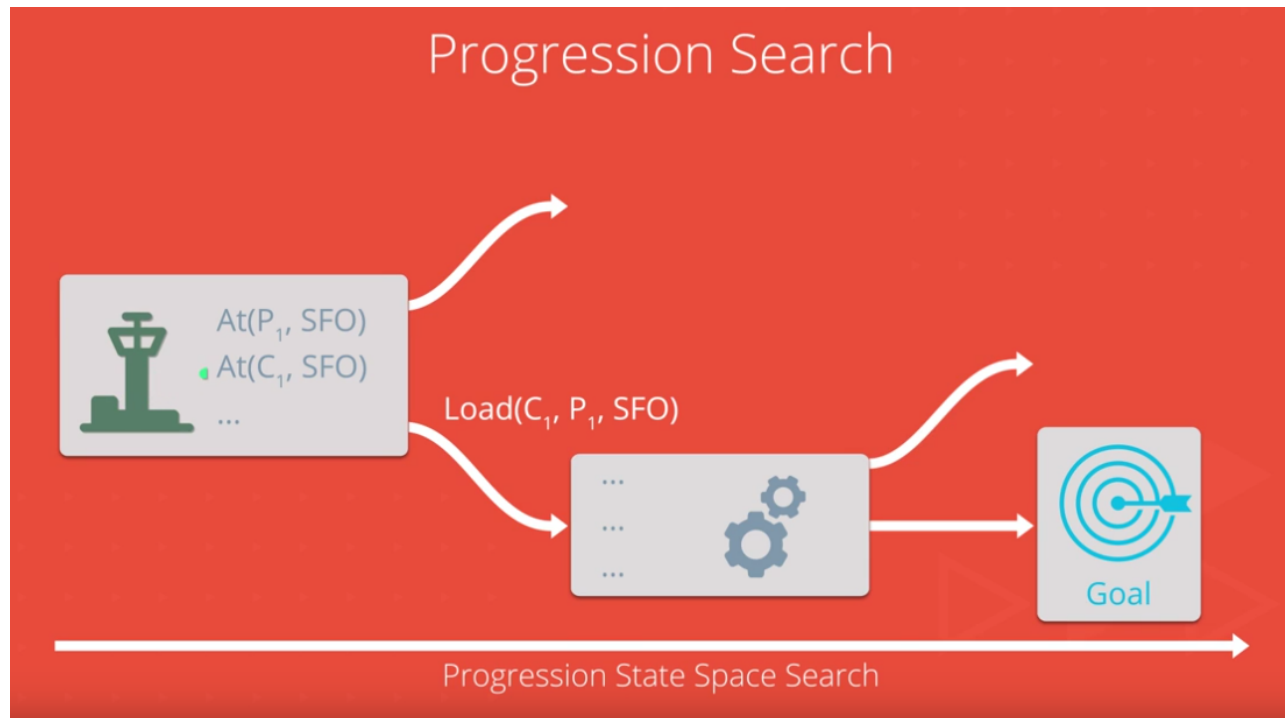


HEURISTIC ANALYSIS FOR IMPLEMENTING A PLANNING SEARCH AGENT

Tejasvi Nuthalapati

As part of [Artificial Intelligence Nano Degree Program](#) at [Udacity](#)



INDEX OF CONTENTS

SNO	Title	Page No.
1.	Synopsis	3
2.	Analysis	5
2.1	Un-Informed Search Strategies	5
2.1.1	Comparative Analysis	6
2.2	Informed Search Strategies	7
2.2.2	Comparative Analysis	7
3.	Final Analysis Recommendation	8
4.	Appendix	9
4.1	Problem-1 Results	9
4.2	Problem-2 Results	12
4.3	Problem-3 Results	15

1. SYNOPSIS

In this project I implemented a planning search agent to solve **deterministic logistics** planning problem for an **Air Cargo Transport system**.

