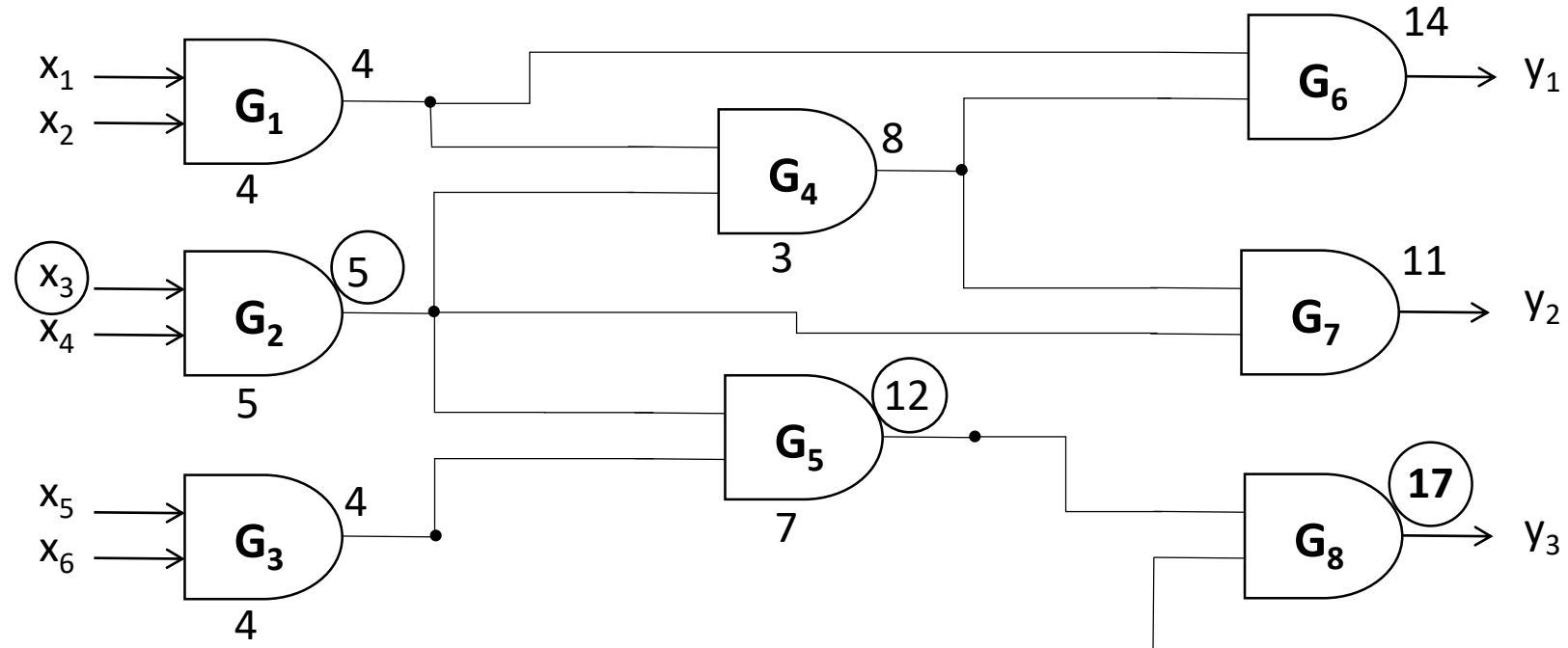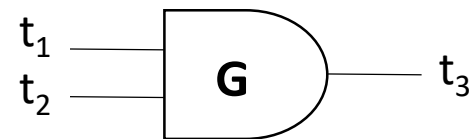# Critical Path: Dynamic Programming

Critical Path: $x_3 \longrightarrow G_2 \longrightarrow G_5 \longrightarrow G_8 \longrightarrow y_3$

$t_3 = \max(t_1, t_2) + d(G)$

Critical Path Calculation