

The Role of Variability in Learning Generalization: A Computational Modeling Approach

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Learning Generalization

- ▶ Learning is often specific
- ▶ Longstanding scientific interest in how to improve generalization or transfer

Variability

- ▶ Variation during training linked to improved transfer in numerous domains
- ▶ What does “variability mean in the context of learning interventions?”

Types of Variability

- ▶ The number of unique items/problems experienced
- ▶ How spread out examples are

My Dissertation Focus

- ▶ Number of unique examples
- ▶ Visuomotor skill learning and function learning
- ▶ Addressing methodological shortcomings of previous work
- ▶ Adapting cognitive models from other domains to account for results

Common Experimental Manipulations

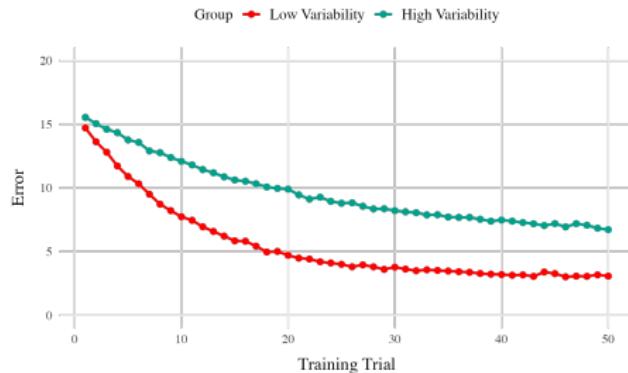
- ▶ Varied vs. Constant

Common Empirical Patterns

Training

- ▶ Both training conditions complete the same number of training trials.
- ▶ Varied group has worse training performance.

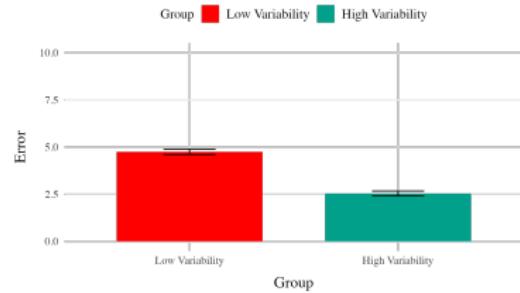
Learning Curves for Low and High Variability Training



Testing

- ▶ Tested from novel conditions.
- ▶ Varied group has better test performance

Testing Performance for Low and High Variability Training



But also plenty of contradictory results and complications

- ▶ Cases where varied training doesn't benefit generalization
- ▶ Cases where more training variation results in worse outcomes
- ▶ Cases where the influence of variation interacts with some other factor
 - ▶ difficulty
 - ▶ prior knowledge
 - ▶ Frequency effects, or amount of training/learning before testing

Theoretical Frameworks

- ▶ Schema Theory (Schmidt, 1975)
- ▶ Desirable Difficulties Framework (Bjork & Bjork, 2011)
- ▶ Challenge Point Framework (Guadagnoli & Lee, 2004)

Schmidt (1975) Bjork & Bjork (2011) Guadagnoli & Lee (2004)

Overview of Current Work

Project 1^[^1]

- ▶ Visuomotor projectile launching task
- ▶ two experiments
- ▶ Beneficial effect of variability
- ▶ Instance-based similarity model

Project 2

- ▶ Visuomotor extrapolation task
 - ▶ Three experiments
 - ▶ Effect of variability is null or negative
 - ▶ Connectionist model (ALM) and hybrid associative & rule model (EXAM)
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Project 1 - Issues with previous research

- ▶ Assumptions about what is encoded
- ▶ Assumptions about the formation of abstractions
- ▶ Aggregation issues and similarity confounds

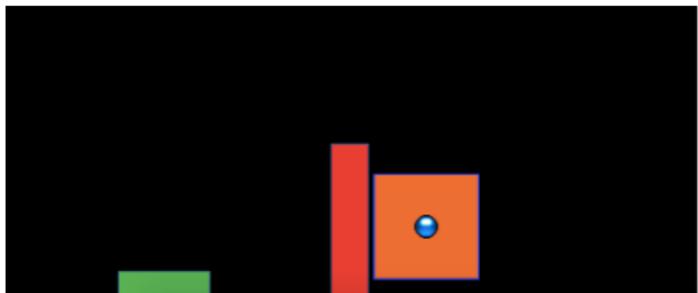
designs that seemingly overcome these issues

