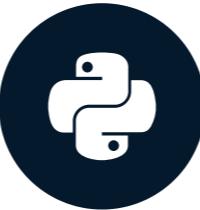


# Image restoration

## IMAGE PROCESSING IN PYTHON



**Rebeca Gonzalez**  
Data Engineer

# Restore an image

Image to restore



Image restored



# Image reconstruction

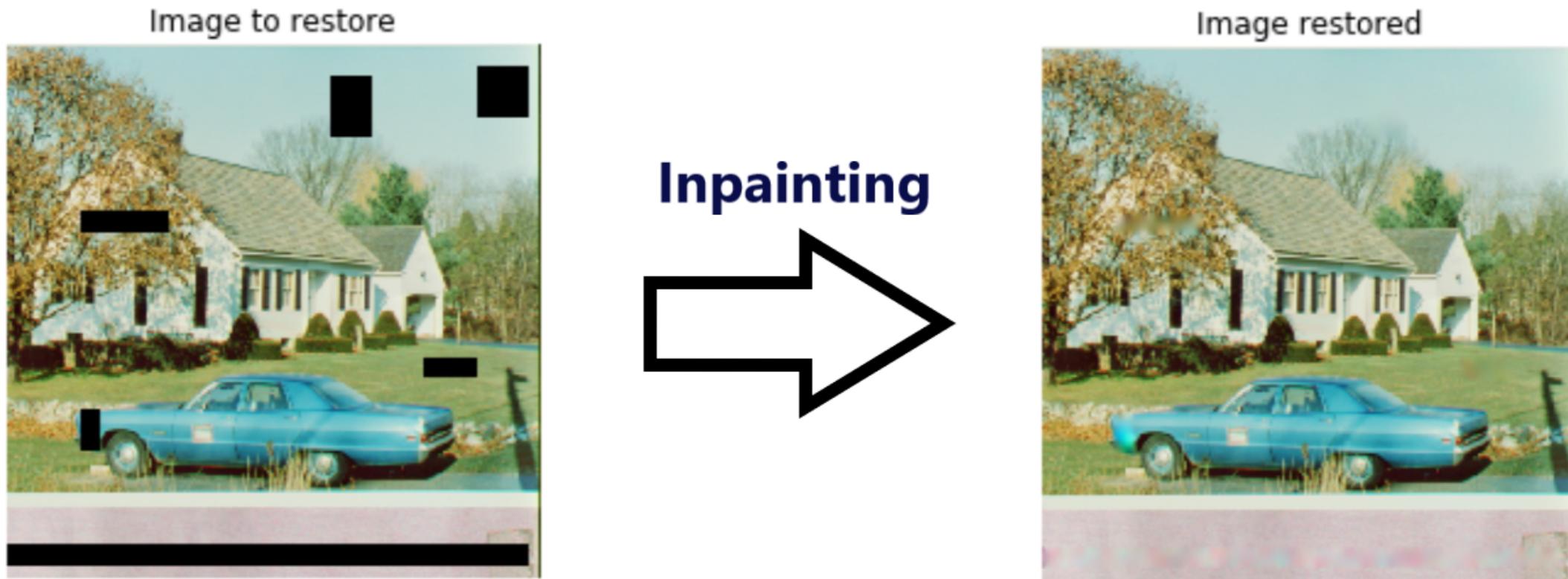
- Fixing damaged images
- Text removing
- Logo removing
- Object removing



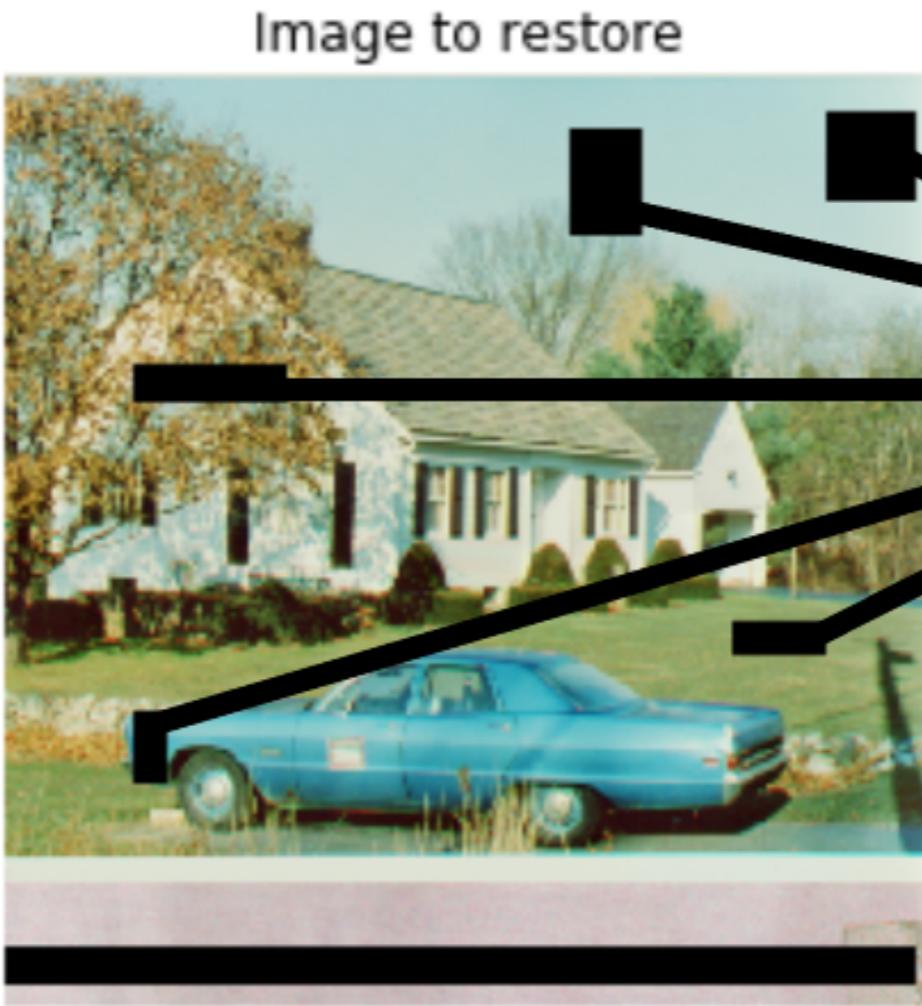
# Image reconstruction

## Inpainting

- Reconstructing lost parts of images
- Looking at the non-damaged regions



# Image reconstruction



**Damaged pixels**



**Set as a mask**

# Image reconstruction in scikit-image

```
from skimage.restoration import inpaint

# Obtain the mask
mask = get_mask(defect_image)

# Apply inpainting to the damaged image using the mask
restored_image = inpaint.inpaint_biharmonic(defect_image,
                                             mask,
                                             multichannel=True)

# Show the resulting image
show_image(restored_image)
```

# Image reconstruction in scikit-image

```
# Show the defect and resulting images  
show_image(defect_image, 'Image to restore')  
show_image(restored_image, 'Image restored')
```

Image to restore



Image restored



# Masks

Image to restore



Mask



# Masks

```
def get_mask(image):
    ''' Creates mask with three defect regions '''
    mask = np.zeros(image.shape[:-1])

    mask[101:106, 0:240] = 1

    mask[152:154, 0:60] = 1
    mask[153:155, 60:100] = 1
    mask[154:156, 100:120] = 1
    mask[155:156, 120:140] = 1

    mask[212:217, 0:150] = 1
    mask[217:222, 150:256] = 1

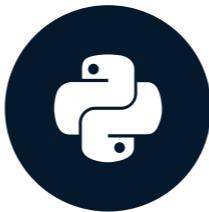
    return mask
```

