



# PHY109: ENGINEERING PHYSICS

## Unit I: Electromagnetic theory

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# Outline

- **Vectors**
- **Scalar and vectors fields**
- **Integral calculus**
- **Differential calculus: Concept of gradient, divergence and curl**
- **Gauss theorem and Stokes theorem**
- **Electrostatics: Gauss law, Poisson and Laplace equations, continuity equation**
- **Magnetostatics and time varying fields**
- **Displacement current, correction in Ampere circuital law, dielectric constant**
- **Maxwell's equations**

# Vectors

**Vectors:** A physical quantity with direction and magnitude.

$$\vec{A} = |\vec{A}|\hat{A}$$

**In component form:**

$$\vec{A} = A_x\hat{i} + A_y\hat{j} + A_z\hat{k}$$

$$|\vec{A}|^2 = A_x^2 + A_y^2 + A_z^2$$

**Example:** position vector ( $\vec{r} = x\hat{i} + y\hat{j} + z\hat{k}$ ), force, electric field etc.

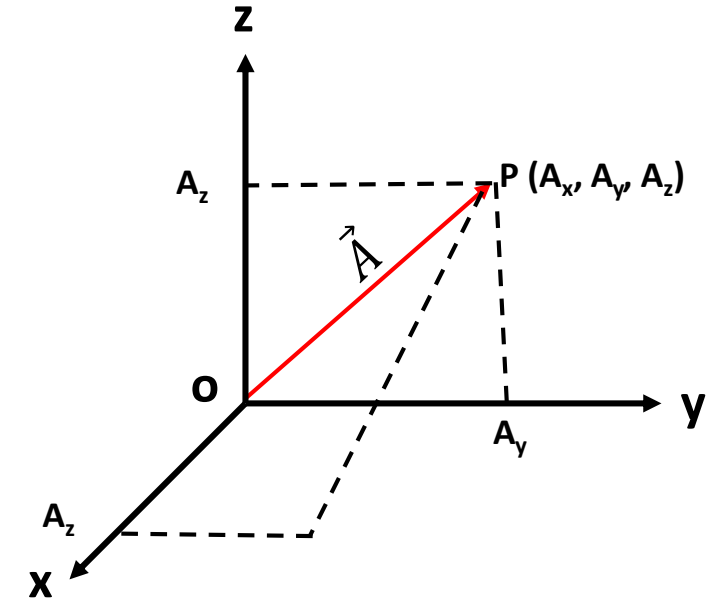
▪ **Product of vectors:**

a) **Scalar (Dot) product:**

$$\vec{A} \cdot \vec{B} = |\vec{A}||\vec{B}|\cos\theta = A_xB_x + A_yB_y + A_zB_z$$

b) **Vector (Cross) product:**

$$\vec{A} \times \vec{B} = |\vec{A}||\vec{B}|\sin\theta\hat{n} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ A_x & A_y & A_z \\ B_x & B_y & B_z \end{vmatrix}$$



# Field concept

**Field:** A function that specifies a particular quantity everywhere in the region.

**If the quantity is scalar=> Scalar field.**

Examples:

- Temperature distribution in a building,
- sound intensity in a theatre,
- electric potential in a region,
- refractive index of a stratified medium.

**If the quantity is vector=> Vector field.**

Examples:

- Gravitational force on a body in space,
- velocity of raindrops in the atmosphere,
- magnetic field in a region,
- electric field in a region.

# Integral calculus

- **Line integral:** Integration along a line/path  $L$ .

$$\int \vec{A} \cdot \vec{dl} = \int A \cos \theta \, dl$$

where,  $\vec{dl} = dx\hat{i} + dy\hat{j} + dz\hat{k}$  is a *differential line element of line/path  $L$* .

- **Circulation:** Line integral in a closed path, where a closed path bounds surface.

$$\text{circulation} = \oint \vec{A} \cdot \vec{dl}$$

- **Surface integral:** Integration over a surface  $S$ .

$$\int \vec{A} \cdot \vec{da} = \int A \cos \theta \, da$$

$$\begin{aligned} \text{where, } \vec{da} &= dx dy \hat{k} \\ &= dy dz \hat{i} \\ &= dz dx \hat{j} \end{aligned}$$

is a *differential area element of surface  $S$* .

