

Multimedia (Lab 01)

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[Lab01-1] Introduction to OpenCV

- Install Visual C++ and OpenCV library in your computer
- Load an image and display it on your screen

What is OpenCV

- OpenCV (Open Source Computer Vision Library: <http://opencv.org>) is an open-source BSD-licensed library that includes several hundreds of computer vision algorithms.
- Online documentation :
<https://docs.opencv.org/4.2.0/>
- Tutorial :
https://docs.opencv.org/4.2.0/d3/d81/tutorial_contrib_root.html

OpenCV

- Install Visual C++ and OpenCV library in your computer
 - OpenCV4.2 – vc15 (Visual Studio2017), vc14 (VS2015)
 - OpenCV4.0 – vc15 (Visual Studio2017), vc14 (VS2015)
 - OpenCV3.4 – vc15 (VS2017), vc14 (VS2015)
 - OpenCV3.2 – vc14 (VS2015)
 - OpenCV3.1 – vc14 (VS2015), vc12 (VS2013)
 - OpenCV3.0 – vc12, vc11 (VS2012)
- If you are using x86 computer, you have to install OpenCV3.0 prebuild or you have to build the source code by yourself.

OpenCV Tutorials

- https://docs.opencv.org/4.2.0/d3/d81/tutorial_contrib_root.html
- **Introduction to OpenCV**
 - You will learn how to setup OpenCV on your computer!
- **The Core Functionality (core module)**
 - Here you will learn the about the basic building blocks of the library. A must read and know for understanding how to manipulate the images on a pixel level.

How to setup OpenCV

How to setup OpenCV

- **Step 1: Download and extract the pre-built library**
 - Release files for 4.2.0 are listed at <https://github.com/opencv/opencv/releases/tag/4.2.0>.




OpenCV 4.2.0

 alek released this 4 days ago · 1 commit to master since this release

OpenCV 4.2.0 has been released.

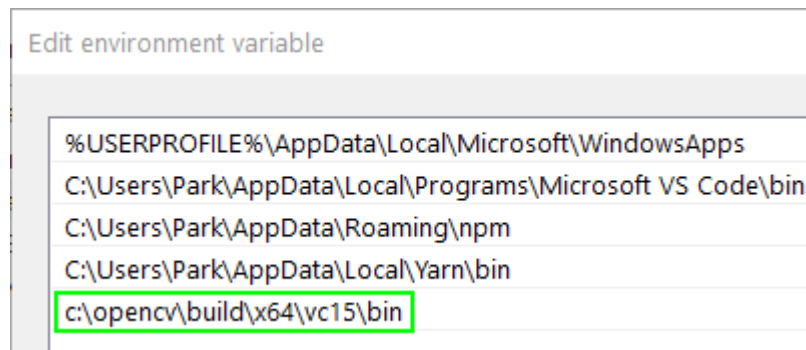
Change log is [here](#).

▼ Assets 6

 opencv-4.2.0-android-sdk.zip	218 MB
 opencv-4.2.0-docs.zip	80.3 MB
 opencv-4.2.0-ios-framework.zip	150 MB
 opencv-4.2.0-vc14_vc15.exe	206 MB
 Source code (zip)	
 Source code (tar.gz)	

How to setup OpenCV

- **Step 2: Add to path**
 - Add opencv's bin directory to path.



. v14 v15

How to setup OpenCV

• Step 3: Create a project in Visual Studio 2019



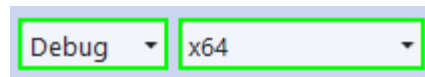
Choose “콘솔 앱”