# **Let's practice!**

## **IMAGE PROCESSING IN PYTHON**

# Noise

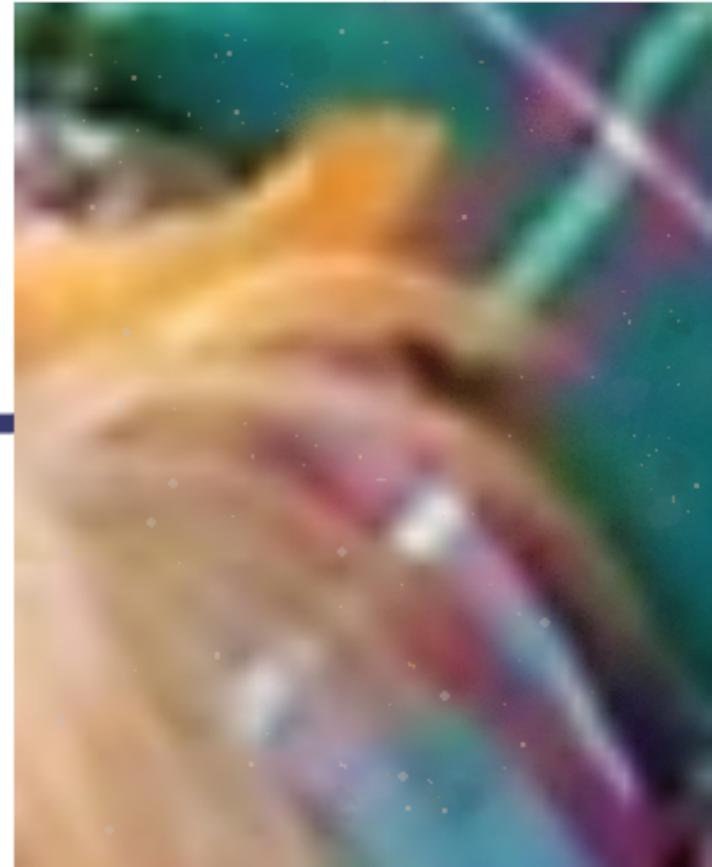
IMAGE PROCESSING IN PYTHON



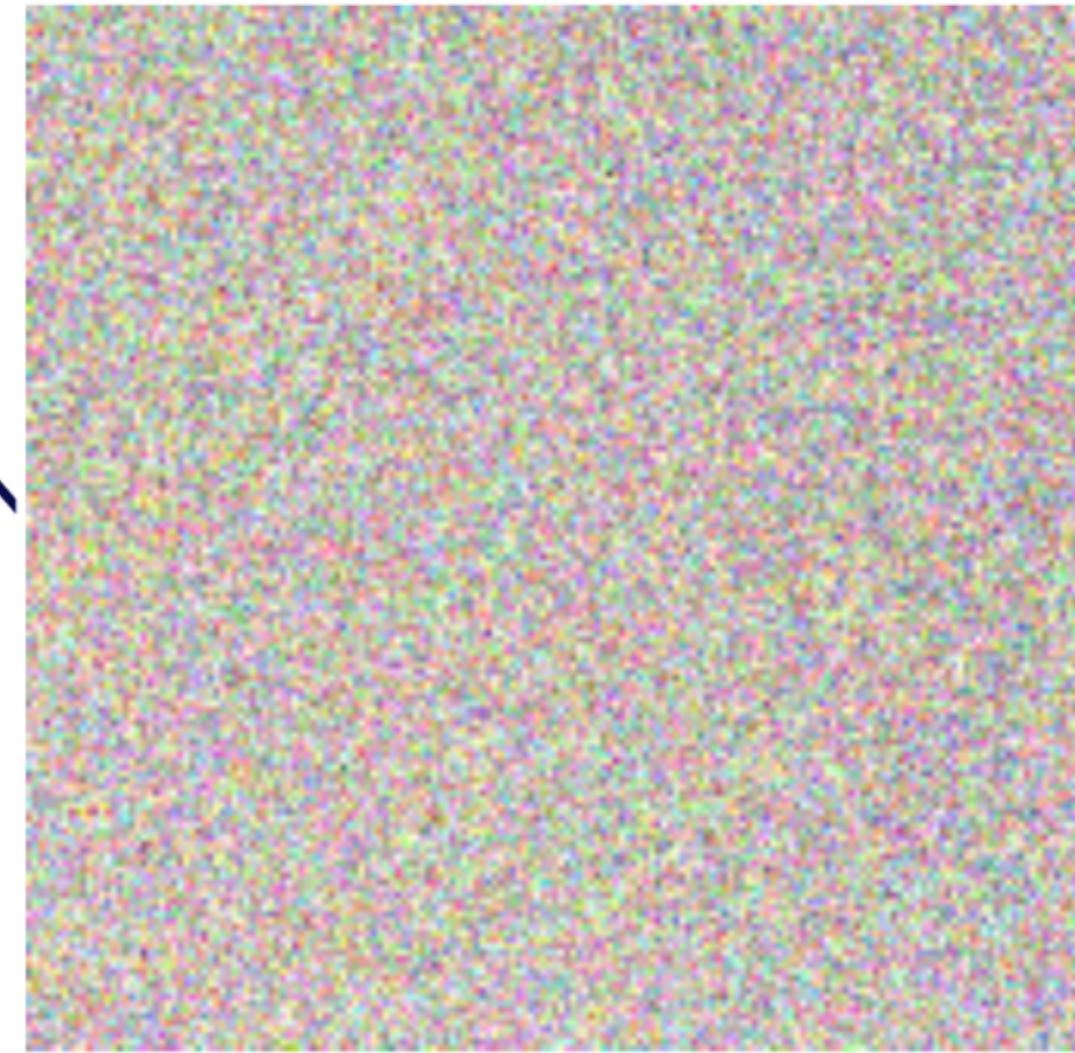
**Rebeca Gonzalez**

Data Engineer

# Noise



# Noise



# Apply noise in scikit-image

```
# Import the module and function
from skimage.util import random_noise

# Add noise to the image
noisy_image = random_noise(dog_image)

# Show original and resulting image
show_image(dog_image)
show_image(noisy_image, 'Noisy image')
```

