

Multimedia (Lab 03)

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Summary

- In Previous Lab, you have exercised a basic pixel processing of images.
- In this lab, you will learn simple image processing techniques.
 - histogram equalization
 - image filtering techniques.

[Lab03-1]

- Histogram equalization to enhance the contrast of an image
 - Load a color image (using [`cv::imread`](#))
 - Convert the original image to grayscale
 - `cvtColor(src, src, CV_BGR2GRAY);`
 - Equalize the Histogram by using the OpenCV function [`EqualizeHist`](#)
 - `equalizeHist(src, dst);`
 - Display the source and equalized images in a window (using [`cv::imshow`](#))

//Lab3 - 1: histogram equalization

```
#include "opencv2/highgui/highgui.hpp"
#include "opencv2/imgproc/imgproc.hpp"
#include <iostream>
#include <stdio.h>

using namespace cv;
using namespace std;

/** @function main */
int main( int argc, char** argv )
{
    Mat src, dst;

    char* source_window = "Source image";
    char* equalized_window = "Equalized Image";

    /// Load image
    src = imread( argv[1], 1 );

    if( !src.data )
    { cout<<"Usage: ./Histogram_Demo <path_to_image>"<<endl;
      return -1;}

    /// Convert to grayscale
    cvtColor( src, src, CV_BGR2GRAY );

    /// Apply Histogram Equalization
    equalizeHist( src, dst );

    /// Display results
    namedWindow( source_window, CV_WINDOW_AUTOSIZE );
    namedWindow( equalized_window, CV_WINDOW_AUTOSIZE );

    imshow( source_window, src );
    imshow( equalized_window, dst );

    /// Wait until user exits the program
    waitKey(0);

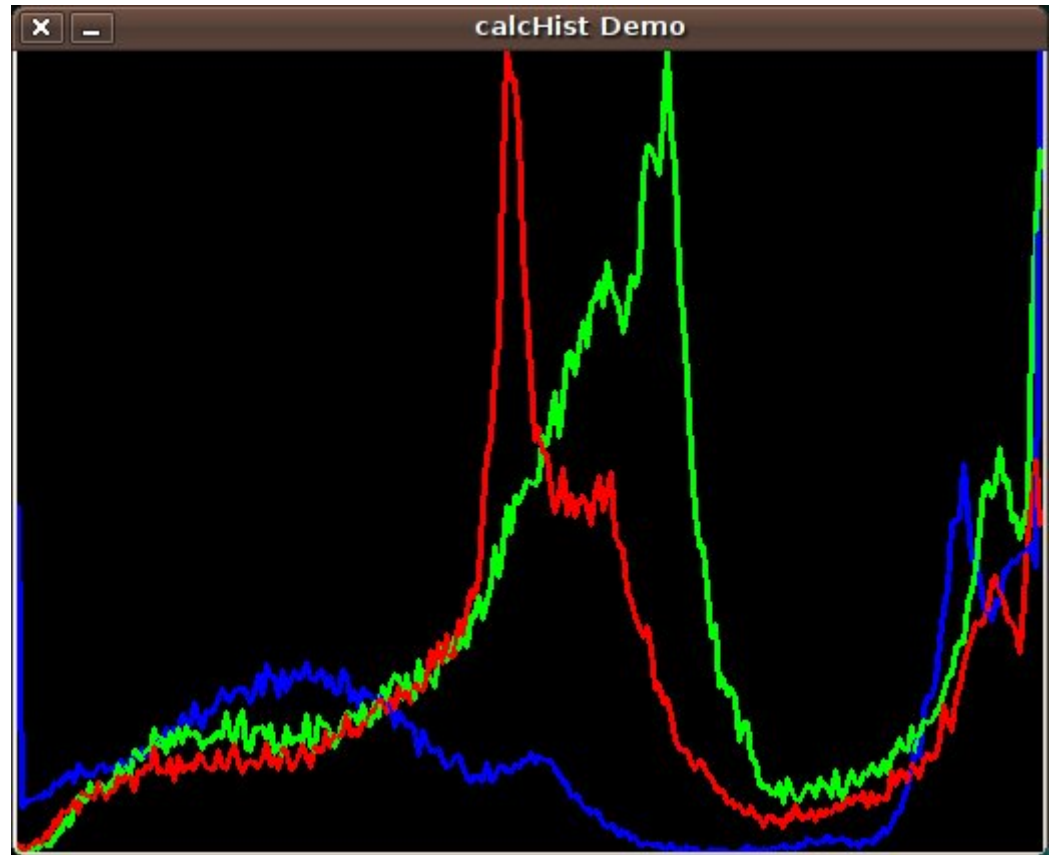
    return 0;
}
```

```
string srcImg_Path = "D:\\\\repos_VS\\\\Project_source\\IMG\\\\Lena_color.
string equalizedImg_Path = "D:\\\\repos_VS\\\\Project_source\\IMG\\\\
\\lena_noise.png";
//Load image
if (argc > 1) {
    srcImg_Path = argv[1];
    equalizedImg_Path = argv[2];
}
Mat src, dst;
src = imread(srcImg_Path.c_str(), IMREAD_COLOR);
if (src.empty()) {
    cout << "Could not open or find the image1" << std::endl;
    return -1;
}
//convert to gray scale
cvtColor(src, src, COLOR_BGR2GRAY);
//apply histogram equalization
equalizeHist(src, dst);
//Display results
imshow("source Image", src);
imshow("equalized Image", dst);
//Wait until user exits program
waitKey(0);
return 0;
```

