOLDS EXCEPT FOR λ SOURCE & SINK

MAX FLOW PROBLEM

$$\begin{aligned} \max \sum f_x & \quad \min \sum c_x \quad (\text{MIN CUT}) \\ \text{s.t. } M^T x = 0 & \quad (\text{FLOW CONSERV.}) \quad \forall \text{ PATH } \sum c_x \leq 1 \\ x \leq c & \quad (\text{CAPACITY CONSTRAINT}) \quad x_e \in \{0, 1\} \\ x \geq 0 & \end{aligned}$$

(M^T BEING Π EXCEPT 2 ROWS PRODUCING λ, t)
 \uparrow YOU DON'T CARE ABOUT FLOW CONSERVATION

INTEGRITY GAP: (= 1 IF THE GRAPH IS BIPARTITE, ≤ 2 IN GENERAL)
 $\max c^T x$ s.t. $Ax \leq b$ \rightarrow x^I OPTIMAL ILP \rightarrow $\frac{c \cdot x^I}{c^T x^*}$ (YOU INVERT FRACTION IN MINIMISATION EXAMPLES)
 $x \in \mathbb{N}$ \rightarrow x^* OPTIMAL OF RELAXATION

APPROXIMATION RATIO (r):

$$\frac{\text{OPT}(I)}{\text{ALG}(I)} = \frac{\text{BEST OBJECTIVE}}{\text{SOLUTION}} \rightarrow \frac{\text{OPT}(I)}{\text{ALG}(I)} \leq r \quad (\text{YOU INVERT FRACTION IN MINIMISATION EXAMPLES})$$

MIN COST FLOW

$$\begin{aligned} \min \sum c^T x \\ \text{s.t. } M^T x = 0 \\ x \leq c \quad (\text{CAPACITY CONSTRAINT}) \\ W^T x \geq \alpha \quad (\text{AT LEAST FLOW } \alpha) \\ x \geq 0 \end{aligned}$$

IF $c \in \mathbb{Z}_+^E$
 \Downarrow
INTEGER OPTIMAL SOLUTION EXISTS

ROW THAT CORRESPONDS TO THE SOURCE

MIN-COST NON BIPARTITE PERFECT MATCH

$$\begin{aligned} \min \sum_{e \in E} c_e x_e \\ \forall v \in V \quad x(\delta(v)) = 1 \quad (\text{SELECT ONE EDGE PER VERTEX}) \\ \forall u \in V \quad x(\delta(u)) \geq 1 \\ |U| \geq 3 \\ \forall e \in E \quad x_e \geq 0 \end{aligned}$$

MATROID

$(X, I) \leftarrow I \subseteq 2^X$ (SET OF SUBSETS OF X)
 ↑
 GIVES THE ELEMENTS

- $\emptyset \in I$
- $\forall e \in I, z \subseteq y \Rightarrow z \in I$ (CONTAINS ALL SUBSETS OF ITS ELEMENTS)
- $\forall y, z \in I, |y| < |z| \Rightarrow \exists x \in z \setminus y: \forall u \{x\} \in I$

$G = (V, E)$ THEN
 $(E, I \subseteq 2^E)$
 IS A MATROID

$w: X \rightarrow \mathbb{R}$, FIND $y \in I$
 ST. $w(y) = \sum_{y \in y} w(y)$ IS MAX

↓
 PICK THE GREATEST y
 (IF GREEDY FINDS y^* ,
 $\forall w$ FUNCTION $\Rightarrow (X, I)$ IS MATROID)

SUBMODULAR FUNCTIONS

X FINITE SET

$f: 2^X \rightarrow \mathbb{R}$

$$\forall A, B \subseteq X \quad f(A) + f(B) \geq f(A \cup B) + f(A \cap B)$$

- LINEAR $\rightarrow f(A) = \sum_{i \in A} w(i)$ [Also $-f(A)$]
- BUDGET $\rightarrow f(A) = \min \left\{ \sum_{i \in A} w(i), B \right\}$ FOR $B \geq 0$
- CUT IN GRAPH $\rightarrow c: E \rightarrow \mathbb{R}_+$
 $f: 2^V \rightarrow \mathbb{R}_+$
 $f(S) = c(\delta(S))$

BRANCH AND BOUND

$$\max c^T x$$

$$\text{st. } Ax \leq b$$

$$x \in \mathbb{Z}^n$$

- SOLVE RELAXATION
- SELECT i ST. $x_i^* \notin \mathbb{Z}$

CREATE TWO BRANCHES:

- $\begin{cases} x_i \leq \lfloor x_i^* \rfloor \\ x_i \geq \lceil x_i^* \rceil + 1 \end{cases} \rightarrow \begin{cases} \text{A. INFEASIBLE} \\ \text{B. INTEGER OPT.} \\ \text{C. RELAXATION IS SUBOPT. WRT. INTEGER} \end{cases}$
- (USE DFS HEURISTICS) STOP BRANCHES