How to setup OpenCV

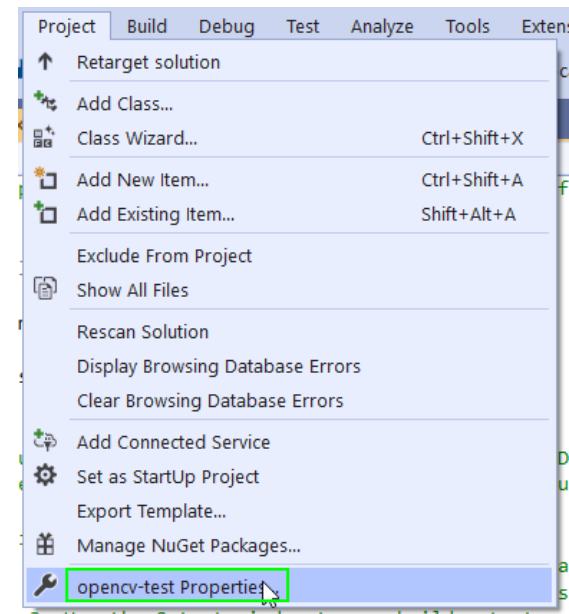
- **Set platform target to x64** — Pre-built binaries are built for x64 Windows platforms.
- **Add to Include Directories** — Tell the compiler how the OpenCV library looks. This is done by providing a path to the header files (build/include).
- **Add to Library Directories** — Tell the linker where it can find the lib files for different modules.
- **Add Additional Dependencies** — List .lib files for different modules. Note that we're only going to list a single all-in-one file named opencv_world.

How to setup OpenCV

- Set platform target to x64



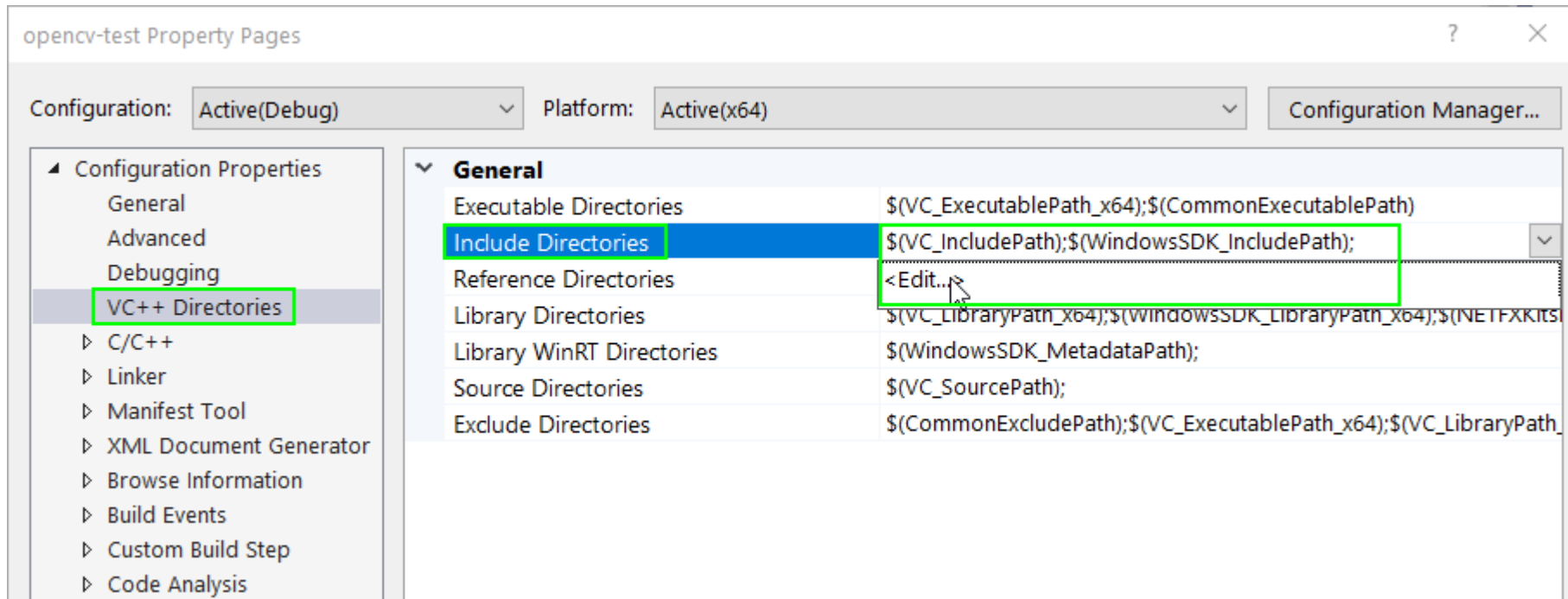
- Now, go to **Project** → *YourProjectName* Properties in the menu.