# Apply noise in scikit-image

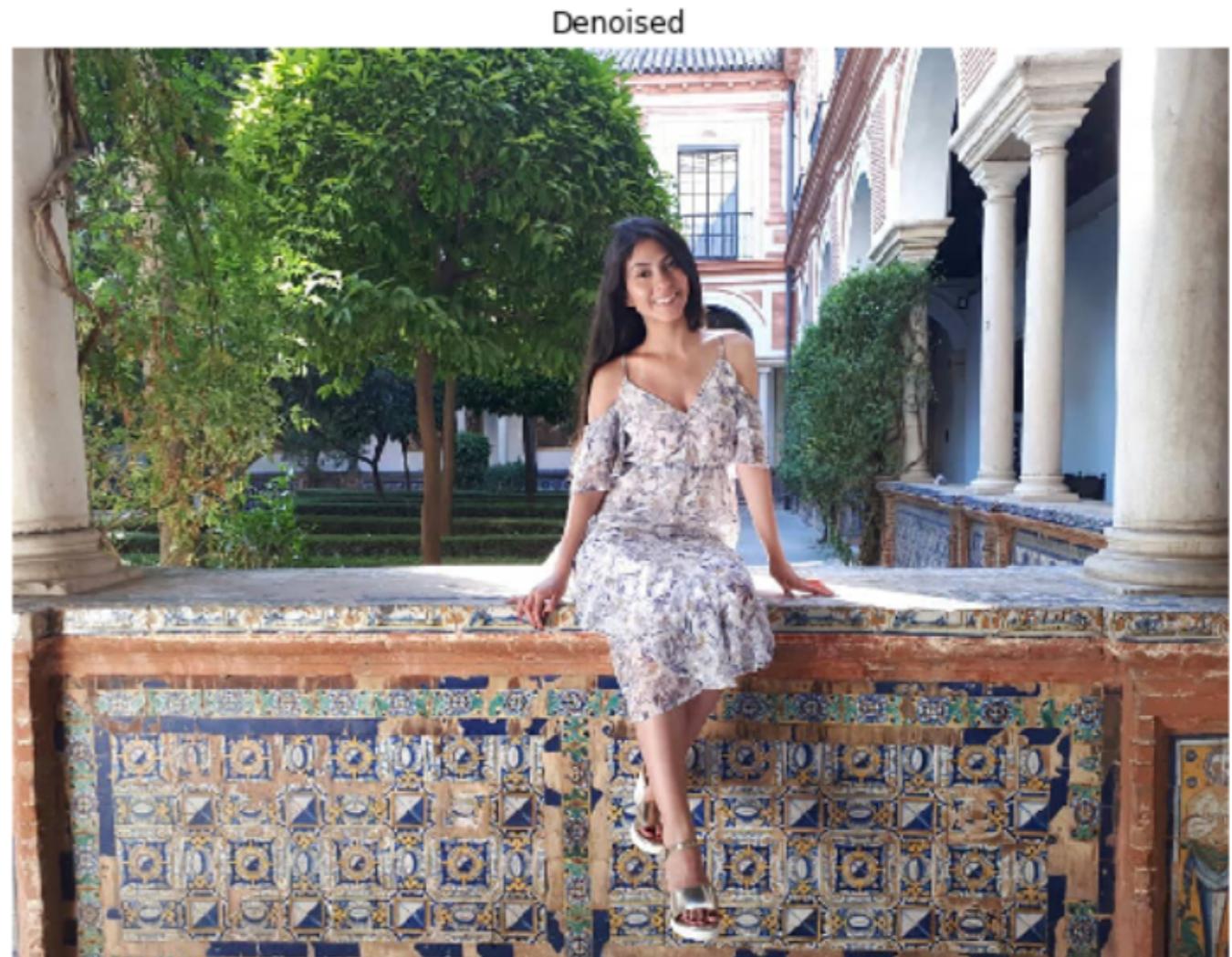
Original



Noisy image

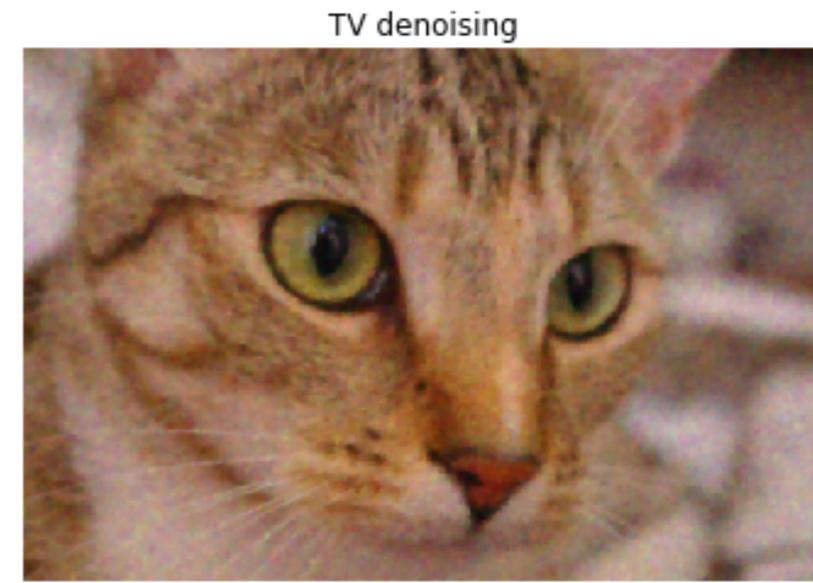


# Reducing noise



# Denoising types

- Total variation (TV)
- Bilateral
- Wavelet denoising
- Non-local means denoising



# Denoising

## Using total variation filter denoising

```
from skimage.restoration import denoise_tv_chambolle

# Apply total variation filter denoising
denoised_image = denoise_tv_chambolle(noisy_image,
                                         weight=0.1,
                                         multichannel=True)

# Show denoised image
show_image(noisy_image, 'Noisy image')
show_image(denoised_image, 'Denoised image')
```

# Denoising

## Total variation filter

Noisy image



Denoised image



# Denoising

## Bilateral filter

```
from skimage.restoration import denoise_bilateral

# Apply bilateral filter denoising
denoised_image = denoise_bilateral(noisy_image, multichannel=True)

# Show original and resulting images
show_image(noisy_image, 'Noisy image')
show_image(denoised_image, 'Denoised image')
```

