T1A3 Portfolio

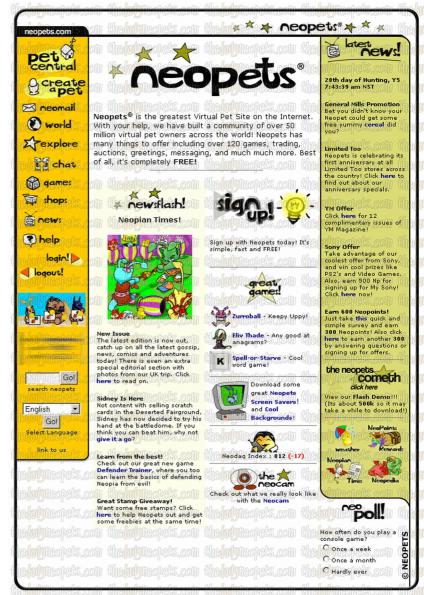
Tessa Peterson

Where to start?

- Getting back to my roots
- The place I first started coding...

Inspiration

- Neopets
- (Specifically, the old style Neopets layout)
- Recreate a similar feel but a bit more modern and prettier (hopefully)



Inspiration























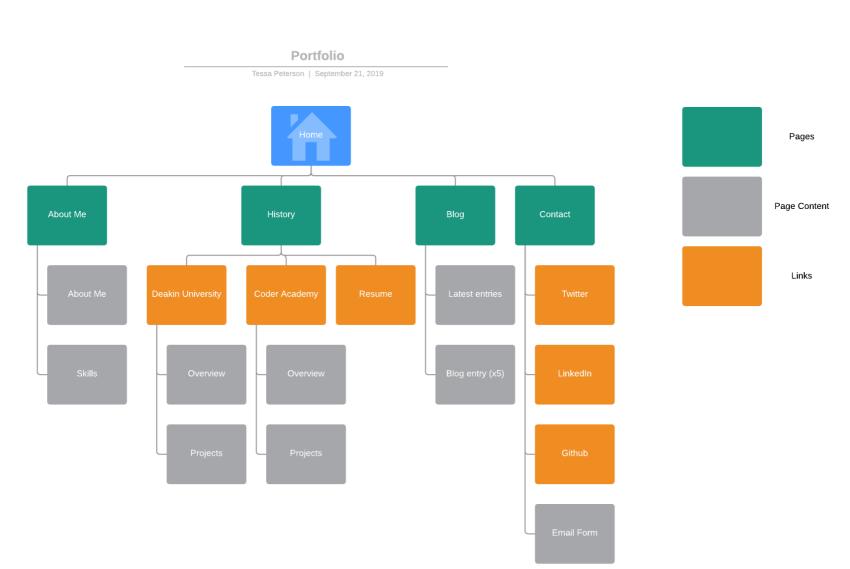




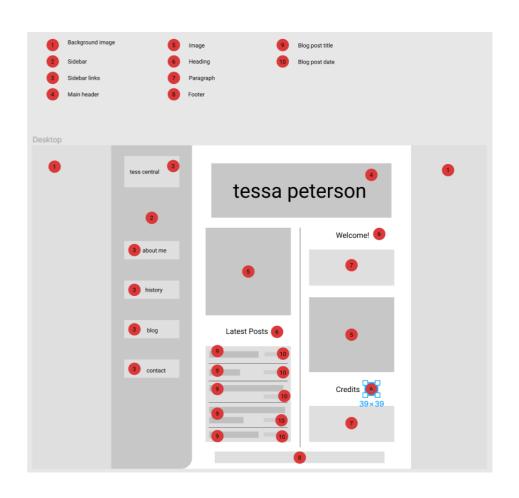




Sitemap

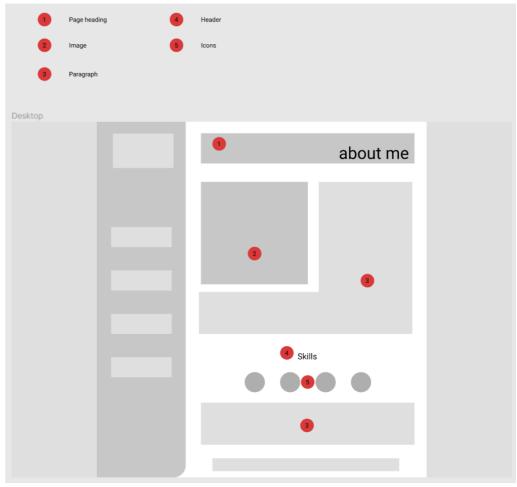


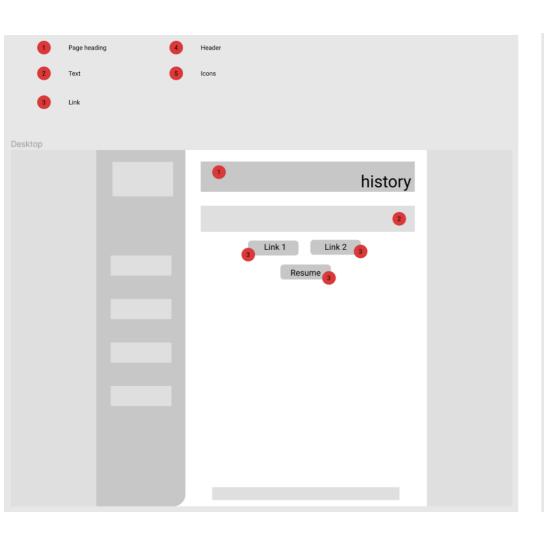
- Index page
- Column layout like the old Neopets index page
- Main heading looks like the Neopets header

