# Configuration Desk

# Glossary

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#### How to Contact dSPACE

Mail: dSPACE GmbH

Rathenaustraße 26 33102 Paderborn

Germany

Tel.: +49 5251 1638-0
Fax: +49 5251 16198-0
E-mail: info@dspace.de
Web: http://www.dspace.com

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# ConfigurationDesk Glossary

#### Introduction

The glossary briefly explains the most important expressions and naming conventions used in the ConfigurationDesk documentation.

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### Α

**Application** There are two types of applications in ConfigurationDesk:

- A part of a ConfigurationDesk project: ConfigurationDesk application ②.
- An application that can be executed on dSPACE real-time hardware: real-time application ②.

**Application process** A component of a processing unit application ②. An application process contains one or more tasks ②.

**Application process component** A component of an application process ②. The following application process components are available in the Components subfolder of an application process:

- Behavior models ② that are assigned to the application process, including their predefined tasks ③, runnable functions ③, and events ③.
- Function blocks 2 that are assigned to the application process.

**AutomationDesk** A dSPACE software product for creating and managing any kind of automation tasks. Within the dSPACE tool chain, it is mainly used for automating tests on dSPACE hardware.

**AUTOSAR system description file** An AUTOSAR XML (ARXML) file that describes a system according to AUTOSAR. A system is a combination of a hardware topology, a software architecture, a network communication, and information on the mappings between these elements. The described network communication usually consists of more than one bus system (e.g., CAN, LIN, FlexRay).

# В

**Basic PDU** A general term used in the documentation to address all the PDUs the Bus Manager supports, except for container IPDUs ②, multiplexed IPDUs ③, and secured IPDUs ③. Basic PDUs are represented by the [ ) or [ ] symbol in

tables and browsers. The Bus Manager provides the same functionalities for all basic PDUs, such as ISignal IPDUs ② or NMPDUs.

**Behavior model** A model that contains the control algorithm for a controller (function prototyping system) or the algorithm of the controlled system (hardware-in-the-loop system). It does not contain I/O functionality nor access to the hardware. Behavior models can be modeled, for example, in MATLAB/Simulink by using Simulink Blocksets and Toolboxes from the MathWorks®.

You can add Simulink behavior models to a ConfigurationDesk application. You can also add code container files containing a behavior model such as Functional Mock-up Units ②, or Simulink implementation containers ② to a ConfigurationDesk application.

**Bidirectional signal port** A signal port that is independent of a data direction or current flow. This port is used, for example, to implement bus communication.

**BSC file** A bus simulation container ② file that is generated with the Bus Manager ② and contains the configured bus communication of one application process ②.

**Build Configuration table** A pane that lets you create build configuration sets and configure build settings, for example, build options, or the build and download behavior.

**Build Log Viewer** A pane that displays messages and warnings during the build process ②.

**Build process** A process that generates an executable real-time application based on your ConfigurationDesk application ② that can be run on a SCALEXIO system ③ or MicroAutoBox III system. The build process can be controlled and configured via the Build Log Viewer ②. If the build process is successfully finished, the build result files (build results ③) are added to the ConfigurationDesk application.

**Build results** The files that are created during the build process ②. Build results are named after the ConfigurationDesk application ② and the application process ② from which they originate. You can access the build results in the Project Manager ③.

**Bus access** The representation of a run-time communication cluster ②. By assigning one or more bus access requests ② to a bus access, you specify which communication clusters form one run-time communication cluster.

In ConfigurationDesk, you can use a bus function block ② (CAN, LIN) to implement a bus access. The hardware resource assignment ③ of the bus function block specifies the bus channel that is used for the bus communication.

**Bus access request** The representation of a request regarding the bus access ②. There are two sources for bus access requests:

■ At least one element of a communication cluster ② is assigned to the Simulated ECUs, Inspection, or Manipulation part of a bus configuration ③. The related bus access requests contain the requirements for the bus channels that are to be used for the cluster's bus communication.

 A frame gateway is added to the Gateways part of a bus configuration. Each frame gateway provides two bus access requests that are required to specify the bus channels for exchanging bus communication.

Bus access requests are automatically included in BSC files ②. To build a real-time application ②, each bus access request must be assigned to a bus access.

**Bus Access Requests table** A pane that lets you access bus access requests ② of a ConfigurationDesk application ③ and assign them to bus accesses ④.

**Bus configuration** A Bus Manager element that implements bus communication in a ConfigurationDesk application ② and lets you configure it for simulation, inspection, and/or manipulation purposes. The required bus communication elements must be specified in a communication matrix ③ and assigned to the bus configuration. Additionally, a bus configuration lets you specify gateways for exchanging bus communication between communication clusters ②. A bus configuration can be accessed via specific tables and its related Bus Configuration function block ③.

**Bus Configuration Function Ports table** A pane that lets you access and configure function ports of bus configurations ②.

**Bus Configurations table** A pane that lets you access and configure bus configurations ② of a ConfigurationDesk application ③.

**Bus Inspection Features table** A pane that lets you access and configure bus configuration features of a ConfigurationDesk application of for inspection purposes.

#### **Bus Manager**

- Bus Manager in ConfigurationDesk

  A ConfigurationDesk component that lets you configure bus communication and implement it in real-time applications ② or generate bus simulation containers ②.
- Bus Manager (stand-alone)
   A dSPACE software product based on ConfigurationDesk that lets you configure bus communication and generate bus simulation containers.

**Bus Manipulation Features table** A pane that lets you access and configure bus configuration features of a ConfigurationDesk application of for manipulation purposes.