# Denoising

## Bilateral filter

Noisy image



Denoised image



# **Let's practice!**

## **IMAGE PROCESSING IN PYTHON**

# Superpixels & segmentation

IMAGE PROCESSING IN PYTHON



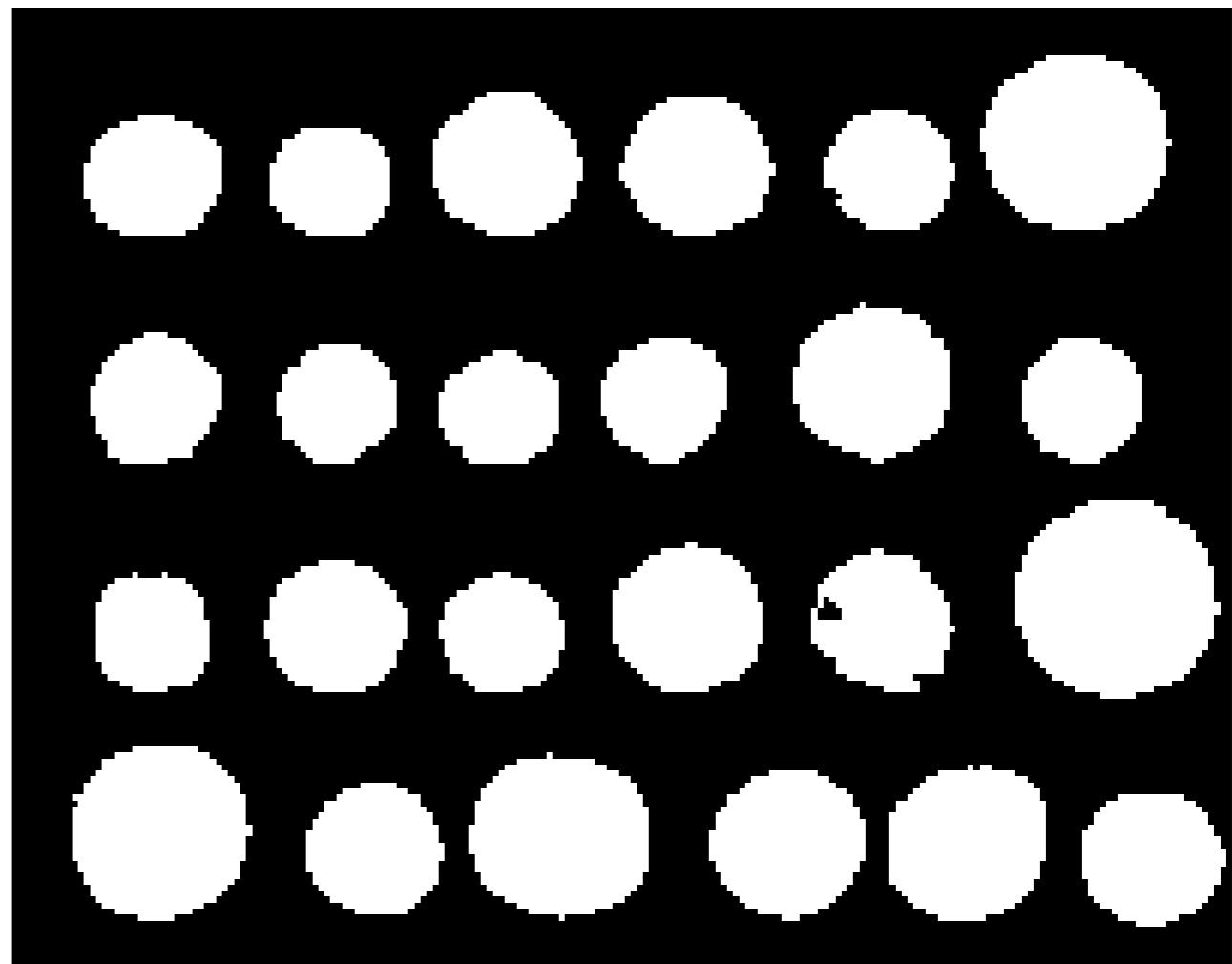
**Rebeca Gonzalez**  
Data Engineer

# Segmentation

Original

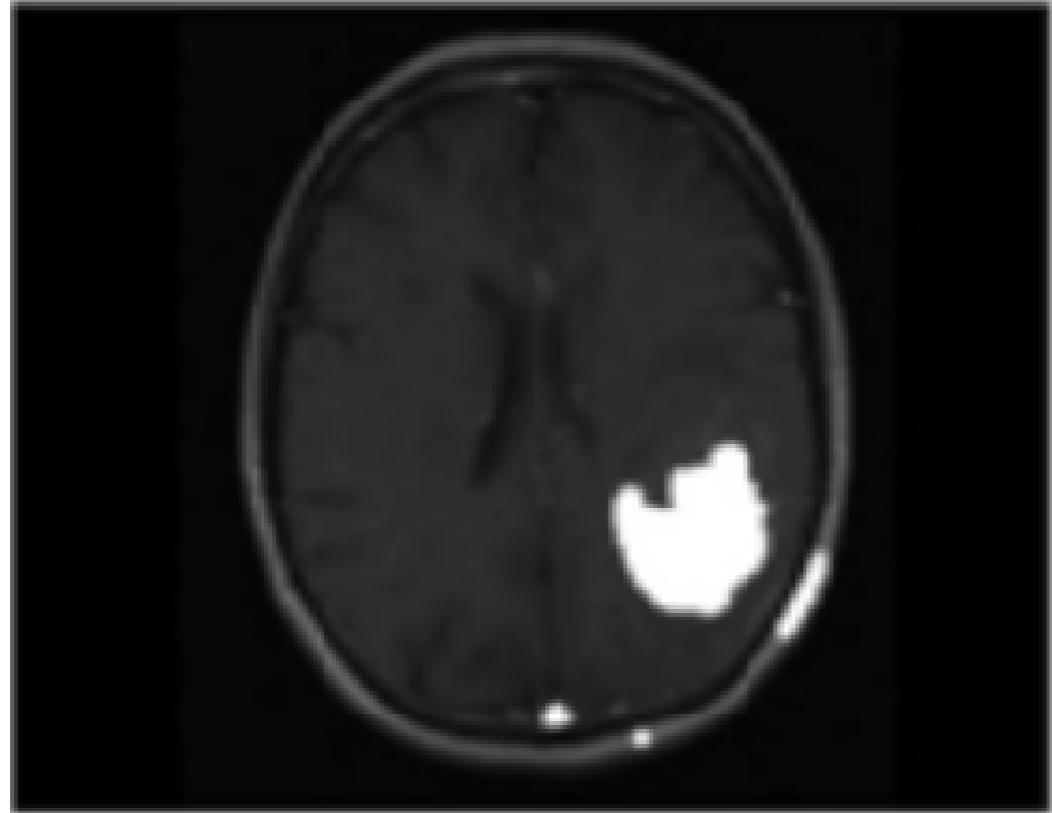


Segmented image



# Segmentation

Segmented



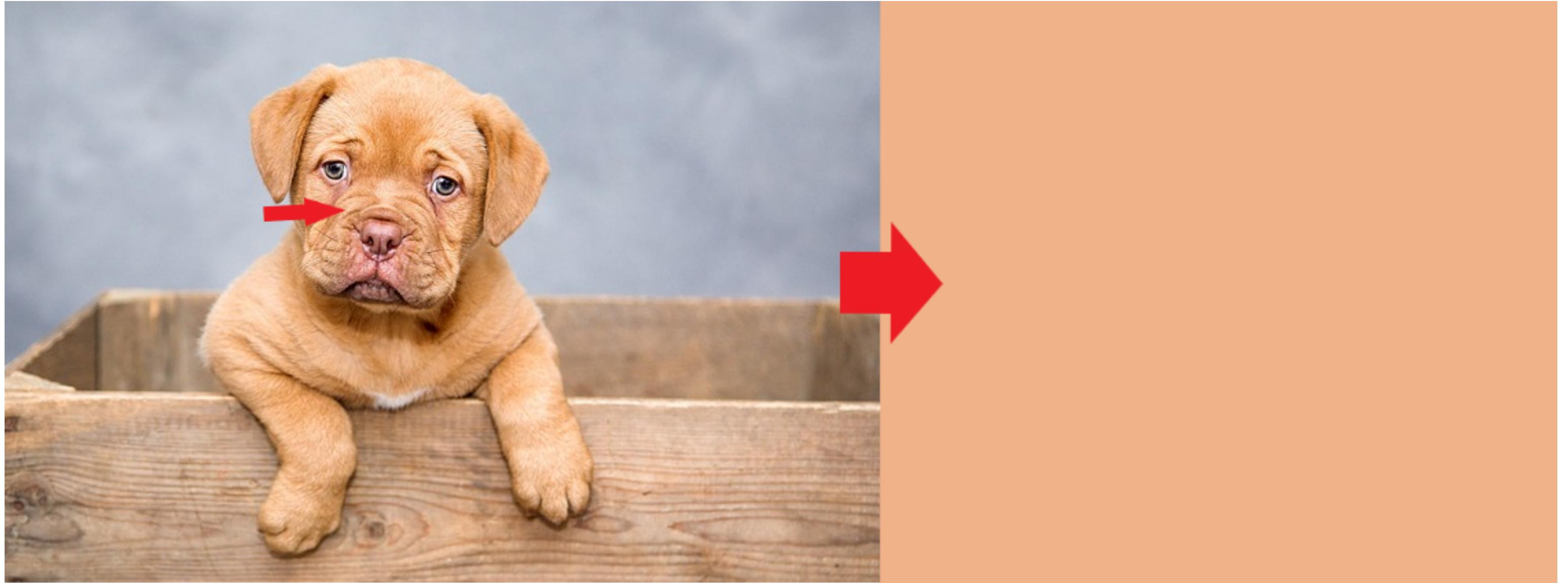
Original



Segmented

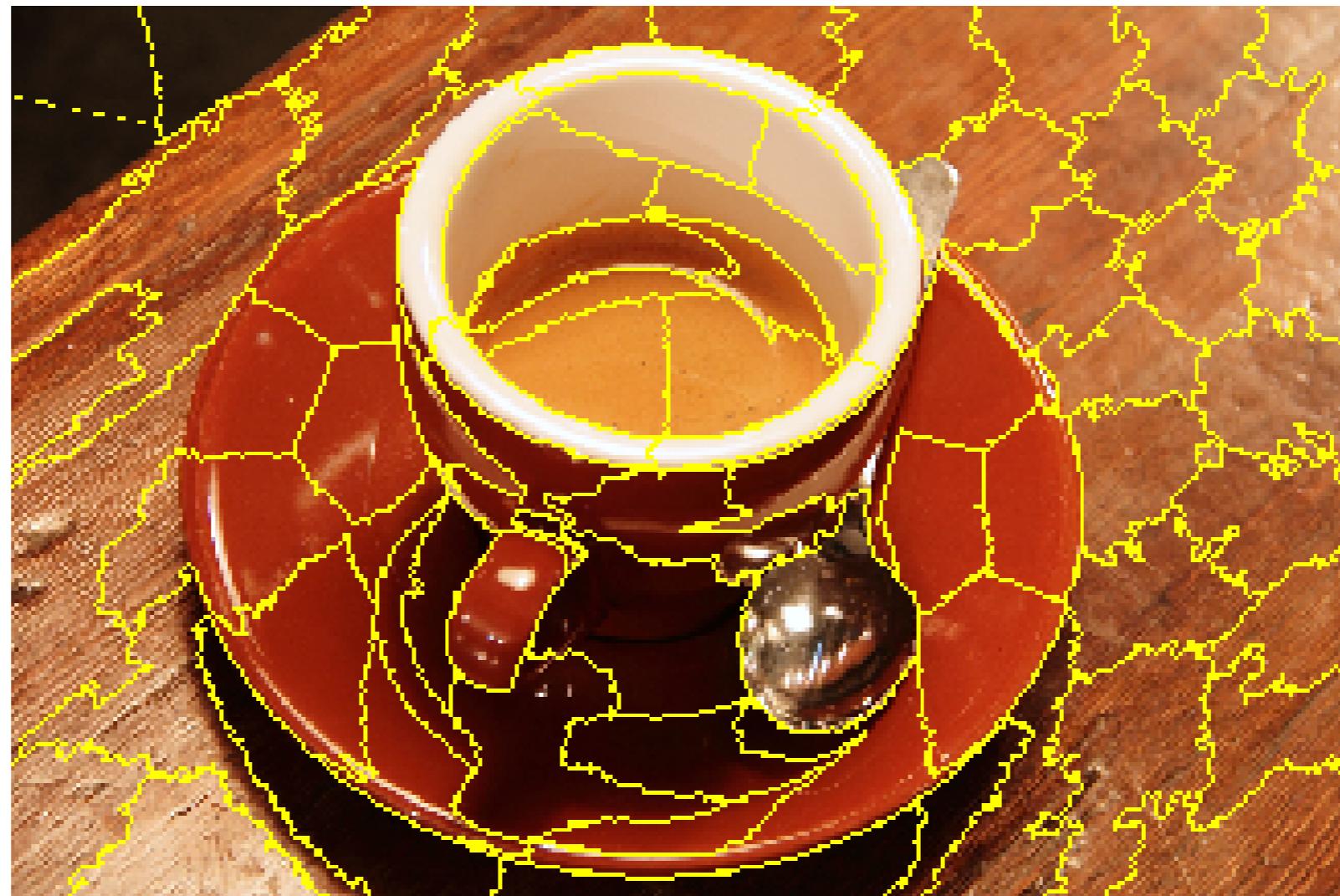


# Image representation



# Superpixels

Superpixel segmentation, 100 segments



# Benefits of superpixels

- More meaningful regions
- Computational efficiency

# Segmentation

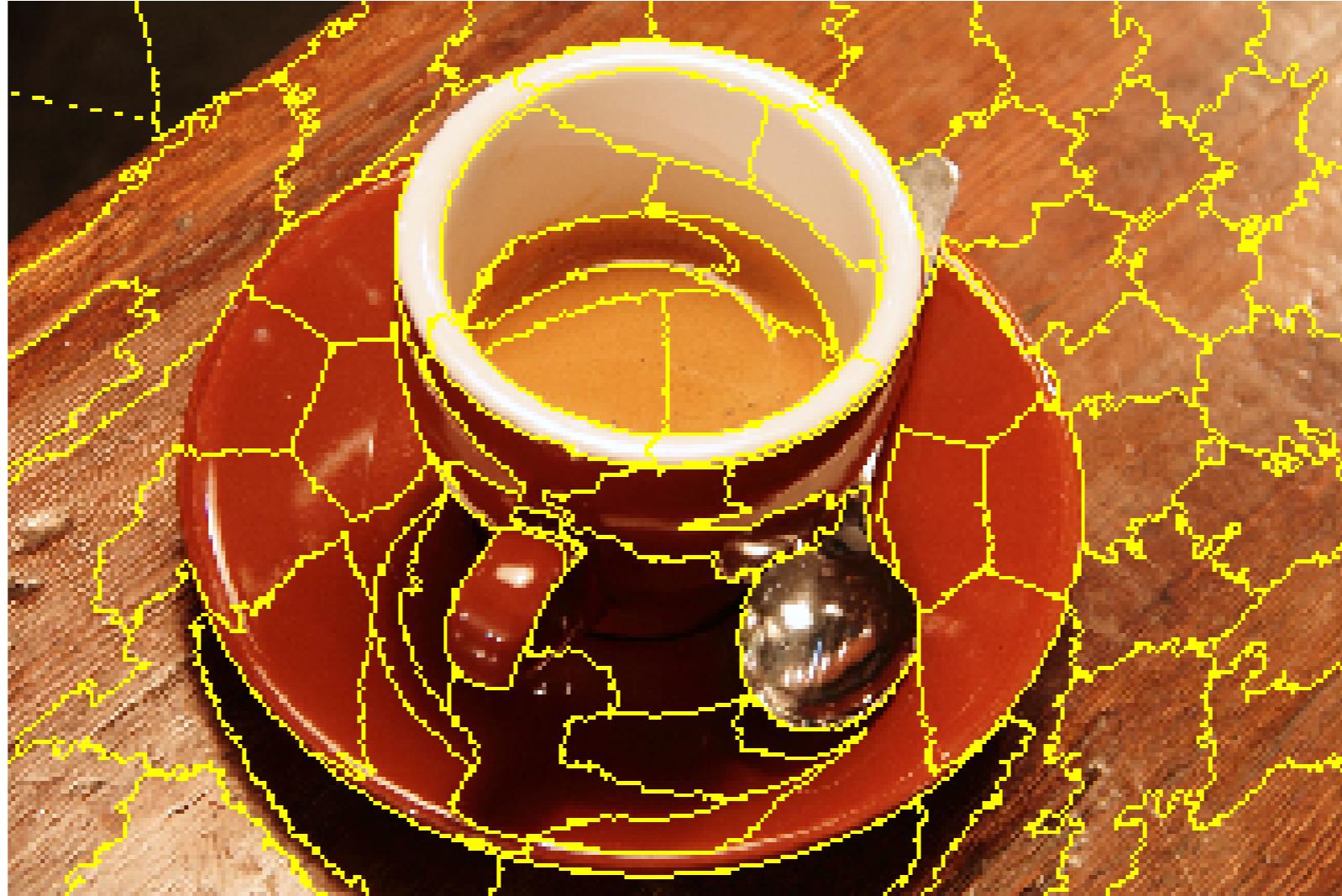
- Supervised
- Unsupervised



# Unsupervised segmentation

## Simple Linear Iterative Clustering (SLIC)

Superpixel segmentation, 100 segments



# Unsupervised segmentation (SLIC)

```
# Import the modules
from skimage.segmentation import slic
from skimage.color import label2rgb

# Obtain the segments
segments = slic(image)