- ▶ Kerr & Booth 1978

Experiment 1

- ▶ Conceptual replication of Kerr & Booth design
- ▶ Testing classic pattern as well

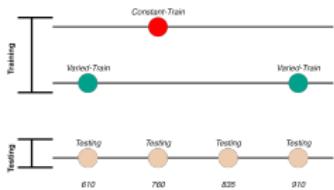
Hit The Target Task



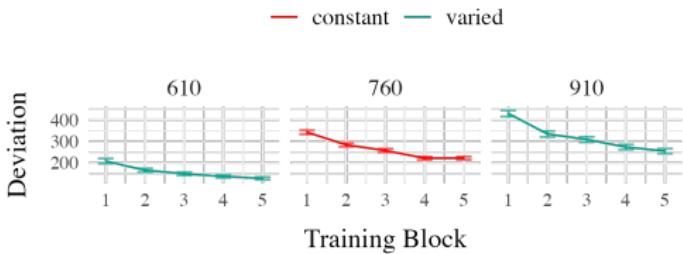
- ▶ **Training Stage** - 200 training trials with feedback. Constant groups trains from single position.
Varied group practices from two positions.
- ▶ **Transfer Stage** - All subjects tested from both positions they were trained, and the positions trained by other group
- ▶ **Data recorded** - For every throw, recorded the X velocity and Y velocity of ball at release

Project 1 - Experiment 1 Results

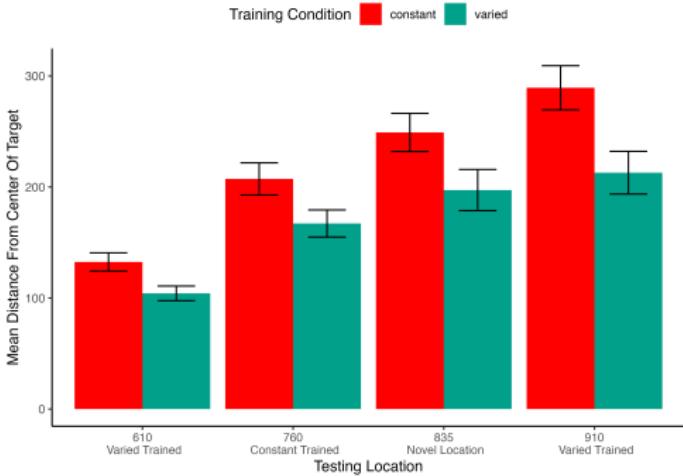
Experiment 1



Training



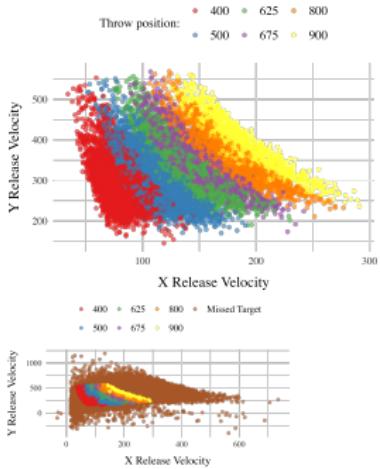
Testing



Project 1 - Discussion

- ▶ Varied training group's superior performance
- ▶ Computational modeling results with IGAS
- ▶ Theoretical implications

Project 1 Computational Model



Model Steps

- ▶ each of the 6 positions has an empirical solution space
- ▶ Compute the summed similarity between training throws, and solution spaces
 - ▶ separately for each participant, and each of the testing positions
- ▶ We now have a measure of how similar training behavior was to testing solutions

Model Definition

- ▶ $d_{i,j} = \sqrt{(x_{Train_i} - x_{Solution_j})^2 + (y_{Train_i} - y_{Solution_j})^2}$
- ▶ $Similarity_{T, I} =$

Project 2 - Variability and Extrapolation in a Function Learning Task

- ▶ Influence of varied practice in a function learning task
- ▶ Experiments 1, 2, and 3:
 - ▶ Training regimes and testing conditions
 - ▶ Learning, discrimination, and extrapolation performance metrics

