

# CSE408 Closest pair & Convex Hull Problem, Insertion Sort

Lecture #13

# Divide-and-Conquer

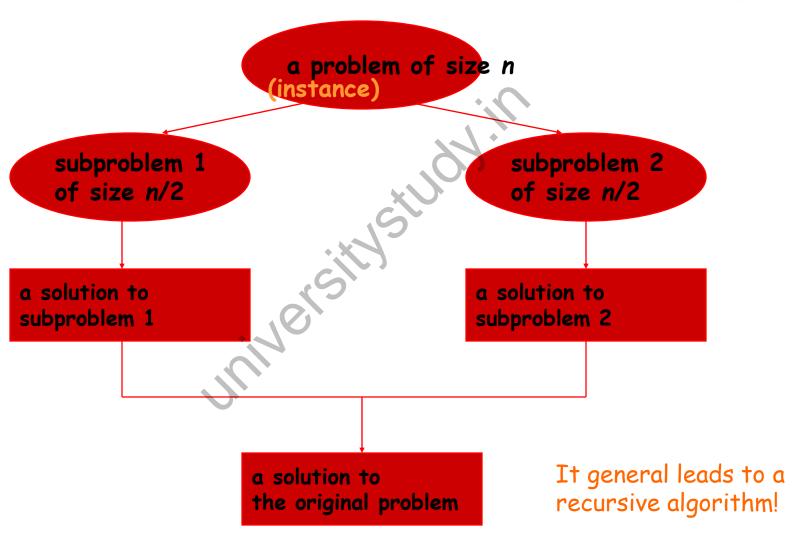


The most-well known algorithm design strategy:

- Divide instance of problem into two or more smaller instances
- 2. Solve smaller instances recursively
- Obtain solution to original (larger) instance by combining these solutions

# Divide-and-Conquer Technique (cont.)

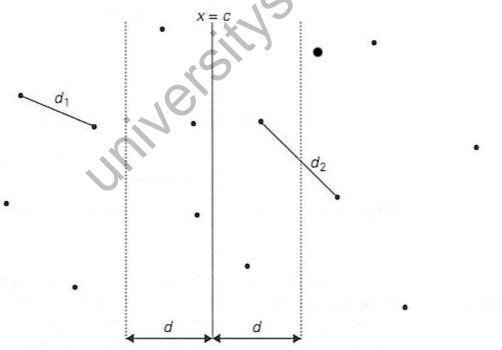




# Closest-Pair Problem by Divide-and-Congrer

Step 0 Sort the points by x (list one) and then by y (list two).

Step 1 Divide the points given into two subsets  $S_1$  and  $S_2$  by a vertical line x = c so that half the points lie to the left or on the line and half the points lie to the right or on the line.

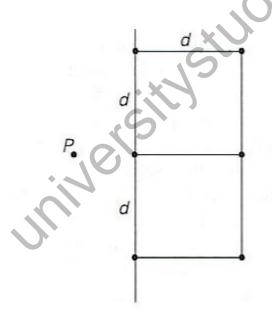


# Closest Pair by Divide-and-Conquer (

- Step 2 Find recursively the closest pairs for the left and right subsets.
- Step 3 Set  $d = \min\{d_1, d_2\}$ We can limit our attention to the points in the symmetric vertical strip of width 2d as possible closest pair. Let  $C_1$  and  $C_2$  be the subsets of points in the left subset  $S_1$  and of the right subset  $S_2$ , respectively, that lie in this vertical strip. The points in  $C_1$  and  $C_2$  are stored in increasing order of their y coordinates, taken from the second list.
- Step 4 For every point P(x,y) in  $C_1$ , we inspect points in  $C_2$  that may be closer to P than d. There can be no more than 6 such points (because  $d \le d_2$ )!

# Closest Pair by Divide-and-Conquer: Worst Case

The worst case scenario is depicted below:



# Efficiency of the Closest-Pair Algorithm

Running time of the algorithm (without sorting) is:

$$T(n) = 2T(n/2) + M(n)$$
, where  $M(n) \in \Theta(n)$ 

By the Master Theorem (with 
$$a=2, b=2, d=1$$
)
$$T(n) \in \Theta(n \log n)$$

So the total time is  $\Theta(n \log n)$ .