**Bus simulation container** A container that contains bus communication configured with the Bus Manager ②. Bus simulation container (BSC ②) files can be used in the VEOS Player ② and in ConfigurationDesk. In the VEOS Player, they let you implement the bus communication in an offline simulation application ③.

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In ConfigurationDesk, they let you implement the bus communication in a real-time application ② independently from the Bus Manager.

**Bus Simulation Features table** A pane that lets you access and configure bus configuration features of a ConfigurationDesk application of for simulation purposes.

**Buses Browser** A pane that lets you display and manage the communication matrices ② of a ConfigurationDesk application ③. For example, you can access communication matrix elements and assign them to bus configurations. This pane is available only if you work with the Bus Manager ④.

 $\mathsf{C}$ 

**Cable harness** A bundle of cables that provides the connection between the I/O connectors of the real-time hardware and the external devices ②, such as the ECUs to be tested. In ConfigurationDesk, it is represented by an external cable harness ② component.

**CAFX file** A ConfigurationDesk application fragment file that contains signal chain elements that were exported from a user-defined working view or the Temporary working view of a ConfigurationDesk application. This includes the elements' configuration and the mapping lines between them.

**CDL file** A ConfigurationDesk application ② file that contains links to all the documents related to an application.

Channel multiplication A feature that allows you to enhance the max. current or max. voltage of a single hardware channel by combining several channels. ConfigurationDesk uses a user-defined value to calculate the number of hardware channels needed. Depending on the function block type ②, channel multiplication is provided either for current enhancement (two or more channels are connected in parallel) or for voltage enhancement (two or more channels are connected in series).

Channel request A channel assignment required by a function block ②. ConfigurationDesk determines the type(s) and number of channels required for a function block according to the assigned channel set②, the function block features, the block configuration and the required physical ranges. ConfigurationDesk provides a set of suitable and available hardware resources② for each channel request. This set is produced according to the hardware topology② added to the active ConfigurationDesk application③. You have to assign each channel request to a specific channel of the hardware topology.

**Channel set** A number of channels of the same channel type ② located on the same I/O board or I/O unit. Channels in a channel set can be combined, for example, to provide a signal with channel multiplication ③.

**Channel type** A term to indicate all the hardware resources (channels) in the hardware system that provide exactly the same characteristics. Examples for

channel type names: Flexible In 1, Digital Out 3, Analog In 1. An I/O board in a hardware system can have channel sets ② of several channel types. Channel sets of one channel type can be available on different I/O boards.

**Cluster** Communication cluster 2.

**Common Program Data folder** A standard folder for application-specific configuration data that is used by all users.

%PROGRAMDATA%\dSPACE\<InstallationGUID>\<ProductName>
or

%PROGRAMDATA%\dSPACE\<ProductName>\<VersionNumber>

**Communication cluster** A communication network of network nodes ② that are connected to the same physical channels and share the same bus protocol and address range.

**Communication matrix** A file that defines the communication of a bus network. It can describe the bus communication of one communication cluster ② or a bus network consisting of different bus systems and clusters. Files of various file formats can be used as a communication matrix: For example, AUTOSAR system description files ②, DBC files ③, LDF files ③, and FIBEX files ②.

Communication package A package that bundles Data Inport blocks which are connected to Data Outport blocks. Hence, it also bundles the signals that are received by these blocks. If Data Inport blocks are executed within the same task ② and belong to the same communication package ③, their data inports are read simultaneously. If Data Outport blocks that are connected to the Data Inport blocks are executed in the same task, their output signals are sent simultaneously in one data package. Thus, communication packages guarantee simultaneous signal updates within a running task (data snapshot).

**Configuration port** A port that lets you create the signal chain ② for the bus communication implemented in a Simulink behavior model. The following configuration ports are available:

- The configuration port of a Configuration Port block ②.
- The Configuration port of a CAN, LIN, or FlexRay function block.

  To create the signal chain for bus communication, the configuration port of a Configuration Port block must be mapped to the Configuration port of a CAN, LIN, or FlexRay function block.

**Configuration Port block** A model port block that is created in ConfigurationDesk during model analysis for each of the following blocks found in the Simulink behavior model:

- RTICANMM ControllerSetup block
- RTILINMM ControllerSetup block
- FLEXRAYCONFIG UPDATE block

Configuration Port blocks are also created for bus simulation containers. A Configuration Port block provides a configuration port d that must be mapped

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to the Configuration port of a CAN, LIN, or FlexRay function block to create the signal chain for bus communication.

**ConfigurationDesk application** A part of a ConfigurationDesk project @ that represents a specific implementation. You can work with only one application at a time, and that application must be activated.

An application can contain:

- Device topology ②
- Hardware topology **②**
- Model topology ②
- Communication matrices ②
- External cable harness ②
- Build results ② (after a successful build process ② has finished)

You can also add folders with application-specific files to an application.

**ConfigurationDesk model interface** The part of the model interface that is available in ConfigurationDesk. This specific term is used to explicitly distinguish between the model interface in ConfigurationDesk and the model interface in Simulink.

**Conflict** A result of conflicting configuration settings that is displayed in the Conflicts Viewer ②. ConfigurationDesk allows flexible configuration without strict constraints. This lets you work more freely, but it can lead to conflicting configuration settings. ConfigurationDesk automatically detects conflicts and provides the Conflicts Viewer to display and help resolve them. Before you build a real-time application ③, you have to resolve at least the most severe conflicts (e.g., errors that abort the build process ④) to get proper build results ②.

**Conflicts Viewer** A pane that displays the configuration conflicts ① that exist in the active ConfigurationDesk application ②. You can resolve most of the conflicts directly in the Conflicts Viewer.

