

## 7 PERCEPTRON

• McCulloch-Pitts NEURON  $y = \Theta(\underline{w} \cdot \underline{x} - T)$

• FEEDFORWARD/RECURRENT  
(PATTERN RECOGNITION) (SHORT-TERM MEMORY)

• PERCEPTRON LEARNING

↳ ALGORITHM:

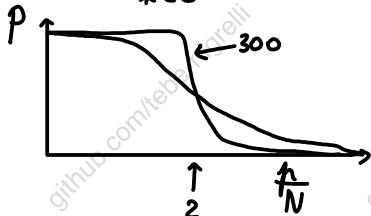
FOR WRONG CLASSIFICATIONS OF  $\vec{x}^k$

$$\vec{w}_{t+1} = \vec{w}_t + \eta \vec{x}^k$$

→ CONVERGENCE IN  $t < \frac{k^2}{\epsilon^2}$  (PROOF)

COVER FORMULA (P FINDING  $\underline{w}$ )  
100% CORRECT

$$P = \frac{1}{2^{p-1}} \sum_{k=0}^{N-1} \binom{p-1}{k}, \quad \binom{p-1}{k} = 0 \text{ if } k > p-1$$



COVER GENERALISATIONS

→ SIGN CONSTRAINED  $\Rightarrow$  CAPACITY  $P = N$

• COVER LIMITATIONS

→ SLOWER LEARNING IF DATA IS UNBIASED

→ NO WAY TO QUANTIFY ROBUSTNESS

↳ LEARNING SHOULD BE ROBUST AGAINST NOISE

## 8 SUPPORT VECTOR MACHINES

LINEAR SEPARABILITY ASSUMPTION

MAXIMISE DISTANCE BETWEEN POINTS:

PICK  $\underline{w}$  ST.

$$\begin{cases} \underline{w}^T \underline{x}_+ + b = 1 \\ \underline{w}^T \underline{x}_- + b = -1 \end{cases} \text{ FOR } \underline{x}_+, \underline{x}_- \text{ SUPPORT VECTORS}$$

OPTIMISATION PROBLEM:

$$\max_{\underline{w}} \frac{2}{\|\underline{w}\|} \text{ (MARGIN)}$$

$$\text{ST. } \begin{cases} \underline{w}^T \underline{x}_n \geq 1 & \text{IF } y_n = +1 \\ \underline{w}^T \underline{x}_n \leq -1 & \text{IF } y_n = -1 \end{cases}$$

OR

$$\min_{\underline{w}} \|\underline{w}\|^2 \text{ ST. } y_n (\underline{w}^T \underline{x}_n + b) \geq 1 \quad \left( \begin{array}{l} \text{USE GRAD.} \\ \text{DESCENT} \end{array} \right)$$

TRADEOFF: MARGIN / # MISTAKES

SOFT MARGIN (ALLOWS FOR SOME MISTAKES)

$$\min_{\underline{w}, b, \xi} \frac{1}{2} \|\underline{w}\|^2 + C \sum_{n=1}^N \xi_n \quad \leftarrow \text{SLACK PER VARIABLE}$$

$$\text{ST. } y_n (\underline{w} \cdot \underline{x}_n + b) \geq 1 - \xi_n$$

$$\xi_n \geq 0$$

C REG. PARAMETER:  
LARGER C MEANS MORE SEVERE PENALISATION, SO NARROWER MARGIN

OR

$$\begin{cases} f(\underline{x}) = \underline{w} \cdot \underline{x} + b \\ y_n f(\underline{x}_n) \geq 1 - \xi_n \\ \xi_n \geq 0 \end{cases}$$

$$\xi_n = \max(0, 1 - y_n f(\underline{x}_n))$$

JUST MINIMISE:

$$\min_{\underline{w}} \frac{1}{2} \|\underline{w}\|^2 + C \sum_{n=1}^N \max(0, 1 - y_n f(\underline{x}_n))$$

↑ REGULARISATION TERM

HINGE LOSS

THE PROBLEM IS CONVEX  
( $\sum \text{CONV} = \text{CONV}$ )

HINGE LOSS

$$\ell(t) = \max\{0, 1 - t\}$$

$$t = y f(\underline{x}) = y (\underline{w} \cdot \underline{x} + b)$$

ONLY IF WRONG

CANNOT BE DIFFERENTIATED, ZERO-ONE LOSS  $\rightarrow$  DIFFICULT TO MINIMISE

GRADIENT DESCENT:

$$\underline{w}_{t+1} = \underline{w}_t - \eta_t \nabla_{\underline{w}} C(\underline{w}_t)$$

$g(\underline{w})$  TO BE MINIMISED

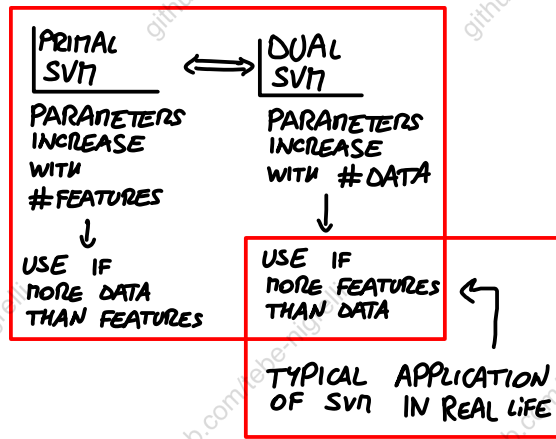
$$= \underline{w}_t - \eta \frac{1}{N} \sum_{n=1}^N (\lambda \underline{w}_t + \nabla_{\underline{w}} \ell(\underline{x}_n, y_n, \underline{w}_t))$$