All problems in the Air Cargo Domain use this, **Action Schema**:

```
Action(Load(c, p, a),
    PRECOND: At(c, a) ∧ At(p, a) ∧ Cargo(c) ∧ Plane(p) ∧ Airport(a)
    EFFECT: ¬ At(c, a) ∧ In(c, p))
Action(Unload(c, p, a),
    PRECOND: In(c, p) ∧ At(p, a) ∧ Cargo(c) ∧ Plane(p) ∧ Airport(a)
    EFFECT: At(c, a) ∧ ¬ In(c, p))
Action(Fly(p, from, to),
    PRECOND: At(p, from) ∧ Plane(p) ∧ Airport(from) ∧ Airport(to)
    EFFECT: ¬ At(p, from) ∧ At(p, to))
```

There are three Problems that are given in this Action Schema

SNO	Initial state and Goals
Problem-1	$\text{Init}(\text{At}(\text{C1, SFO}) \wedge \text{At}(\text{C2, JFK})$ $\wedge \text{At}(\text{P1, SFO}) \wedge \text{At}(\text{P2, JFK})$ $\wedge \text{Cargo}(\text{C1}) \wedge \text{Cargo}(\text{C2})$ $\wedge \text{Plane}(\text{P1}) \wedge \text{Plane}(\text{P2})$ $\wedge \text{Airport}(\text{JFK}) \wedge \text{Airport}(\text{SFO}))$ $\text{Goal}(\text{At}(\text{C1, JFK}) \wedge \text{At}(\text{C2, SFO}))$
Problem-2	$\text{Init}(\text{At}(\text{C1, SFO}) \wedge \text{At}(\text{C2, JFK}) \wedge \text{At}(\text{C3, ATL})$ $\wedge \text{At}(\text{P1, SFO}) \wedge \text{At}(\text{P2, JFK}) \wedge \text{At}(\text{P3, ATL})$ $\wedge \text{Cargo}(\text{C1}) \wedge \text{Cargo}(\text{C2}) \wedge \text{Cargo}(\text{C3})$ $\wedge \text{Plane}(\text{P1}) \wedge \text{Plane}(\text{P2}) \wedge \text{Plane}(\text{P3})$ $\wedge \text{Airport}(\text{JFK}) \wedge \text{Airport}(\text{SFO}) \wedge \text{Airport}(\text{ATL}))$ $\text{Goal}(\text{At}(\text{C1, JFK}) \wedge \text{At}(\text{C2, SFO}) \wedge \text{At}(\text{C3, SFO}))$
Problem-3	$\text{Init}(\text{At}(\text{C1, SFO}) \wedge \text{At}(\text{C2, JFK}) \wedge \text{At}(\text{C3, ATL}) \wedge \text{At}(\text{C4, ORD})$ $\wedge \text{At}(\text{P1, SFO}) \wedge \text{At}(\text{P2, JFK})$ $\wedge \text{Cargo}(\text{C1}) \wedge \text{Cargo}(\text{C2}) \wedge \text{Cargo}(\text{C3}) \wedge \text{Cargo}(\text{C4})$ $\wedge \text{Plane}(\text{P1}) \wedge \text{Plane}(\text{P2})$ $\wedge \text{Airport}(\text{JFK}) \wedge \text{Airport}(\text{SFO}) \wedge \text{Airport}(\text{ATL}) \wedge \text{Airport}(\text{ORD}))$ $\text{Goal}(\text{At}(\text{C1, JFK}) \wedge \text{At}(\text{C3, JFK}) \wedge \text{At}(\text{C2, SFO}) \wedge \text{At}(\text{C4, SFO}))$

And their optimal Sequence of actions identified are:

SNO	Optimal Sequence of Actions
Problem-1	Plan Length - 6 Load(C1,P1,SFO) Load(C2,P2,JFK) Fly(P2,JFK,SFO) UnLoad(C2,P2,SFO) Fly(P1,SFO,JFK) UnLoad(C2,P1,JFK)
Problem-2	Plan Length - 9 Load(C1,P1,SFO) Load(C2,P2,JFK) Load(C3,P3,ATL) Fly(P2,JFK,SFO) UnLoad(C2,P2,SFO) Fly(P1,SFO,JFK) UnLoad(C1,P1,JFK) Fly(P3,ATL,SFO) UnLoad(C3,P3,SFO)
Problem-3	Plan Length - 12 Load(C1,P1,SFO) Load(C2,P2,JFK) Fly(P1,SFO,ATL) Load(C3,P1,ATL) Fly(P2,JFK,ORD) Load(C4,P2,ORD) Fly(P2,ORD,SFO) Fly(P1,ATL,JFK) UnLoad(C4,P2,SFO) UnLoad(C3,P1,JFK) UnLoad(C2,P2,SFO) UnLoad(C1,P1,JFK)