Project 2 - Questions and Goals

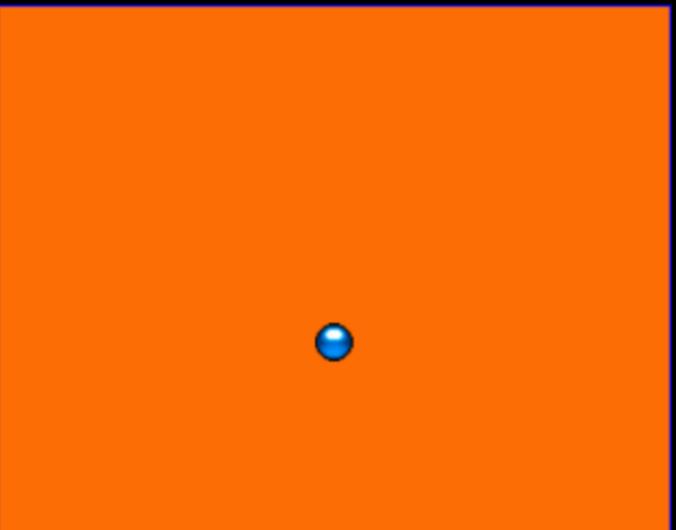
Empirical - Design a task-space large enough to assess multiple degrees of extrapolation - Compare varied and constant generalization from several distinct distances from their nearest training condition

Model-based - If variation does influence extrapolation, can an associative learning model with similarity-based activation provide a good account? - Can our modelling framework simultaneously account for both training and testing data? - Accounting for the full distribution of responses

