

04 - LAN

LAN

- fiber unidirectional 1 to 1
- Ethernet is many to many link
- however bc its a single link, we need to be able to demux the signal to the correct receiver → Media Access Control Adress (MAC addr.)
- LAN is also known as
 - Multi access link - multiple nodes on the same link
 - broadcast links - every transmission can be heard by all nodes
 - LAN - geographically serviced by a local region 1-10 km(s)
- Pros
 - cost - connect all devices on a campus on a single link
 - bandwidth - ethernet i high bandwidth distributed computing
 - statistical multiplexing - time division multiplexing (TDM) is not good when user traffic is busy → many collisions
 - each user splits the bandwidth, high bandwidth when low traffic

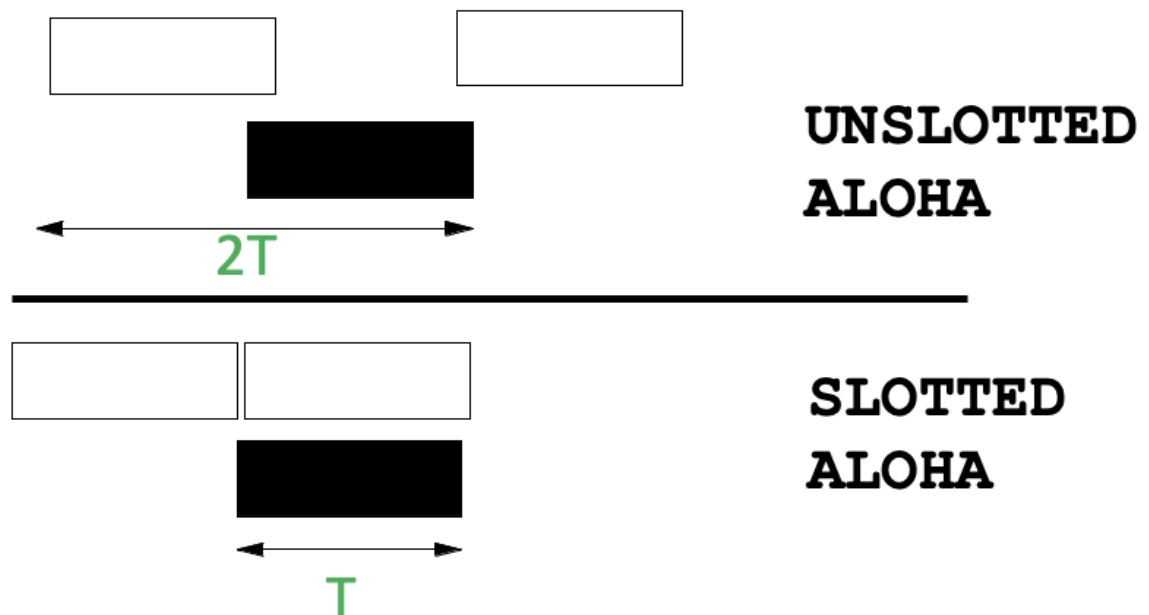
Statistical vs Strict Mux

- strict - TDM/FDM where user given fix allocation regardless of whether user want to send → bad
- bursty - traffic has aa high and average peak
- therefore, strict gives each user B/N bandwidth

- stat mux gives B/x where x is number of busy users,
 $x \ll N$

ALOHA

- ethernet predecessor - multiple ground stations across Hawaii
- problem - no collision detection when traffic was high → similar problems in wireless 802.11
- sol - slotted aloha, allocate bandwidth and reduce collision period by half but require shared clock



CSMA/CD & Ethernet

Bob Metcalfe - inventor of Ethernet at Xerox PARC and CSMA/CD for Harvard PhD thesis

CSMA/CD

- to be better than aloha
- CS - carrier sense → nodes listen before sending
- MA - Multiple access - many to many