**Container IPDU** A term according to AUTOSAR. An IPDU that contains one or more other IPDUs (i.e., contained IPDUs). When a container IPDU is mapped to a frame , all its contained IPDUs are included in that frame as well.

**ControlDesk** A dSPACE software product for managing, instrumenting and executing experiments for ECU development. ControlDesk also supports calibration, measurement and diagnostics access to ECUs via standardized protocols such as CCP, XCP, and ODX.

**CTLGZ file** A ZIP file that contains a V-ECU implementation. CTLGZ files are exported by TargetLink ② or SystemDesk ③. You can add a V-ECU implementation based on a CTLGZ file to the model topology ② just like adding a Simulink model based on an SLX file ②.

**Cycle time restriction** A value of a runnable function 2 that indicates the sample time the runnable function requires to achieve correct results. The cycle time restriction is indicated by the Period property of the runnable function in the Properties Browser 2.

### D

**Data inport** A port that supplies data from ConfigurationDesk's function outports to the behavior model.

In a multimodel application, data inports also can be used to provide data from a data outport associated to another behavior model (model communication 2).

**Data outport** A port that supplies data from behavior model signals to ConfigurationDesk's function inports.

In a multimodel application, data outports also can be used to supply data to a data inport associated to another behavior model (model communication ②).

**DBC file** A Data Base Container file that describes CAN or LIN bus systems. Because the DBC file format was primarily developed to describe CAN networks, it does not support definitions of LIN masters and schedules.

**Device block** A graphical representation of devices from the device topology ② in the signal chain ③. It can be mapped to function blocks ③ via device ports ②.

**Device connector** A structural element that lets you group device pins ② in a hierarchy in the External Device Connectors table ③ to represent the structure of the real connector of your external device ③.

**Device pin** A representation of a connector pin of your external device ②. Device ports ② are assigned to device pins. ConfigurationDesk can use the device pin assignment together with the hardware resource assignment ③ and the device port mapping to calculate the external cable harness ②.

**Device port** An element of a device topology ① that represents the signal of an external device ② in ConfigurationDesk.

**Device port group** A structural element of a device topology ② that can contain device ports ③ and other device port groups.

**Device topology** A component of a ConfigurationDesk application② that represents external devices③ in ConfigurationDesk. You can create a device topology from scratch or easily extend an existing device topology. You can also merge device topologies to extend one. To edit or create device topologies independently of ConfigurationDesk, you can export and import DTFX② and XLSX② files.

**DSA file** A dSPACE archive file that contains a ConfigurationDesk application ② and all the files belonging to it as one unit. It can later be imported to another ConfigurationDesk project ③.

**dSPACE Help** The dSPACE online help that contains all the relevant user documentation for dSPACE products. Via the F1 key or the Help button in the dSPACE software you get context-sensitive help on the currently active context.

**dSPACE Log** A collection of errors, warnings, information, questions, and advice issued by all dSPACE products and connected systems over more than one session.

**DTFX file** A device topology ② export file that contains information on the interface to the external devices ③, such as the ECUs to be tested. The information includes details of the available device ports ③, their characteristics, and the assigned pins.

Ε

**ECHX file** An external cable harness ② file that contains the wiring information for the external cable harness. The external cable harness is the connection between the I/O connectors of the real-time hardware and the devices to be tested, for example, ECUs.

**ECU** Abbreviation of *electronic control unit*.

An embedded computer system that consists of at least one CPU and associated peripherals. An ECU contains communication controllers and communication connectors, and usually communicates with other ECUs of a bus network. An ECU can be member of multiple bus systems and communication clusters ②.

**ECU application** An application that is executed on an ECU ①. In ECU interfacing ② scenarios, parts of the ECU application can be accessed (e.g., by a real-time application ③) for development and testing purposes.

**ECU function** A function of an ECU application ① that is executed on the ECU ②. In ECU interfacing ② scenarios, an ECU function can be accessed by functions that are part of a real-time application ②, for example.

**ECU Interface Manager** A dSPACE software product for preparing ECU applications ② for ECU interfacing ②. The ECU Interface Manager can generate ECU interface container (EIC ③) files to be used in ConfigurationDesk.

**ECU interfacing** A generic term for methods and tools to read and/or write individual ECU functions ② and variables of an ECU application ②. In ECU interfacing scenarios, you can access ECU functions and variables for development and testing purposes while the ECU application is executed on the ECU ③. For example, you can perform ECU interfacing with SCALEXIO systems ③ or MicroAutoBox III systems to access individual ECU functions by a real-time application ③.

**EIC file** An ECU interface container file that is generated with the ECU Interface Manager ② and describes an ECU application ③ that is configured for ECU interfacing ③. You can import EIC files to ConfigurationDesk to perform ECU interfacing with SCALEXIO systems ③ or MicroAutoBox III systems.

**Electrical interface unit** A segment of a function block ① that provides the interface to the external devices ② and to the real-time hardware (via hardware

resource assignment ②). Each electrical interface unit of a function block usually needs a channel set ② to be assigned to it.

**Event** A component of a ConfigurationDesk application ① that triggers the execution of a task ②. The following event types are available:

- Timer event ②
- I/O event ②
- Software event ②

**Event port** An element of a function block ②. The event port can be mapped to a runnable function port ② for modeling an asynchronous task.

**Executable application** The generic term for real-time applications ② and offline simulation applications ③. In ConfigurationDesk, an executable application is always a real-time application since ConfigurationDesk does not support offline simulation applications.