# Put segments on top of original image to compare
segmented_image = label2rgb(segments, image, kind='avg')

show_image(image)
show_image(segmented_image, "Segmented image")
```

# Unsupervised segmentation (SLIC)

Original



Segmented image



# More segments

```
# Import the modules
from skimage.segmentation import slic
from skimage.color import label2rgb

# Obtain the segmentation with 300 regions
segments = slic(image, n_segments= 300)

# Put segments on top of original image to compare
segmented_image = label2rgb(segments, image, kind='avg')

show_image(segmented_image)
```

# More segments

Original



Segmented image



# **Let's practice!**

## **IMAGE PROCESSING IN PYTHON**

# Finding contours

IMAGE PROCESSING IN PYTHON



Rebeca Gonzalez

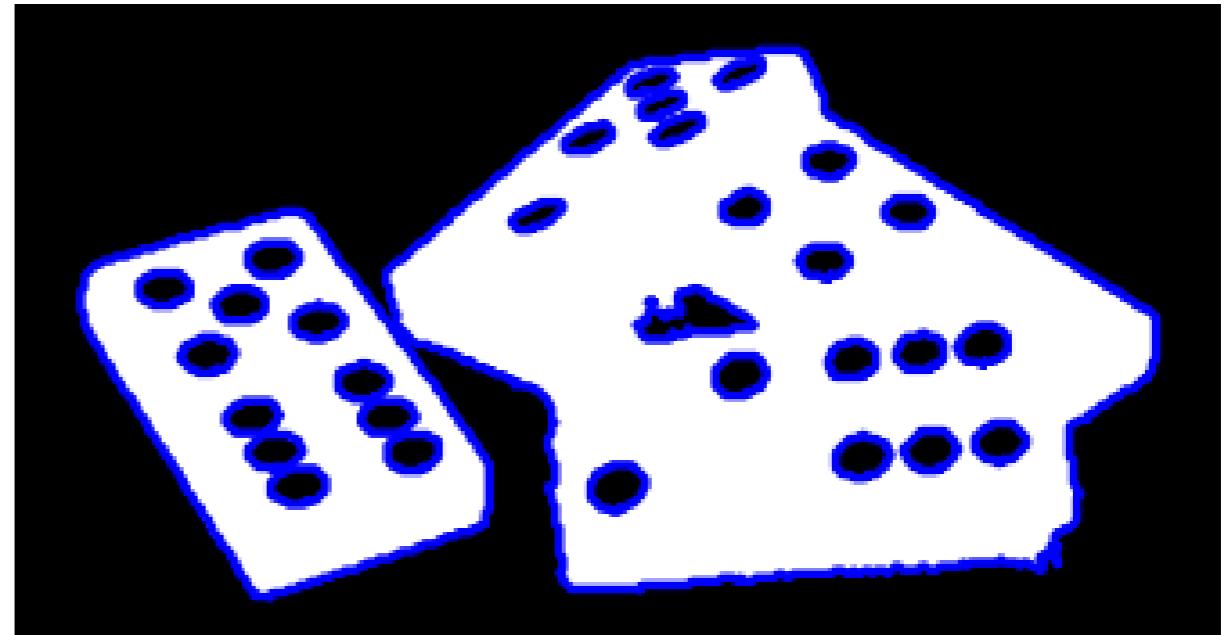
Data Engineer

# Finding contours

Original image



Contours

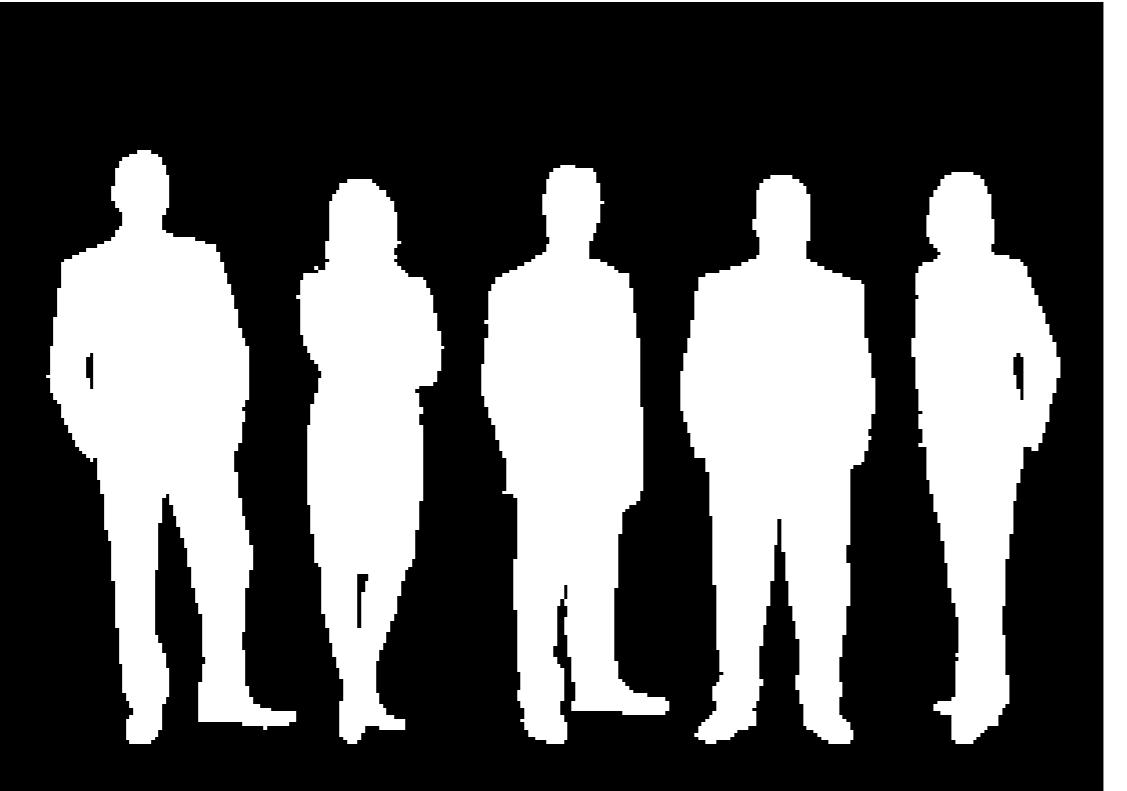


- Measure size
- Classify shapes
- Determine the number of objects

Total points in domino tokens: 29.