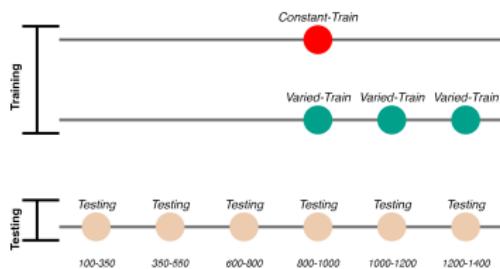
Hit The Wall Task

Hit the wall at a force between 800-1000 units

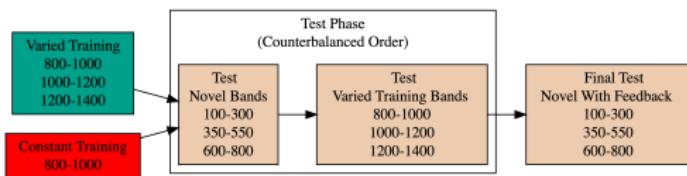
Trial: 1 / 207



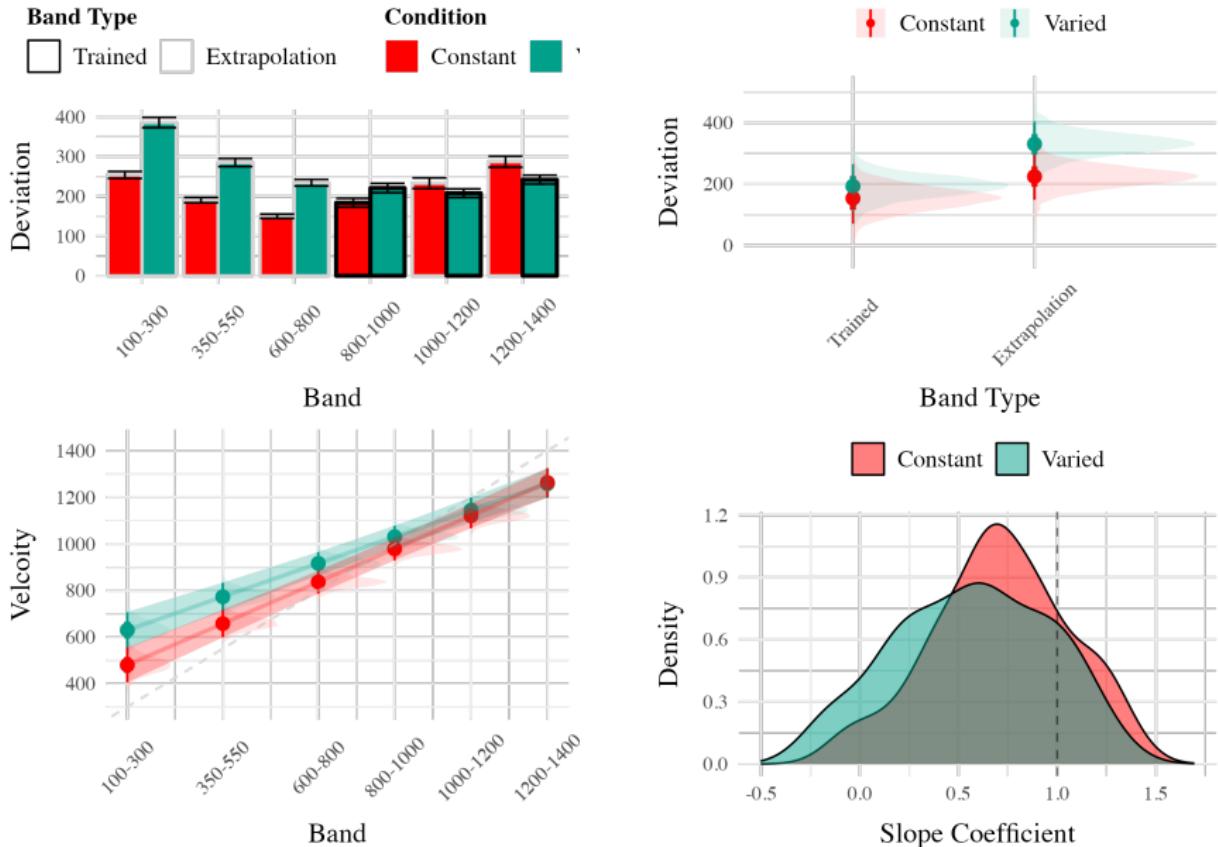
Project 2 - Experiment 1 Design



- ▶ 156 participants included in final analysis
- ▶ Varied group trains from 3 “velocity bands”, constant group from 1