2. ANALYSIS

2.1 Un-Informed Search Strategies:

Uninformed search strategies use only the information available in the problem definition, the strategies are: Breadth First Search, Uniform-cost search, Depth-first search, Depth-limited search and Iterative deepening search.

Problem 1 Results:

Strategy	Optimal	Path Length	Time(sec)	Node Expansions
BFS	Yes	6	0.03	43
BF-Tree Search	Yes	6	0.967	1458
DF-Graph Search	No	20	0.014	21
Depth Limited Search	No	50	0.09	101
Uniform Cost Search	Yes	6	0.04	55
Recursive Best First Search	Yes	6	2.81	4229
Greedy Best First Search	Yes	6	0.005	7

Problem 2 Results:

Strategy	Optimal	Path Length	Time(sec)	Node Expansions
BFS	Yes	9	14.10	3343
BF-Tree Search	-	-	-	-
DF-Graph Search	No	619	3.5175	624
Depth Limited Search	No	50	945.28	222719
Uniform Cost Search	Yes	9	12.51	4852
Recursive Best First Search	-	-	-	-
Greedy Best First Search	Yes	21	2.56	990

Problem 3 Results:

Strategy	Optimal	Path Length	Time(sec)	Node Expansions
BFS	Yes	12	117.22	14663
BF-Tree Search	-	-	-	-
DF-Graph Search	No	392	2.163	408
Depth Limited Search	-	-	-	-
Uniform Cost Search	Yes	12	62.028	18236

Recursive Search	Best	First	-	-	-	-
Greedy Search	Best	First	No	14	12.36	3373

2.1.1 Comparative Analysis

After considering all three (3) scenarios, among un-informed search strategies **Breadth First Search(BFS)** and **Uniform Cost Search** always find the optimal path length. If we need to be hard and fast to find the most optimal path length, I recommend using **BFS** over Uniform Cost Search as BFS is optimal and complete(AIMA-3.4.1). If we only consider time of execution and memory usage and not optimal path length: **Depth First Graph Search** outperforms among all and it's next best alternative would be Greedy Best First Search. This result doesn't come as a surprise after studying through the performance comparison below(AIMA-3.4.7) of these strategies.

3.4.7 Comparing uninformed search strategies

Figure 3.21 compares search strategies in terms of the four evaluation criteria set forth in Section 3.3.2. This comparison is for tree-search versions. For graph searches, the main differences are that depth-first search is complete for finite state spaces and that the space and time complexities are bounded by the size of the state space.

Criterion	Breadth-First	Uniform-Cost	Depth-First	Depth-Limited	Iterative Deepening	Bidirectional (if applicable)
Complete?	Yes ^a	Yes ^{a,b}	No	No	Yes ^a	Yes ^{a,d}
Time	$O(b^d)$	$O(b^{1+ C^*/\epsilon })$	$O(b^m)$	$O(b^l)$	$O(b^d)$	$O(b^{d/2})$
Space	$O(b^d)$	$O(b^{1+ C^*/\epsilon })$	$O(bm)$	$O(bl)$	$O(bd)$	$O(b^{d/2})$
Optimal?	Yes ^c	Yes	No	No	Yes ^c	Yes ^{c,d}

Figure 3.21 Evaluation of tree-search strategies. b is the branching factor; d is the depth of the shallowest solution; m is the maximum depth of the search tree; l is the depth limit. Superscript caveats are as follows: ^a complete if b is finite; ^b complete if step costs $\geq \epsilon$ for positive ϵ ; ^c optimal if step costs are all identical; ^d if both directions use breadth-first search.