SGD USES MINI BATCHES INSTEAD OF ALL THE DATA

SINGLE LOSS OVER DATA, MODEL

DUE TO HINGE LOSS, ONLY POINTS STRICTLY VIOLATING THE MARGIN CONTRIBUTE TO THE GRADIENT

## 9 SUPPORT VECTOR MACHINES II



NONLINEAR SVM → MORE FLEXIBLE

DISCRIMINANT FUNCTION:  
 $f(x) = \begin{cases} 1 & \hat{w} \cdot \phi(x) + b > 0 \\ -1 & \text{ELSE} \end{cases}$

"LINEARITY" IS KEPT

SHORTCUT TO APPLY THE NONLINEARITY WHILE SKIPPING SOME COMPUTATIONS AND ONLY OBTAINING THE  $f(x) \cdot f(y) = ?$  INSTEAD OF EVAL.  $f$  TWICE

→ MORE FLEXIBLE  
→ LESS COMPUTE

**KERNEL FUNCTION:**  
 $k: X \times X \rightarrow \mathbb{R}$   
•  $k(x, y) = k(y, x)$   
• POS-DEFINIT.

**KERNEL TRICK:**  
APPLY NON-LIN TO DATA THEN APPLY LINEAR SVM

ENSURES CONVEXITY

$\phi(x)$  IS QUICKER TO COMPUTE BECAUSE IT SKIPS INTERMEDIATE HIGH-DIM STEPS

$k(x_1, x_2) = \phi(x_1) \cdot \phi(x_2)$

↑  
WANT TO DESCRIBE  
↑  
REARRANGE IN TERMS OF  $\phi$

KERNEL PROPERTY IS KEPT.

- $\lambda \geq 0 \rightarrow \lambda k_1$
- $k_1 + k_2$
- $k_1^n, \Pi k_i$

USING CONVEX DUALITY,  
 $w^* = \sum_{n=1}^N \alpha_n y_n x_n$

→ REPRESENTER THEOREM:  
SOLUTION TO OPTIMISATION IS IN SPAN OF DATA

**SAMPLE KERNELS**

- POLYN. DEG =  $d \rightarrow k(x, y) = (x \cdot y)^d$   
DEG  $\leq d \rightarrow (1 + x \cdot y)^d$
- RADIAL BASIS FUNCTIONS  $\rightarrow \exp\left(-\frac{\|x - y\|^2}{2\sigma^2}\right)$

## 10 RECURRENT NN

ALLOW FOR MEMORY OPERATIONS

TYPES OF NEURONS

- $\pm 1$
- $\{0, 1\}$
- $1, \dots, N$

$$S_i(t+1) = \phi\left(\sum_j w_{ij} S_j(t) + I_i(t)\right)$$

OFFSET DEPENDS ON  $i, t$   
W MATRIX OF WEIGHTS FOR CROSS-BEHAVIOUR

PARALLEL / ASYNCHRONOUS UPDATES

DISCRETE / CONTINUOUS TIME  $\rightarrow r_i(t+1) = \dots$

$\phi$  ACTIVATION FUNCTION (SIGMOID, RELU)

$$\tau \frac{dr_i}{dt} = -r_i + \dots$$

## 11 HOPFIELD MODEL

DESCRIPTION:  $N$  BINARY ( $\pm 1$ ) NEURONS,

$$S_i(t+1) = \text{sgn}\left(\sum_j J_{ij} S_j(t)\right)$$

$P$  PATTERNS TO MEMORISE ( $\xi_i^{\mu} = \pm 1$ )

HEBBIAN MATRIX:  $J_{ij} = \frac{1}{N} \sum_{\mu} \xi_i^{\mu} \xi_j^{\mu}$

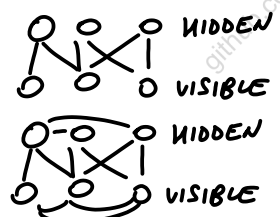
NOISE, CROSS-INTERACTIONS

PATTERN COMPLETION: IF THERE IS AN OVERLAP WITH A STORED PATTERN, THE NETWORK CONVERGES TO IT IN ONE STEP

## 12 RESTRICTED BOLTZMANN MACHINES

• TRAIN MACHINES TO LEARN THE DISTRIBUTION OF THE DATA FEATURES

- RESTRICTED  $\rightarrow$  CONNECTIONS ONLY BETWEEN VISIBLE  $\leftrightarrow$  HIDDEN
- BOLTZMANN MACHINE  $\rightarrow$  SAME TYPE NEURONS ARE CONNECTED



PHASES

- LEARN: VISIBLE =  $x$ , MUST LEARN TO GENERATE  $x$  WITH HIGH PROB.
- SAMPLE: FIXED WEIGHTS, DEFINE ENERGY  $f$ , NATURAL CONVERGENCE TO LOWEST VALUE

SYMMETRIC NETWORK ( $J_{ij} = J_{ji}$ )  $\rightarrow$  ENERGY FUNCTION (LAPLACE):  $-\frac{1}{2} \sum_{i,j} J_{ij} S_i S_j = E(S_1 \dots S_N)$

$\Downarrow$  AS "TEMP. DECREASES" AND CONVERGENCE

$$P(S_1 \dots S_N) = \frac{1}{Z} \exp(-\beta E(S_1 \dots S_N))$$