- CD - w/ Collision detection → only handles collision errors

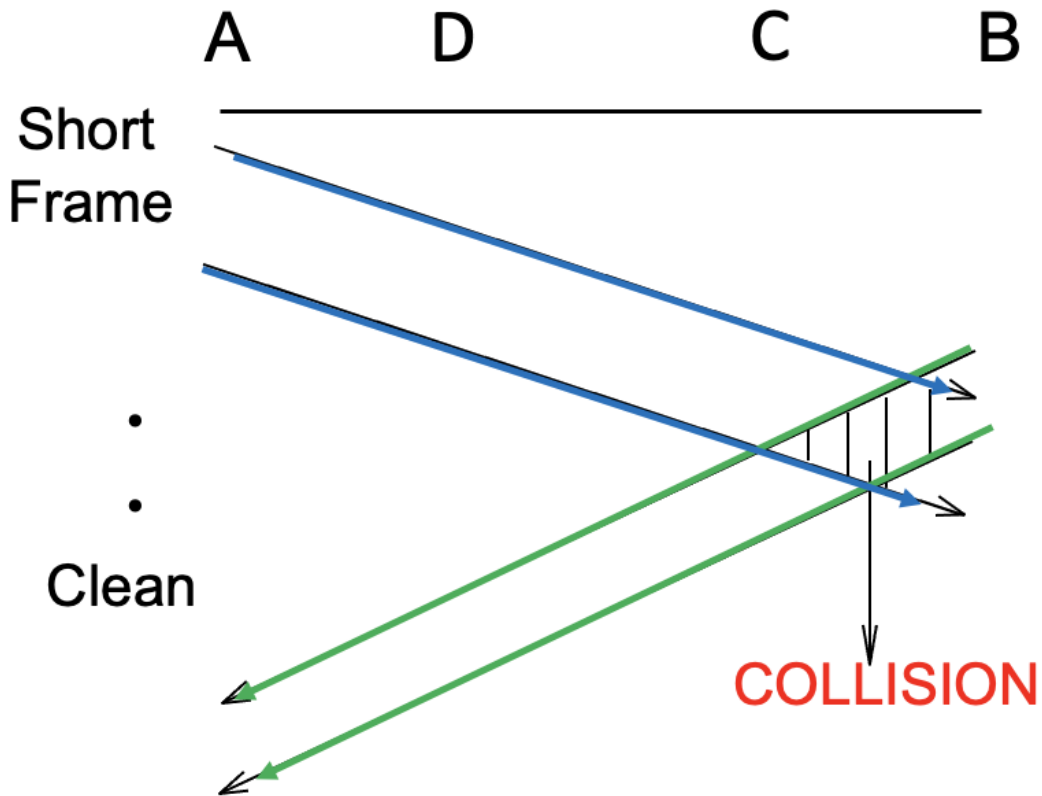
Ethernet

- aborts transmission after 64 bytes if a collision is detected while aloha sends full 1500 byte datagram
- only handles collision detection (frequent) but not frame corruption recovery
- senders cannot detect collisions, only nodes at the intersection of 2 signals can detect collisions at their node
- note that collision are between waves in ethernet and 802.11 not mass-based particles

Packet Size dependence

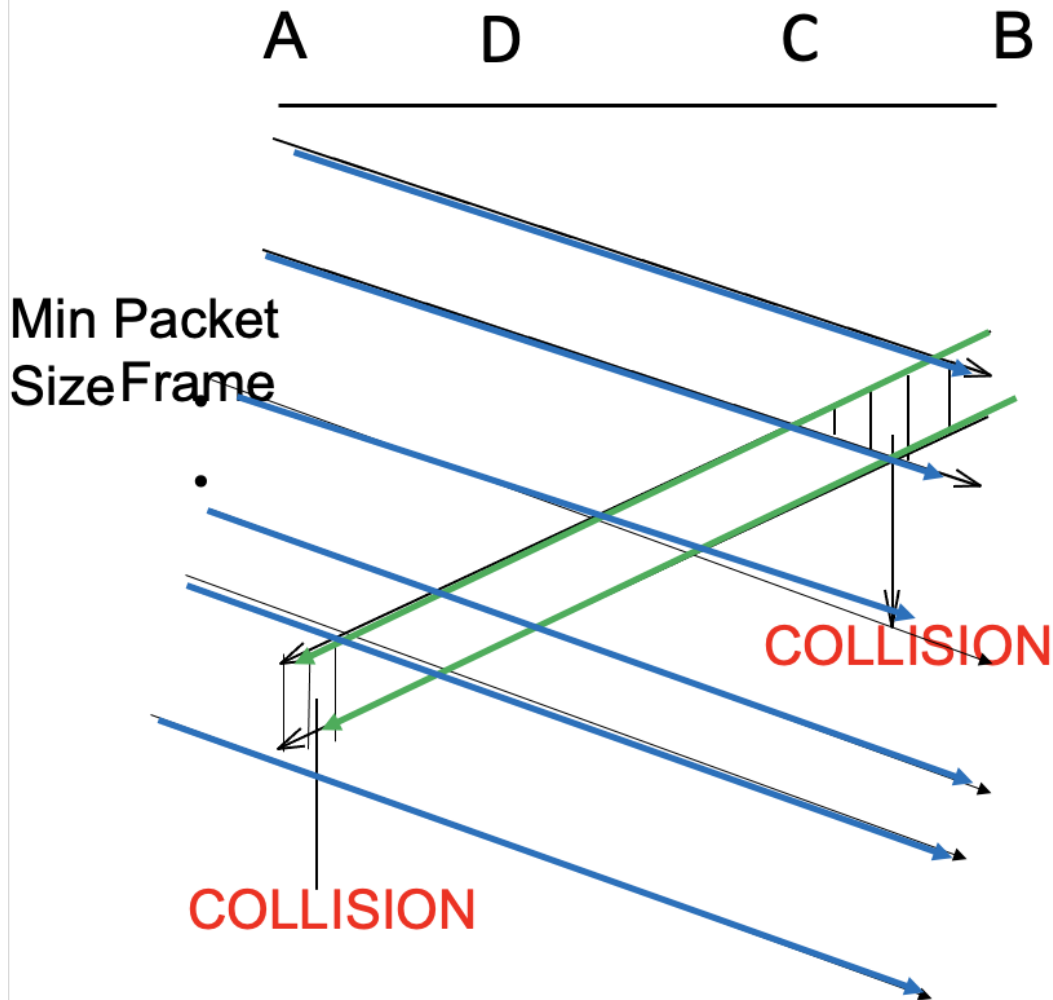
- ethernet enforces minimum packet size of 64 bytes for CD