# Binary images

Thresholded Image



Contours



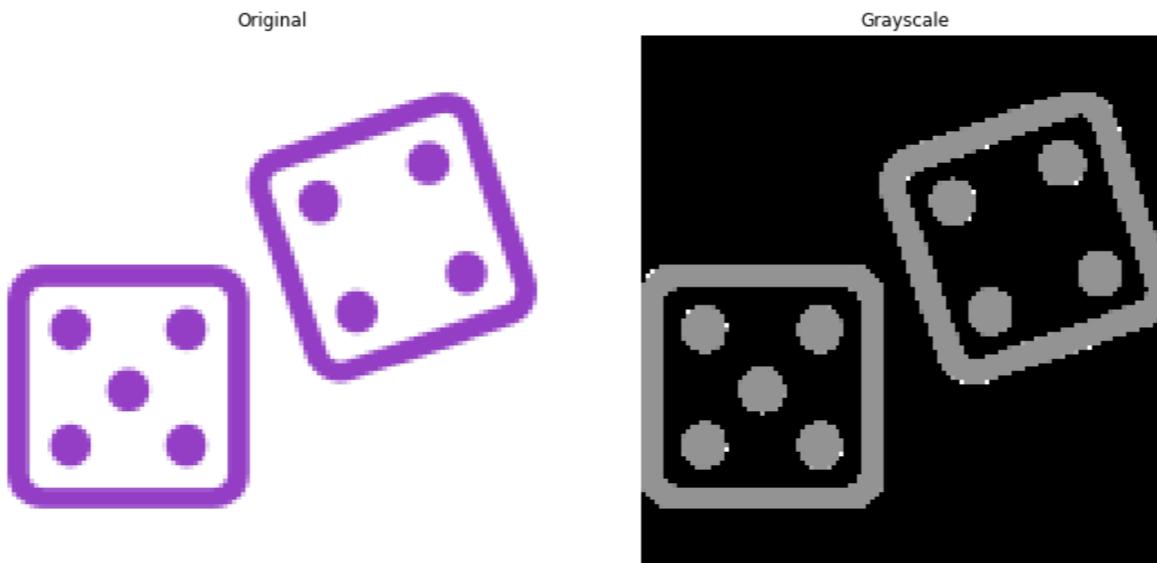
We can obtain a binary image applying  
**thresholding** or using **edge detection**

# Find contours using scikit-image

## PREPARING THE IMAGE

Transform the image to 2D grayscale.

```
# Make the image grayscale  
image = color.rgb2gray(image)
```



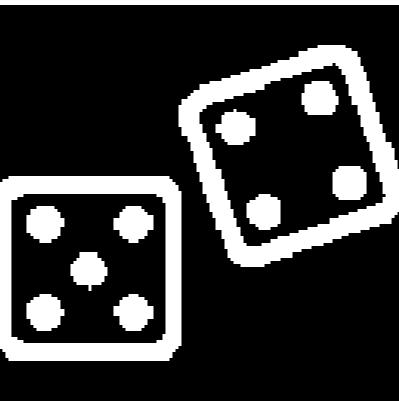
# Find contours using scikit-image

## PREPARING THE IMAGE

Binarize the image

```
# Obtain the thresh value  
thresh = threshold_otsu(image)  
  
# Apply thresholding  
thresholded_image = image > thresh
```

Thresholded



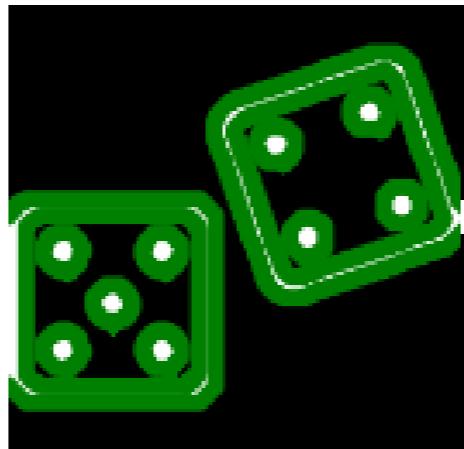
# Find contours using scikit-image

And then use `findContours()`.

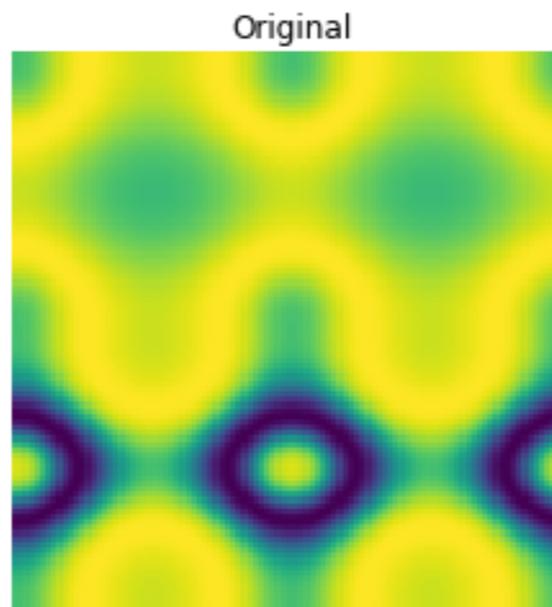
```
# Import the measure module
from skimage import measure

# Find contours at a constant value of 0.8
contours = measure.find_contours(thresholded_image, 0.8)
```

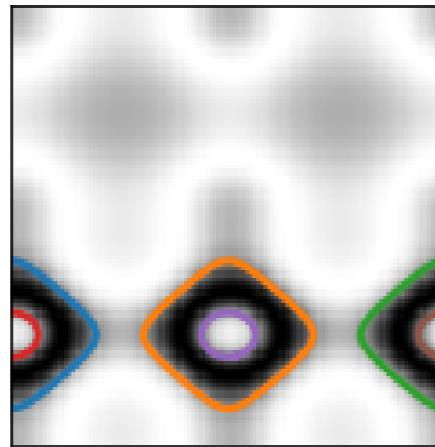
Contours



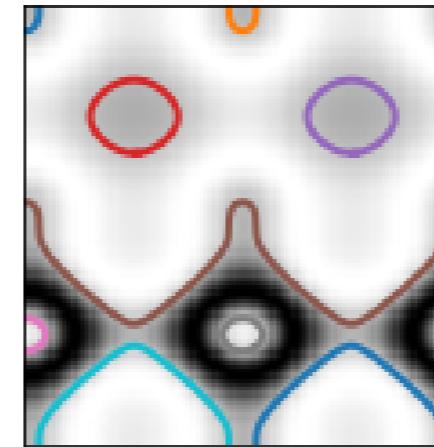
# Constant level value



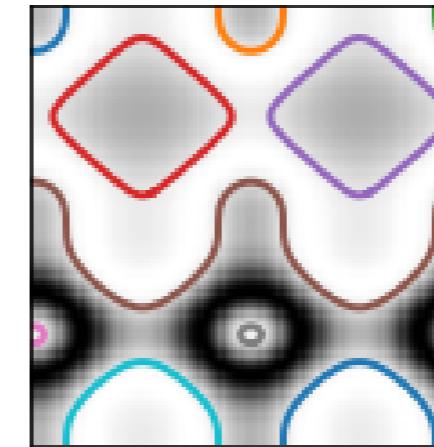
Level value of 0.1



Level value of 0.5



Level value of 0.8



# The steps to spotting contours

```
from skimage import measure
from skimage.filters import threshold_otsu

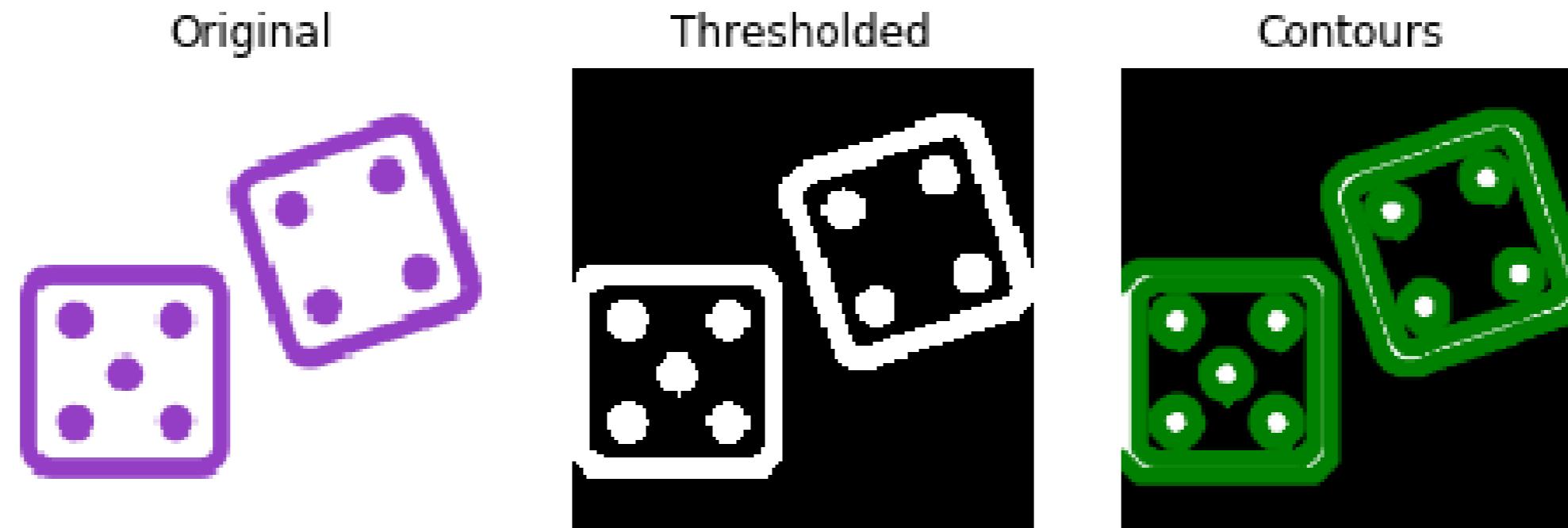
# Make the image grayscale
image = color.rgb2gray(image)
# Obtain the optimal thresh value of the image
thresh = threshold_otsu(image)

# Apply thresholding and obtain binary image
thresholded_image = image > thresh

# Find contours at a constant value of 0.8
contours = measure.find_contours(thresholded_image, 0.8)
```