2.2 Informed Search Strategies:

Problem 1 Results:

Strategy	Optimal	Path Length	Time(sec)	Node Expansions
A* Search with h1 heuristic	Yes	6	0.03	55
A* Search with Ignore Preconditions heuristic	Yes	6	0.047	41
A* Search with Level Sum heuristic	Yes	6	0.847	11

Problem 2 Results:

Strategy	Optimal	Path Length	Time(sec)	Node Expansions
A* Search with h1 heuristic	Yes	9	12.743	4852
A* Search with Ignore Preconditions heuristic	Yes	9	4.397	1450
A* Search with Level Sum heuristic	Yes	9	76.405	86

Problem 3 Results:

Strategy	Optimal	Path Length	Time(sec)	Node Expansions
A* Search with h1 heuristic	Yes	12	83.482	18236
A* Search with Ignore Preconditions heuristic	Yes	12	31.378	5040
A* Search with Level Sum heuristic	Yes	12	558.294	403

2.2.1 Comparative Analysis:

After considering all three (3) scenarios, all A* search strategies with heuristics yield and optimal solution. **A* Search with Ignore Preconditions heuristic** is the best when considering the execution time and **A* Search with Level Sum heuristic** is the best when considering the memory usage.

3. Final Analysis Recommendation

For Solution 3:

Strategy	Optimal	Path Length	Time(sec)	Node Expansions
BFS	Yes	12	117.22	14663
A* Search with Ignore Preconditions heuristic	Yes	12	31.378	5040

Whilst comparison among Informed & Un-Informed Search strategies recommendations of **Breadth First Search** and **A* Search with Ignore Preconditions heuristic**, it's the [A*](#) that outperforms BFS in terms of time and node expansions and is more optimal.

4. APPENDIX

4.1 Results for Problem-1 using for all the heuristics 1-10

```
(/Users/tnuthalapati/anaconda/envs/aind) BELC02R1223G8WN:AIND-Planning tnuthalapati$ python run_search.py -p 1 -s 1 2 3

Solving Air Cargo Problem 1 using breadth_first_search...

Expansions   Goal Tests   New Nodes
    43         56       180

Plan length: 6 Time elapsed in seconds: 0.031340790999820456
Load(C1, P1, SF0)
Load(C2, P2, JFK)
Fly(P2, JFK, SF0)
Unload(C2, P2, SF0)
Fly(P1, SF0, JFK)
Unload(C1, P1, JFK)

Solving Air Cargo Problem 1 using breadth_first_tree_search...

Expansions   Goal Tests   New Nodes
    1458       1459     5960

Plan length: 6 Time elapsed in seconds: 0.9671830959996441
Load(C1, P1, SF0)
Load(C2, P2, JFK)
Fly(P2, JFK, SF0)
Unload(C2, P2, SF0)
Fly(P1, SF0, JFK)
Unload(C1, P1, JFK)

Solving Air Cargo Problem 1 using depth_first_graph_search...

Expansions   Goal Tests   New Nodes
    21         22      84

Plan length: 20 Time elapsed in seconds: 0.014235555005143397
Fly(P1, SF0, JFK)
Fly(P2, JFK, SF0)
Load(C2, P1, JFK)
Fly(P1, JFK, SF0)
Fly(P2, SF0, JFK)
Unload(C2, P1, SF0)
Fly(P1, SF0, JFK)
Fly(P2, JFK, SF0)
Load(C2, P2, SF0)
Fly(P1, JFK, SF0)
Load(C1, P2, SF0)
Fly(P2, SF0, JFK)
Fly(P1, SF0, JFK)
Unload(C2, P2, JFK)
Unload(C1, P2, JFK)
Fly(P2, JFK, SF0)
Load(C2, P1, JFK)
Fly(P1, JFK, SF0)
Fly(P2, SF0, JFK)
Unload(C2, P1, SF0)
```

Solving Air Cargo Problem 1 using depth_limited_search...

```
Plan length: 50 Time elapsed in seconds: 0.09232856999733485
```

```
Fly(P2, JFK, SF0)
Unload(C2, P2, SF0)
Fly(P1, SF0, JFK)
Unload(C1, P1, JFK)
```

```
(/Users/tnuthalapati/anaconda/envs/aind) BELC02R1223G8W:N:AIND-Planning tnuthalapati$ python run_search.py -p 1 -s 5 6 7 8
```

Solving Air Cargo Problem 1 using uniform_cost_search...