**Executable application component** A component of an executable application ②. The following components can be part of an executable application:

- Imported behavior models ② including predefined tasks ③, runnable functions ③, and events ③. You can assign these behavior models to application processes ② via drag & drop or by selecting the Assign Model command from the context menu of the relevant application process.
- Function blocks added to your ConfigurationDesk application including associated I/O events ②. Function blocks are assigned to application processes via their model port mapping.

**Executable Application table** A pane that lets you model executable applications ② (i.e., real-time applications ②) and the tasks ③ used in them.

**EXPSWCFG file** An experiment software configuration file that contains configuration data for automotive fieldbus communication. It is created during the build process ② and contains the data in XML format.

External cable harness A component of a ConfigurationDesk application ② that contains the wiring information for the external cable harness (also known as cable harness ③). It contains only the logical connections and no additional information such as cable length, cable diameters, dimensions or the arrangement of connection points, etc. It can be calculated by ConfigurationDesk or imported from a file so that you can use an existing cable harness and do not have to build a new one. The wiring information can be exported to an ECHX file ② or XLSX file ②.

**External device** A device that is connected to the dSPACE hardware, such as an ECU or external load. The external device topology ② is the basis for using external devices in the signal chain ③ of a ConfigurationDesk application ③.

**External Device Browser** A pane that lets you display and manage the device topology ② of your active ConfigurationDesk application ③.

**External Device Configuration table** A pane that lets you access and configure the most important properties of device topology elements via table.

**External Device Connectors table** A pane that lets you specify the representation of the physical connectors of your external device ② including the device pin assignment.

F

**FIBEX file** An XML file according the ASAM MCD-2 NET standard (also known as Field Bus Exchange Format) defined by ASAM. The file can describe more than one bus system (e.g., CAN, LIN, FlexRay). It is used for data exchange between different tools that work with message-oriented bus communication.

**Find Results Viewer** A pane that displays the results of searches you performed via the Find command.

**FMU file** A Functional Mock-up Unit 1 file that describes and implements the functionality of a model. It is an archive file with the file name extension FMU. The FMU file contains:

- The functionality defined as a set of C functions provided either in source or in binary form.
- The model description file (modelDescription.xml) with the description of the interface data.
- Additional resources needed for simulation.

You can add an FMU file to the model topology ② just like adding a Simulink model based on an SLX file ③.

**Frame** A piece of information of a bus communication. It contains an arbitrary number of non-overlapping PDUs ② and the data length code (DLC). CAN frames and LIN frames can contain only one PDU. To exchange a frame via bus channels, a frame triggering ③ is needed.

**Frame triggering** An instance of a frame ② that is exchanged via a bus channel. It includes transmission information of the frame (e.g., timings, ID, sender, receiver). The requirements regarding the frame triggerings depend on the bus system (CAN, LIN, FlexRay).

**Function block** A graphical representation in the signal chain that is instantiated from a function block type to A function block provides the I/O functionality and the connection to the real-time hardware. It serves as a container for functions, for electrical interface units that and their logical signals the function block's ports (function ports and/or signal ports to the neighboring blocks in the signal chain.

**Function block type** A software plug-in that provides a specific I/O functionality. Every function block type has unique features which are different from other function block types.

To use a function block type in your ConfigurationDesk application ②, you have to create an instance of it. This instance is called a function block ③. Instances of function block types can be used multiple times in a ConfigurationDesk

application. The types and their instantiated function blocks are displayed in the function library ② of the Function Browser ②.

**Function Browser** A pane that displays the function library 1 in a hierarchical tree structure. Function block types 2 are grouped in function classes. Instantiated function blocks 2 are added below the corresponding function block type.

**Function inport** A function port 1 that inputs the values from the behavior model ② to the function block ③ to be processed by the function.

**Function library** A collection of function block types 1 that allows access to the I/O functionality in ConfigurationDesk. The I/O functionality is based on function block types. The function library provides a structured tree view on the available function block types. It is displayed in the Function Browser 2.

**Function outport** A function port 1 that outputs the value of a function to be used in the behavior model 4.

**Function port** An element of a function block ② that provides the interface to the behavior model 2 via model port blocks 2.

**Functional Mock-up Unit** An archive file that describes and implements the functionality of a model based on the Functional Mock-up Interface (FMI) standard.

G

Global working view The default working view 1 that always contains all signal chain 2 elements.

Н

A hardware element (normally a channel on an I/O Hardware resource board or I/O unit) which is required to execute a function block ②. A hardware resource can be localized unambiguously in a hardware system. Every hardware resource has specific characteristics. A function block therefore needs a hardware resource that matches the requirements of its functionality. This means that not every function block can be executed on every hardware resource. There could be limitations on a function block's features and/or the physical ranges.

**Hardware resource assignment** An action that assigns the electrical interface unit ② of a function block ② to one or more hardware resources ②. Function blocks can be assigned to any hardware resource which is suitable for

ConfigurationDesk Glossary May 2021 the functionality and available in the hardware topology ② of your ConfigurationDesk application ②.

**Hardware Resource Browser** A pane that lets you display and manage all the hardware components of the hardware topology ① that is contained in your active ConfigurationDesk application ② in a hierarchical structure.

Hardware topology A component of a ConfigurationDesk application that contains information on a specific hardware system which can be used with ConfigurationDesk. It provides information on the components of the system, such as channel type and slot numbers. It can be scanned automatically from a registered platform, created in ConfigurationDesk's Hardware Resource Browser from scratch, or imported from an HTFX file.

**HTFX file** A file containing the hardware topology ② after an explicit export. It provides information on the components of the system and also on the channel properties, such as board and channel types ③ and slot numbers.