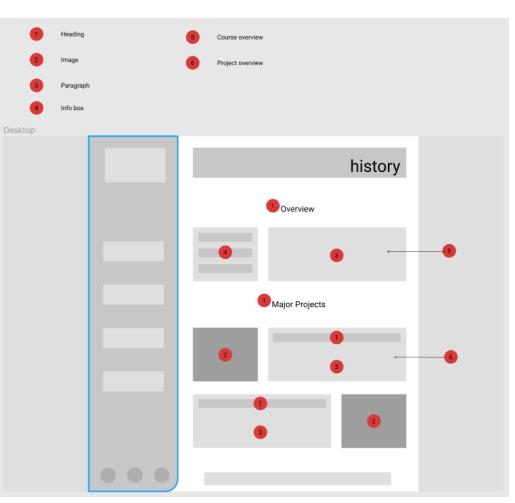


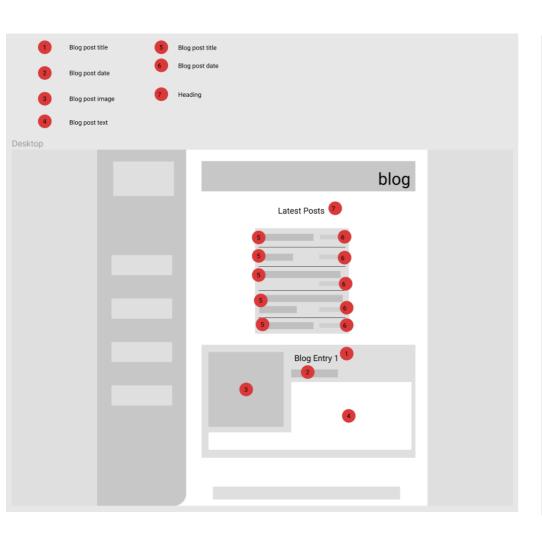
- About page with profile pic, description and list of tech skills
- Page header also resembles the old Neopets headers

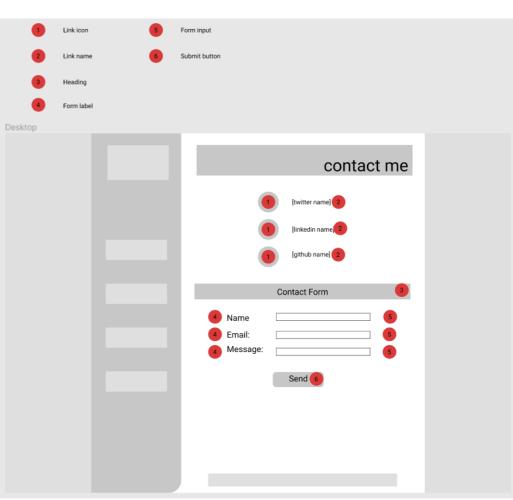




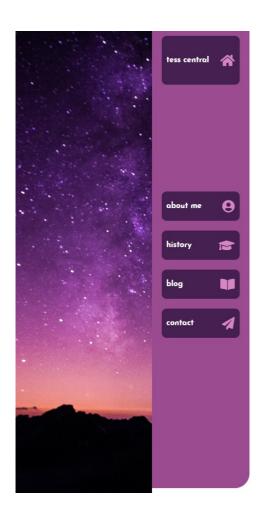








Ta-da!







Latest	Posts

Cats are great	20-09-2019
Status update: home again	20-09-2019
Status Update: still home	18-09-2019
Status Update: working from home	18-09-2019
A walk in the park	17-09-2019



I'm junior developer Tessa Peterson, and you're looking at my portfolio website. Feel free to browse my study history, personal interests and showcased projects.



Me presenting my Cluedo Ruby app



Background photo by Vincentiu Solomon on Unsplash Icons from Font Awesome and simpleicons Contact form by Formspree





Components





Caption: Bailey, asleep, somehow

Cats are great

Posted on 20 Sept 2019

Aren't cats good? They can curl up like pretzels and still be comfortable somehow. I found Bailey sleeping like this earlier. Isn't it cute? Cats are ridiculous.

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 - **5**









- Nav sidebar with text/icons
- Animated main header
- Graphic page header
- Icons for tech skills/contact links
- Blog post container
- Image with border and caption

Components



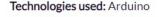
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A robot designed for "fighting" in a circular arena, with the intention of pushing an opponent out of the ring without being pushed out itself. The robot was designed, built and programmed by me. It looks a bit messy, but it worked!

The robot makes use of multiple sensors to detect objects and arena boundaries. Primarily ultrasonic sensors are used for object detection in multiple directions, and line sensors on each edge of the robot detect the arena boundary. Differential steering is used to control the robot.





- List of blog posts with links to individual posts
- Decorative section header elements
- Button-style links
- Info container for projects
- Small bordered image that links to full size image

Variations









Let's check it out!

https://techspeterson-portfolio.netlify.com/