How to setup OpenCV

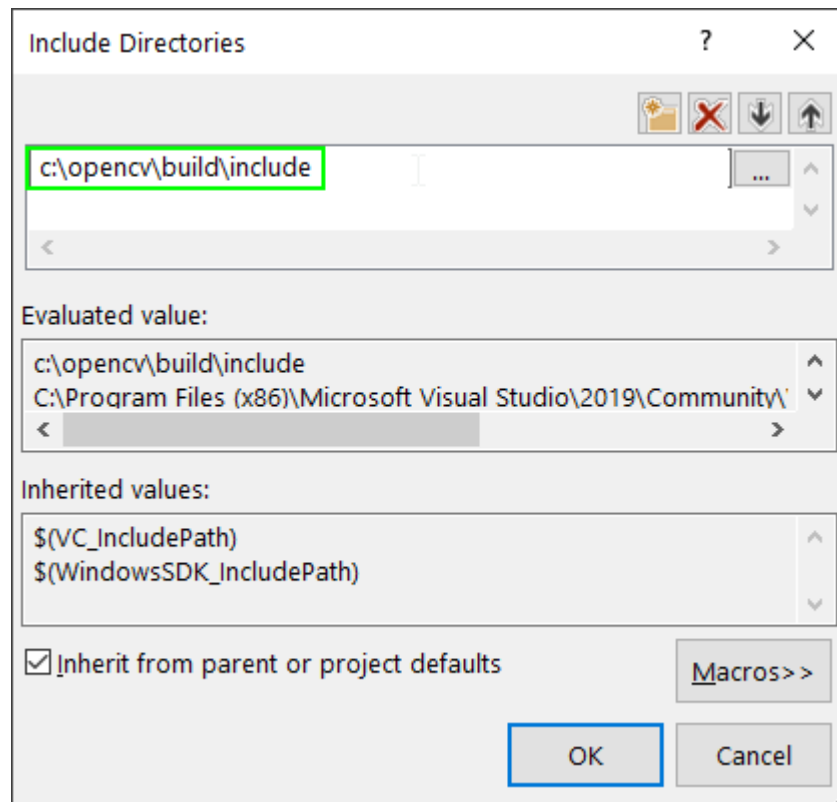
• Add to Include Directories

- select **VC++ Directories** page on the left and click on **Include Directories** row.



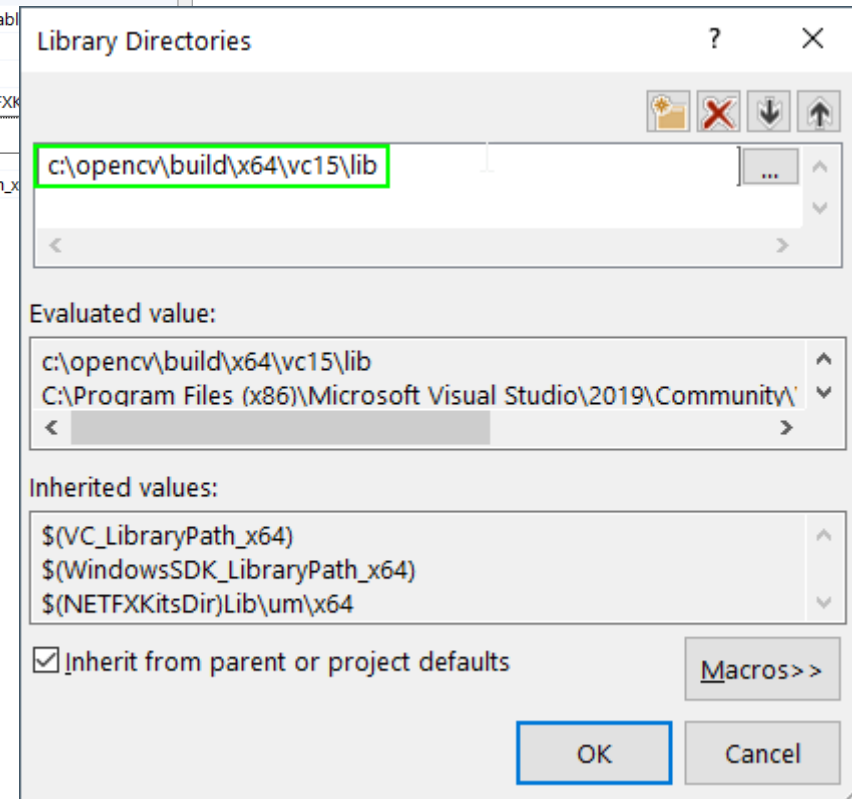
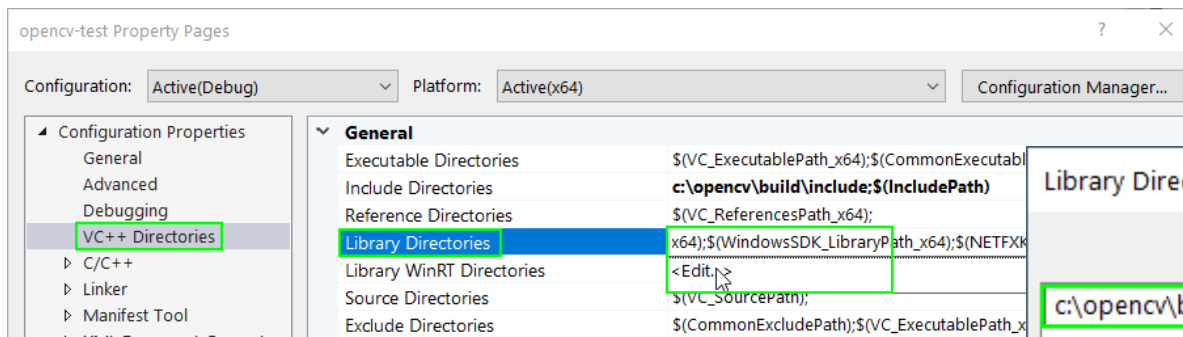
How to setup OpenCV