I/O event An asynchronous event 1 triggered by I/O functions. You can use I/O events to trigger tasks in your application process asynchronously. You can assign the events to the tasks via drag & drop, via the Properties Browser if you have selected a task, or via the Assign Event command from the context menu of the relevant task

**Interface model** A temporary Simulink model that contains blocks from the Model Interface Blockset. ConfigurationDesk initiates the creation of an interface model in Simulink. You can copy the blocks with their identities from the interface model and paste them into an existing Simulink behavior model.

**Interpreter** A pane that lets you run Python scripts and execute line-based commands.

**Inverse model port block** A model port block that has the same configuration (same name, same port groups, and port names) but the inverse data direction as the original model port block from which it was created.

**IOCNET** Abbreviation of I/O carrier network.

A dSPACE proprietary protocol for internal communication in a SCALEXIO system between the real-time processors and I/O units. The IOCNET lets you connect more than 100 I/O nodes and place the parts of your SCALEXIO system long distances apart.

**IPDU** Abbreviation of interaction layer protocol data unit.

A term according to AUTOSAR. An IPDU contains the communication data that is routed from the interaction layer to a lower communication layer and vice

versa. An IPDU can be implemented, for example, as an ISignal IPDU②, multiplexed IPDU②, or container IPDU②.

**ISignal** A term according to AUTOSAR. A signal of the interaction layer that contains communication data as a coded signal value. To transmit the communication data on a bus, ISignals are instantiated and included in ISignal IPDUs (?).

**ISignal IPDU** A term according to AUTOSAR. An IPDU ② whose communication data is arranged in ISignals ③. ISignal IPDUs allow the exchange of ISignals between different network nodes ③.

L

**LDF file** A LIN description file that describes networks of the LIN bus system according to the LIN standard.

**LIN master** A member of a LIN communication cluster ② that is responsible for the timing of LIN bus communication. A LIN master provides one LIN master task and one LIN slave task. The LIN master task transmits frame headers on the bus, and provides LIN schedule tables ③ and LIN collision resolver tables. The LIN slave task transmits frame responses on the bus. A LIN cluster must contain exactly one LIN master.

**LIN schedule table** A table defined for a LIN master 2 that contains the transmission sequence of frame headers on a LIN bus. For each LIN master, several LIN schedule tables can be defined.

**LIN slave** A member of a LIN communication cluster that provides only a LIN slave task. The LIN slave task transmits frame responses on the bus when they are triggered by a frame header. The frame header is sent by a LIN master 3. A LIN cluster can contain several LIN slaves.

**Logical signal** An element of a function block ① that combines all the signal ports ② which belong together to provide the functionality of the signal. Each logical signal causes one or more channel requests ②. Channel requests are available after you have assigned a channel set ② to the logical signal.

**Logical signal chain** A term that describes the logical path of a signal between an external device ② and the behavior model ②. The main elements of the logical signal chain are represented by different graphical blocks (device blocks ②, function blocks ③ and model port blocks ③). Every block has ports to provide the mapping to neighboring blocks.

In the documentation, usually the short form 'signal chain' is used instead.

**MAP file** A file that maps symbolic names to physical addresses.

**Mapping line** A graphical representation of a connection between two ports in the signal chain ②. You can draw mapping lines in a working view ②.

**MCD file** A model communication description file that is used to implement a multimodel application ②. It lets you add several behavior models ② that were separated from an overall model to the model topology ②.

The MCD file contains information on the separated models and information on the connections between them. The file is generated with the Model Separation Setup Block ② in MATLAB/Simulink. The block resides in the Model Interface Blockset (dsmpblib) from dSPACE.

**MDL file** A Simulink model file that contains the behavior model ②. You can add an MDL file to your ConfigurationDesk application ②.

As of MATLAB® R2012a, the file name extension for the Simulink model file has been changed from MDL to SLX by The MathWorks®.

**Message Viewer** A pane that displays a history of all error and warning messages that occur during work with ConfigurationDesk.

**Model analysis** A process that analyzes the model to determine the interface of a behavior model ②. You can select one of the following commands:

- Analyze Simulink Model (Model Interface Only)

  Analyzes the interface of a behavior model. The model topology ② of your active ConfigurationDesk application ③ is updated with the properties of the analyzed behavior model.
- Analyze Simulink Model (Including Task Information)
   Analyzes the model interface (2) and the elements of the behavior model that are relevant for the task configuration. The task configuration in ConfigurationDesk is then updated accordingly.

**Model Browser** A pane that lets you display and access the model topology ② of an active ConfigurationDesk application ③. The Model Browser provides access to all the model port blocks ③ available in the behavior models ② which are linked to a ConfigurationDesk application. The model elements are displayed in a hierarchy, starting with the model roots. Below the model root, all the subsystems containing model port blocks are displayed as well as the associated model port blocks.

**Model communication** The exchange of signal data between the models within a multimodel application ②. To set up model communication, you must use a mapping line ② to connect a data outport (sending model) to a data inport

(receiving model). The best way to set up model communication is using the Model Communication Browser 2.

**Model Communication Browser** A pane that lets you open and browse working views ② like the **Signal Chain Browser** ②, but shows only the Data Outport and Data Inport blocks and the mapping lines ② between them.

Model Communication Package table A pane that lets you create and configure model communication packages which are used for model communication ② in multimodel applications ③.

**Model implementation** An implementation of a behavior model ②. It can consist of source code files, precompiled objects or libraries, variable description files and a description of the model's interface. Specific model implementation types are, for example, model implementation containers ②, such as Functional Mock-up Units ② or Simulink implementation containers ②.

