

# TIME SERIES ANALYSIS

## LECTURE 1

---

**[datascience@berkeley](mailto:datascience@berkeley)**

# Stationarity: Example 3

### 3. Moving Average Model of Order 1:

MA(1) An MA(1) model takes the form

$$x_t = w_t + \beta w_{t-1}$$

where  $w_t$  is a white noise series with mean zero and variance  $\sigma_w^2$ .

The expected value of  $x_t$  is

$$\begin{aligned} E(x_t) &= E(w_t + \beta w_{t-1}) \\ &= \alpha E(w_t) + E(w_{t-1}) \\ &= 0 \end{aligned}$$

since  $E(w_t) = 0 \forall t$

It is straight-forward (left as an exercise) to derive the autocorrelation function for the MA(1) model:

$$\rho_k = \begin{cases} 1 & \text{if } k = 0 \\ \frac{\sum_{i=0}^{q-k} \beta_i \beta_{i+k}}{\sum_{i=0}^q \beta_i^2} & \text{if } k = 1 \dots q \\ 0 & \text{if } k > q \end{cases}$$

### 3. Moving Average Process: Simulations (1)

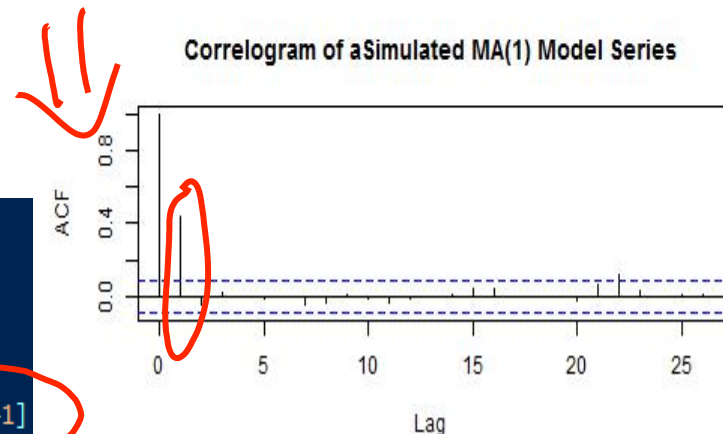
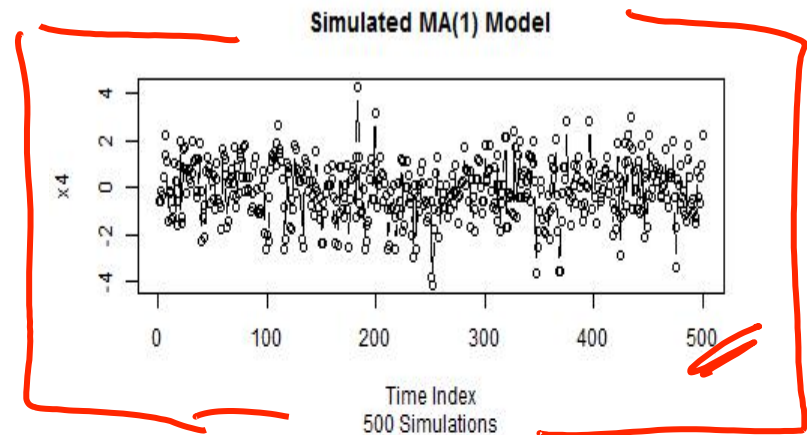
- As seen in various places in the course, a useful way to learn about the empirical patterns of a econometric model is to use simulate to simulate realizations from a theoretical model.
- In this example, we simulated from a MA(1) model 500 realization:

$$\begin{aligned} x_t &= \omega_t + \beta \omega_{t-1} \\ &= \omega_t + 0.8 \omega_{t-1} \end{aligned}$$

```
## 4. MA(1) Model
# Simulation
set.seed(898)
beta1 = 0.8
x4 <- w <- rnorm(500,0,sigma_w)
for (t in 2:500) x4[t] <- w[t] + beta1*w[t-1]
```

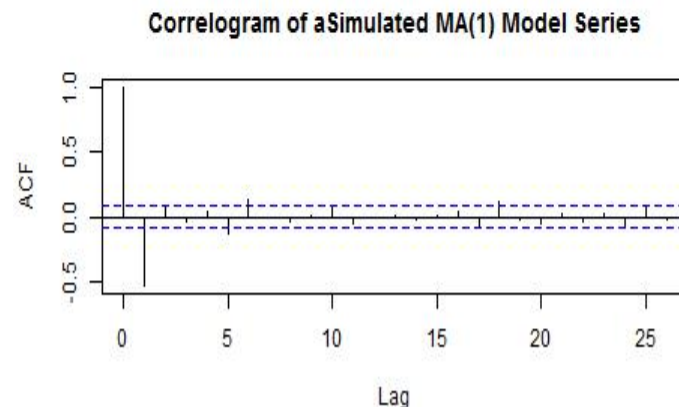
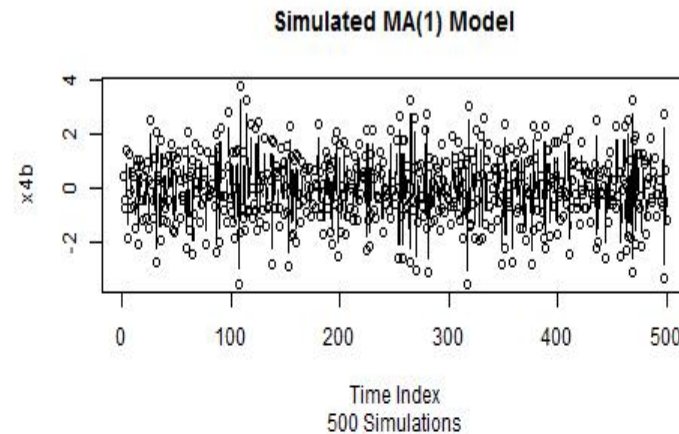
```
> summary(x4)
   Min. 1st Qu.  Median    Mean 3rd Qu.    Max.
-41.5400 -8.9360 -0.8613 -0.9833  7.5360  43.0900

> sd(x4)
[1] 12.28474
```



### 3. Moving Average Process: Simulations (2)

- A distinguish property of a  $MA(q)$  model is that its ACF drops off abruptly at  $q$  lags.
- In the case of  $MA(1)$  model, the ACF drops off to almost zero after the first lag, as shown in the correlogram.



# Berkeley

SCHOOL OF  
INFORMATION