- In Include Directories window, add `c:\opencv\build\include`.

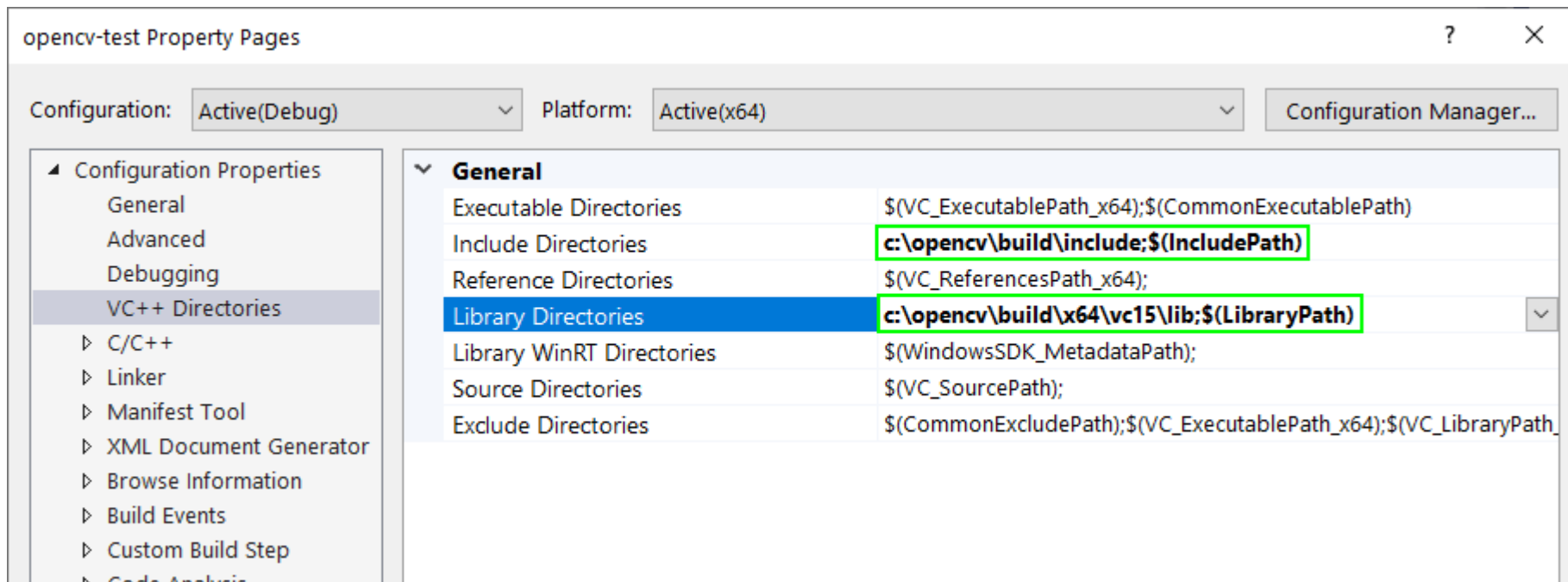


How to setup OpenCV

- In the same tab, look for **Library Directories**
- Add **c:\opencv\build\x64\vc15\lib**