Extension of Lab03-1

- Plot two histograms
 - One for input image
 - The other for output image after histogram equalization

Histogram Calculation & Plot



Histogram Calculation

- Calculate & plot the histogram of your input image.
- [calcHist](#)(&image, 1, 0, Mat(), hist, 1, &histSize, &histRange, uniform, accumulate);
 - Mat image; // input image
 - Mat hist; // output histogram
 - int histSize = 256; //from 0 to 255
 - Set the range of values (as we said, between 0 and 255)
 - float range[] = { 0, 256 } ; //the upper boundary is exclusive
 - const float* histRange = { range };
 - bool uniform = true;
 - bool accumulate = false;

Draw a histogram

- `// Draw the histogram for a grayscale image`
- `int hist_w = 512; int hist_h = 400;`
- `int bin_w = cvRound((double) hist_w/histSize);`
- `Mat histImage(hist_h, hist_w, CV_8UC3, Scalar(0,0,0));`
- `normalize(hist, hist, 0, histImage.rows, NORM_MINMAX, -1, Mat());`
- `for(int i = 1; i < histSize; i++)`
 `line(histImage, Point(bin_w*(i-1), hist_h -`
 `cvRound(hist.at<float>(i-1))), Point(bin_w*(i), hist_h -`
 `cvRound(hist.at<float>(i))), Scalar(255, 0, 0), 2, 8, 0);`
- `namedWindow("calcHist Demo", WINDOW_AUTOSIZE);`
- `imshow("calcHist Demo", histImage);`

[Lab03-2]

- Smoothing filter for an image
 - Download an image from E-Class. The file is Lena in gray-scale.
 - Load the image (using [`cv::imread`](#))
 - Perform NxN smoothing (average) filtering for the image, as you learn in this lecture (see Figure in page 40 in lecture 08).
 - Display the result image in an OpenCV window (using [`cv::imshow`](#))

[Lab03-3]

- Median filter for an image
 - Download an image from E-Class. The file is the noisy Lena image.
 - Load the image (using [`cv::imread`](#))
 - Perform median filtering with $N \times N$ window for the image, as you learn in this lecture (slide #40 in lecture 08).^{3*3 median filtering}
 - Display the result image in an OpenCV window (using [`cv::imshow`](#))



[Lab03-4]

- Derivative filter to obtain image gradient for an image
 - Download a gray-scale image.
 - Load the image (using [cv::imread](#)).
 - Perform 3x3 **Sobel** filtering for the image.
 - Display the gradient magnitude map of the filter output in an OpenCV window (using [cv::imshow](#))

$$\mathbf{G}_x = \begin{bmatrix} +1 & 0 & -1 \\ +2 & 0 & -2 \\ +1 & 0 & -1 \end{bmatrix} * \mathbf{A} \quad \text{and} \quad \mathbf{G}_y = \begin{bmatrix} +1 & +2 & +1 \\ 0 & 0 & 0 \\ -1 & -2 & -1 \end{bmatrix} * \mathbf{A}$$

$$\mathbf{G} = \sqrt{\mathbf{G}_x^2 + \mathbf{G}_y^2}$$

[Lab03-5]

;', $F''(x)$
가 .

68

2 가

- Sharpening filter by using Laplacian filter
 - Download an image from E-Class. The file is Lena in gray-scale.
 - Load an image (using [cv::imread](#))
 - Perform the **sharpening** filtering for the image by using a **Laplacian filter**, as you learn in this lecture (see Fig. 3.40 in page 39 in lecture 08).
 - Display the Laplacian image and the sharpened result image in OpenCV windows (using [cv::imshow](#))
- Try to use the blurred image as an input, which you have submitted for HW#1. Then perform the Sharping filtering using Laplacian filter.