SPECTRAL NORM

$$\|A\| = \max_{\|v\|=1} \|Av\| = \max_{\|v\|=1} \|Av\|$$

GRADIENT DESCENT $\rightarrow x_{t+1} = x_t - \gamma \nabla f(x_t)$

PROJECTED $\rightarrow y_{t+1} = x_t - \gamma \nabla f(x_t)$
 $x_{t+1} = \Pi_x(y_{t+1}) = \arg \min_{x \in X} \|x - y_{t+1}\|^2$

SUBGRADIENT $\rightarrow (g_t \in \partial f(x_t)) x_{t+1} = x_t - \gamma_t g_t$

STOCHASTIC
 $i \sim \text{UNIF}(1..n)$

$$f(x) = \frac{1}{n} \sum_{i=1}^n f_i(x)$$

$$x_{t+1} = x_t - \gamma_t \nabla f_i(x_t)$$

STOCHASTIC SUBGRADIENT

$$g_t \in \partial f_i(x_t)$$

$$x_{t+1} = x_t - \gamma_t g_t$$

STOCHASTIC MINIGATCH

$$i_1, \dots, i_m \sim \text{UNIF}(1..n)$$

$$\tilde{g}_t = E_m(g_t^i)$$

$$x_{t+1} = x_t - \gamma_t \tilde{g}_t$$

YOU CAN ADD REDUNDANT CONSTRAINTS TO LP FORMULATIONS TO REDUCE THE SIZE OF THE POLYEDRON

P POLYEDRON REPRESENTED WITH $\{x | Ax \leq b\}$
 TDI: A INTEGRAL b RATIONAL
 $P' = \{Ax \leq \lfloor b \rfloor\}$
 AND $P' \subseteq P$

ONLINE OPTIMISATION

- ROUNDS:
 \rightarrow PICK x_t ACTION
 \rightarrow LOSS $f_t(x_t)$
- MINIMISE REGRET
 $R_T = \sum_{t=1}^T (f_t(x_t) - f(x^*))$

ONLINE GO
 $y_{t+1} = x_t - \gamma_t \ell_t$
 $x_{t+1} = \Pi_x(y_{t+1})$
 $R_T \leq RBUT$

TELLS HOW TO CHANGE EACH EXPERT'S ACTIONS USING LOSS

FOLLOW THE (FTL) LEADER

$$i_t = \arg \min_i \left\{ \sum_{j=1}^{t-1} \ell_j \cdot e_i \right\}$$

(KEEP TRACK RECORD FOR EACH, PICK THE BEST)

REGULARISED / USES PROB. DISTRIBUTION

$$x_0 = \arg \min_{x \in X} \phi(x)$$

$$i_t = \arg \min_i \left\{ \sum_{j=1}^{t-1} \ell_j \cdot x + \frac{1}{\gamma} \phi(x) \right\}$$

ϕ CONVEX | x AS ACTION MEANS TAKING A DISTRIBUTION OVER THE CHOICES

DUAL $\rightarrow \|x\|_p = \max \{z^T x | \|z\|_q \leq 1\}$
 NORM OF NORM $\ell_p \leftrightarrow \ell_q$

ENTROPY REGULARISATION

$$\phi(x) = \sum x_i \log(x_i)$$

1. STRONG CONVEX WITH $\|\cdot\|_2$ ON Δ_n = PROBABILITY SIMPLEX
 $R_T \leq 2RBUT$

IF ℓ_2 REGULARISED, EQUIVALENT TO:

$$y_{t+1} = y_t - \gamma \nabla f_t(x_t)$$

$$x_{t+1} = \Pi_x(y_{t+1})$$

THIS IS LAZY BECAUSE y IS UPDATED FROM y , IT'S LIKE x_t FOLLOWS y_t FROM INSIDE $X \subseteq \mathbb{R}^d$. LIKE A DOG INSIDE AN ENCLOSURE, TRYING TO GET AS CLOSE AS POSSIBLE TO THE MAINW

HEDGE

$$w_1 = \mathbb{I}$$

$$w_{t+1} = w_t(i) \cdot e^{-\gamma \ell_t(i)} \quad (\text{UPDATE WEIGHTS})$$

$$x_{t+1} = \frac{w_{t+1}}{\|w_{t+1}\|_1} \quad (\text{NEW IP FOR } x)$$

$Ax \leq b$ CAN BE TDI WITH b NON-INTEGER

RATIONAL INEQUALITY A, b

MEANING THE DUAL HAS INTEGRAL SOLUTIONS:
 $\min \{b^T y | A^T y = c, y \geq 0\}$
 $\forall c \in \mathbb{Z}^n$

A TU MATRIX

\oplus b INTEGRAL

\downarrow
 $Ax \leq b$ TDI SYSTEM \oplus A RATIONAL
 \downarrow
 POLYTOPE IS INTEGRAL

TDI \Rightarrow DUAL SOLUTION IMPLIES BOUNDED PRIMAL OPTIMUM
 \downarrow
 POLYTOPE, NOT POLYHEDRON

YOU CAN WRITE POLYHEDRON AS TDI SYSTEM, A INTEGRAL \rightarrow AS A RESULT b INTEGRAL \updownarrow P INTEGRAL
 $Ax \leq b$ TDI