Expansions	Goal Tests	New Nodes
55	57	224

Plan length: 6 Time elapsed in seconds: 0.04177670400531497

```
Load(C1, P1, SF0)
Load(C2, P2, JFK)
Fly(P1, SF0, JFK)
Fly(P2, JFK, SF0)
Unload(C1, P1, JFK)
Unload(C2, P2, SF0)
```

Solving Air Cargo Problem 1 using recursive_best_first_search with h_1...

Expansions	Goal Tests	New Nodes
4229	4230	17023

Plan length: 6 Time elapsed in seconds: 2.815006757999072

```
Load(C2, P2, JFK)
Load(C1, P1, SF0)
Fly(P2, JFK, SF0)
Unload(C2, P2, SF0)
Fly(P1, SF0, JFK)
Unload(C1, P1, JFK)
```

Solving Air Cargo Problem 1 using greedy_best_first_graph_search with h_1...

Expansions	Goal Tests	New Nodes
7	9	28

Plan length: 6 Time elapsed in seconds: 0.005308961990522221

```
Load(C1, P1, SF0)
Load(C2, P2, JFK)
Fly(P1, SF0, JFK)
Fly(P2, JFK, SF0)
Unload(C1, P1, JFK)
Unload(C2, P2, SF0)
```

Solving Air Cargo Problem 1 using astar_search with h_1...

Expansions	Goal Tests	New Nodes
55	57	224

Plan length: 6 Time elapsed in seconds: 0.0434651100076735

```
Load(C1, P1, SF0)
Load(C2, P2, JFK)
Fly(P1, SF0, JFK)
Fly(P2, JFK, SF0)
Unload(C1, P1, JFK)
Unload(C2, P2, SF0)
```

```
(/Users/tnuthalapati/anaconda/envs/aind) BELC02R1223G8WN:AIND-Planning tnuthalapati$ python run_search.py -p 1 -s 9
Solving Air Cargo Problem 1 using astar_search with h_ignore_preconditions...

Expansions   Goal Tests   New Nodes
    41         43       170

Plan length: 6 Time elapsed in seconds: 0.04775216500274837
Load(C1, P1, SF0)
Fly(P1, SF0, JFK)
Unload(C1, P1, JFK)
Load(C2, P2, JFK)
Fly(P2, JFK, SF0)
Unload(C2, P2, SF0)
```

```
(/Users/tnuthalapati/anaconda/envs/aind) BELC02R1223G8WN:AIND-Planning tnuthalapati$ python run_search.py -p 1 -s 10
Solving Air Cargo Problem 1 using astar_search with h_pg_levelsum...

Expansions   Goal Tests   New Nodes
    11         13       50

Plan length: 6 Time elapsed in seconds: 0.8472066940157674
Load(C1, P1, SF0)
Fly(P1, SF0, JFK)
Load(C2, P2, JFK)
Fly(P2, JFK, SF0)
Unload(C1, P1, JFK)
Unload(C2, P2, SF0)
```