- without min packet size - no retransmission



A transmits to C and B transmits to D, if A sends a short frame *C will detect a collision and A will not.* So A **won't retransmit**

- with limited packet size



A transmits to C and B transmits to D, if A sends a “long enough” frame, *C will detect a collision and A will too. So A will retransmit*

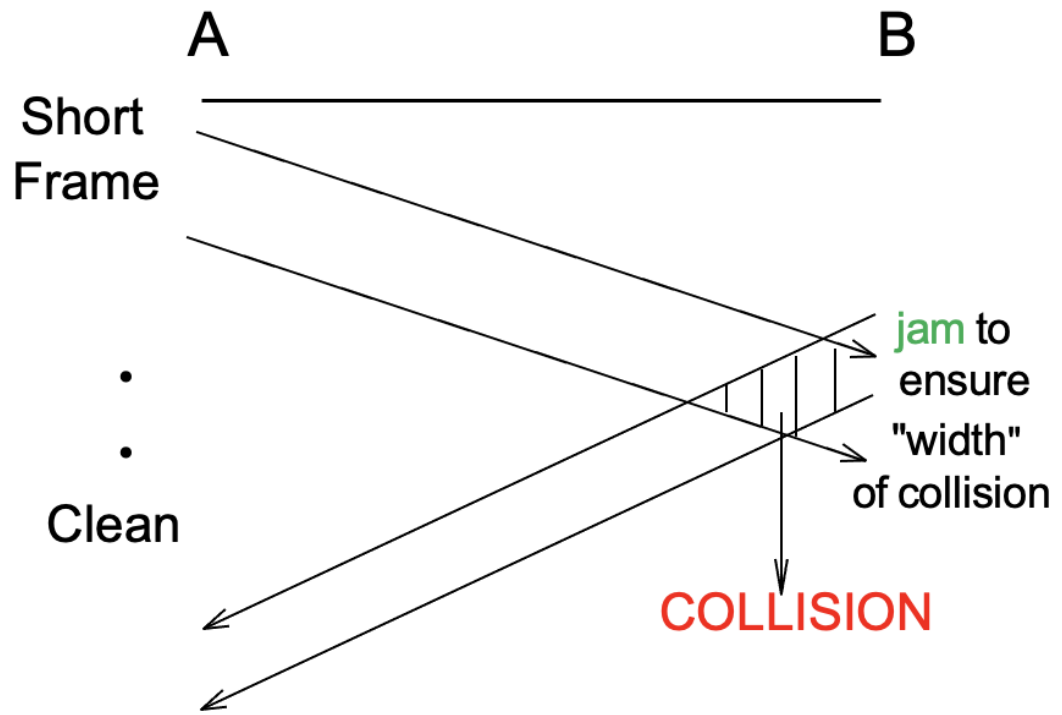
- the min-size of the packet depends on the pipe size = transmission rate \times round trip prop delay
 - e.g., if $R = 10\text{Mbit/s}$, $\text{RTPD} = 25.6\mu\text{s}$; then pipe size = 512 bits = 64 bytes

Collision Detection

- consider 2 colliders, one should wait 1 slot and the other 0 slots, mux collision or time with coin toss \rightarrow just pick 1 signal to pass through the detecting node,

e.g. if C detects collision of $A \rightarrow B$ and $B \rightarrow A$ and order is $A \rightarrow C \rightarrow B$ then C just muxes one of the signals

