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B.E. IT PROJECT

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Title: Library Assistant Robot

Abstract

The Digital Library Book Recommendation System project seeks to redefine the library user experience by harnessing advanced AI-driven recommendation algorithms. This innovative system integrates traditional cataloging with real-time data analytics, providing users with tailored interactions. It enables users to effortlessly discover books that align with their interests, authenticate their sources, and precisely locate their desired literature within the library's collection.

On the other hand, the Library Robot project introduces a visionary concept of integrating robotics and artificial intelligence (AI) into traditional libraries. This transformative initiative addresses the challenges of our digital age, with a primary focus on enhancing accessibility for all community members. Through the deployment of robotic assistance mechanisms, the project aims to assist individuals with physical limitations in navigating library spaces. Furthermore, it emphasizes the importance of operational efficiency by implementing AI-driven systems that maintain up-to-date book records and optimize inventory management. Additionally, the project aims to create engaging library experiences by introducing interactive robots that guide visitors, particularly young learners, provide book recommendations, and offer assistance with inquiries. Ultimately, these initiatives envision a future where libraries seamlessly blend tradition and technology, ensuring their continued relevance as vibrant centers of knowledge and community engagement.

Introduction

The Digitalized Library Book Recommendation System (DLBRS) addresses this paradigm shift. Drawing from advanced natural language processing (NLP) techniques and AI-driven user profiling, the DLBRS intends to revolutionize library interactions. By analyzing both the metadata of books and the historical interaction patterns of users, this system aims to provide dynamic, real-time recommendations that are both relevant and insightful. Furthermore, the integration of machine learning models promises continuous improvement in recommendation accuracy over time, as the system learns and adapts. DLBRS is not just a bridge between conventional library science and modern AI—it represents the next evolutionary step in how we perceive and interact with repositories of knowledge.

Literature Survey

The integration of chatbot technology in libraries has gained significant attention due to its potential in enhancing user experience and improving library services. This literature survey explores the existing research and developments related to Library Assistant Chatbots. The aim is to understand the evolution of chatbot technology in library settings and analyze its impact on user engagement, information retrieval, and overall library efficiency.

1. Historical Development of Chatbots:

Several types of tour guide robots have been introduced in the past, each with a unique navigation technique. Researches Yelamarthi et al [1] proposed a tour guide robot equipped with an RFID reader for localization and sonar and IR sensors for obstacle detection and avoidance. However, passive RFID readers tend to have a limited operating range which makes them less reliable as the robot has high chances of missing a tag. Furthermore, RFID readers are quite costly.[1]

2. User Experience and Interaction:

developed an autonomous human-like guide robot for a science museum. Its identifies individuals, estimates the exhibits at which visitors are looking, and proactively approaches them to provide explanations with gaze autonomously, using our new approach called speak-and-retreat interaction. The robot also performs such relation-building behaviors as greeting visitors by their names and expressing a friendlier attitude to repeat visitors.[2]

3. Information Retrieval:

‘Theano-The Chaperone’, who will offer a distributed, modular software and hardware architecture that combines modules for user interface, interaction, localization and collision avoidance. The software strategy depends on artifact detection, voice-enabled information delivery, voice assistant capable of answering user questions, reinforcement learning and path planning algorithms to give a complete museum tour experience.[3]

Proposed Work of Project

Although tour guide robots with various self-localization abilities such as mapping has been introduced in the past, these technologies performance still remain challenged by indoor navigation obstacles. The current approach consists of implementing a low cost autonomous indoor tour guide robot running on an embedded system which is the Raspberry pi 2. The autonomous navigation is achieved through wall following using ultrasonic sensors and image processing using a simple webcam. The bitwise image processing comparison method introduced is writing in OpenCV and runs on the Raspberry pi. It grabs images and look for the tags to identify each lab.

1. User Interaction and Engagement:

- Natural Language Processing (NLP): Implement advanced NLP algorithms for understanding and responding to user queries in a conversational manner.
- Voice Interaction: Enable voice-based interactions for users, allowing them to ask questions and receive responses audibly.
- Multimodal Interface: Support text, voice, and image inputs, enhancing accessibility and accommodating diverse user preferences.
- Personalization: Utilize machine learning to analyze user behavior and preferences, providing personalized recommendations and services.

2. Information Retrieval and Guidance:

- Search Capabilities: Offer robust search functionalities, enabling users to find books, articles, and other resources using natural language queries.
- Location Services: Assist users in locating books and resources within the library using RFID or similar technologies.
- Book Recommendations: Provide intelligent book recommendations based on user interests, borrowing history, and popular trends.
- Interactive Maps: Integrate interactive maps to guide users to specific sections, shelves, or facilities within the library.

3. Library Services Automation:

- Book Check-In/Check-Out: Automate the process of borrowing and returning books using RFID technology, reducing queues and wait times.

System Requirements

A. Hardware Requirements

| | |
|---------|----------------------------|
| CPU | Quad-core 2.5GHz or faster |
| RAM | 16GB |
| STORAGE | 150GB HDD |
| GPU | OPTIONAL |
| NETWORK | MIN 1Mbps |

B. Software Requirements

| | |
|------------------|---|
| OPERATING SYSTEM | WINDOWS, LINUX, MAC-OS |
| RUNTIME | PYTHON 3.X.X |
| DATABASE | MYSQL, SYSTEM DATABASE |
| LIBRARIES | FLASK, PANDAS, NLP TOOLS, TENSORFLOW |
| BROWSER | CHROMIUM EQUIVALENT |

Expected Result

Digital Library Book Recommendation System Project:

Improved User Experience: The implementation of AI-driven recommendation algorithms is expected to significantly enhance the user experience in libraries. Users can anticipate personalized book recommendations that match their interests, simplified authentication of sources, and precise location information for the books they seek. This, in turn, should lead to increased user satisfaction and a more efficient use of library resources.

Library Robot Project:

Enhanced Library Accessibility and Efficiency: The introduction of robotics and AI into libraries is anticipated to result in increased accessibility, particularly for individuals with physical limitations. These technologies are expected to make library spaces more user-friendly and efficient, improving inventory management and resource allocation.

Engaging and Interactive Library Environments: The deployment of interactive robots is expected to create engaging library experiences, especially for young learners. These robots will offer guidance, recommend books, and assist with inquiries, thereby enhancing visitor engagement and satisfaction.

Overall, the expected result is a transformation of traditional libraries into dynamic, technology-enhanced spaces that are more inclusive, efficient, and engaging, ultimately ensuring that libraries remain essential hubs of knowledge and community for future generations.

References

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- [3] Kulkarni, Ms., & Deshpande, Prof. (2023, April 15). Innovative Software and Hardware Design for a User-Friendly Tour Guide Robot . In TIJER (ISSN 2349-9249). Technix International Journal for Engineering Research UGC CARE Norms. Retrieved August 16, 2023, from <https://www.tijer.org/papers/TIJER2304126.pdf>