4.2 Results for Problem-2 using for all the heuristics 1-10

```
(/Users/tnuthalapati/anaconda/envs/aind) BELC02R1223G8WN:AIND-Planning tnuthalapati$ python run_search.py -p 2 -s 1 2 3
Solving Air Cargo Problem 2 using breadth_first_search...

Expansions   Goal Tests   New Nodes
   3343       4609   30509

Plan length: 9 Time elapsed in seconds: 14.104584180997335
Load(C1, P1, SF0)
Load(C2, P2, JFK)
Load(C3, P3, ATL)
Fly(P2, JFK, SF0)
Unload(C2, P2, SF0)
Fly(P1, SF0, JFK)
Unload(C1, P1, JFK)
Fly(P3, ATL, SF0)
Unload(C3, P3, SF0)

Solving Air Cargo Problem 2 using breadth_first_tree_search...
^Z
[1]+  Stopped                  python run_search.py -p 2 -s 1 2 3
(/Users/tnuthalapati/anaconda/envs/aind) BELC02R1223G8WN:AIND-Planning tnuthalapati$ python run_search.py -p 2 -s 3
Solving Air Cargo Problem 2 using depth_first_graph_search...

Expansions   Goal Tests   New Nodes
    624       625    5602

Plan length: 619 Time elapsed in seconds: 3.5175055869913194
Fly(P3, ATL, SF0)
Fly(P1, SF0, ATL)
Fly(P3, SF0, JFK)
Fly(P1, ATL, JFK)
Fly(P2, JFK, ATL)
Fly(P3, JFK, ATL)
Fly(P2, ATL, SF0)
```

```
(/Users/tnuthalapati/anaconda/envs/aind) BELC02R1223G8MN:AIND-Planning tnuthalapati$ python run_search.py -p 2 -s 4

Solving Air Cargo Problem 2 using depth_limited_search...

Expansions   Goal Tests   New Nodes
    222719      2053741      2054119

Plan length: 50 Time elapsed in seconds: 945.2863207619957
Load(C1, P1, SF0)
Load(C2, P2, JFK)
Load(C3, P3, ATL)
Unload(C1, P1, SF0)
Load(C1, P1, SF0)
Unload(C1, P1, SF0)
```

```
(/Users/tnuthalapati/anaconda/envs/aind) BELC02R1223G8MN:AIND-Planning tnuthalapati$ python run_search.py -p 2 -s 5

Solving Air Cargo Problem 2 using uniform_cost_search...

Expansions   Goal Tests   New Nodes
    4852      4854      44030

Plan length: 9 Time elapsed in seconds: 12.507718041000771
Load(C1, P1, SF0)
Load(C2, P2, JFK)
Load(C3, P3, ATL)
Fly(P1, SF0, JFK)
Fly(P2, JFK, SF0)
Fly(P3, ATL, SF0)
Unload(C3, P3, SF0)
Unload(C2, P2, SF0)
Unload(C1, P1, JFK)
```

```
(/Users/tnuthalapati/anaconda/envs/aind) BELC02R1223G8MN:AIND-Planning tnuthalapati$ python run_search.py -p 2 -s 6

Solving Air Cargo Problem 2 using recursive_best_first_search with h_1...
^Z
[1]+  Stopped                  python run_search.py -p 2 -s 6
(/Users/tnuthalapati/anaconda/envs/aind) BELC02R1223G8MN:AIND-Planning tnuthalapati$ python run_search.py -p 2 -s 7
```

Solving Air Cargo Problem 2 using greedy_best_first_graph_search with h_1...

```
Expansions   Goal Tests   New Nodes
    990      992      8910

Plan length: 21 Time elapsed in seconds: 2.5605853330052923
Load(C1, P1, SF0)
Load(C2, P2, JFK)
Load(C3, P3, ATL)
Fly(P1, SF0, ATL)
Fly(P2, JFK, ATL)
Fly(P3, ATL, JFK)
Fly(P2, ATL, SF0)
Unload(C2, P2, SF0)
Fly(P2, SF0, ATL)
Fly(P3, JFK, SF0)
Load(C2, P3, SF0)
Fly(P3, SF0, JFK)
Fly(P1, ATL, JFK)
Unload(C1, P1, JFK)
Load(C1, P3, JFK)
Fly(P1, JFK, ATL)
Fly(P3, JFK, SF0)
Unload(C3, P3, SF0)
Unload(C2, P3, SF0)
Fly(P3, SF0, JFK)
Unload(C1, P3, JFK)
```

```
(/Users/tnuthalapati/anaconda/envs/aind) BELC02R1223G8WN:AIND-Planning tnuthalapati$ python run_search.py -p 2 -s 8
```

Solving Air Cargo Problem 2 using astar_search with h₁...

