

## Question 4: Mean Reverting (OU) Process

For the SDE, we are asked to:

- (i). Write down the SDE with its initial condition.
- (ii). Define and describe all terms, variables, and parameters.
- (iii). Solve the SDE using an appropriate method.
- (iv). Choose specific parameters and plot several stochastic paths on the same graph.
- (v). Study the expectation, variance, autocorrelation, and any other interesting properties.
- (vi). Conduct a literature search and discuss one or two applications of the SDE.

### (i), (ii) SDE with Initial Condition

We begin with the general linear SDE:

$$dX_t = a_1(t)X_t dt + a_2(t)dt + b_1(t)X_t dW_t + b_2(t)dW_t. \quad (1)$$

We now consider the case:

$$a_1(t) = -a = \text{const}, \quad a_2(t) = \theta \cdot a, \quad b_1(t) = 0, \quad b_2(t) = b = \text{const},$$

with constants  $a > 0$  and  $b > 0$ . Then (1) simplifies to the Mean Reverting OU SDE:

$$dX_t = a(\theta - X_t) dt + b dW_t, \quad (2)$$

with initial condition:

$$X_0 = x_0.$$

### (iii) Solving the Mean Reverting OU SDE via Integrating Factor

To solve (2), we multiply both sides by an integrating factor:

$$M_t = e^{at}, \quad \text{and let} \quad (3)$$

$$Y_t = X_t \cdot M_t = X_t e^{at} \quad (4)$$

Using Itô's formula of case IV,

$$\varphi(X_t, t) = X_t e^{at} \quad \text{with (2):} \quad (5)$$

$$dX_t = \mu_t dt + \sigma_t dW_t, \quad \text{where} \quad (6)$$

$$\mu_t = a(\theta - X_t) \quad \text{and} \quad (7)$$

$$\sigma_t = b \quad (8)$$

$$\frac{\partial \varphi}{\partial t} = aX_t e^{at}, \quad (9)$$

$$\frac{\partial \varphi}{\partial x} = e^{at}, \quad (10)$$

$$\frac{\partial^2 \varphi}{\partial x^2} = 0. \quad (11)$$

Now apply Itô's formula using (8) with evaluating expressions at  $x = X_t$  gives:

$$dY_t = d(X_t e^{at}) = \quad (12)$$

$$= \left( \frac{\partial \varphi}{\partial t} + \mu_t \frac{\partial \varphi}{\partial x} + \frac{1}{2} \sigma_t^2 \frac{\partial^2 \varphi}{\partial x^2} \right) dt + \sigma_t \frac{\partial \varphi}{\partial x} dW_t \quad (13)$$

$$= \left( aX_t e^{at} + a(\theta - X_t) e^{at} + \frac{1}{2} \cdot (b)^2 \cdot 0 \right) dt + (b)e^{at} dW_t \quad (14)$$

$$= a\theta e^{at} dt + be^{at} dW_t. \quad (15)$$

$$dY_t = a\theta e^{at} dt + be^{at} dW_t. \quad (16)$$

which we can integrate directly since the  $\mu(X_t, t) = a\theta e^{at}$ , and  $\sigma(X_t, t) = be^{at} = \sigma(t)$ ,  $\mu$   $\sigma$  only depend on time  $t$ . Thus integrating both sides of (16) from 0 to  $t$  gives:

$$Y_t = Y_0 + \theta [e^{at} - 1] + \int_0^t be^{a\tau} dW_\tau, \quad (17)$$

$$(18)$$

by (4), and solving for  $X_t$  give the final solution.

$$X_t = e^{-at} Y_t \quad \text{hence,}$$

$$X_t = x_0 e^{-at} + \theta [1 - e^{-at}] + b \int_0^t e^{-a(t-\tau)} dW_\tau. \quad (19)$$

#### (iv) Graphing the Solution

To visualize the OU process:

- Use parameters:  $a = 0.7$ ,  $\theta = 2$ ,  $b = 0.5$ ,  $x_0 = 4$ .
- Simulate 100 paths using (??).
- Overlay the theoretical mean:  $\mathbb{E}[X_t] = \theta + (x_0 - \theta)e^{-at}$ .