# The steps to spotting contours

Resulting in



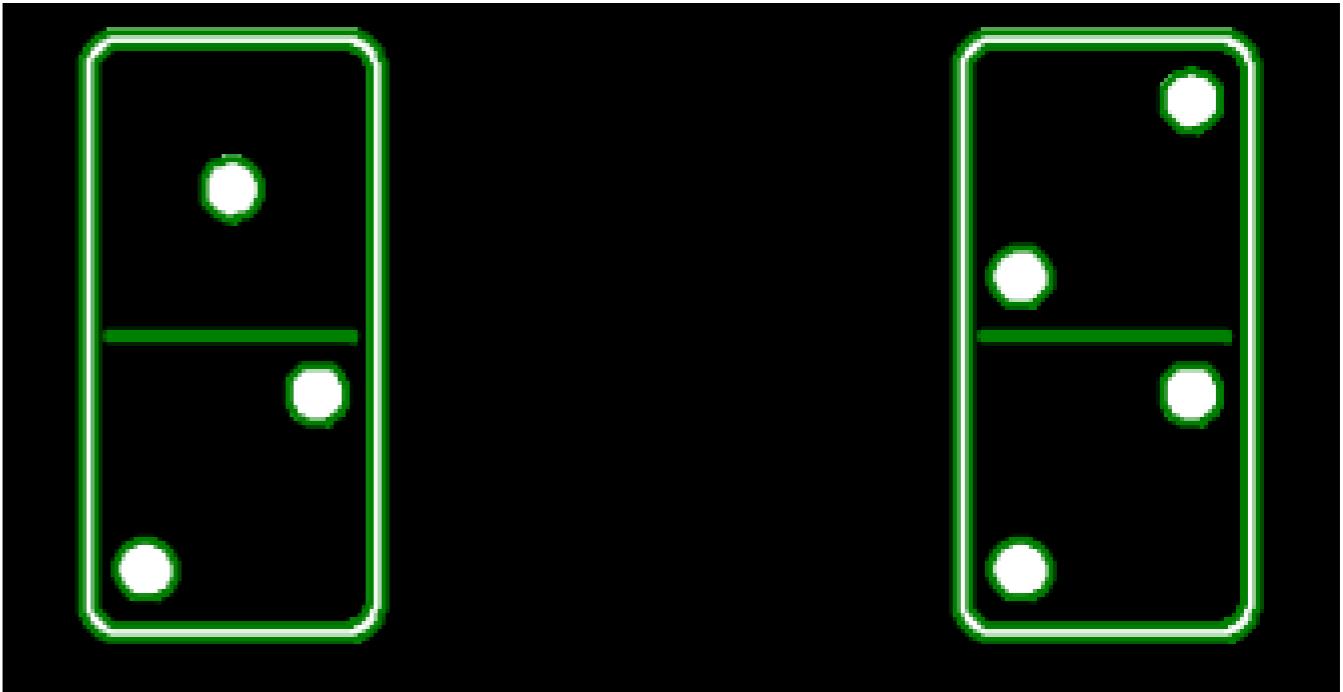
# A contour's shape

Contours: list of (n,2) - ndarrays.

```
for contour in contours:  
    print(contour.shape)
```

```
(433, 2)  
(433, 2)  
(401, 2)  
(401, 2)  
(123, 2)  
(123, 2)  
(59, 2)  
(59, 2)  
(59, 2)  
(57, 2)  
(57, 2)  
(59, 2)
```

Contours

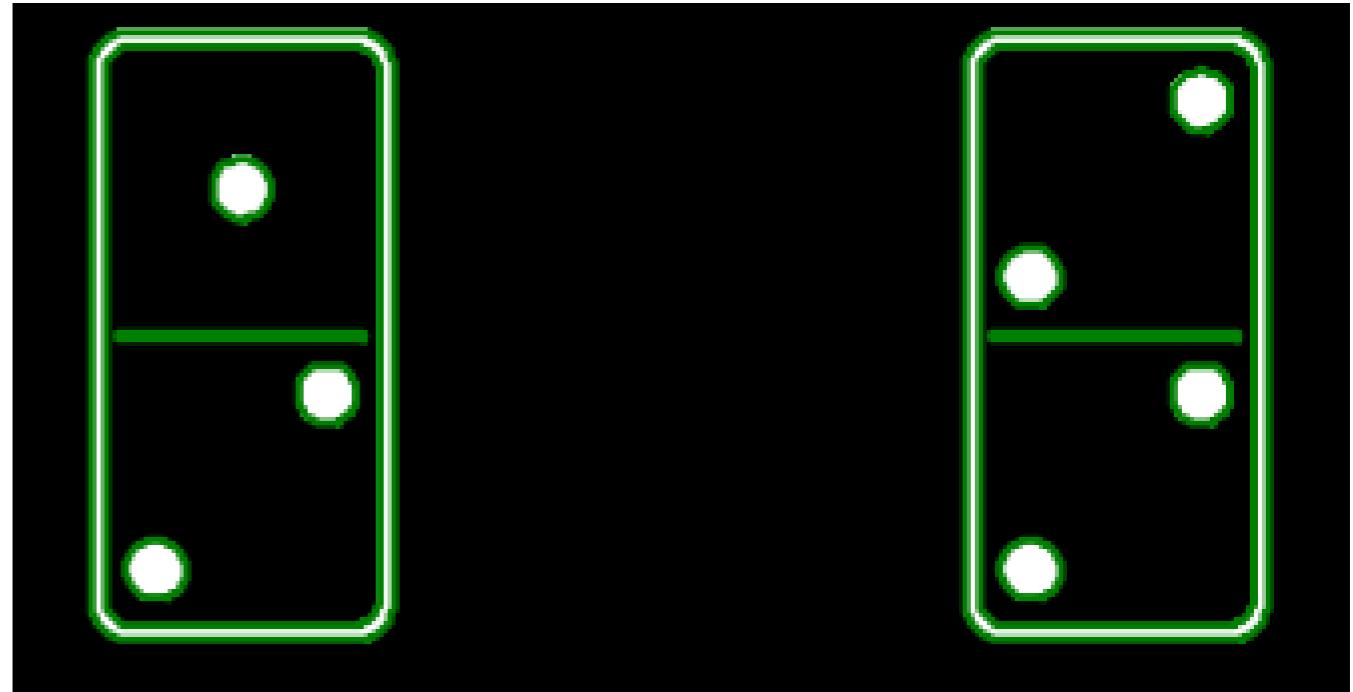


# A contour's shape

```
for contour in contours:  
    print(contour.shape)
```

```
(433, 2)  
(433, 2) --> Outer border  
(401, 2)  
(401, 2)  
(123, 2)  
(123, 2)  
(59, 2)  
(59, 2)  
(59, 2)  
(57, 2)  
(57, 2)  
(59, 2)  
(59, 2)
```