Expansions	Goal Tests	New Nodes
4852	4854	44030

Plan length: 9 Time elapsed in seconds: 12.74289013100497

```
Load(C1, P1, SF0)
Load(C2, P2, JFK)
Load(C3, P3, ATL)
Fly(P1, SF0, JFK)
Fly(P2, JFK, SF0)
Fly(P3, ATL, SF0)
Unload(C3, P3, SF0)
Unload(C2, P2, SF0)
Unload(C1, P1, JFK)
```

```
(/Users/tnuthalapati/anaconda/envs/aind) BELC02R1223G8WN:AIND-Planning tnuthalapati$ python run_search.py -p 2 -s 9
```

Solving Air Cargo Problem 2 using astar_search with h_{ignore_preconditions}...

Expansions	Goal Tests	New Nodes
1450	1452	13303

Plan length: 9 Time elapsed in seconds: 4.397033620000002

```
Load(C3, P3, ATL)
Fly(P3, ATL, SF0)
Unload(C3, P3, SF0)
Load(C2, P2, JFK)
Fly(P2, JFK, SF0)
Unload(C2, P2, SF0)
Load(C1, P1, SF0)
Fly(P1, SF0, JFK)
Unload(C1, P1, JFK)
```

```
(/Users/tnuthalapati/anaconda/envs/aind) BELC02R1223G8WN:AIND-Planning tnuthalapati$ python run_search.py -p 2 -s 10
```

Solving Air Cargo Problem 2 using astar_search with h_{pg_levelsum}...

Expansions	Goal Tests	New Nodes
86	88	841

Plan length: 9 Time elapsed in seconds: 76.40491897700122

```
Load(C1, P1, SF0)
Fly(P1, SF0, JFK)
Load(C2, P2, JFK)
Fly(P2, JFK, SF0)
Load(C3, P3, ATL)
Fly(P3, ATL, SF0)
Unload(C3, P3, SF0)
Unload(C2, P2, SF0)
Unload(C1, P1, JFK)
```

4.3 Results for Problem-3 using for all the heuristics 1-10

```
(/Users/tnuthalapati/anaconda/envs/aind) BELC02R1223G8WN:AIND-Planning tnuthalapati$ python run_search.py -p 3 -s 1

Solving Air Cargo Problem 3 using breadth_first_search...

Expansions   Goal Tests   New Nodes
    14663         18098       128605

Plan length: 12 Time elapsed in seconds: 117.21889737099991
Load(C1, P1, SF0)
Load(C2, P2, JFK)
Fly(P2, JFK, ORD)
Load(C4, P2, ORD)
Fly(P1, SF0, ATL)
Load(C3, P1, ATL)
Fly(P1, ATL, JFK)
Unload(C1, P1, JFK)
Unload(C3, P1, JFK)
Fly(P2, ORD, SF0)
Unload(C2, P2, SF0)
Unload(C4, P2, SF0)
```

```
(/Users/tnuthalapati/anaconda/envs/aind) BELC02R1223G8WN:AIND-Planning tnuthalapati$ python run_search.py -p 3 -s 3

Solving Air Cargo Problem 3 using depth_first_graph_search...

Expansions   Goal Tests   New Nodes
     408         409       3364

Plan length: 392 Time elapsed in seconds: 2.1629074160009623
Fly(P1, SF0, ORD)
Fly(P2, JFK, ORD)
Fly(P1, ORD, ATL)
Fly(P2, ORD, ATL)
Fly(P1, ATL, JFK)
Fly(P2, ATL, SF0)
Load(C2, P1, JFK)
Fly(P2, SF0, ORD)
Fly(P1, JFK, ORD)
Fly(P2, ORD, ATL)
Fly(P1, ORD, ATL)
Fly(P2, ATL, JFK)
Fly(P1, ATL, SF0)
Unload(C2, P1, SF0)
Fly(P1, SF0, ORD)
Fly(P2, JFK, ORD)
Fly(P1, ORD, ATL)
Fly(P2, ORD, ATL)
Fly(P1, ATL, JFK)
```

```
(/Users/tnuthalapati/anaconda/envs/aind) BELC02R1223G8WN:AIND-Planning tnuthalapati$ python run_search.py -p 3 -s 5

Solving Air Cargo Problem 3 using uniform_cost_search...

Expansions   Goal Tests   New Nodes
    18236         18238       158282

Plan length: 12 Time elapsed in seconds: 62.02808952500345
Load(C1, P1, SF0)
Load(C2, P2, JFK)
Fly(P1, SF0, ATL)
Load(C3, P1, ATL)
Fly(P2, JFK, ORD)
Load(C4, P2, ORD)
Fly(P2, ORD, SF0)
Fly(P1, ATL, JFK)
Unload(C4, P2, SF0)
Unload(C3, P1, JFK)
Unload(C2, P2, SF0)
Unload(C1, P1, JFK)
```

```
(/Users/tnuthalapati/anaconda/envs/aind) BELC02R1223G8WN:AIND-Planning tnuthalapati$ python run_search.py -p 3 -s 7
```