- It is a measure of flux through the surface  $S$ .
- Integration over closed surface that bounds volume is closed surface integral.

$$\oint \vec{A} \cdot \vec{da}$$

- **Volume integral:** Integration of a scalar field over a volume  $V$

$$\int \phi \, dv$$

where,  $dv = dx dy dz$  is a *differential volume element of volume  $V$* .

# Differential calculus

- **Derivative:** Change of a function  $f(x)$  w.r.t. a variable  $x$ ;  $df = \frac{\partial f}{\partial x} dx$
- **For three variables, change of the function  $f(x, y, z)$  can be written as:**

$$df = \frac{\partial f}{\partial x} dx + \frac{\partial f}{\partial y} dy + \frac{\partial f}{\partial z} dz \quad (1)$$

where,  $\frac{\partial f}{\partial x}$ ,  $\frac{\partial f}{\partial y}$  and  $\frac{\partial f}{\partial z}$  are *partial derivatives*.

- **Del operator ( $\vec{\nabla}$ ):** Derivative vector operator.

$$\vec{\nabla} = \frac{\partial}{\partial x} \hat{i} + \frac{\partial}{\partial y} \hat{j} + \frac{\partial}{\partial z} \hat{k} \quad (2)$$

Using equation (2), equation (1) can be rearranged as:

$$df = \left( \frac{\partial f}{\partial x} \hat{i} + \frac{\partial f}{\partial y} \hat{j} + \frac{\partial f}{\partial z} \hat{k} \right) \cdot (dx \hat{i} + dy \hat{j} + dz \hat{k}) = \vec{\nabla} f \cdot \vec{dl}$$

# Differential calculus

- **Gradient:** operated on a **scalar field**.

$$\vec{\nabla} f = \frac{\partial f}{\partial x} \hat{i} + \frac{\partial f}{\partial y} \hat{j} + \frac{\partial f}{\partial z} \hat{k}$$

- Gradient of a scalar field is a **vector field**.
- It measures maximum increase of the function f.
- Its magnitude gives the slope (rate of increase) along its maximal direction.
- If  $\vec{\nabla} f = 0$ , the function f has either a maxima, minima or saddle point.

- **Divergence:** operated on a **vector field**.

$$\vec{\nabla} \cdot \vec{A} = \frac{\partial A_x}{\partial x} + \frac{\partial A_y}{\partial y} + \frac{\partial A_z}{\partial z}$$

where,  $\vec{A} = A_x \hat{i} + A_y \hat{j} + A_z \hat{k}$

Divergence of a vector field is a **scalar field**.

It is a measure of spread of vector  $\vec{A}$  from a point.

If  $\vec{\nabla} \cdot \vec{A} = 0$ ,  $\vec{A}$  is **solenoidal**.

- **Curl:** operated on a vector field.

$$\vec{\nabla} \times \vec{A} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ A_x & A_y & A_z \end{vmatrix}$$

where,  $\vec{A} = A_x \hat{i} + A_y \hat{j} + A_z \hat{k}$

Curl of a vector field is a **vector field**.

It is a measure of circulation of vector  $\vec{A}$  around a point.

If  $\vec{\nabla} \times \vec{A} = 0$ ,

$\vec{A}$  is **irrotational**.

$\vec{A}$  is a conservative vector field.

# Differential calculus

- **Directional derivative:**  $\vec{\nabla} f \cdot \hat{n}$ .
- Divergence of curl of a vector is zero.

$$\vec{\nabla} \cdot \vec{\nabla} \times \vec{A} = 0$$

- Curl of gradient of a scalar is zero.

$$\vec{\nabla} \times \vec{\nabla} f = 0$$



# Fundamental theorem

- **Gauss's theorem (Divergence theorem/Green's theorem):** Total outward flux (closed surface integral) of a vector field  $\vec{A}$  is the volume integral of the divergence of the vector field  $\vec{A}$ .

$$\oint \vec{A} \cdot \vec{da} = \int (\vec{\nabla} \cdot \vec{A}) dv$$

- **Stokes' theorem (Curl theorem):** The line integral of a vector field  $\vec{A}$  around a closed path  $L$  (circulation) is the surface integral of the vector field  $\vec{A}$  over the surface bound by the path  $L$ .

$$\oint \vec{A} \cdot \vec{dl} = \int (\vec{\nabla} \times \vec{A}) \cdot \vec{da}$$

