

Problem 2.

Global coordinate approach

$$(1) \quad \varphi_i(x) = \frac{x - x_{i-\frac{1}{2}}}{h_i} \left[\frac{2}{h_i} (x - x_{i-\frac{1}{2}}) + 1 \right], \quad x \in [x_{i-1}, x_i]$$

Solution:

This approach is about finding the quadratic basis functions φ_{i-1} and φ_i on a subinterval (x_{i-1}, x_i) s.t.

$$(2) \quad \varphi_{i-1}(x_{i-1}) = 1, \quad \varphi_i(x_i) = 0, \quad \varphi_i(x_{i-1}) = 0, \quad \varphi_i(x_i) = 1,$$

a quadratic function $\varphi_{i-1}(x)$ is in the form

$$(3) \quad \varphi_{i-1}(x) = a + bx + cx^2, \quad x \in [x_{i-1}, x_i]$$

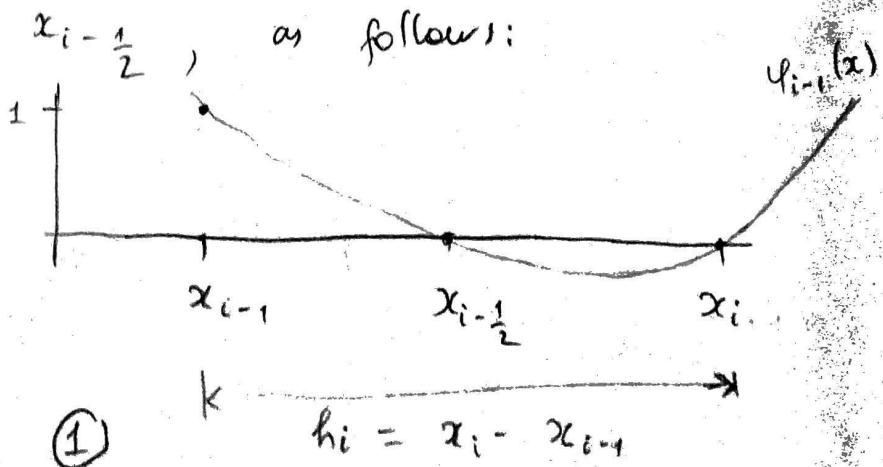
We have now two equations from (2):

$$(1) \quad \varphi_{i-1}(x_{i-1}) = 1 \Leftrightarrow a + bx_{i-1} + c(x_{i-1})^2 = 1$$

$$(5) \quad \varphi_{i-1}(x_i) = 0 \Leftrightarrow a + bx_i + c(x_i)^2 = 0$$

We need one more independent eq-n to find unknowns a, b, c . To do this, let's introduce an additional node

$$(6) \quad \boxed{\begin{aligned} h_i &:= x_i - x_{i-1} \\ x_{i-\frac{1}{2}} &:= \frac{x_{i-1} + x_i}{2} \Rightarrow \\ x_i &= x_{i-\frac{1}{2}} + \frac{h_i}{2} \quad \& \\ x_{i-1} &= x_{i-\frac{1}{2}} - \frac{h_i}{2} \end{aligned}}$$



So this $x_{i-\frac{1}{2}}$ point satisfies

$$(7) \quad \psi_{i-1}(x_{i-\frac{1}{2}}) = 0 \Leftrightarrow a + bx_{i-\frac{1}{2}} + cx_{i-\frac{1}{2}}^2 = 0;$$

Thus we have 3 equations, (4), (5), (7), to find unknowns a, b, c making a 3×3 system of linear equations to solve:

$$(8) \quad \begin{cases} a + bx_{i-1} + c(x_{i-1})^2 = 1 & \dots \dots \dots (4) \\ a + bx_i + c(x_i)^2 = 0 & \dots \dots \dots (5) \\ a + bx_{i-\frac{1}{2}} + c(x_{i-\frac{1}{2}})^2 = 0 & \dots \dots \dots (7) \end{cases}$$

where $x_i, x_{i-1}, x_{i-\frac{1}{2}}$ are all

(4) - (5) subtraction gives:

$$\begin{aligned} b(x_{i-1} - x_i) + c[(x_{i-1})^2 - (x_i)^2] &= 1 \\ -b \cdot h_i + c \cdot (-h_i) \cdot \underbrace{(x_{i-1} + x_i)}_{\text{+} (-1)} &= 1 \end{aligned}$$

$$b h_i + c h_i \cdot (2x_{i-\frac{1}{2}}) = -1$$

$$(9) \quad \boxed{b h_i + 2 c h_i x_{i-\frac{1}{2}} = -1}$$

Now similarly subtracting eq-n (7) from eq-n (5) yields:

(5) - (7) :

$$\begin{aligned} b \cdot (x_i - x_{i-\frac{1}{2}}) + c \cdot \underbrace{[(x_i - x_{i-\frac{1}{2}}) \cdot (x_i + x_{i-\frac{1}{2}})]}_{\text{by (6)}} &= 0 \\ b \cdot \frac{h_i}{2} + c \cdot \frac{h_i}{2} \cdot \left(x_{i-\frac{1}{2}} + \frac{h_i}{2} + x_{i-\frac{1}{2}} \right) &= 0 \Rightarrow \end{aligned}$$

(2)

$$(10) \Rightarrow \boxed{b \cdot \frac{h_i}{2} + \frac{ch_i}{2} \left(2x_{i-\frac{1}{2}} + \frac{h_i}{2} \right) = 0} \text{ by eq. (5)-(7).}$$

So by (9) & (10) we have now 2×2 system to solve for b & c :

$$(11) \quad \left\{ \begin{array}{l} b h_i + 2 c h_i \cdot x_{i-\frac{1}{2}} = -1 \\ \frac{b h_i}{2} + \frac{c h_i}{2} \left(2 x_{i-\frac{1}{2}} + \frac{h_i}{2} \right) = 0 \end{array} \right\} + 2 \text{ of BS:}$$

$$\Rightarrow \left\{ \begin{array}{l} b h_i + c h_i \cdot (2 x_{i-\frac{1}{2}}) = -1 \\ b h_i + c h_i \left(2 x_{i-\frac{1}{2}} + \frac{h_i}{2} \right) = 0 \end{array} \right\} \quad \left\{ \text{eq (1) - (2):} \right.$$

$$c h_i \cdot \left(2 x_{i-\frac{1}{2}} - 2 x_{i-\frac{1}{2}} - \frac{h_i}{2} \right) = -1 \Rightarrow$$

$$c = \frac{2}{h_i \cdot h_i} = \frac{2}{h_i^2};$$

$$(12) \quad \boxed{c = \frac{2}{h_i^2}}$$

Then using (10) & substituting c in (12) back into the eqn (12), we get

$$\begin{aligned} b &= -c \left(2 x_{i-\frac{1}{2}} + \frac{h_i}{2} \right) = -\frac{2}{h_i^2} \cdot \left(2 x_{i-\frac{1}{2}} + \frac{h_i}{2} \right) \\ &= -\frac{1}{h_i} \left(\frac{4 x_{i-\frac{1}{2}}}{h_i} + 1 \right); \quad \Rightarrow \end{aligned}$$

(3)

$$(13) \quad \left\{ b = -\frac{1}{h_i} \left(\frac{4x_{i-\frac{1}{2}}}{h_i} + 1 \right) \right\} \quad \text{& finally for } a,$$

using eqn (7), we have

$$\begin{aligned} a &= -b x_{i-\frac{1}{2}} - c \cdot (x_{i-\frac{1}{2}})^2 \\ &= \frac{1}{h_i} \left(\frac{4x_{i-\frac{1}{2}}}{h_i} + 1 \right) \cdot x_{i-\frac{1}{2}} - \frac{2}{h_i^2} \cdot (x_{i-\frac{1}{2}})^2 = \\ &= \frac{x_{i-\frac{1}{2}}}{h_i} \left[\frac{4x_{i-\frac{1}{2}}}{h_i} + 1 - \frac{2x_{i-\frac{1}{2}}}{h_i} \right] \\ &= \frac{x_{i-\frac{1}{2}}}{h_i} \cdot \left[\frac{2x_{i-\frac{1}{2}}}{h_i} + 1 \right]; \quad \Rightarrow \end{aligned}$$

$$(14) \quad \boxed{a = \frac{x_{i-\frac{1}{2}}}{h_i} \left[\frac{2x_{i-\frac{1}{2}}}{h_i} + 1 \right]}, \quad \text{and putting}$$

these (12), (13), (14) back to (3), we have

$$\begin{aligned} (15) \quad u_{i-1}(x) &= a + bx + cx^2 \\ &= \frac{x_{i-\frac{1}{2}}}{h_i} \left[\frac{2x_{i-\frac{1}{2}}}{h_i} + 1 \right] - \frac{x}{h_i} \left(\frac{4x_{i-\frac{1}{2}}}{h_i} + 1 \right) + \frac{2x^2}{h_i^2} \\ &= \frac{x - x_{i-\frac{1}{2}}}{h_i} \cdot \left[\frac{2}{h_i} (x - x_{i-\frac{1}{2}}) - 1 \right], \quad x \in [x_{i-1}, x_i], \end{aligned}$$

as desired. 

(4)