

SMART PARKING SOLUTION

Technical Documentation

ABSTRACT

Includes the technical specifications and configurations related to the sensor nodes, gateways and AWS cloud. Purpose is to map with the current progress with the initial specifications.

REVISION

1.1

CREATED BY

Thusara Grero On 3rd May 2018

Security Credentials

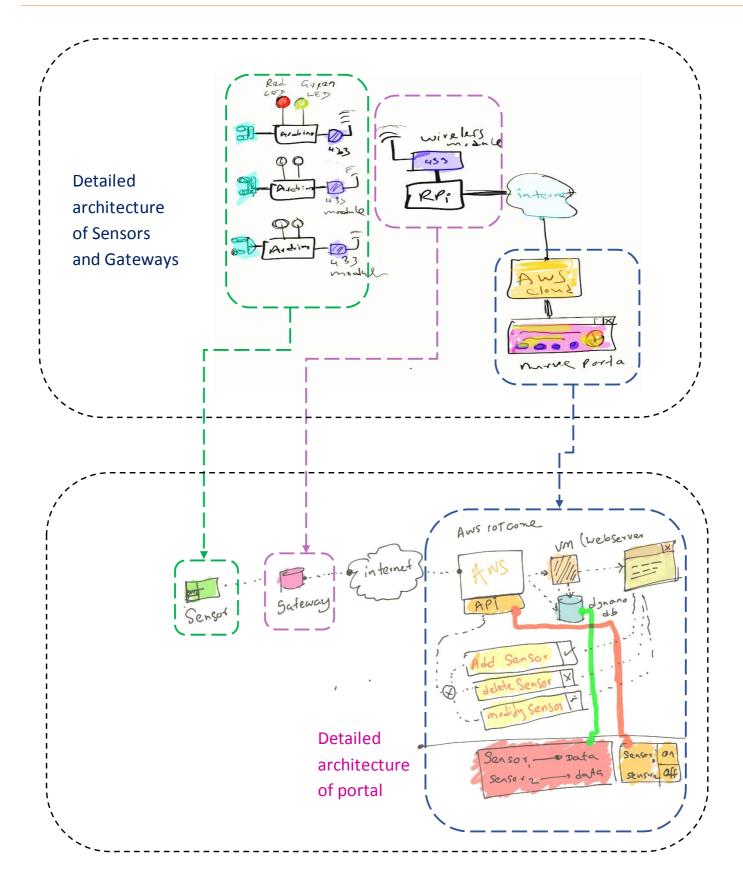
```
*** Raspberry Pi Login **
    username : pi
    password : raspberry

** MySQL credentials **
    username : root2
    password : root2
    database : parking

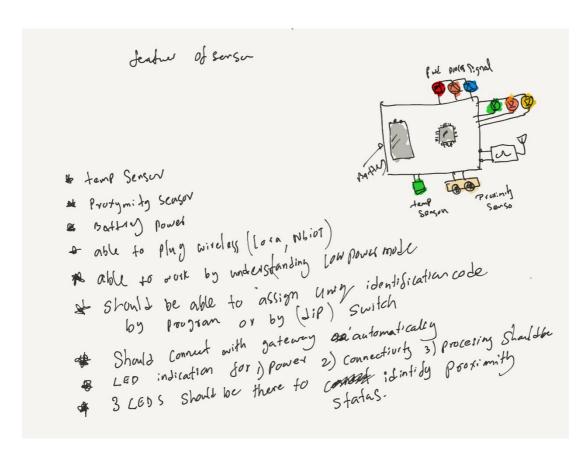
** AWS configurations with Node-RED **
    Thing name : Gateway_1
    Server : a2ktipjm632gcm.iot.us-east-2.amazonaws.com
    port: 8883
    Certificate : /home/pi/cert/a4ce6b7c13-certificate.pem.crt
    Private Key : /home/pi/cert/a4ce6b7c13-private.pem.key
```

Certificate files : Click here.

