## 6.3-Higher-Order Linear Systems

#UCLA #Y1Q3 #Math33B

# Higher-Order Linear Systems

### **Key Definitions**

Limited to homogenous, constant coefficient, linear higher order differentials

Determinant by Laplace (Cofactor) Expansion:

$$ext{det}(A) = \sum_{I}^{N} A_{IJ} (-1)^{I+J} ext{det}(cof(A_{IJ}))$$

### **Steps**

- 1. Convert nth order to nxn matrix
- 2. Solve linear system
- 3. Convert to linear differential equation

### Solution

Given nth order diff. eq.

**Auxiliary Functions** 

$$X_1(T) := Y(T)$$

$$x_1' = x_2$$

and so on.

Then, create a nxn matrix of aux. funcs.:

$$x'_1(t) = x_2(t)$$
  
 $x'_2(t) = x_3(t)$   
 $x'_3(t) = x_4(t)$ 

What about  $x'_4(t) = y^{(4)}(t)$ ? The original differential equation itself tells us how to relate this to the lower derivatives:

$$x_4'(t) = 13y''(t) - 36y(t) = 13x_3(t) - 36x_1(t)$$

Combining these four equations yields the system:

$$\begin{bmatrix} x_1'(t) \\ x_2'(t) \\ x_3'(t) \\ x_4'(t) \end{bmatrix} = \begin{bmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ -36 & 0 & 13 & 0 \end{bmatrix} \begin{bmatrix} x_1(t) \\ x_2(t) \\ x_3(t) \\ x_4(t) \end{bmatrix}$$

General Solution

$$ec{x}( au; C_{\scriptscriptstyle I}) = \sum_{\scriptscriptstyle I}^{\scriptscriptstyle N} C_{\scriptscriptstyle I} extit{E}^{\scriptscriptstyle A_{\scriptscriptstyle I} T} ec{v}_{\scriptscriptstyle I}$$

Such that, we can find the original diff. eq.

$$Y(T; C_I) = X_1(T) = \sum_{I}^{N} C_I E^{A_I T} \vec{V}_{I,1}$$

E.g.

$$\mathbf{x}(t; C_1, C_2, C_3, C_4) = e^{2t} \begin{bmatrix} 1\\2\\4\\8 \end{bmatrix} + C_2 e^{-2t} \begin{bmatrix} -1\\2\\-4\\8 \end{bmatrix} + C_3 e^{3t} \begin{bmatrix} 1\\3\\9\\27 \end{bmatrix} + C_4 e^{-3t} \begin{bmatrix} -1\\3\\-9\\27 \end{bmatrix}$$

$$=\begin{bmatrix} C_1e^{2t}-C_2e^{-2t}+C_3e^{3t}-C_4e^{-3t}\\ 2C_1e^{2t}2C_2e^{-2t}+3C_3e^{3t}+3C_4e^{-3t}\\ 4C_1e^{2t}-4C_2e^{-2t}+9C_3e^{3t}-9C_4e^{-3t}\\ 8C_1e^{2t}+8C_2e^{-2t}+27C_3e^{3t}+27C_4e^{-3t} \end{bmatrix}$$

In particular, the general solution to  $y^{(4)} - 13y'' + 36y = 0$  is

$$y(t; C_1, C_2, C_3, C_4) = x_1(t) = C_1 e^{2t} - C_2 e^{-2t} + C_3 e^{3t} - C_4 e^{-3t}$$

which we might as well instead write as

$$y(t) = C_1 e^{2t} + C_2 e^{-2t} + C_3 e^{3t} + C_4 e^{-3t}$$

#### **General Solution**

We can find a solution of form:

$$\vec{x}' = A\vec{x}$$

where A is the companion matrix and if:

$$\mathbf{x}(t) = \begin{bmatrix} y(t) \\ y'(t) \\ y''(t) \\ \vdots \\ y^{(n-1)}(t) \end{bmatrix}$$

So we get the equation in matrix form: We then form the linear system:

$$\begin{bmatrix} x_1'(t) \\ x_2'(t) \\ \vdots \\ x_{n-1}'(t) \\ x_n'(t) \end{bmatrix} = \begin{bmatrix} 0 & 1 & 0 & \cdots & 0 \\ 0 & 0 & 1 & \cdots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & \cdots & 1 \\ -a_n & -a_{n-1} & -a_{n-2} & \vdots & -a_1 \end{bmatrix} \begin{bmatrix} x_1(t) \\ x_2(t) \\ \vdots \\ x_{n-1}(t) \\ x_n(t) \end{bmatrix}$$

Then, if  $y_1, \ldots, y_n$  are solutions to the nth order differential equation, we ca get the vector valued functions:

$$\begin{bmatrix} y_1(t) \\ y'_1(t) \\ y''_1(t) \\ \vdots \\ y_1^{(n-1)}(t) \end{bmatrix}, \dots, \begin{bmatrix} y_n(t) \\ y'_n(t) \\ y''_n(t) \\ \vdots \\ y_n^{(n-1)}(t) \end{bmatrix}$$

For which, the 4.1-2nd Order Linear Differentials >  $\frac{\text{Wronskian}}{\text{Wronskian}} \neq 0$ 

$$W(t) = \det \begin{bmatrix} y_1(t) & y_2(t) & \cdots & y_n(t) \\ y_1'(t) & y_2'(t) & \cdots & y_n'(t) \\ \vdots & \vdots & \ddots & \vdots \\ y_1^{(n-1)}(t) & y_2^{n-1}(t) & \cdots & y_n^{(n-1)}(t) \end{bmatrix}$$

Thus the matrix has linearly independent column vectors  $ec{y}_1,\dots,ec{y}_n$ 

Then finally, we get the general solution:

$$Y(T) = \sum_I^N C_I ec{Y}_I(T)$$