

## **TASK-5**

### **Face Detection and Recognition**

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### **FACE DETECTION AND RECOGNITION**

Develop an AI application that can detect and recognize faces in images or videos. Use pre-trained face detection models like Haar cascades or deep learning-based face detectors, and optionally add face recognition capabilities using techniques like Siamese networks or ArcFace.

#### **CODE:**

##### **Input:**

```
import cv2
import face_recognition
import os
import numpy as np

# Load known faces
Known_faces_dir = "known_faces"
Known_face_encodings = []
```

```
Known names = []
```

```
print("Loading known faces...")
```

```
for name in os. Listdir (known faces dir):
```

```
    person dir = os. path. Join (known faces dir, name)
```

```
    for filename in os. Listdir (person dir):
```

```
        image path = os .path. join(person dir, filename)
```

```
        image = face recognition. load image file (image path)
```

```
        encodings = face recognition. Face encodings(image)
```

```
        if encodings:
```

```
            known encodings. Append (encodings [0])
```

```
            known names. Append (name)
```

```
# Start webcam
```

```
Video capture = cv2.VideoCapture(0)
```

```
Print ("Starting video stream...")
```

```
while True:
```

```
    ret, frame = video capture. Read ()
```

```
    if not ret:
```

```
        break
```

```
small frame = cv2.resize(frame, (0, 0), fx=0.25, fy=0.25)
```

```
rgb small frame = small frame[:, :, :-1]
```

```
face locations = face recognition. face locations (rgb small frame)
```

face encodings = face\_recognition.face\_encodings(rgb\_small\_frame, face\_locations)

for face\_encoding, face\_location in zip(face\_encodings, face\_locations):

    matches = face\_recognition.compare\_faces(known\_encodings, face\_encoding)

    name = "Unknown"

face\_distances = face\_recognition.face\_distance(known\_encodings, face\_encoding)

best\_match\_index = np.argmin(face\_distances)

if matches[best\_match\_index]:

    name = known\_names[best\_match\_index]

top, right, bottom, left = [v \* 4 for v in face\_location]

cv2.rectangle(frame, (left, top), (right, bottom), (0, 255, 0), 2)

cv2.rectangle(frame, (left, bottom - 35), (right, bottom), (0, 255, 0), cv2.FILLED)

    cv2.putText(frame, name, (left + 6, bottom - 6), cv2.FONT\_HERSHEY\_SIMPLEX, 0.8, (0, 0, 0), 2)

cv2.imshow("Face Detection & Recognition", frame)

if cv2.waitKey(1) & 0xFF == ord("q"):

    break

video\_capture.release()

cv2.destroyAllWindows()

```
Traceback (most recent call last):
  File "/data/user/0/ru.iiec.pydroid3/files/accomp_files/iiec_run/iiec_run.py", line 31, in <module>
    start(fakepyfile,mainpyfile)
    ~~~~~^~~~~~
  File "/data/user/0/ru.iiec.pydroid3/files/accomp_files/iiec_run/iiec_run.py", line 30, in start
    exec(open(mainpyfile).read(), __main__.__dict__)
    ~~~~~^~~~~~
  File "<string>", line 1, in <module>
ModuleNotFoundError: No module named 'cv2'

[Program finished]
```

### [code explanation :](#)

#### **Imports**

import cv2

import face\_recognition

import os

import numpy as np

- cv2: OpenCV library used for video capture and drawing on frames.
- face\_recognition: Library built on top of dlib for face detection and recognition.
- os: For navigating directories to load known faces.
- numpy: For array operations, especially calculating distances between face encodings.

```
known_faces_dir = "known_faces"
```

```
known_encodings = []
```

```
known_names = []
```

### **Loading Known Faces**

- `known_faces_dir`: The directory that stores images of people (each person in a subfolder).
- `known_encodings`: List of face encodings (128-dimensional vectors) for each known person.
- `known_names`: Stores the names corresponding to each encoding.

### **Looping Through Images**

```
for name in os.listdir(known_faces_dir):
```

```
    person_dir = os.path.join(known_faces_dir, name)
```

```
    for filename in os.listdir(person_dir):
```

```
        image_path = os.path.join(person_dir, filename)
```

```
        image = face_recognition.load_image_file(image_path)
```

```
        encodings = face_recognition.face_encodings(image)
```

```
        if encodings:
```

```
            known_encodings.append(encodings[0])
```

```
            known_names.append(name)
```

- Reads each image in every person's folder.
- Converts the image into a face encoding.
- Stores the encoding and the person's name for later recognition.

### **Starting Webcam**

```
Video capture = cv2.VideoCapture(0)
```

Starts the webcam feed (0 = default camera).

### **Main Loop: Face Detection & Recognition**

while True:

ret, frame = video capture. read()

if not ret:

break

- Reads each frame from the webcam.
- If the frame isn't received correctly (ret == False), break the loop.

### **Resize and Convert to RGB**

Small\_frame = cv2.resize(frame, (0, 0), fx=0.25, fy=0.25)

rgb\_small\_frame = small\_frame[:, :, ::-1]

- Downscales the frame for faster processing ( $\frac{1}{4}$  of the original size).
- Converts BGR to RGB (OpenCV uses BGR, face recognition expects RGB).

### **Face Detection and Encoding**

Face\_locations = face\_recognition. Face\_locations (rgb\_small\_frame)

face\_encodings = face\_recognition. Face\_encodings (rgb\_small\_frame, face\_locations)

- Face\_locations: Returns coordinates of detected faces.
- Face\_encodings: Generates face encodings for detected faces.

for face\_encoding, face\_location in zip (face\_encodings, face\_locations):

matches = face\_recognition. compare\_faces (known\_encodings, face\_encoding)

name = "Unknown"

- Compares the new face encoding with the known ones.
- Initially assumes the person is "Unknown".

### Find the Closest Match

Face distances = face recognition. Face distance(known encodings, face encoding)

```
best match index = np. Argmin(face distances)
```

```
if matches[best match index]:
```

```
    name = known names [best match index]
```

- Calculates distances between the current face and known faces.
- Picks the best match using the smallest distance.
- If the best match is True in matches, it assigns the correct name.

### Draw Bounding Box and Label

```
top, right, bottom, left = [v * 4 for v in face location]
```

```
cv2.rectangle(frame, (left, top), (right, bottom), (0, 255, 0), 2)
```

```
cv2.rectangle(frame, (left, bottom - 35), (right, bottom), (0, 255, 0),  
cv2.FILLED)
```

```
cv2.putText(frame, name, (left + 6, bottom - 6),  
cv2.FONT_HERSHEY_SIMPLEX, 0.8, (0, 0, 0), 2)
```

- Multiplies coordinates by 4 (since we scaled down earlier).
- Draws a green rectangle around the face.
- Displays the person's name below their face.

```
cv2.imshow("Face Detection & Recognition", frame)
```

```
if cv2.waitKey(1) & 0xFF == ord("q"):
```

```
    break
```

```
cv2.imshow("Face Detection & Recognition", frame)
```

```
if cv2.waitKey(1) & 0xFF == ord("q"):
```

```
    break
```

### **Show the Frame**

```
cv2.imshow("Face Detection & Recognition", frame)
```

```
if cv2.waitKey(1) & 0xFF == ord("q"):
```

```
    break
```

- How is the annotated video in a window.
- Exits when the user presses the "q" key.

### **Clean Up**

```
Video capture release ()
```

```
cv2.destroyAllWindows()
```

- Stops the camera.
- Closes all OpenCV windows.