- consider 16 colliders - ethernet does **Binary Exponential Backoff**
 - after attempt A, each station randomly picks a number of slots between 0 and $2^A - 1$. A slot is $51.2\mu s$ (because of prev question pipe). after 1 collision pick 0 or 1 slot, after 2 collisions pick up to 4 slots, after 3 up to 8 slots (slots 0 ... 7)
- ethernet's 3 mechanisms
 - CS - don't transmit when someone else is (imagine the detecting node wants to transmit)
 - CD - stop frame if CD before 64 bytes of frame
 - Exponential backoff - collisions are frequent so must retransmit, random backoff avoids synchronized collisions, dynamically adjust number of colliders with backoff
- terms
 - slot time - $2T$, where T is 1-way prop delay, limited to $51.2\mu s$ to allow 64 byte pipe size
 - min packet size - 64 bytes to avoid transmission end before CD
 - jam - transmit small number of bits after CD to ensure other transmitters also detect collision

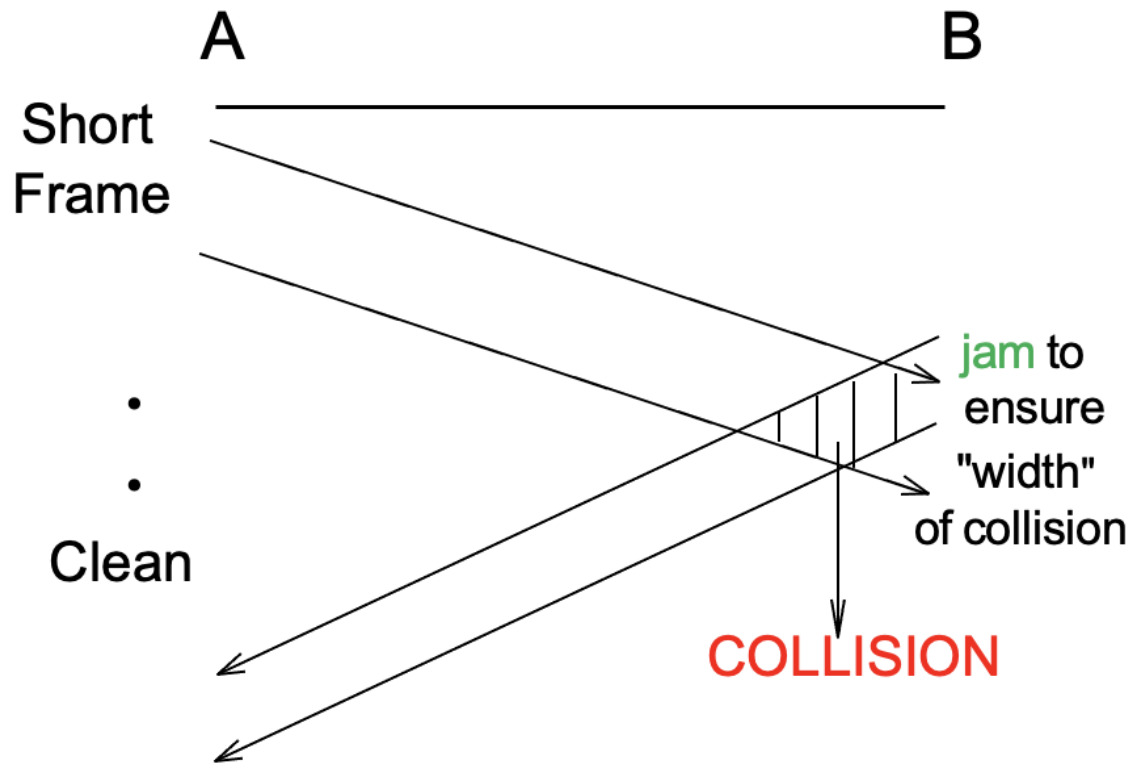


- CD - one option is use Manchester encoding average voltage, e.g. 0 (0V) or 1 (1.5V) has avg 0.75V, collision \Rightarrow average 1.5V

Ethernet Details

Terms

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Header

- dest for mux, source for mux ack, length in case frame is smaller than min packet size, CRC - error detection hash

01010111 preamble	Dest (6)	Source (6)	Length (2)	Data	Pad	CRC
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Total Frame length
 $64 \leq L \leq 1500$