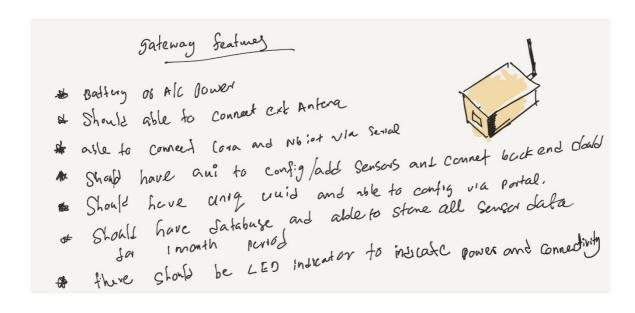
CA Certificate:/home/pi/cert/rootCA.pem



Features expected on the sensor



Features expected on the gateway



Features expected on the Nurve platform

mure 'ot feature.

** ability to add-Sensors

** ability to add-Jateury

** ability to view Sensor data

** each Sensor Jata Should retain 1 year Period

** option Should be there to view real time data on the

Sensors

** work flow

able to Jesign work flow based on Sensors and

able to trigger Sensors and Jevices based on

Contions.

** ability to goof Sensors and Jevices called

"riesonice group." — eg: resoure good con be "room"

** able to tag each Sensor, gateury, Jevice.

*** Amendments possible for expected features

Project initialization

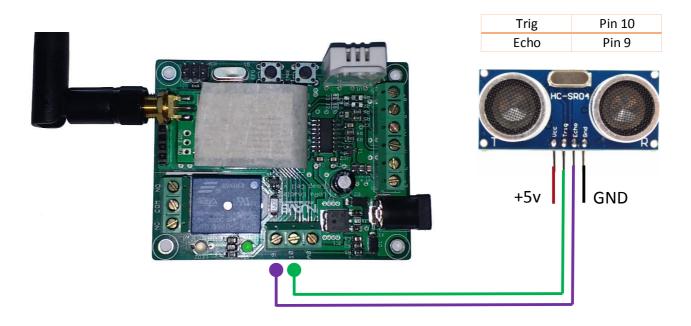
- The initial hardware prototype of the parking solution was built using a PCB designed for a previous project (Lora Enabled load cell).
- Certain features of the past project was also utilized (ie. Temperature, Battery Level, Humidity etc.)
- 9th and 10th pin which were exposed from the above PCB was used to mount the ultrasonic sensor (HC-SR06)
- In this revision (1.1) no modifications to the PCB was done and was utilized as it is.

Hardware Setup & Software Setup for the prototype

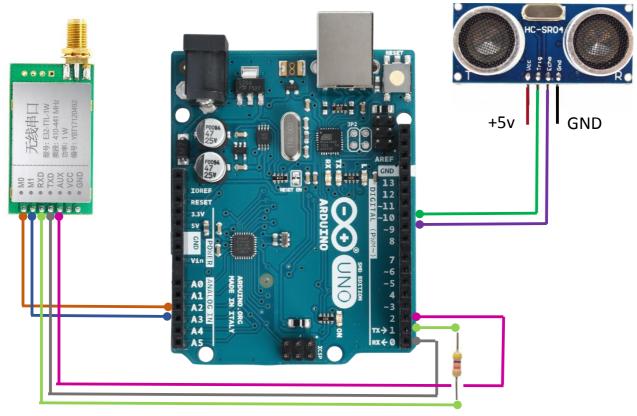
Sensor node setup

- Hardware setup was done in two forms.
 - 1. From load cell PCB
 - 2. From Arduino (because only two working PCBs were available and was required to be tested with multiple sensors)
- Refer the attached schematic for the PCB architecture. LoRa Enabled Load Cell ver1 (rev A) Schematic.pdf

Load cell PCB integration



Arduino UNO integration



HC-SR04	Arduino
Trig	Pin 10
Echo	Pin 9

Lora Module	Arduino
M0	Pin A2
M1	Pin A3
RxD	Pin 1
	TX (with 4-10k resistor)
TxD	Pin 0
	RX
AUX	Pin 2
VCC	+5v
GND	GND

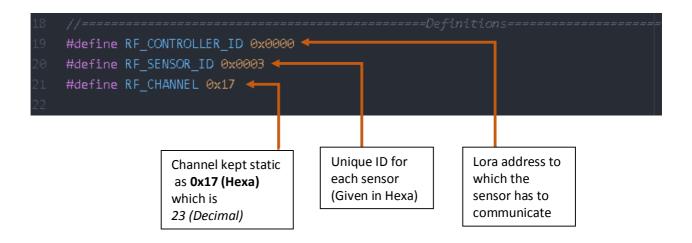
Note: *** 4-10 K Ohm resistor is necessary to connect the Rx(Lora) -> Tx (Uno) because of impedance issue as it will not transmit properly. This is properly discussed here.