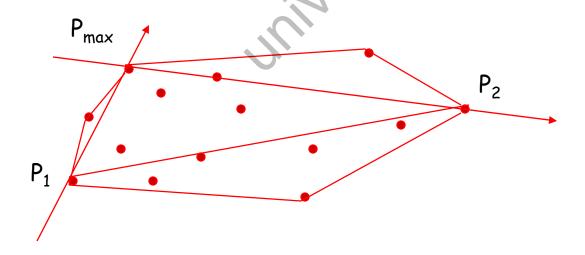
# Convex hull Algorithm



Convex hull: smallest convex set that includes given points. An  $O(n^3)$  bruteforce time is given in Levitin, Ch 3.

Assume points are sorted by x-coordinate values Identify extreme points  $P_1$  and  $P_2$  (leftmost and rightmost) Compute upper hull recursively:

- find point  $P_{\text{max}}$  that is farthest away from line  $P_1P_2$
- $_{\scriptscriptstyle \square}$  compute the upper hull of the points to the left of line  $P_1P_{\scriptscriptstyle{\text{max}}}$
- $_{\rm o}$  compute the upper hull of the points to the left of line  $P_{\rm max}P_{\rm 2}$  Compute lower hull in a similar manner



# Efficiency of Convex hull Algorithm



Finding point farthest away from line  $P_1P_2$  can be done in linear time Time efficiency: T(n) = T(x) + T(y) + T(z) + T(v) + O(n),

where 
$$x + y + z + v <= n$$
.

worst case:  $\Theta(n^2)$  T(n) = T(n-1) + O(n)

average case:  $\Theta(n)$  (under reasonable assumptions about distribution of points given)

If points are not initially sorted by x-coordinate value, this can be accomplished in  $O(n \log n)$  time

Several  $O(n \log n)$  algorithms for convex hull are known

Iteration i. Repeatedly swap element i with the one to its left if smaller.

Property. After ith iteration, a[0] through a[i] contain first i+1 elements in ascending order.

Array index	0	1	2	3	4	5	6	7	8	9
Value	2.78	7.42	0.56	1.12	1.17	0.32	6.21	4.42	3.14	7.71

Iteration 0: step 0.

Iteration i. Repeatedly swap element i with the one to its left if smaller.

Property. After ith iteration, a[0] through a[i] contain first i+1 elements in ascending order.

Array index	0	1	2	3	4	5	6	7	8	9
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Iteration 2: step 0.

Iteration i. Repeatedly swap element i with the one to its left if smaller.

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Array index	0	1	2	3	4	5	6	7	8	9
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Value	0.56	2.78	1.12	7.42	1.17	0.32	6.21	4.42	3.14	7.71

Iteration 3: step 0.

Iteration i. Repeatedly swap element i with the one to its left if smaller.

Property. After ith iteration, a[0] through a[i] contain first i+1 elements in ascending order.

Array index	0	1	2	3	4	5	6	7	8	9
Value	0.56	1.12	2.78	7.42	1.17	0.32	6.21	4.42	3.14	7.71

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Iteration 4: step 2.

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Property. After ith iteration, a[0] through a[i] contain first i+1 elements in ascending order.

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Iteration 5: step 0.

Iteration i. Repeatedly swap element i with the one to its left if smaller.

Property. After ith iteration, a[0] through a[i] contain first i+1 elements in ascending order.

Array index	0	1	2	3	4	5	6	7	8	9
Value	0.56	1.12	1.17	0.32	2.78	7.42	6.21	4.42	3.14	7.71

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Iteration 5: step 4.

Iteration i. Repeatedly swap element i with the one to its left if smaller.

Property. After ith iteration, a[0] through a[i] contain first i+1 elements in ascending order.

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Iteration 6: step 0.

Iteration i. Repeatedly swap element i with the one to its left if smaller.

Property. After ith iteration, a[0] through a[i] contain first i+1 elements in ascending order.

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Iteration 7: step 0.

Iteration i. Repeatedly swap element i with the one to its left if smaller.

Property. After ith iteration, a[0] through a[i] contain first i+1 elements in ascending order.

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Iteration 7: step 1.

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Iteration 7: step 2.

Iteration i. Repeatedly swap element i with the one to its left if smaller.

Property. After ith iteration, a[0] through a[i] contain first i+1 elements in ascending order.

Array index	0	1	2	3	4	5	6	7	8	9
Value	0.32	0.56	1.12	1.17	2.78	4.42	6.21	3.14	7.42	7.71

Iteration 8: step 0.

Iteration i. Repeatedly swap element i with the one to its left if smaller.

Property. After ith iteration, a[0] through a[i] contain first i+1 elements in ascending order.

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Iteration 9: step 0.

Iteration i. Repeatedly swap element i with the one to its left if smaller.

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Value	0.32	0.56	1.12	1.17	2.78	3.14	4.42	6.21	7.42	7.71

Iteration 10: DONE.