- The VC++ Directories tab should look like below:



How to setup OpenCV

• Add Additional Dependencies

The screenshot shows the 'opencv-test Property Pages' dialog in Visual Studio. The 'Configuration' is set to 'Active(Debug)' and the 'Platform' is 'Active(x64)'. The 'Linker' tab is selected under 'C/C++'. The 'Additional Dependencies' field is highlighted, and a secondary dialog box is open showing the 'Additional Dependencies' list. The list contains 'opencv_world420d.lib' and '%(AdditionalDependencies)'. The 'Evaluated value' section shows the same list. The 'Inherited values' section lists 'kernel32.lib', 'user32.lib', 'gdi32.lib', and 'winspool.lib'. The 'Inherit from parent or project defaults' checkbox is checked.

opencv-test Property Pages

Configuration: Active(Debug) Platform: Active(x64) Configuration Manager...

Configuration Properties

- General
- Advanced
- Debugging
- VC++ Directories
- C/C++
 - Linker
 - General
 - Input
 - Manifest File
 - Debugging

Additional Dependencies

2.lib;uuid.lib;odbc32.lib;odbc32.lib;%(AdditionalDependencies)

Ignore All Default Libraries <Edit>

Ignore Specific Default Libraries

Module Definition File

Add Module to Assembly

Embed Managed Resource File

Force Symbol References

Delay Loaded DLLs

Assembly Link Resource

Additional Dependencies

opencv_world420d.lib

Evaluated value:

opencv_world420d.lib
%(AdditionalDependencies)

Inherited values:

kernel32.lib
user32.lib
gdi32.lib
winspool.lib

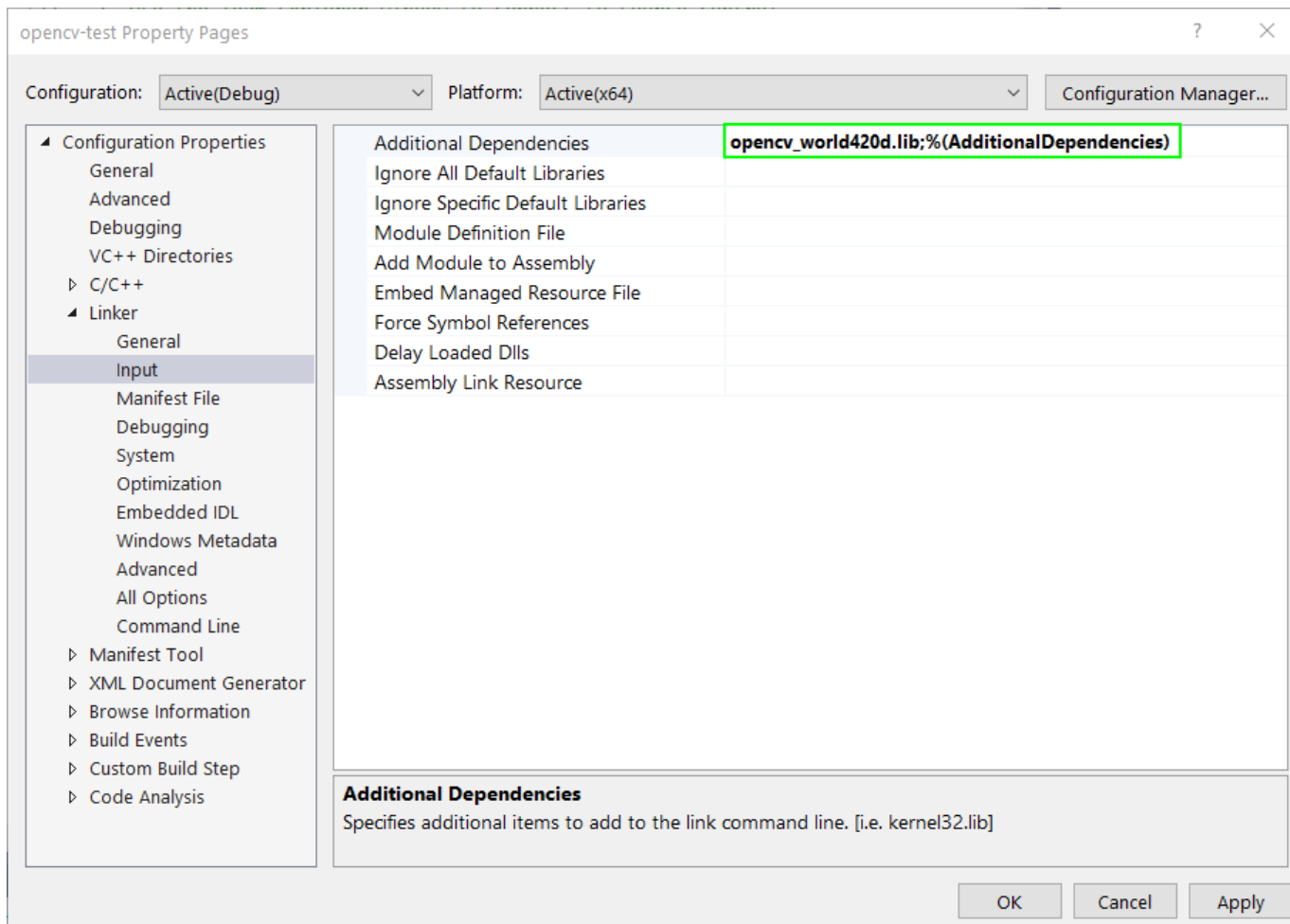
☒ Inherit from parent or project defaults