Latest modified source code of the sensor node

Source code file(s): <u>SENSOR NODE SOURCE CODE</u>

Last updated: April 11 - 2018

Summary: The load cell code was modified and load cell component was replaced with ultrasonic component.



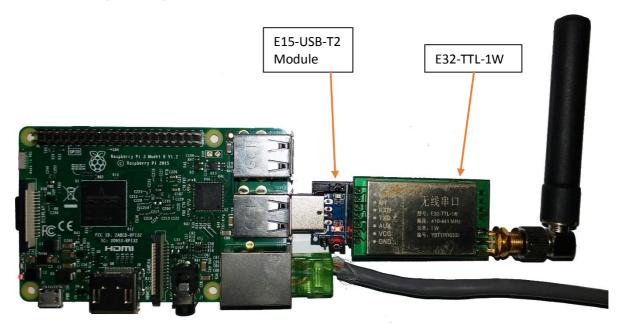
New variable definitions

```
91
92 // defines pins numbers
93 const int trigPin = 10;
94 const int echoPin = 9;
95
96 // defines variables
97 long duration;
98 int distance;
99 int Ultrasonic_Value;
100
```

Function which reads the ultrasonic sensor

```
520 v int readUltrasonic(){
522 digitalWrite(trigPin, LOW);
523 digitalWrite(COM_IND_LED_PIN,HIGH);
524 delayMicroseconds(2);
526 digitalWrite(trigPin, HIGH);
529 duration = pulseIn(echoPin, HIGH);
531 distance= duration*0.034/2;
536 v if(distance>=10){
       digitalWrite(COM_IND_LED_PIN, LOW); // LOW means HIGH here
       return 1;
541 v else if(distance>=0 && distance<10){
       digitalWrite(COM_IND_LED_PIN, HIGH); // HIGH means LOW here
       return 0;
545 ~ }
```

Gateway Setup



Source file(s) : <u>GATEWAY SOURCE CODE</u>

Certificates for AWS : <u>CERTIFICATE FILES</u>

The script to be executed : main1.js (command: node main1.js)

Other important files : config/default.json

Local database architecture : MySQL (database -> parking)

```
mysql> use parking
Database changed
mysql> show tables;
+-----+
| Tables_in_parking |
+----+
| data |
| data_log |
| gateway |
| sensor |
+----+
4 rows in set (0.00 sec)
```

Configurations:

Source files should be available in *lora_mod* in the home directory.
 Browse to it by

cd ~/lora_mod

```
pi@raspberrypi:~ $ cd ~/lora mod pi@raspberrypi:~/lora_mod $
```

2. Certificate files of AWS should be located in **cert** directory in **home**. (MQTT node in node red will depend on this)

```
pi@raspberrypi:~ $ cd cert
pi@raspberrypi:~/cert $ ls
a4ce6b7c13-certificate.pem.crt a4ce6b7c13-public.pem.key
a4ce6b7c13-private.pem.key rootCA.pem
```

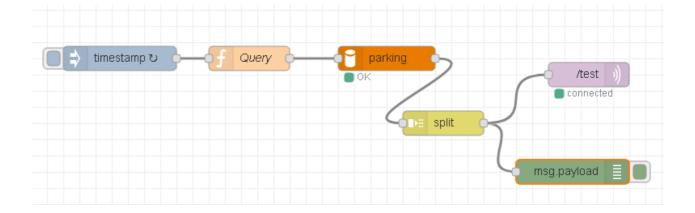
- 3. *main1.js* is the latest code to be executed. It will;
 - a. Read the data of the sensors by requesting each sensor recorded in the sensor table in the database.
 - b. Display the values in the terminal
 - c. Record the payload in the table 'data' in the local database 'parking'.