**Model implementation container** A file archive that contains a model implementation ②. Examples are FMUs, SIC files, and VECU files.

**Model interface** An interface that connects ConfigurationDesk with a behavior model ②. This interface is part of the signal chain and is implemented via model port blocks. The model port blocks in ConfigurationDesk can provide the interface to:

- Model port blocks (from the Model Interface Package for Simulink ②) in a Simulink behavior model. In this case, the model interface is also called ConfigurationDesk model interface to distinguish it from the Simulink model interface available in the Simulink behavior model.
- Different types of model implementations based on code container files, e.g.,
   Simulink implementation containers, Functional Mock-up Units, and V-ECU implementations.

**Model Interface Package for Simulink** A dSPACE software product that lets you specify the interface of a behavior model 2 that you can directly use in ConfigurationDesk. You can also create a code container file (SIC file 2) that contains the model code of a Simulink behavior model 2. The SIC file can be used in ConfigurationDesk and VEOS Player 2.

**Model port** An element of a model port block ②. Model ports provide the interface to the function ports ② and to other model ports (in multimodel applications ③).

These are the types of model ports:

- Data inport
- Data outport
- Runnable function port
- Configuration port

**Model port block** A graphical representation of the ConfigurationDesk model interface ② in the signal chain ②. Model port blocks contain model ports that can be mapped to function blocks to provide the data flow between the function blocks in ConfigurationDesk and the behavior model ③. The model ports can also be mapped to the model ports of other model port blocks with

data inports or data outports to set up model communication ②. Model port blocks are available in different types and can provide different port types:

- Data port blocks with data inports ② and data outports ③
- Runnable Function blocks ② with runnable function ports ③
- Configuration Port blocks ② with configuration ports ②. Configuration Port blocks are created during model analysis for each of the following blocks found in the Simulink behavior model:
  - RTICANMM ControllerSetup block
  - RTILINMM ControllerSetup block
  - FLEXRAYCONFIG UPDATE block

Configuration Port blocks are also created for bus simulation containers.

Model Separation Setup Block A block that is contained in the Model Interface Package for Simulink ②. It is used to separate individual models from an overall model in MATLAB/Simulink. Additionally, model separation generates a model communication description file (MCD file ③) that contains information on the separated models and their connections. You can use this MCD file in ConfigurationDesk.

**Model topology** A component of a ConfigurationDesk application ① that contains information on the subsystems and the associated model port blocks of all the behavior models that have been added to a ConfigurationDesk application.

**Model-Function Mapping Browser** A pane that lets you create and update signal chains ② for Simulink behavior models ③. It directly connects them to I/O functionality in ConfigurationDesk.

MTFX file A file containing a model topology ② when explicitly exported. The file contains information on the interface to the behavior model ③, such as the implemented model port blocks ③ including their subsystems and where they are used in the model.

**Multicore real-time application** A real-time application ② that is executed on several cores of one PU③ of the real-time hardware.

**Multimodel application** A real-time application ② that executes several behavior models ③ in parallel on dSPACE real-time hardware (SCALEXIO ② or MicroAutoBox III).

**Multiplexed IPDU** A term according to AUTOSAR. An IPDU that consists of one dynamic part, a selector field, and one optional static part. Multiplexing is used to transport varying ISignal IPDUs via the same bytes of a multiplexed IPDU.

 The dynamic part is one ISignal IPDU that is selected for transmission at run time. Several ISignal IPDUs can be specified as dynamic part alternatives. One of these alternatives is selected for transmission.

- The selector field value indicates which ISignal IPDU is transmitted in the dynamic part during run time. For each selector field value, there is one corresponding ISignal IPDU of the dynamic part alternatives. The selector field value is evaluated by the receiver of the multiplexed IPDU.
- The static part is one ISignal IPDU that is always transmitted.

Multi-PU application Abbreviation of multi-processing-unit application. A multi-PU application is a real-time application that is partitioned into several processing unit applications to Each processing unit application is executed on a separate PU of the real-time hardware. The processing units are connected via IOCNET and can be accessed from the same host PC.

#### Ν

**Navigation bar** An element of ConfigurationDesk's user interface that lets you switch between view sets ②.

**Network node** A term that describes the bus communication of an ECU <sup>②</sup> for only one communication cluster <sup>③</sup>.

## 0

**Offline simulation** A purely PC-based simulation scenario without a connection to a physical system, i.e., neither simulator hardware nor ECU hardware prototypes are needed. Offline simulations are independent from real time and can run on VEOS ②.

**Offline simulation application** An application that runs on VEOS ② to perform offline simulation ③. An offline simulation application can be built with the VEOS Player ③ and the resulting OSA file ② can be downloaded to VEOS.

**OSA file** An offline simulation application ① file that is built with the VEOS Player ② and can be downloaded to VEOS ② to perform offline simulation ②.

# P

**Parent port** A port that you can use to map multiple function ports ② and model ports ③. All child ports with the same name are mapped. ConfigurationDesk enforces the mapping rules and allows only mapping lines ③ which agree with them.

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**PDU** Abbreviation of protocol data unit.

A term according to AUTOSAR. A PDU transports data (e.g., control information or communication data) via one or multiple network layers according to the AUTOSAR layered architecture. Depending on the involved layers and the function of a PDU, various PDU types can be distinguished, e.g., ISignal IPDUs ②, multiplexed IPDUs ②, and NMPDUs.

**Physical signal chain** A term that describes the electrical wiring of external devices ② (ECU and loads) to the I/O boards of the real-time hardware. The physical signal chain includes the external cable harness ②, the pinouts of the connectors and the internal cable harness.