# Electrostatics

- **Coulomb's law:**

$$\vec{F} = \frac{1}{4\pi\epsilon_0} \frac{q_1 q_2}{r^2} \hat{r}$$

Unit of force: N

- **Electric field:**

$$\vec{E} = \frac{1}{4\pi\epsilon_0} \frac{q}{r^2} \hat{r} = \frac{\vec{F}}{Q}$$

Unit of electric field: N/C or V/m

- **Electric potential:**

$$V = - \int \vec{E} \cdot d\vec{l} = \frac{W}{q}$$

Unit of electric potential: V or J/C

# Electrostatics

## ■ Properties:

- Electric potential is path independent i.e. it depends on initial and final positions.
- The line integral of electric field over a closed path is zero i.e.

$$\oint \vec{E} \cdot d\vec{l} = 0$$

- In differential form we can write,  $\vec{\nabla} \times \vec{E} = 0$ . This shows  $\vec{E}$  is conservative field.
- In differential form, electric field be written as negative of potential gradient i.e.

$$\vec{E} = -\vec{\nabla}V$$

In one dimension,

$$\vec{E} = -\frac{dV}{dx} \hat{x}$$

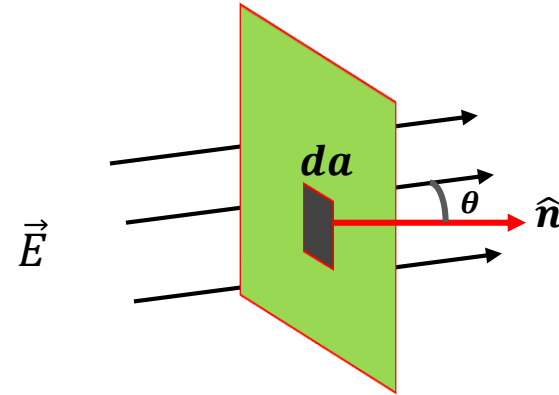
Thus unit of electric field is V/m.

# Electrostatics

- **Electric flux:** Number of electric field lines passes through a surface S.

$$\phi = \int \vec{E} \cdot d\vec{a} = \int E \cos \theta \, da$$

Unit of electric flux:  $\text{Nm}^2/\text{C}$



- **Gauss's law:** The total flux through closed surface is the  $1/\epsilon_0$  times total charge enclosed in a volume bounded by the surface.

$$\oint \vec{E} \cdot d\vec{a} = \frac{q_{enc}}{\epsilon_0}$$

$$\oint \vec{E} \cdot d\vec{a} = \frac{1}{\epsilon_0} \int \rho \, dv$$

Maxwell equation in integral form.

$$q = \int \rho \, dv$$

$$\vec{\nabla} \cdot \vec{E} = \frac{\rho}{\epsilon_0},$$

Maxwell equation in differential form.

where,  $\rho$  is volume charge density and unit is  $\text{C}/\text{m}^3$ .

# Electrostatics

- Poisson's equation:

$$\vec{\nabla}^2 V = -\frac{\rho}{\epsilon_0} \quad \text{where, } \vec{\nabla}^2 = \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2}$$

- If volume charge density,  $\rho = 0$ ,

$$\vec{\nabla}^2 V = 0$$

**Laplace equation**

- Continuity equation

$$\vec{\nabla} \cdot \vec{J} = -\frac{\partial \rho}{\partial t}$$

If volume charge density  $\rho$  is constant with time then  $\vec{\nabla} \cdot \vec{J} = 0$ , which is the steady state condition.

# Magnetostatics (when E and B are independent)

- **Lorentz force:** Force on charge (Q) while moving with velocity ( $\vec{v}$ ) in electric ( $\vec{E}$ ) and magnetic ( $\vec{B}$ ) fields:

$$\vec{F} = Q(\vec{E} + \vec{v} \times \vec{B})$$

- Magnetic force on current carrying conductor ( $I\vec{dl}$ ) can be expressed as:

$$\vec{F}_{mag} = I(\vec{dl} \times \vec{B})$$

where,  $\vec{B} = \frac{\mu_0 I}{4\pi} \int \frac{\vec{dl} \times \hat{r}}{r^2}$  is the magnetic field due to steady current in line (**Biot-Savart's Law**). The direction of the field is around the circular loop.

The unit of magnetic field: T or N(Am)<sup>-1</sup>.

- If current between two parallel wires flows in **same direction**, magnetic ( $\vec{F}_{mag}$ ) will be **perpendicular** to the wires and **opposite in direction** i.e. **attract**.
- If current between **two parallel wires** flows in **opposite direction**, magnetic ( $\vec{F}_{mag}$ ) will be **perpendicular** to the wires and **same in direction** i.e. **repel**.