Solving Air Cargo Problem 3 using greedy_best_first_graph_search with h_1...

Expansions	Goal Tests	New Nodes
3373	3375	28945

Plan length: 14 Time elapsed in seconds: 12.355338275025133

```
Load(C1, P1, SF0)
Load(C2, P2, JFK)
Fly(P1, SF0, ATL)
Load(C3, P1, ATL)
Fly(P2, JFK, ORD)
Load(C4, P2, ORD)
Fly(P2, ORD, ATL)
Fly(P1, ATL, JFK)
Unload(C3, P1, JFK)
Unload(C1, P1, JFK)
Fly(P1, JFK, ATL)
Fly(P2, ATL, SF0)
Unload(C4, P2, SF0)
Unload(C2, P2, SF0)
```

```
(/Users/tnuthalapati/anaconda/envs/aind) BELC02R1223G8WN:AIND-Planning tnuthalapati$ python run_search.py -p 3 -s 8
```

Solving Air Cargo Problem 3 using astar_search with h_1...

Expansions	Goal Tests	New Nodes
18236	18238	158282

Plan length: 12 Time elapsed in seconds: 83.48219851899194

```
Load(C1, P1, SF0)
Load(C2, P2, JFK)
Fly(P1, SF0, ATL)
Load(C3, P1, ATL)
Fly(P2, JFK, ORD)
Load(C4, P2, ORD)
Fly(P2, ORD, SF0)
Fly(P1, ATL, JFK)
Unload(C4, P2, SF0)
Unload(C3, P1, JFK)
Unload(C2, P2, SF0)
Unload(C1, P1, JFK)
```



```
(/Users/tnuthalapati/anaconda/envs/aind) BELC02R1223G8WN:AIND-Planning tnuthalapati$ python run_search.py -p 3 -s 9
```

Solving Air Cargo Problem 3 using astar_search with h_ignore_preconditions...

Expansions	Goal Tests	New Nodes
5040	5042	44769

Plan length: 12 Time elapsed in seconds: 31.378003905003425

```
Load(C2, P2, JFK)
Fly(P2, JFK, ORD)
Load(C4, P2, ORD)
Fly(P2, ORD, SF0)
Unload(C4, P2, SF0)
Load(C1, P1, SF0)
Fly(P1, SF0, ATL)
Load(C3, P1, ATL)
Fly(P1, ATL, JFK)
Unload(C3, P1, JFK)
Unload(C2, P2, SF0)
Unload(C1, P1, JFK)
```

```
(/Users/tnuthalapati/anaconda/envs/aind) BELC02R1223G8WN:AIND-Planning tnuthalapati$ python run_search.py -p 3 -s 10
```

Solving Air Cargo Problem 3 using astar_search with h_pg_levelsum...

Expansions	Goal Tests	New Nodes
403	405	3703

Plan length: 12 Time elapsed in seconds: 558.2942133890174

```
Load(C2, P2, JFK)
Fly(P2, JFK, ORD)
Load(C4, P2, ORD)
Fly(P2, ORD, SF0)
Load(C1, P1, SF0)
Fly(P1, SF0, ATL)
Load(C3, P1, ATL)
Fly(P1, ATL, JFK)
Unload(C4, P2, SF0)
Unload(C3, P1, JFK)
Unload(C2, P2, SF0)
Unload(C1, P1, JFK)
```