Hardware

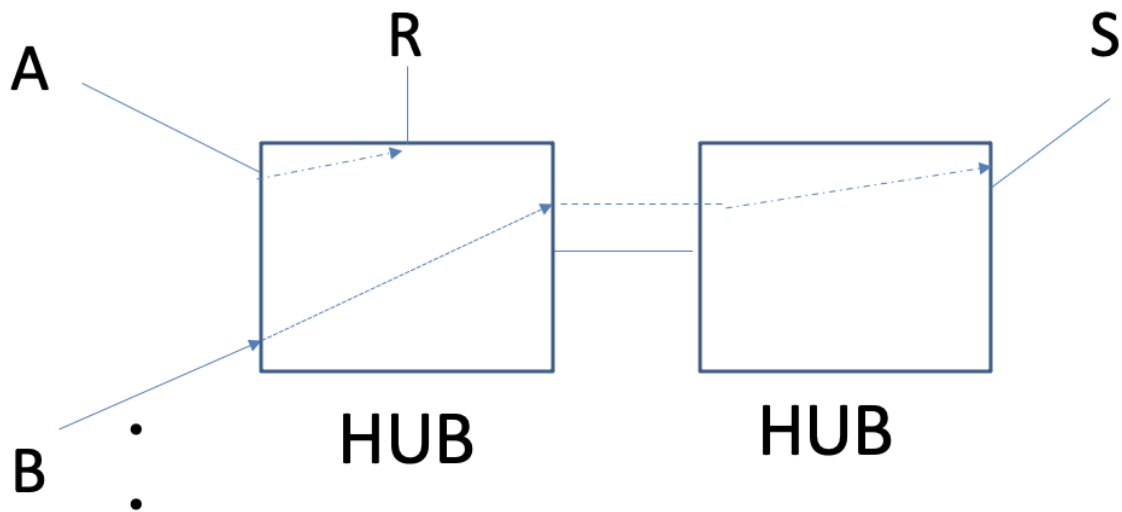
- limited distance of 2.5 km with 500m wires and 4 repeaters

- thin wire or thick wire
- physical topology of star (all nodes connected to hub) or tree (bus with main line and branches)

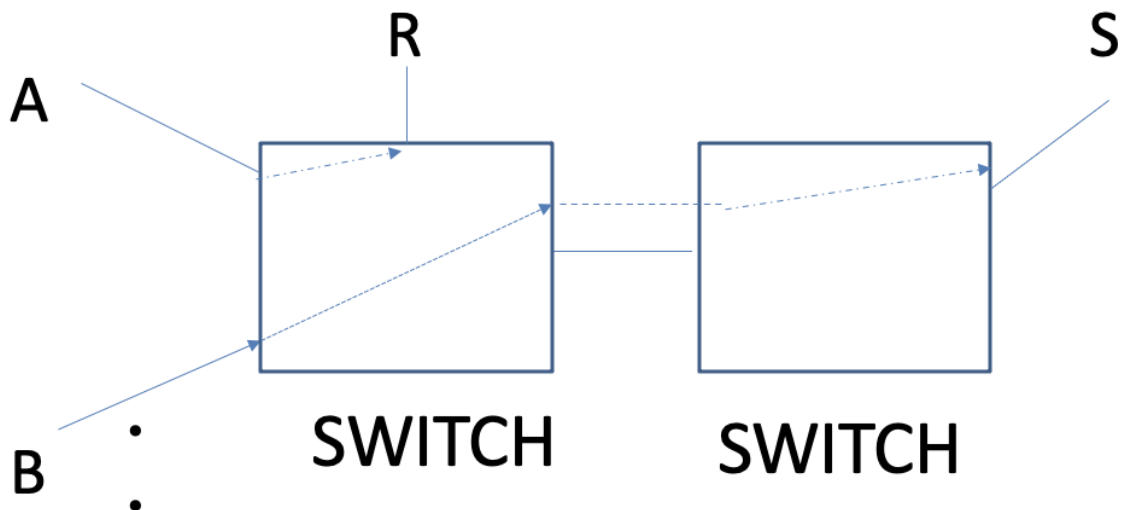
Limitations

- Bandwidth and distance, if speed increased, distance must be shorter, e.g. 100 Mbps ether has 200m extent
- Gigabit ether has 2m extent → switches, hubs, point to point
- therefore, cost of stat mux is why ethernet is limited to LAN
- so modern day shift from mainline ethernet to series of point to point switches but keep ethernet header

- CSMA/CD to Switches



If A talks to R at same time as B talks to S there is a **collision**. True for 10 and 100 M Ethernet.



A can talk to R at same time as B talks to S with **no collision**. Switch buffers and allows parallel connections. True for Gigabit Ethernet