# **COMP20007 Design of Algorithms**

Hashing

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Lecture 15

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- Requires a hash function:  $h(K) \rightarrow i \in [0, m-1]$ .
- A hash function should:
  - Be efficient  $(\Theta(1))$ .
  - Distribute keys evenly (uniformly) along the table.

**Question:** if keys are integers, why do I need a hash function? I could just use the key as the index, no?

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- Note that  $K \in [0, m-1]$ . In other words we need to know the maximum number of keys in advance.
- Sometimes this is possible: postcodes, for example.
- Many times it is not:
  - *m* is too large (need to preallocate)
  - Unbounded integers (student IDs)
  - Non-integer keys (games)

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- Allow us to set the size m.
- Small m results in lots of collisions, large m takes excessive memory. Best m will vary.

## **Hashing Strings**

- Assume A  $\mapsto$  0, B  $\mapsto$  1, etc.
- Assume 26 characters and m = 101.
- Each character can be mapped to a *binary* string of length 5 ( $2^5 = 32$ ).

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We can think of a string as a long binary number:

$$M \ Y \ K \ E \ Y \ \mapsto 0110011000010100010011000 \ (= 13379736)$$

$$13379736 \mod 101 = 64$$

So 64 is the position of string M Y K E Y in the hash table.

## **Hashing Strings**

We deliberately chose m to be prime.

$$13379736 = 12 \times 32^4 + 24 \times 32^3 + 10 \times 32^2 + 4 \times 32 + 24$$

With m = 32, the hash value of any key is the last character's value!

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where m is a prime number. For example,

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The term between parenthesis can become quite large and result in overflow.

#### Horner's Rule

Instead of

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Now utilize these properties of modular arithmetic:

$$(x + y) \mod m = ((x \mod m) + (y \mod m)) \mod m$$
  
 $(x \times y) \mod m = ((x \mod m) \times (y \mod m)) \mod m$ 

So for each sub-expression it suffices to take values modulo m.

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Practical efficiency will depend on the table **load factor**:

$$\alpha = n/m$$

Assign multiple records per cell (usually through a linked list)

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- Worst case  $\Theta(n)$  only with a bad hash function (load factor is more of an issue).
- Requires extra memory.

## **Linear Probing**

Populate successive empty cells.

- Much harder analysis, simplified results show:
- A sucessful search requires  $(1/2) \times (1 + 1/(1 \alpha))$  operations on average.
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- Similar numbers for Insert. Delete virtually impossible.
- Does not require extra memory.
- Worst case  $\Theta(n)$  with a bad hash function and/or clusters.

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- Second try:  $(h(K) + s(K)) \mod m$
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Both Linear Probing and Double Hashing are sometimes referred as *Open Addressing* methods.

## Rehashing

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- High load factors deteriorate the performance of a hash table (for linear probing, ideally we should have  $\alpha < 0.9$ ).
- Rehashing allocates a new table (usually around double the size) and move every item from the previous table to the new one.
- Very expensive operation, but happens infrequently.

#### Hash Tables:

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- Requires good collision handling.

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- Also: memory requirements of a hash table are much higher.

That being said, if hashing is applicable, a well-tuned hash table will typically outperform BSTs.

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Next lecture: what happens if records/data is too large?