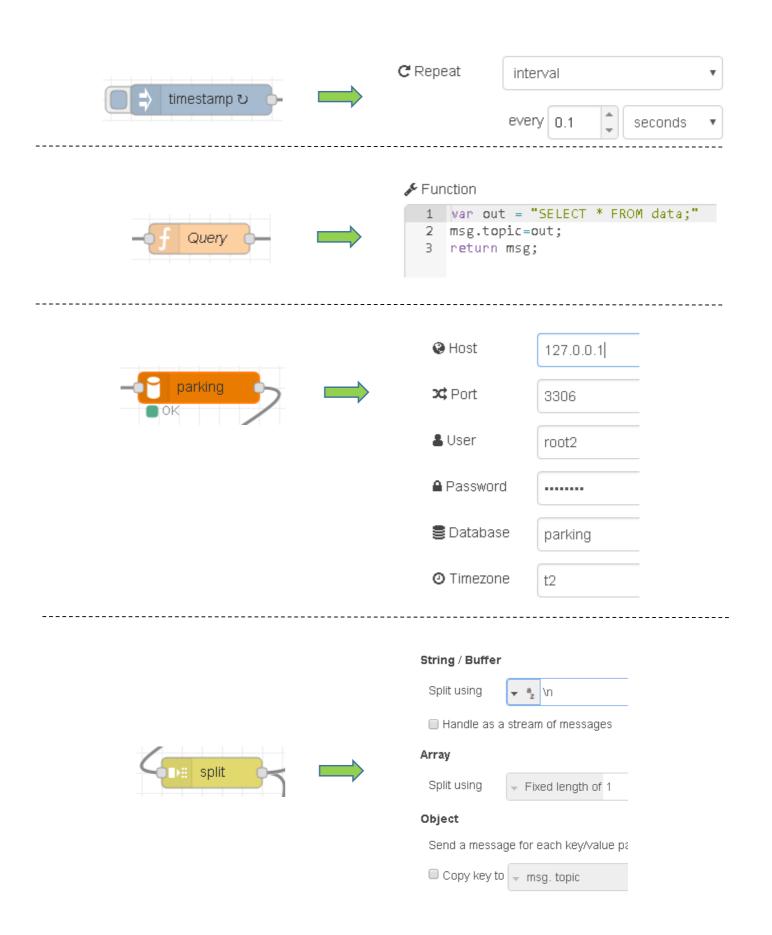
(Here if a record exist from that sensor it will be updated and if not a new record will be created)

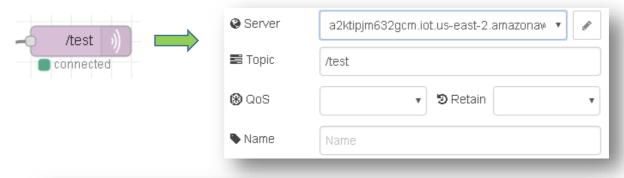
4. Config/default.json has following configurations;

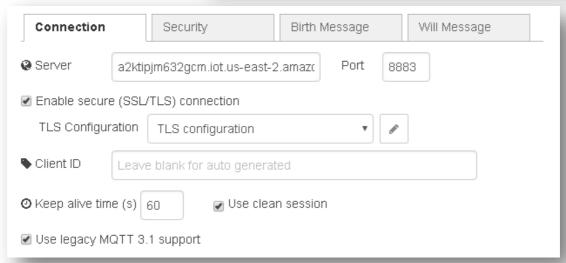
```
"db_config": {
    "host" : "127.0.0.1",
    "user" : "root2",
    "password" : "root2",
    "database" : "parking",
    "timezone": "Asia/Colombo"
},
    "gateway_id" : 1,  Unique ID to identify a gateway
    "log_interval" : 10000,  Frequency to send data to database
    "sensor_call_interval" : 1000  Frequency to request
}
```

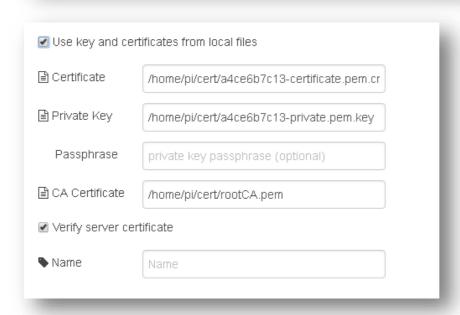
- Node-red has to be installed and if the code fails to run after node-red installation follow;
 Serial Port Installation
- 6. Node red configurations











LORA Module configuration

Software to configure: RF Setting v3.45.exe

Address is the unique ID used to identify each Lora module. Screen capture shows the one on the gateway.

Channel is the path which we use to transmit and receive. In our scenario we have made it a static channel where all gateways and sensors uses this channel 23 (Hex 0x17).



Data Sheet of USB module: E15-USB-T2 Datasheet EN v1.0 .pdf