Macros>>

OK Cancel

How to setup OpenCV

- The Linker tab should look like below:



How to setup OpenCV

• Step 4: Check out demo code!

```
#include <opencv2/core/core.hpp>
#include <opencv2/highgui/highgui.hpp>
#include <opencv2/imgproc.hpp>
#include <iostream>

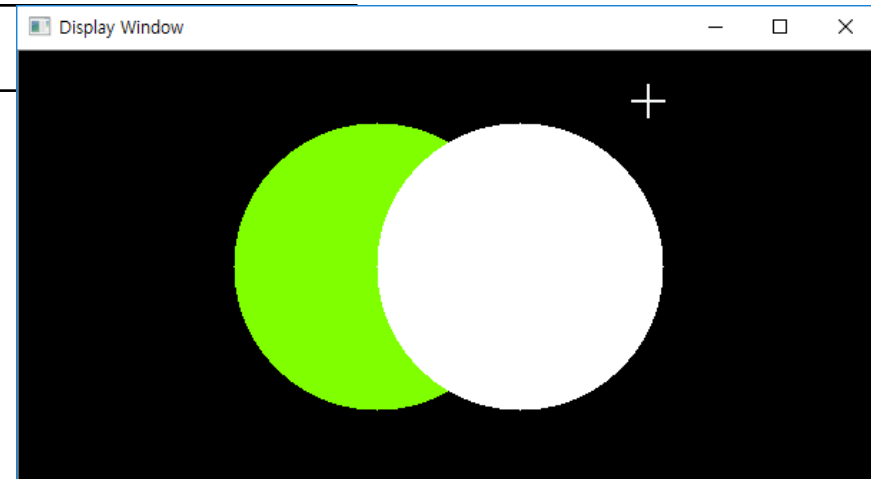
using namespace cv;
using namespace std;

int main()
{
    Mat image = Mat::zeros(300, 600, CV_8UC3);

    circle(image, Point(250, 150), 100, Scalar(0, 255, 128), -100); //2

    circle(image, Point(350, 150), 100, Scalar(255, 255, 255), -100);

    imshow("Display Window", image); //
    waitKey(0); //
    return 0;
}
```



Overview of OpenCV

Modular Structure

- OpenCV has a **modular structure**, which means that the package includes several shared or static libraries. The following modules are available:
 - **Core functionality** - a compact module defining basic data structures, including the dense multi-dimensional array 'Mat' and basic functions used by all other modules.
 - **Image processing** - an image processing module that includes linear and non-linear image filtering, geometrical image transformations (resize, affine and perspective warping, generic table-based remapping), color space conversion, histograms, and so on.
 - **video** - a video analysis module that includes motion estimation, background subtraction, and object tracking algorithms.
 - **calib3d** - basic multiple-view geometry algorithms, single and stereo camera calibration, object pose estimation, stereo correspondence algorithms, and elements of 3D reconstruction.
 - **features2d** - salient feature detectors, descriptors, and descriptor matchers.
 - **objdetect** - detection of objects and instances of the predefined classes (for example, faces, eyes, mugs, people, cars, and so on).
 - **highgui** - an easy-to-use interface to simple UI capabilities.
 - **videoio** - an easy-to-use interface to video capturing and video codecs.
 - **gpu** - GPU-accelerated algorithms from different OpenCV modules.
 - ... some other helper modules