**Pins and External Wiring table** A pane that lets you access the external wiring information

**Platform** A dSPACE real-time hardware system that can be registered and displayed in the Platform Manager 2.

Platform Manager A pane that lets you handle registered hardware platforms ②. You can download, start, and stop real-time applications ③ via the Platform Manager. You can also update the firmware of your SCALEXIO system ② or MicroAutoBox III system.

**Preconfigured application process** An application process ② that was created via the Create preconfigured application process command. If you use the command, ConfigurationDesk creates new tasks ③ for each runnable function ④ provided by the model which is not assigned to a predefined task. ConfigurationDesk assigns the corresponding runnable function and (for periodic tasks) timer events ② to the new tasks. The tasks are preconfigured (e.g., DAQ raster name, period).

**Processing Resource Assignment table** A pane that lets you configure and inspect the processing resources in an executable application ②. This table is useful especially for multi-processing-unit applications ②.

**Processing unit application** A component of an executable application ②. A processing unit application contains one or more application processes ②.

**Project** A container for ConfigurationDesk applications ② and all project-specific documents. You must define a project or open an existing one to work with ConfigurationDesk. Projects are stored in a project root folder ②.

**Project Manager** A pane that provides access to ConfigurationDesk projects ② and applications ② and all the files they contain.

**Project root folder** A folder on your file system to which ConfigurationDesk saves all project-relevant data, such as the applications ② and documents of a project ③. Several projects can use the same project root folder. ConfigurationDesk uses the Documents folder ② as the default project root

folder. You can specify further project root folders. Each can be made the default project root folder.

**Properties Browser** A pane that lets you access the properties of selected elements.

**PU** Abbreviation of processing unit.

A hardware assembly that consists of a motherboard or a dSPACE processor board, possibly additional interface hardware for connecting I/O boards, and an enclosure, i.e., a SCALEXIO Real-Time PC.

R

Real-time application An application that can be executed in real time on dSPACE real-time hardware. The real-time application is the result of a build process ②. It can be downloaded to real-time hardware via an RTA file ③. There are different types of real-time applications:

- Single-core real-time application ②.
- Multicore real-time application <a>\mathcal{L}</a>.
- Multi-PU application ②.

**Restbus simulation** A simulation method to test real ECUs ② by connecting them to a simulator that simulates the other ECUs in the communication clusters ③.

**RTA file** A real-time application ② file. An RTA file is an executable object file for processor boards. It is created during the build process ③. After the build process it can be downloaded to the real-time hardware.

Runnable function A function that is called by a task ② to compute results. A model implementation provides a runnable function for its base rate task. This runnable function can be executed in a task that is triggered by a timer event. In addition, a Simulink behavior model provides a runnable function for each Hardware-Triggered Runnable Function block contained in the Simulink behavior model. This runnable function is suitable for being executed in an asynchronous task.

**Runnable Function block** A type of model port block ②. A Runnable Function block provides a runnable function port ③ that can be mapped to an event port ③ of a function block ④ for modeling an asynchronous task.

**Runnable function port** An element of a Runnable Function block ②. The runnable function port can be mapped to an event port ② of a function block ③ for modeling an asynchronous task.

**RX** Communication data that is received by a bus member.

SCALEXIO system A dSPACE hardware-in-the-loop (HIL) system consisting of one or more real-time industry PCs (PUs ②), I/O boards, and I/O units. They communicate with each other via the IOCNET ②. The system simulates the environment to test an ECU ②. It provides the sensor signals for the ECU, measures the signals of the ECU, and provides the power (battery voltage) for the ECU and a bus interface for restbus simulation ②.

**SDF file** A system description file that contains information on the CPU name(s), the corresponding object file(s) to be downloaded and the corresponding variable description file(s). It is created during the build process.

**Secured IPDU** A term according to AUTOSAR. An IPDU② that secures the payload of another PDU (i.e., authentic IPDU) for secure onboard communication (SecOC). The secured IPDU contains the authentication information that is used to secure the authentic IPDU's payload. If the secured IPDU is configured as a cryptographic IPDU, the secured IPDU and the authentic IPDU are mapped to different frames ②. If the secured IPDU is not configured as a cryptographic IPDU, the authentic IPDU is directly included in the secured IPDU.

**SIC file** A Simulink implementation container ② file that contains the model code of a Simulink behavior model ③. The SIC file can be used in ConfigurationDesk and in VEOS Player.

**Signal chain** A term used in the documentation as a short form for logical signal chain ②. Do not confuse it with the physical signal chain ③.

**Signal Chain Browser** A pane that lets you open and browse working views 2 such as the Global working view 2 or user-defined working views.

**Signal inport** A signal port ② that represents an electrical connection point of a function block ③ which provides signal measurement (= input) functionality.

**Signal outport** A signal port ② that represents an electrical connection point of a function block ② which provides signal generation (= output) functionality.

**Signal port** An element of a function block ② that provides the interface to external devices ③ (e.g., ECUs ②) via device blocks ③. It represents an electrical connection point of a function block.

**Signal reference port** A signal port ② that represents a connection point for the reference potential of inports ②, outports ② and bidirectional ports ③. For example: With differential signals, this is a reference signal, with single-ended signals, it is the ground signal (GND).

**Simulink implementation container** A container that contains the model code of a Simulink behavior model. A Simulink implementation container is generated from a Simulink behavior model by using the Model Interface Package

for Simulink  $\@delta$  . The file name extension of a Simulink implementation container is SIC.

**Simulink model interface** The part of the model interface ② that is available in the connected Simulink behavior model.

