# Kaustav Ghosh

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#### **INTERNSHIPS**

#### • Microsoft Student Partners-Machine Learning Internship

-Guided a team of 10 individuals to collaborate and accomplish a Regression task of price prediction of used cars in a machine learning pipeline through Exploratory Data Analysis, Feature Engineering and Model Building.

### • Qbotics Labs - Robot Operating System Internship

- Constructed a Differential Drive with caster wheel from scratch using URDF and XACRO files and mounted the same with laser scanner , IMU and Velodyne Puck VLP-16 Lidar and simulated the same in Gazebo and Webots

# • United Nations TakenMind - Global Data Analytics Internship

- Performed Exploratory Data Analysis techniques using Matplotlib and Seaborn
- Implemented several boxplots, countplots, heatmaps on several datasets
- Documentated several practical examples of Numpy and Pandas

# • Ineuron Deep Learning with Masters in Computer Vision and Natural Language Processing

- Postponed due to Covid Situation

#### ACADEMIC PROJECTS

# • Compiler Frontend for subset of C-Language

- Coded a Lexical Analyser that extracts tokens from a C source file and a Symbol Table Generator to store information of identifiers and functions
- Coded a **Recursive Decent Parser** that semantically parses the grammar for subset of C-Language by analysing the tokens generated by a Lexical Analyser

# • Finland Labs in association with NSS IIT Roorkee - Covid 19 Data Analysis, Time Series Forecasting and Web Scraping

- Prepared a complete Data Analysis report on the World-wide COVID-19 attack statistics and used the Facebook's flyprophet Time-series Forecasting library to speculate the number of active corona victim cases in the upcoming days.

#### • Backtracking Algorithms

- Coded a Crossword Solver that takes a 10\*10 grid and word list and outputs a grid with the words accurately filled
- Coded a **Sudoku Solver** that takes a partially filled 9\*9 sudoku grid and outputs a solution so that every row, column and nine 3x3 subgrids contains exactly 1 instance of the digits from 1 to 9.

## • Food Labs Robotics Startup Competition - ROS Engineer Role

- Designed, modelled, constructed and Assembled a plethora of sensors and Robots across multiple software platforms like freeCad, Blender, Gazebo and also fabricated a Defense Building from scratch using floor plan and Gazebo World Editor

# • Analysis of Selective Compliance Assembly Robot Arm and Modelling of T3R Robot

- Computed DH parameters for the SCARA robot and used it to formulate the Forward and Inverse Kinematics of the robot arm. Also formulated Lagrange Euler Dynamics

#### POSITIONS OF RESPONSIBILITY

Local Committee Member of IOSD(International Organization of Software Developers)

#### TECHNICAL SECTION

Softwares Used: AutoCAD, Matlab, Keil, Altera MaxPlus 2, VirtualBox, Vm Ware, Oracle SQL, GNS 3 Network Simulator Programming Languages: Fluent in C/C++ & Python , Familiar with Java , Verilog, LATEX, Linux Shell Scripting, fair acquaintance with ARM assembly programming (NXP LPC 1768)

Libraries & Frameworks: C++-STL Java-JavaFX GUI Python-Numpy, Pandas, Scikit-Learn, Keras, Tensorflow, PyTorch Operating Systems Used: Windows-XP, Vista, 7,10 Linux-Ubuntu