API Concepts

- **cv Namespace**

- All the OpenCV classes and functions are placed into the cv namespace. Therefore, to access this functionality from your code, use the **cv::** specifier or using namespace cv;

- 1 #include "opencv2/core.hpp"
- 2 ...
- 3 **cv::**Mat H = **cv::**findHomography(points1, points2, CV_RANSAC, 5);
- 4 ...

- or :

- 1 #include "opencv2/core.hpp"
- 2 **using namespace cv;** // cv:: .
- 3 ...
- 4 Mat H = findHomography(points1, points2, CV_RANSAC, 5);
- 5 ...

- **Automatic Memory Management**

- First of all, `std::vector`, `Mat`, and other data structures used by the functions and methods have destructors that deallocate the underlying memory buffers when needed. This means that the destructors do not always deallocate the buffers as in case of `Mat`. They take into account possible data sharing. A destructor *decrements the reference counter* associated with the matrix data buffer. The buffer is deallocated *if and only if the reference counter reaches zero*, that is, when no other structures refer to the same buffer.
- Similarly, when a `Mat` instance is copied, no actual data is really copied. Instead, the reference counter is incremented to memorize that there is another owner of the same data.
 - There is also the **`Mat::clone`** method that creates a full copy of the matrix data. See the example in the next slide:

• Automatic Allocation of the Output Data

- OpenCV deallocates the memory automatically, as well as automatically allocates the memory for output function parameters most of the time.
- The size and type of the output arrays are determined from the size and type of input arrays.

```

1  #include "opencv2/imgproc.hpp"
2  #include "opencv2/highgui.hpp"
3
4  using namespace cv;
5
6  int main(int, char**)
7  {
8      VideoCapture cap(0);
9      if(!cap.isOpened()) return -1;
10
11     Mat frame, edges;
12     namedWindow("edges",1);
13     for(;;)
14     {
15         cap >> frame;
16         cvtColor(frame, edges, COLOR_BGR2GRAY);
17         GaussianBlur(edges, edges, Size(7,7), 1.5, 1.5);
18         Canny(edges, edges, 0, 30, 3);
19         imshow("edges", edges);
20         if(waitKey(30) >= 0) break;
21     }
22     return 0;
23 }

```

Data Types

- A limited fixed set of primitive data types
- That is, array elements should have one of the following types:
 - 8-bit unsigned integer (uchar)
 - 8-bit signed integer (schar)
 - 16-bit unsigned integer (ushort)
 - 16-bit signed integer (short)
 - 32-bit signed integer (int)
 - 32-bit floating-point number (float)
 - 64-bit floating-point number (double)

```
1 enum { CV_8U=0, CV_8S=1, CV_16U=2, CV_16S=3, CV_32S=4, CV_32F=5, CV_64F=6 };
```


- Examples of array data construction

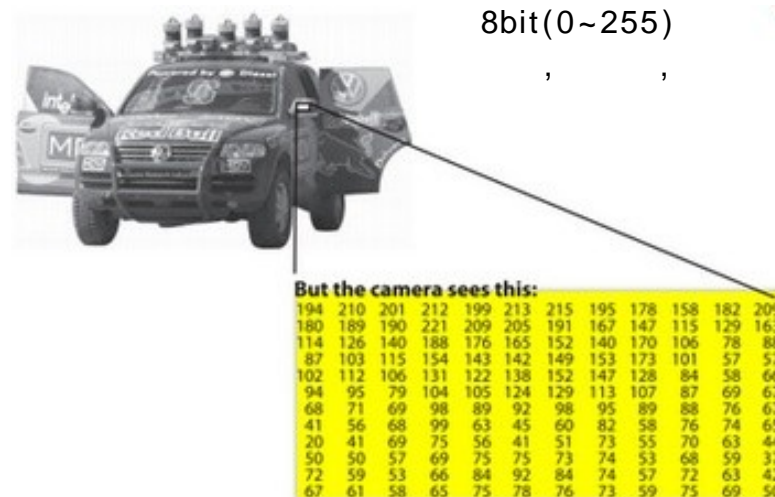
```

1 Mat mtx(3, 3, CV_32F); // make a 3x3 floating-point matrix
2 Mat cmtx(10, 1, CV_64FC2); // make a 10x1 2-channel floating-point
3                               // matrix (10-element complex vector)
4 Mat img(Size(1920, 1080), CV_8UC3); // make a 3-channel (color) image
5                               // of 1920 columns and 1080 rows.
6 Mat grayscale(image.size(), CV_MAKETYPE(image.depth(), 1)); // make a 1-channel image of
7                               // the same size and same
8                               // channel type as img

