

DEBUG pins



Female. The male connector is 852-10-004-20-001101 or 852-80-004-20-001101

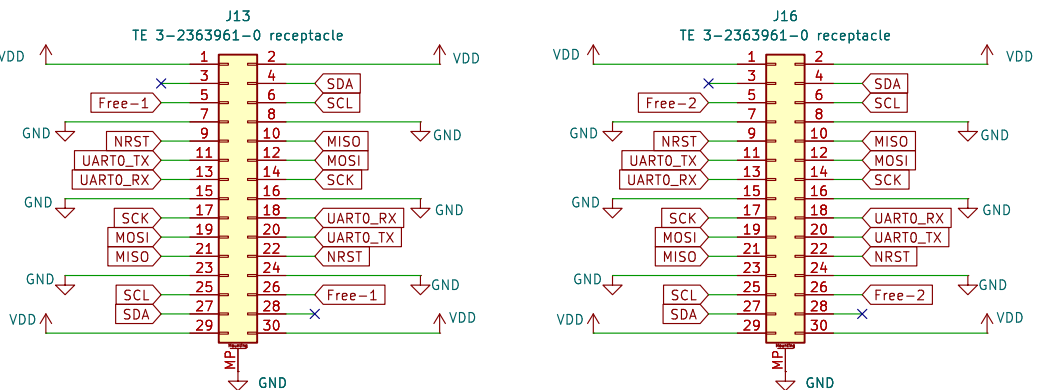
CS pullup helps during device startup and decreases randomness

Maybe buffer the clock net and MOSI. Won't screw up edges depending offboard stuff. SN74LVC2G17

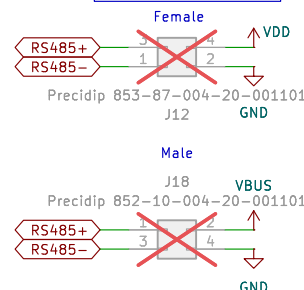
Communication/Chaining/Stacking Connectors

Reverse orientation top side receptacles, all pins are the same on both sides. This hub can hold two sensors

All connectors need: SPI, I2C, programming, and 1 multipurpose pin. Beyond that, nothing is guaranteed (what do the free pins do, are they different on each side, etc...)



VBUS — Hotswap controller power input. Chained together, so VDD is up top



Can't populate due to parts not being available from China. Will have to manually populate

Motor Drivers

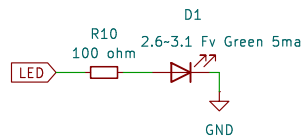
Author: Asher Edwards
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Sheet: /Connectors/
 File: Connectors.kicad_sch

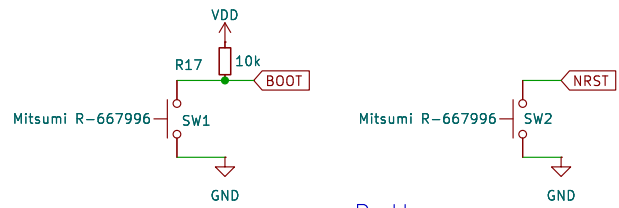
Title: CACKLE — Hub

Size: A4 Date: 2025-11-08
 KiCad E.D.A. 9.0.6

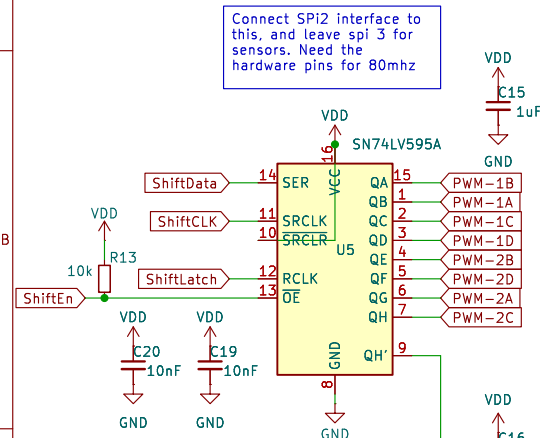
Rev: V1.2
 Id: 3/3



LED



Buttons



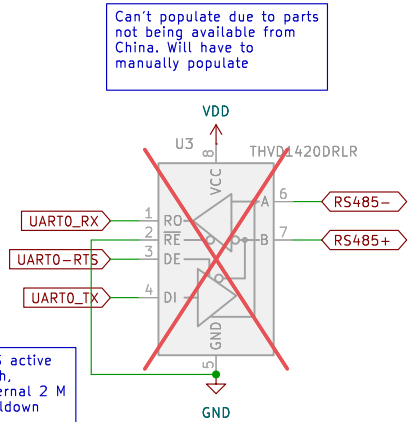
Connect SPI2 interface to this, and leave spi 3 for sensors. Need the hardware pins for 80mhz

10nF stitching caps for high frequency return paths

Shift clear is not used, so it is tied high to have a defined state

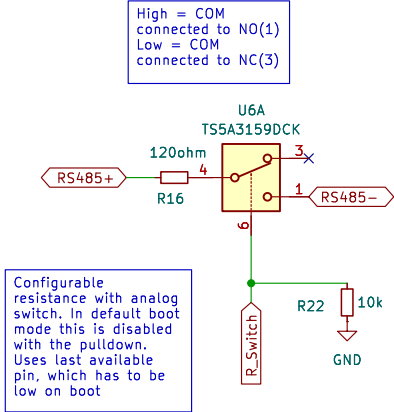
PWM Frequency: 20 kHz (50µs period).
PWM Resolution: 8-bit (256 steps)
Time per Step: 50µs/256 steps ≈ 195.3 nanoseconds per step.
Data Required: Every 195.3 ns, a new 16-bit pattern to the shift registers.
Required SPI Clock Speed: 16 bits/195.3 ns ≈ 81.92 Mbits/s.

PWM Shift Registers



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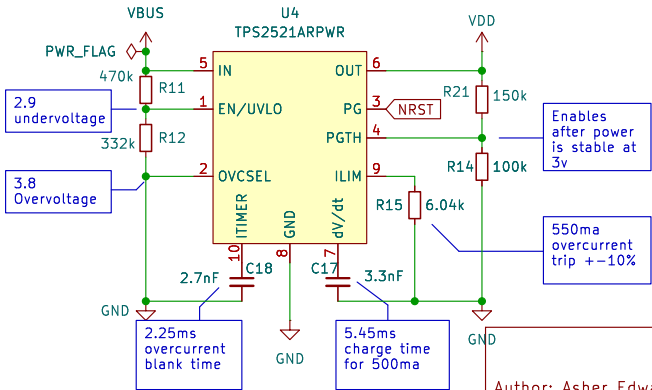
RTS active high, internal 2 M pull-down



High = COM connected to NO(1)
Low = COM connected to NC(3)

Configurable resistance with analog switch. In default boot mode this is disabled with the pull-down. Uses last available pin, which has to be low on boot

RS485



Hotswap Power

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Sheet: /Periphery/
File: Periphery.kicad_sch

Title: CACKLE - Hub

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