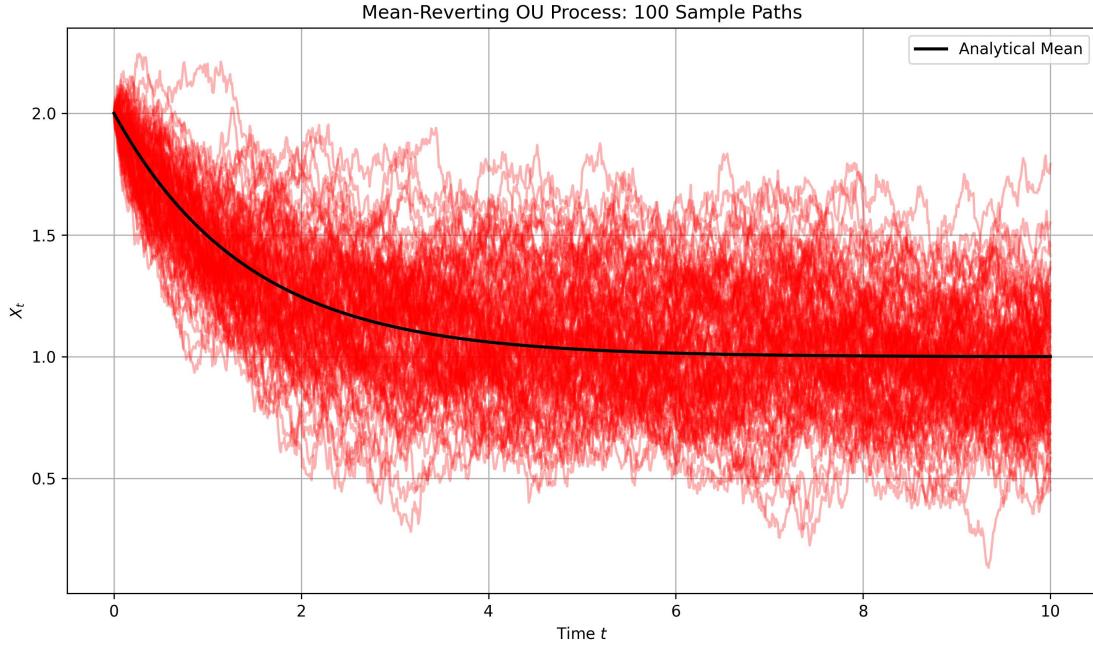


Figure 1: 100 Simulated Paths of Mean-Reverting OU Process with Nonzero Mean

## (v) Statistics of the Mean-Reverting OU Process

### Expectation

Taking the expectation in (19), and noting that the Itô integral has zero mean:

$$\mathbb{E}[X_t] = \mathbb{E} \left[ x_0 e^{-at} + \theta(1 - e^{-at}) + b \int_0^t e^{-a(t-\tau)} dW_\tau \right] \quad (20)$$

$$= x_0 e^{-at} + \theta(1 - e^{-at}) + 0 \quad (21)$$

$$= \theta + (x_0 - \theta)e^{-at}. \quad (22)$$

As  $t \rightarrow \infty$ ,  $\mathbb{E}[X_t] \rightarrow \theta$ , confirming that  $\theta$  is the long-term mean.

### Variance

Only the stochastic integral contributes to the variance:

$$\text{Var}(X_t) = \mathbb{E} \left[ \left( b \int_0^t e^{-a(t-\tau)} dW_\tau \right)^2 \right] \quad (23)$$

$$= b^2 \int_0^t e^{-2a(t-\tau)} d\tau \quad (\text{by Itô isometry}) \quad (24)$$

$$= \frac{b^2}{2a} (1 - e^{-2at}). \quad (25)$$

As  $t \rightarrow \infty$ ,  $\text{Var}(X_t) \rightarrow \frac{b^2}{2a}$ , which is the variance of the stationary distribution.