Contours

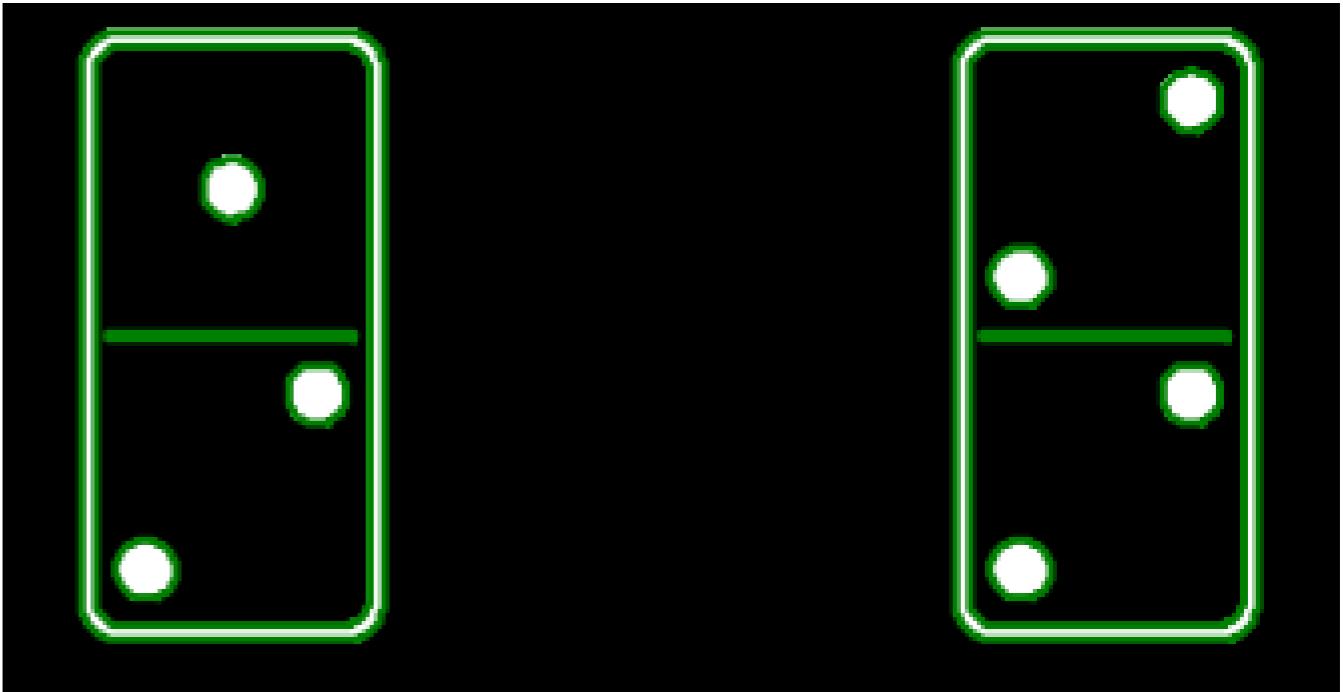


# A contour's shape

```
for contour in contours:  
    print(contour.shape)
```

```
(433, 2)  
(433, 2) --> Outer border  
(401, 2)  
(401, 2) --> Inner border  
(123, 2)  
(123, 2)  
(59, 2)  
(59, 2)  
(59, 2)  
(57, 2)  
(57, 2)  
(59, 2)  
(59, 2)
```

Contours

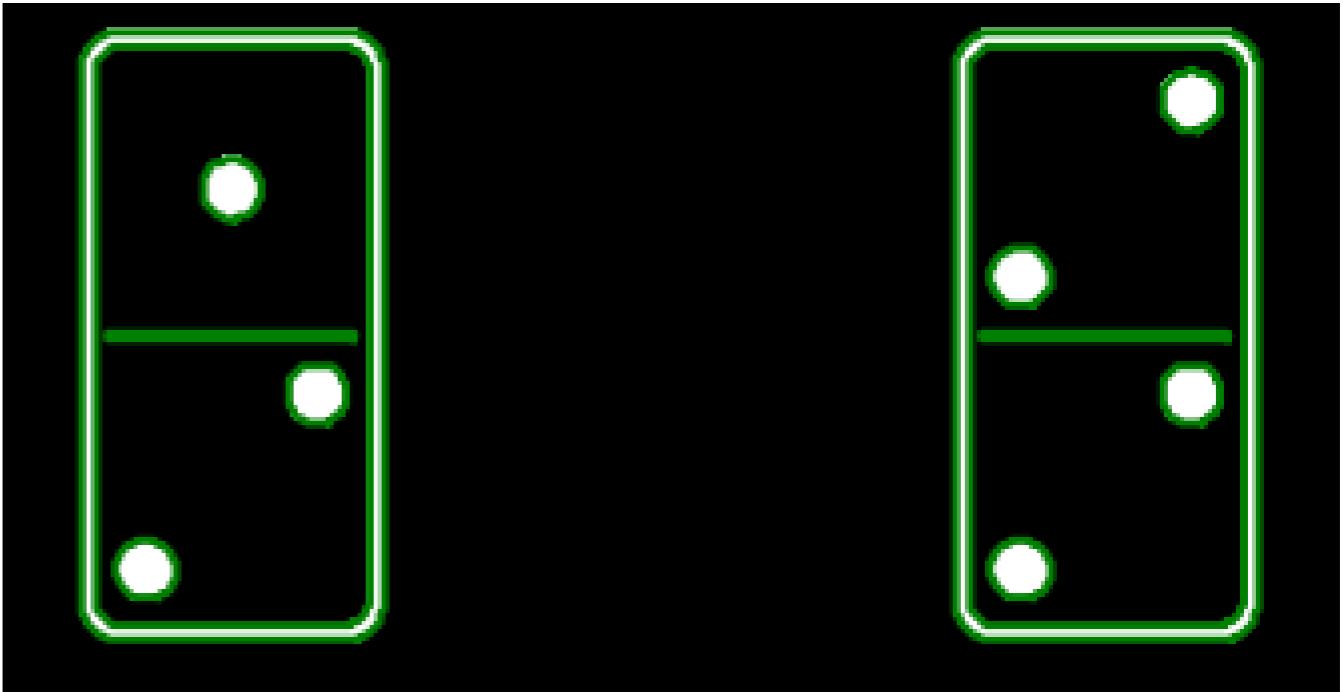


# A contour's shape

```
for contour in contours:  
    print(contour.shape)
```

```
(433, 2)  
(433, 2) --> Outer border  
(401, 2)  
(401, 2) --> Inner border  
(123, 2)  
(123, 2) --> Divisory line of tokens  
(59, 2)  
(59, 2)  
(59, 2)  
(57, 2)  
(57, 2)  
(59, 2)  
(59, 2)
```

Contours

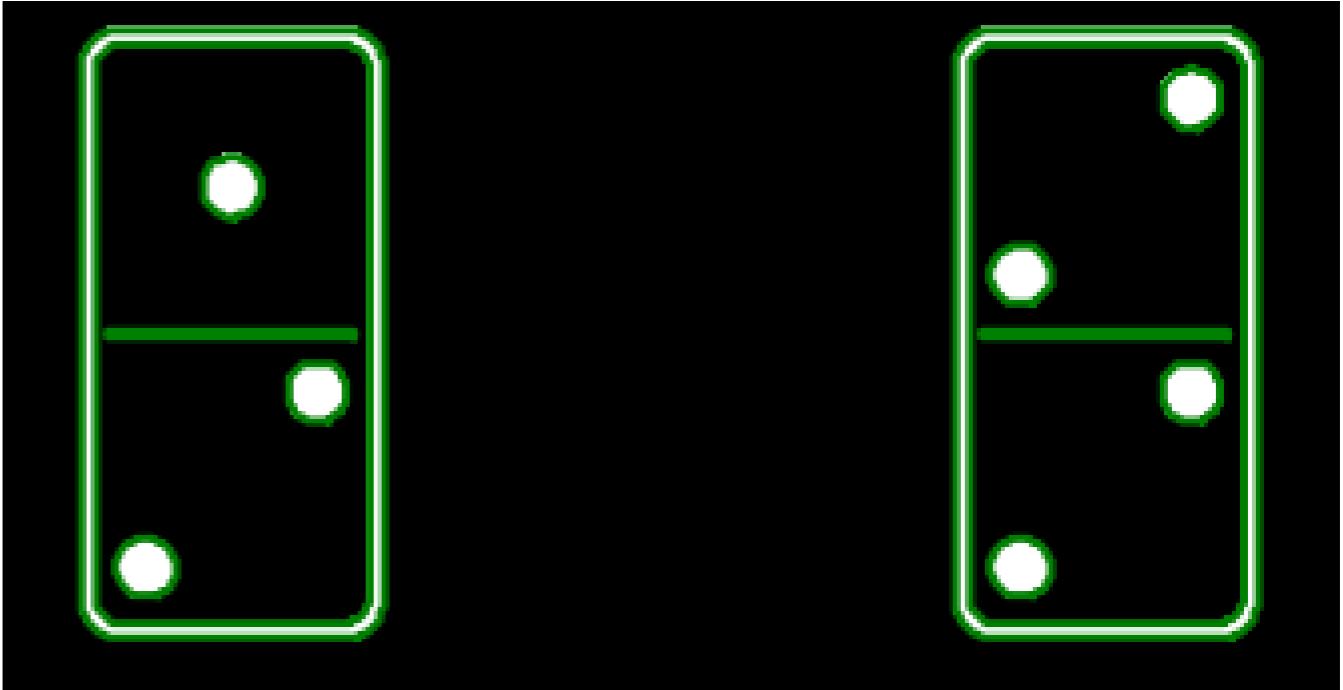


# A contour's shape

```
for contour in contours:  
    print(contour.shape)
```

```
(433, 2)  
(433, 2) --> Outer border  
(401, 2)  
(401, 2) --> Inner border  
(123, 2)  
(123, 2) --> Divisory line of tokens  
(59, 2)  
(59, 2)  
(59, 2)  
(57, 2)  
(57, 2)  
(59, 2)  
(59, 2) --> Dots
```

Contours



Number of dots: 7.

# **Let's practice!**

## **IMAGE PROCESSING IN PYTHON**