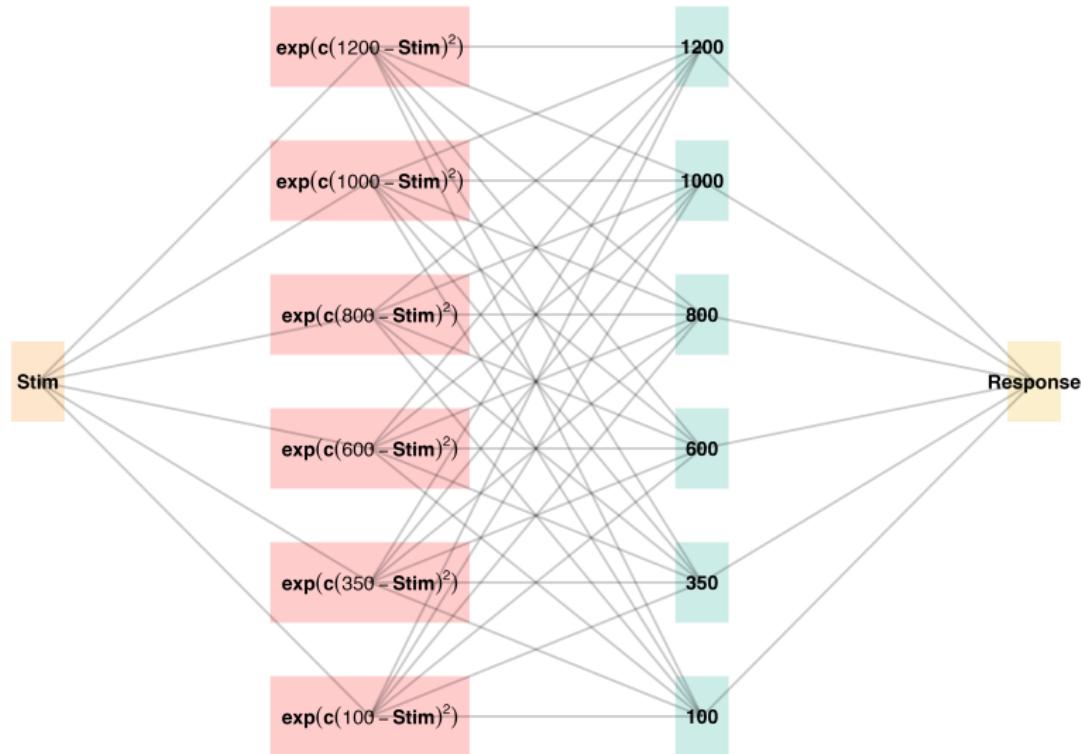
Project 2 - Experiment 1 Results



Project 2 - Experiment 2 Design

Project 2 - Computational Modeling

Project 2 - ALM



ALM Response Generation

Input Activation

$$a_i(X) = \frac{e^{-c(X-X_i)^2}}{\sum_{k=1}^M e^{-c(X-X_k)^2}}$$

Input nodes activate as a function of Gaussian similarity to stimulus

Output Activation

$$O_j(X) = \sum_{k=1}^M w_{ji} \cdot a_i(X)$$

Output unit O_j activation is the weighted sum of input activations and association weights

Output Probability

$$P[Y_j|X] = \frac{O_j(X)}{\sum_{k=1}^M O_k(X)}$$

The response, Y_j probabilities computed via Luce's choice rule

Mean Output

$$m(X) = \sum_{j=1}^L Y_j \cdot \frac{O_j(x)}{\sum_{k=1}^M O_k(X)}$$

Weighted average of probabilities

EXAM

EXAM Response Generation

Instance $P[X_i|X] = \frac{a_i(X)}{\sum_{k=1}^M a_k(X)}$

Re-
trieval

Slope $S = \frac{m(X_1) - m(X_2)}{X_1 - X_2}$

Com-
pu-
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tion

Response $E[Y|X_i] =$
 $m(X_i) + S \cdot [X - X_i]$

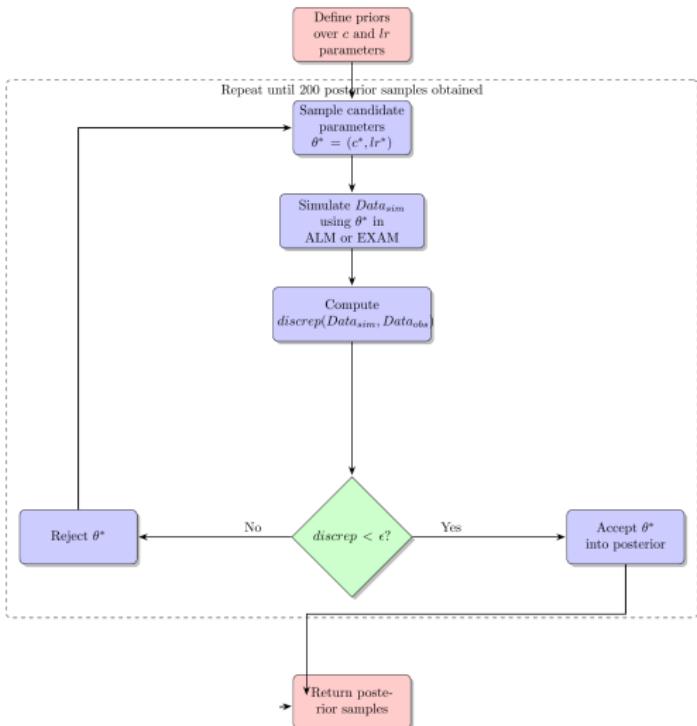
Novel test stimulus X
activates input nodes X_i

Slope value, S computed
from nearest training
instances

Final EXAM response is the
ALM response for the
nearest training stimulus,
 $m(X_i)$, adjusted by local
slope S .