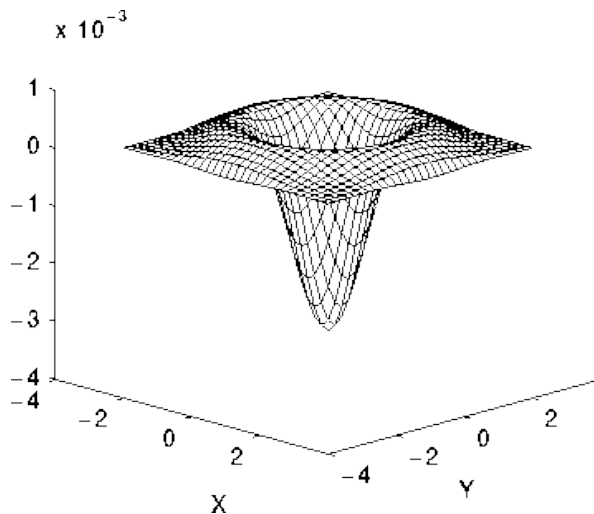
• Laplacian Filter

- Second derivatives

$$\nabla^2 f = \frac{\partial^2 f}{\partial x^2} + \frac{\partial^2 f}{\partial y^2}$$

$$\frac{\partial^2 f}{\partial x^2} = f(x+1, y) + f(x-1, y) - 2f(x, y)$$

$$\frac{\partial^2 f}{\partial y^2} = f(x, y+1) + f(x, y-1) - 2f(x, y)$$



0	1	0	1	1	1
1	-4	1	1	-8	1
0	1	0	1	1	1
0	-1	0	-1	-1	-1
-1	4	-1	-1	8	-1
0	-1	0	-1	-1	-1

a b
c d

FIGURE 3.39

(a) Filter mask used to implement the digital Laplacian, as defined in Eq. (3.7-4).

(b) Mask used to implement an extension of this equation that includes the diagonal neighbors. (c) and (d) Two other implementations of the Laplacian.

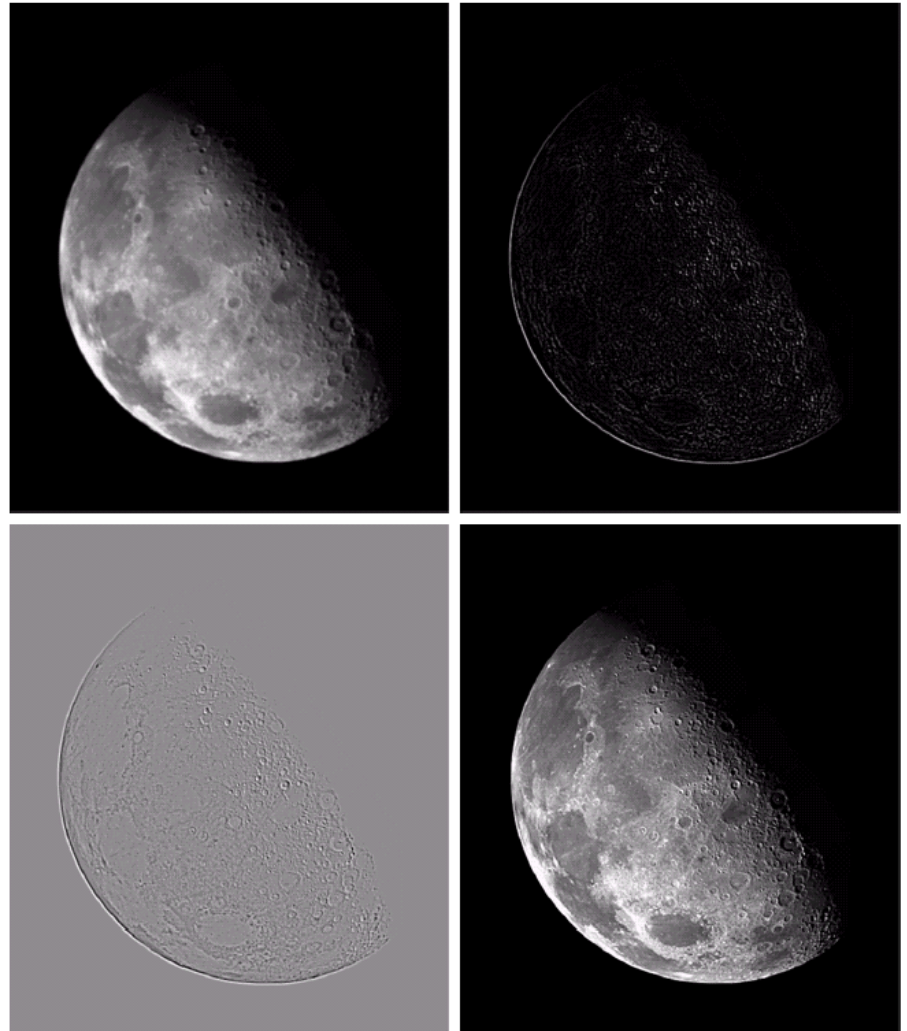
Sharpness Enhancement using Laplacian Filter

$$g(x, y) = f(x, y) + |\nabla^2 f(x, y)|$$

a b
c d

FIGURE 3.40

(a) Image of the North Pole of the moon.
(b) Laplacian-filtered image.
(c) Laplacian image scaled for display purposes.
(d) Image enhanced by using Eq. (3.7-5). (Original image courtesy of NASA.)



Tip

- Save/Load project properties
 - Click on “Add New Project Property Sheet”
→ name your new property sheet
 - Set OpenCV properties for your new property sheet
 - Click on Save button on the “Property Manager”
- Then, at the next time, you just need to “Add Existing Property Sheet”