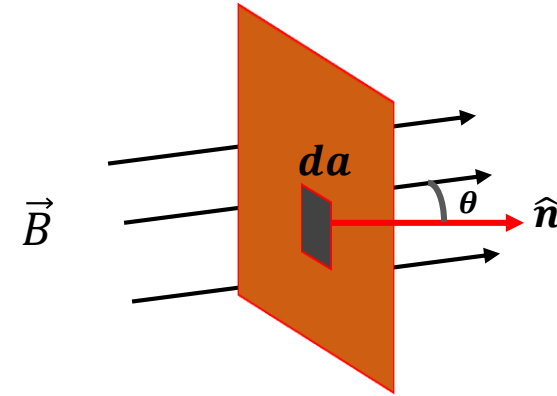
# Magnetostatics

- **Magnetic flux:** Number of magnetic field lines passes through a surface S.

$$\phi = \int \vec{B} \cdot d\vec{a} = \int B \cos\theta \, da$$

Unit of magnetic flux: Wb or Tm<sup>2</sup>.

The unit of magnetic field (B) also written as Wb/m<sup>2</sup>.



- The net magnetic flux **through a closed surface is zero** i.e. the number of magnetic field lines entering the closed surface is equal to the number of lines coming out of the surface.

$$\oint \vec{B} \cdot d\vec{a} = 0$$

Maxwell equation in integral form.

$$\vec{\nabla} \cdot \vec{B} = 0$$

Maxwell equation in differential form.

The magnetic field ( $\vec{B}$ ) is called **solenoidal**.

# For time varying fields

- **Faraday's law:** work done in moving a test charge around a closed loop equals the rate of decrease of the magnetic flux through the enclosed surface.

$$\varepsilon = \oint \vec{E} \cdot d\vec{l} = -\frac{d\Phi}{dt}$$

$$\oint \vec{E} \cdot d\vec{l} = -\int \frac{\partial \vec{B}}{\partial t} \cdot d\vec{a}$$

Maxwell equation in integral form.

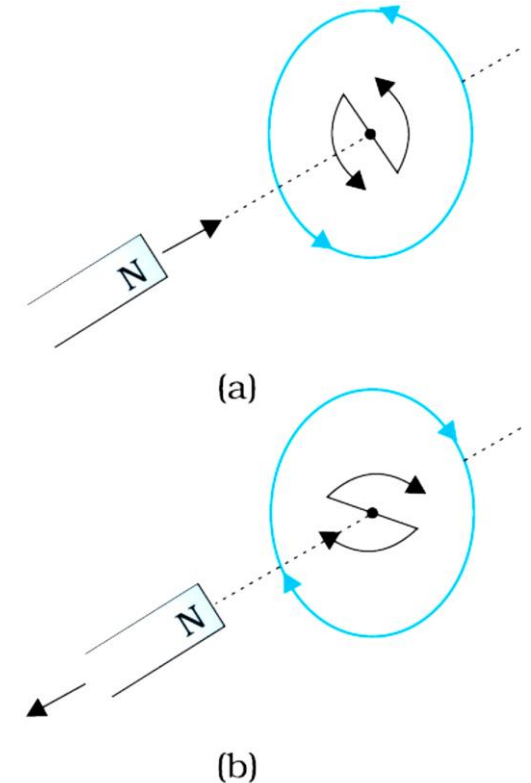
$$\vec{\nabla} \times \vec{E} = -\frac{\partial \vec{B}}{\partial t}$$

Maxwell equation in differential form.

- For steady state condition i.e.  $\vec{B}$  is constant, last equation reduces to:

$$\vec{\nabla} \times \vec{E} = 0$$

which is for electrostatic condition.



