

COMPREHENSIVE ANALYSIS - DEGRADATION ML MODEL

1. DATA DESCRIPTION & PRE-PROCESSING

a) Datasets Used:

- **Source:** Initial Dataset
- **Content:** Time-series sequences of vibration features with progressive wear
- **Format:** 30-day sequences with daily feature vectors (12 features × 30 days)

b) Why We Choose This Approach:

- **No real degradation data available** → we simulate realistic wear patterns
- **Digital twin needs aging simulation** → create synthetic lifecycle data
- **Foundation for RUL prediction** → train ML on controlled degradation scenarios

c) Data Cleaning:

- **Smooth degradation trends** - real wear doesn't jump suddenly
- **Add realistic noise** to simulate sensor measurement errors
- **Handle missing data** in long sequences (interpolation)
- **Normalize features** for LSTM training

d) Train/Test Splits:

- **Time-based splitting:** First 70% of sequences for training, last 30% for testing
- **Cross-validation:** 5-fold cross-validation on training sequences
- **Separate degradation scenarios:** Different wear patterns for generalization testing

e) Augmentations:

- **Variable degradation rates** (slow, medium, fast wear)
- **Different failure modes** (bearing wear vs imbalance vs combined)
- **Noise injection** to simulate sensor variability
- **Sequence cropping** for different time horizons

2. SYSTEM/MODEL ARCHITECTURE

a) Model Used: LSTM (Long Short-Term Memory) Network

b) Model Type: Recurrent Neural Network for sequence prediction

c) Number of Layers:

Input Layer: (30 timesteps × 12 features)
LSTM Layer 1: 100 units (return sequences=True)
Dropout: 0.2
LSTM Layer 2: 50 units (return sequences=False)
Dropout: 0.2
Dense Layer: 32 units (ReLU activation)
Output Layer: 1 unit (Linear activation for RUL)

d) Important Hyperparameters:

- **Sequence Length:** 30 days (how much history to consider)
- **Hidden Units:** 100 → 50 (captures complex temporal patterns)
- **Learning Rate:** 0.001 (Adam optimizer)
- **Batch Size:** 32 (balance between speed and stability)
- **Dropout Rate:** 0.2 (prevents overfitting)

e) How Model Processes Input:

Input: [Day1_features, Day2_features, ..., Day30_features]
↓
LSTM Layer 1: Extracts short-term patterns, maintains memory
↓
LSTM Layer 2: Captures long-term dependencies, degradation trends
↓
Dense Layers: Combines temporal features for final prediction
↓
Output: RUL (Remaining Useful Life in days)

f) Why Architecture is Suitable:

- **LSTM memory cells** track degradation trends over time

- **Handles variable-length sequences** for different operational histories
- **Proven for time-series forecasting** and predictive maintenance
- **Can learn both short-term and long-term patterns** in vibration data

3. EXPERIMENTAL SETUP

a) **Batch Size: 32 sequences per training step**

b) **Learning Rate: 0.001 (standard for Adam optimizer)**

c) **Optimizer: Adam (adaptive learning rate, good for RNNs)**

d) **Epochs: 200 maximum, with early stopping**

e) **Loss Function: Huber Loss (robust to outliers in RUL prediction)**

f) **Metrics:**

- **RMSE** (Root Mean Square Error) - primary metric
- **MAE** (Mean Absolute Error) - interpretable in days
- **R² Score** - explains variance captured
- **Accuracy within $\pm X$ days** - practical usefulness

g) **How Models are Trained:**

- **Mini-batch gradient descent** with backpropagation through time
- **Teacher forcing** during training (use true previous values)
- **Gradient clipping** to prevent explosion in RNNs

h) **Early Stopping:**

- **Monitor:** Validation loss
- **Patience:** 15 epochs
- **Restore best weights:** Yes

i) **Validation Split: 20% of training data for validation**

j) **Checkpoints:**

- **Save best model** based on validation RMSE
- **Model weights** + architecture + training history
- **Automatic saving** when validation improves

4. EVALUATION METRICS

a) Accuracy:

- **Definition:** Percentage of predictions within acceptable error margin
- **Calculation:** $(\text{predictions within } \pm 10 \text{ days}) / \text{total_predictions}$
- **Target:** >80% within ± 10 days, >95% within ± 20 days

b) Perplexity: NOT USED (for language models only)

c) Loss Curve:

- **Monitor:** Training vs validation loss over epochs
- **Good sign:** Both decreasing, gap not too large
- **Bad sign:** Validation loss increasing (overfitting)

d) BLEU Score: NOT USED (for text generation only)

e) Confusion Matrix: NOT USED (for classification only)

f) F1 Score: NOT USED (for classification only)

g) Qualitative Comparison:

- **Visual analysis:** Plot actual vs predicted RUL over time
- **Degradation trend analysis:** Does model capture acceleration points?
- **Failure point prediction:** How early can it detect impending failure?

5. EXPERIMENTAL PLAN

Experiment 1 - Baseline Physics Model:

- **Model:** Simple linear degradation $RUL = 100 - \text{total_days}$
- **Purpose:** Basic benchmark - minimum performance to beat

- **Expected:** Poor performance (real degradation is non-linear)

Experiment 2 – Proposed LSTM Model:

- **Phase 2a:** Train basic LSTM with default parameters
- **Phase 2b:** Hyperparameter tuning (sequence length, hidden units, learning rate)
- **Phase 2c:** Compare against baseline and report improvement
- **Target:** 30-50% RMSE reduction compared to baseline

Experiment 3 – Error Analysis:

- **3a:** Analyze worst-case predictions (largest errors)
- **3b:** Feature importance analysis (which vibration features matter most?)
- **3c:** Failure mode analysis (does model work better for certain degradation types?)
- **3d:** Uncertainty quantification (how confident are predictions?)

KEY SUCCESS METRICS

Excellent Performance:

- **RMSE < 5 days** (highly accurate)
- **$R^2 > 0.85$** (explains most variance)
- **>85% within ± 10 days** (practically useful)

Good Performance:

- **RMSE 5-10 days** (acceptable for maintenance planning)
- **R^2 0.70-0.85** (reasonable explanation)
- **>70% within ± 10 days**





Poor Performance:

- **RMSE > 15 days** (needs improvement)
- **$R^2 < 0.60$** (not capturing patterns well)

EXPECTED OUTCOMES

Your degradation ML model will:

-  **Learn complex wear patterns** from vibration sequences

-  **Predict remaining useful life** with good accuracy
-  **Provide early warnings** for maintenance planning
-  **Adapt to different degradation scenarios**
-  **Create a truly intelligent digital twin** that knows its own health

This transforms your system from simple simulation to predictive maintenance platform! 