Project 2 - Model Fitting Procedure

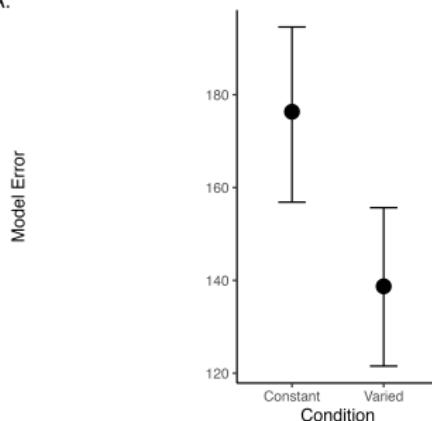
Approximate Bayesian Computation



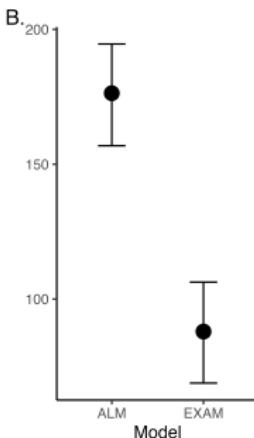
- ▶ simulation based approach
- ▶ approximate likelihood
- ▶ uncertainty in parameter values
- ▶ full distribution of plausible model predictions for each participant

Modelling Results

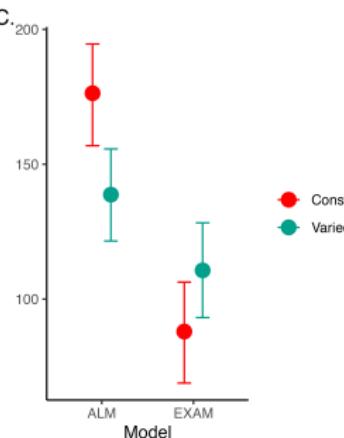
A.



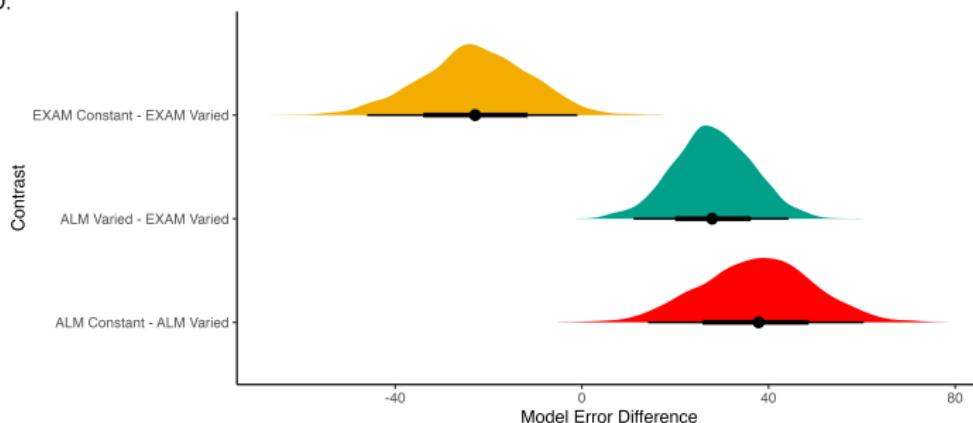
B.



C.



D.



General Discussion

- ▶ Compare HTT and HTW
- ▶ Empirical findings summary
- ▶ Computational modeling contributions

Comparison

Dimension	HTT (Project 1)	HTW (Project 2)
Task Description	Projectile launching to hit a target	Projectile launching to hit wall at a specific velocity
Task Complexity	More complex parabolic trajectory, both x and y velocities relevant to outcome	Simpler 1D mapping of force to outcome. Only x velocity is relevant.
Task Space	More complex: xy velocity combinations closer to the solution space may still result in worse feedback due to striking the barrier.	Simpler: smooth, linear mapping between velocity and feedback.
Perceptual salience of Varied Conditions	Varied conditions (# of throwing distances) are perceptually distinct, i.e. salient differences in distance between	Varied conditions (# of velocity bands) are less salient - only difference is the numeral displayed on

Conclusion

References

- Bjork, E. L., & Bjork, R. A. (2011). Making things hard on yourself, but in a good way: Creating desirable difficulties to enhance learning. *Psychology and the Real World: Essays Illustrating Fundamental Contributions to Society*, 2, 59–68.
- Guadagnoli, M. A., & Lee, T. D. (2004). Challenge Point: A Framework for Conceptualizing the Effects of Various Practice Conditions in Motor Learning. *Journal of Motor Behavior*, 36(2), 212–224. <https://doi.org/10.3200/JMBR.36.2.212-224>
- Schmidt, R. A. (1975). A schema theory of discrete motor skill learning. *Psychological Review*, 82(4), 225–260. <https://doi.org/10.1037/h0076770>