**Single-core real-time application** An executable application ② that is executed on only one core of the real-time hardware.

**Single-PU system** Abbreviation of single-processing-unit system.

A system consisting of exactly one PU  ${}^{\circ}$  and the directly connected I/O units and I/O routers.

**SLX file** A Simulink model file that contains the behavior model ②. You can add an SLX file to your ConfigurationDesk application ③.

As of MATLAB® R2012a, the file name extension for the Simulink model file has been changed from MDL to SLX by The MathWorks®.

**Software event** An event that is activated from within a task ② to trigger another subordinate task. Consider the following example: A multi-tasking Simulink behavior model has a base rate task with a sample time = 1 ms and a periodic task with a sample time = 4 ms. In this case, the periodic task is triggered on every fourth execution of the base rate task via a software event. Software events are available in ConfigurationDesk after model analysis ②.

**Source Code Editor** A Python editor that lets you open and edit Python scripts that you open from or create in a ConfigurationDesk project in a window in the working area ②. You cannot run a Python script in a Source Code Editor window. To run a Python script you can use the Run Script command in the Interpreter ② or on the Automation ribbon or the Run context menu command in the Project Manager ②.

**Structured data port** A hierarchically structured port of a Data Inport block or a Data Outport block. Each structured data port consists of more structured and/or unstructured data ports. The structured data ports can consist of signals with different data types (single, double, int8, int16, int32, int64, uint8, uint16, uint32, uint64, Boolean).

**SystemDesk** A dSPACE software product for development of distributed automotive electrics/electronics systems according to the AUTOSAR approach. SystemDesk is able to provide a V-ECU implementation container (as a VECU file ②) to be used in ConfigurationDesk.

Τ

**Table** A type of pane that offers access to a specific subset of elements and properties of the active ConfigurationDesk application ② in rows and columns.

**TargetLink** A dSPACE software product for production code generation. It lets you generate highly efficient C code for microcontrollers in electronic control

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units (ECUs). It also helps you implement control systems that have been modeled graphically in a Simulink/Stateflow diagram on a production ECU. TargetLink is able to provide a V-ECU implementation container (as a VECU file 2) or a Simulink implementation container (SIC file) to be used in ConfigurationDesk.

**Task** A piece of code whose execution is controlled by a real-time operating system (RTOS). A task is usually triggered by an event ②, and executes one or more runnable functions ③. In a ConfigurationDesk application, there are predefined tasks that are provided by executable application components ③. In addition, you can create user-defined tasks that are triggered, for example, by I/O events. Regardless of the type of task, you can configure the tasks by specifying the priority, the DAQ raster name, etc.

**Task Configuration table** A pane that lets you configure the tasks ② of an executable application ②.

**Temporary working view** A working view that can be used for drafting a signal chain segment, like a notepad.

**Timer event** A periodic event with a sample rate and an optional offset.

**Topology** A hierarchy that serves as a repository for creating a signal chain . All the elements of a topology can be used in the signal chain, but not every element needs to be used. You can export each topology from and import it to a ConfigurationDesk application. Therefore a topology can be used in several applications.

A ConfigurationDesk application can contain the following topologies:

- Device topology ②
- Hardware topology
- Model topology ②

**TRC file** A variable description file that contains all variables (signals and parameters) which can be accessed via the experiment software. It is created during the build process ②.

**TX** Communication data that is transmitted by a bus member.

U

**User function** An external function or program that is added to the Automation – User Functions ribbon group for quick and easy access during work with ConfigurationDesk.

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**VECU file** A ZIP file that contains a V-ECU implementation. A VECU file can contain data packages for different platforms. VECU files are exported by TargetLink② or SystemDesk②. You can add a V-ECU implementation based on a VECU file to the model topology③ in the same way as adding a Simulink model based on an SLX file③.

**VEOS** The dSPACE software product for performing offline simulation ②. VEOS is a PC-based simulation platform which allows offline simulation independently from real time.

**VEOS Player** A software running on the host PC for building offline simulation applications ②. Offline simulation applications can be downloaded to VEOS ③ to perform offline simulation ③. ConfigurationDesk lets you generate a bus simulation container ③ (BSC file) via the Bus Manager ④. You can then import the BSC file into the VEOS Player.

**View set** A specific arrangement of some of ConfigurationDesk's panes. You can switch between view sets by using the navigation bar ②. ConfigurationDesk provides preconfigured view sets for specific purposes. You can customize existing view sets and create user-defined view sets.

**VSET file** A file that contains all view sets and their settings from the current ConfigurationDesk installation. A VSET file can be exported and imported via the View Sets page of the Customize dialog.

W

**Working area** The central area of ConfigurationDesk's user interface.

Working view A view of the signal chain ② elements (blocks, ports, mappings, etc.) used in the active ConfigurationDesk application ③. A working view can be opened in the Signal Chain Browser ② or the Model Communication Browser ③. ConfigurationDesk provides two default working views: The Global working view ④ and the Temporary working view ④. In the Working View Manager ②, you can also create user-defined working views that let you focus on specific signal chain segments according to your requirements.

**Working View Manager** A pane that lets you manage the working views ② of the active ConfigurationDesk application③. You can use the Working View Manager for creating, renaming, and deleting working views, and also to open a working view in the Signal Chain Browser④ or the Model Communication Browser④.

**XLSX file** A Microsoft Excel<sup>™</sup> file format that is used for the following purposes:

- Creating or configuring a device topology ② outside of ConfigurationDesk.
- Exporting the wiring information for the external cable harness ②.
- Exporting the configuration data of the currently active ConfigurationDesk application ② for documentation purposes.

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