```

cv:Mat

- In the below image, you can see that the mirror of the car is nothing more than a matrix containing all the intensity values of the pixel points.
- All images inside a computer world are numerical matrices and other information describing the matrix itself.
- *OpenCV* is a computer vision library whose main focus is to process and manipulate this information.
- Therefore, the first thing you need to be familiar with is how OpenCV stores and handles images.



??

- *Mat* is basically a class with two data parts:
 - The **matrix header** (containing information such as the size of the matrix, the method used for storing, at which address is the matrix stored, and so on)
 - and a **pointer** to the matrix containing the pixel values (taking any dimensionality depending on the method chosen for storing).
 - The matrix header size is constant, however the size of the matrix itself may vary from image to image and usually is larger by orders of magnitude.
- You need to know about *Mat* is that you no longer need to manually allocate its memory and release it as soon as you do not need it.
- Most of the OpenCV functions will allocate its output data automatically.

- OpenCV uses a reference counting system.
- The idea is that each *Mat* object has its own header, however the matrix may be shared between two instances of them by having their matrix pointers point to the same address.
- Moreover, the copy operators will only copy the headers and the pointer to the large matrix, not the data itself.

**	A	C	A	- > C	A	A,C	가
	가	reference					
Mat A, C;							
A = imread(argv[1], IMREAD_COLOR);							
Mat B(A);							
C = A;							

// creates just the header parts

// here we'll know the method used (allocate matrix)

// Use the copy constructor

// Assignment operator

- All the above objects, in the end, point to the same single data matrix.
- Their headers are different, however, and making a modification using any of them will affect all the other ones as well.
- To create a region of interest (*ROI*) in an image you just create a new header with the new boundaries:

```
Mat D (A, Rect(10, 10, 100, 100) ); // using a rectangle
Mat E = A(Range::all(), Range(1,3)); // using row and column boundaries
```

- When the counter reaches zero the matrix too is freed.
- Sometimes you will want to copy the matrix itself too, so OpenCV provides the [Mat::clone\(\)](#) and [Mat::copyTo\(\)](#) functions.

```
Mat F = A.clone();  
Mat G;  
A.copyTo(G);
```

Practice

- [Lab01-2]
 - Load an image (using [cv::imread](#))
 - Create a named OpenCV window (using [cv::namedWindow](#))
 - Display an image in the OpenCV window (using [cv::imshow](#))

http://docs.opencv.org/3.2.0/db/deb/tutorial_display_image.html

```
#include <opencv2/core/core.hpp>
#include <opencv2/imgcodecs.hpp>
#include <opencv2/highgui/highgui.hpp>

#include <iostream>
#include <string>

using namespace cv;
using namespace std;

int main( int argc, char** argv )
{
    string imageName("../data/HappyFish.jpg"); // by default //
    if( argc > 1)
    {
        imageName = argv[1];
    }

    Mat image;

    image = imread(imageName.c_str(), IMREAD_COLOR); // Read the file

    if( image.empty() ) // Check for invalid input
    {
        cout << "Could not open or find the image" << std::endl ;
        return -1;
    }

    //Display window
    namedWindow( "Display window", WINDOW_AUTOSIZE ); // Create a window for display.

    imshow( "Display window", image ); // Show our image inside it.

    waitKey(0); // Wait for a keystroke in the window
    return 0;
}
```


Tip: include opencv2/opencv.hpp

- Instead the inclusion of each module's header file,

```
#include <opencv2/core/core.hpp>  
#include <opencv2/imgcodecs.hpp>  
#include <opencv2/highgui/highgui.hpp>
```

- only one include statement is enough

#include opencv2/opencv.hpp