## Covariance and Autocorrelation

Let  $0 \leq s \leq t$ . The covariance between  $X_s$  and  $X_t$  is:

$$\text{Cov}(X_s, X_t) = \frac{b^2}{2a} e^{-a(t-s)} (1 - e^{-2as}), \quad (26)$$

$$\text{Corr}(X_s, X_t) = \frac{\text{Cov}(X_s, X_t)}{\sqrt{\text{Var}(X_s) \cdot \text{Var}(X_t)}} = e^{-a(t-s)}. \quad (27)$$

Thus, the autocorrelation decays exponentially with lag  $t - s$ , a key feature of mean-reverting processes.

## (vi) Applications of the Mean-Reverting OU Process

The mean-reverting Ornstein–Uhlenbeck process has numerous real-world applications, especially in areas where variables fluctuate around an equilibrium value:

- **Finance – Interest Rates and Volatility:** The OU process underlies the Vasicek model for interest rates and the Heston model for stochastic volatility. It captures the realistic behavior of rates or volatility reverting to a mean value rather than drifting indefinitely.
- **Physics – Langevin Dynamics:** In statistical physics, the OU process models the velocity of particles subject to random forces and friction (Brownian motion with drag), particularly in the Langevin equation.
- **Econometrics – Commodity Prices:** Energy commodities like electricity and natural gas often follow mean-reverting dynamics due to supply-demand constraints. OU models are used for pricing energy derivatives.
- **Biology – Homeostatic Control:** Biological systems, such as hormone levels or neuron firing rates, often return to a baseline after perturbation. The OU process models this homeostatic regulation effectively.

## References

### References

- [1] Ornstein, L. S., & Uhlenbeck, G. E. (1930). *On the Theory of the Brownian Motion.* Physical Review, 36(5), 823.
- [2] Vasicek, O. (1977). *An Equilibrium Characterization of the Term Structure.* Journal of Financial Economics, 5(2), 177–188.
- [3] Karatzas, I., & Shreve, S. E. (1991). *Brownian Motion and Stochastic Calculus.* Springer.
- [4] Björk, T. (2009). *Arbitrage Theory in Continuous Time.* Oxford University Press.

## Appendix: Python Code for Question 4 (Mean-Reverting OU)

The following Python script was used to simulate the sample paths in Part (iv):

Listing 1: Mean-Reverting OU Simulation (Q4)

```

import numpy as np
import matplotlib.pyplot as plt

# Parameters
x0 = 2.0          # Initial value
theta = 1.0        # Long-term mean
a = 0.7           # Mean reversion speed
b = 0.3           # Volatility
T = 10            # Time horizon
N = 1000          # Number of time steps
M = 100           # Number of sample paths
dt = T / N         # Time increment
t = np.linspace(0, T, N + 1) # Time grid

# Preallocate
X = np.zeros((M, N + 1))
X[:, 0] = x0

# Simulate sample paths using the exact solution
for i in range(M):
    dW = np.sqrt(dt) * np.random.randn(N)
    W = np.concatenate(([0], np.cumsum(dW)))
    integral_term = np.array([np.sum(np.exp(a * t[:j]) * dW[:j]) for j in range(N)])
    integral_term = np.insert(integral_term, 0, 0) # Include initial 0
    X[i, :] = x0 * np.exp(-a * t) + theta * (1 - np.exp(-a * t)) + b * np.exp(integral_term)

# Compute analytical mean
mean_X = theta + (x0 - theta) * np.exp(-a * t)

# Plot
plt.figure(figsize=(10, 6))
for i in range(M):
    plt.plot(t, X[i, :], color='red', alpha=0.3)
plt.plot(t, mean_X, color='black', linewidth=2.0, label='Analytical-Mean')
plt.title('Mean-Reverting-OU-Process: -100-Sample-Paths')
plt.xlabel('Time-$t$')
plt.ylabel('$X_t$')
plt.grid(True)
plt.legend()

```

```
plt.tight_layout()  
plt.savefig('images/q4_mean_reverting_ou_graph.jpg', dpi=300)  
plt.show()
```