**Lenz's rule**



# For time varying fields

- **Ampere's circuital law:** Magnetic field ( $\vec{B}$ ) in a loop due to a current carrying conductor is  $\mu_0$  times of current ( $I_{enc}$ ) enclosed by the loop.

$$\oint \vec{B} \cdot d\vec{l} = \mu_0 I_{enc}$$

$$\vec{\nabla} \times \vec{B} = \mu_0 \vec{J}, \quad \text{where, } I = \int \vec{J} \cdot d\vec{a}$$

- Ampere's circuital law fails to explain in time varying fields. For example charging/discharging of capacitor connected in a circuit.
- The equation is modified by Maxwell by introducing **displacement current** ( $\vec{J}_D = \epsilon_0 \frac{\partial \vec{E}}{\partial t}$ ):

$$\vec{\nabla} \times \vec{B} = \mu_0 (\vec{J} + \vec{J}_D)$$

**Maxwell equation in differential form.**

$$\oint \vec{B} \cdot d\vec{l} = \mu_0 I_{enc} + \mu_0 \epsilon_0 \frac{d}{dt} \int \vec{E} \cdot d\vec{a}$$

**Maxwell equation in integral form.**

# Dielectric constant

- For parallel plate capacitor, capacitance can be expressed as:

$$C = \epsilon_0 \frac{A}{d}, \quad \text{where, } \epsilon_0 \text{ is permittivity of free space.}$$

- Introducing a dielectric material the capacitance is:

$$C = \epsilon \frac{A}{d}, \quad \text{where, } \epsilon \text{ is permittivity of dielectric material.}$$

$$\text{and, } \epsilon = \epsilon_r \epsilon_0$$

$\epsilon_r$  is dielectric constant of the material.

- The displacement current for dielectrics can be written as:

$$\vec{J}_D = \epsilon \frac{\partial \vec{E}}{\partial t}$$

# Maxwell's equation

## In differential form

$$\vec{\nabla} \cdot \vec{E} = \frac{\rho}{\epsilon_0}$$

where  $\rho$  is volume charge density,  $q = \int \rho dv$

$$\vec{\nabla} \cdot \vec{B} = 0$$

$$\vec{\nabla} \times \vec{E} = -\frac{d\vec{B}}{dt}$$

$$\vec{\nabla} \times \vec{B} = \mu_0(\vec{J} + \vec{J}_D)$$

where  $\vec{J}_D = \epsilon_0 \frac{\partial \vec{E}}{\partial t}$  is displacement current density

where  $\vec{J}$  is current density,  $I = \int \vec{J} \cdot \vec{da}$

## In integral form

$$\oint \vec{E} \cdot \vec{da} = \frac{1}{\epsilon_0} \int \rho dv$$

$$\oint \vec{B} \cdot \vec{da} = 0$$

$$\oint \vec{E} \cdot \vec{dl} = - \int \frac{\partial \vec{B}}{\partial t} \cdot \vec{da}$$

$$\oint \vec{B} \cdot \vec{dl} = \mu_0 I_{enc} + \mu_0 \epsilon_0 \frac{d}{dt} \int \vec{E} \cdot \vec{da}$$

# Maxwell's equation in free space

Maxwell's equations in free space where free charge density and current is zero;  $\rho = 0$  &  $J = 0$ .

$$\vec{\nabla} \cdot \vec{E} = 0$$

$$\vec{\nabla} \cdot \vec{B} = 0$$

$$\vec{\nabla} \times \vec{E} = -\frac{d\vec{B}}{dt}$$

$$\vec{\nabla} \times \vec{B} = \mu_0 \epsilon_0 \frac{\partial \vec{E}}{\partial t}$$

By decoupling the above linear differential equations for  $\vec{E}$  and  $\vec{B}$  we get a second order differential wave equation:

$$\vec{\nabla}^2 \vec{E} - \mu_0 \epsilon_0 \frac{\partial^2 \vec{E}}{\partial t^2} = 0$$

$$\vec{\nabla}^2 \vec{B} - \mu_0 \epsilon_0 \frac{\partial^2 \vec{B}}{\partial t^2} = 0$$

$$c = \frac{1}{\sqrt{\mu_0 \epsilon_0}} \approx 3 \times 10^8 \text{ m/s is speed of electromagnetic waves.}$$

**The solution of the wave equations is:**

$$\vec{E} = E_0 e^{i(kz - \omega t + \varphi_1)} \hat{n}$$

$$\vec{B} = B_0 e^{i(kz - \omega t + \varphi_2)} \hat{m}$$

where  $k$ ,  $\omega$ ,  $\varphi$  is wave vector, angular frequency and phase of the waves.  $z$  is the direction of propagation of the em wave. Unit vectors  $n$  and  $m$  are the polarization direction of electric and magnetic field.

$E_0$  and  $B_0$  are the amplitude of the wave;  **$\vec{E}_0 = c\vec{B}_0$ ;  $c = \omega/k$ .**

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