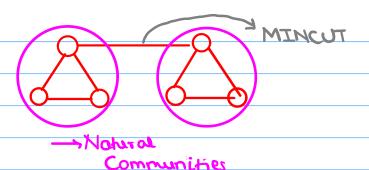
\* Graph Partitioning

\* Clustering



## \* Girvan - Newman Algorithm (CnN algo)

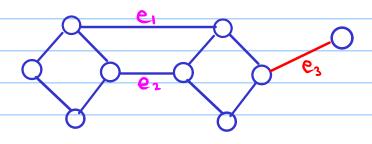
The algorithm's steps for community detection are summarized below

- 1. The betweenness of all existing edges in the network is calculated first.
- 2. The edge(s) with the highest betweenness are removed.
- 3. The betweenness of all edges affected by the removal is recalculated.
- 4. Steps 2 and 3 are repeated until no edges remain.

\* edge betweeness:

> edges in max no. of 20ths

## > Flaw/Limitation:



\* CON requires removal of e, lez Whereas job could be done by removing ez.

\* Internal Connectivity

1 Internal Density

ns (ns-1)/2

G: (VIE) S: Set of nodes

ms: edges in set, ns=151, m=1El Cs ! edges (Outgoing) from s

(Edegrees = 1 xedges)

3 Fraction Over median degree

[[u:ues, [(u,v):ves]] > dm]] ns

## \* External Connectivity

1 Expansion Cs/ns

2 Cut-Rotio Cs/ns(n-ns)

2 Aug Degree



\* Ideal Community:

Small Expansion / Cut-Ratio 4 High Internal Density

