

Summarizing Visual Data Using Bidirectional Similarity

Team Name - LTMG

Project ID - 12

Repository :

<https://github.com/Computer-Vision-IIIIT-2021/project-lmtg>

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Outline of The Paper-(1/3)

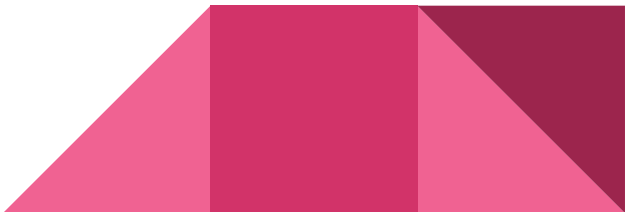
- We propose a principled approach to summarization of visual data (images or video) i.e storing the “important” visual content in a smaller image generated exploiting the data redundancy.
- This can be done based on optimization of a well-defined similarity measure. A good “visual summary” should contain as much as possible visual information from the input data and also shouldn't not introduce new visual artifacts that were not in the input data
- We have an objective function which has constraints as follows:
 - Two signals S and T are considered visually similar if all patches of S (at multiple scales) are contained in T , and vice versa.



Outline of The Paper(2/3)

- The objective function is as follows:

$$d(S, T) = \frac{1}{N_S} \sum_{P \subset S} \min_{Q \subset T} D(P, Q) + \frac{1}{N_T} \sum_{Q \subset T} \min_{P \subset S} D(Q, P)$$

- Here S,T are two signals and P,Q are subsets of S and T respectively which are considered as patches.
 - We are calculating Sum of Squared distances between every 2 patches P,Q
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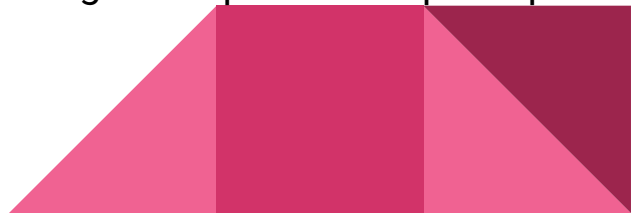
Outline of the Paper(3/3)

- The algorithm is as follows:-
 - There are 2 aspects to this algorithm-Completeness and coherence.
 - Assume S,T are 2 signals, if all patches of S(Source) are in T then T is complete even though T has new aspects introduced (if any)
 - Similarly if all patches in T are present in S without new patches being introduced then T is coherent.
- Our algorithm deals with image summarization such that the output image is both complete and coherent.

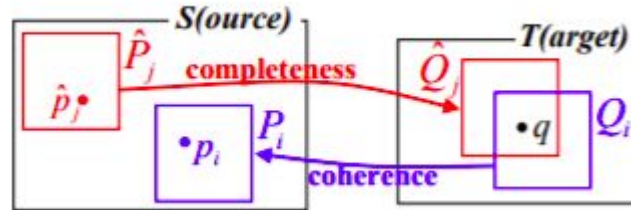


Method Overview(1/3):-

- Let $q \in T$ be a pixel in T , and let $T(q)$ denote its color.
- We calculate distance, $d(S(\text{source}), T(\text{target}))$ by adding both coherence term and complete term in it.
- We minimize this distance as follows:
 - Error every pixel $q \in T$ contributes to coherence term and complete term can be calculated as follows:-
 - Let Q_1, \dots, Q_m denote all the patches in T that contain pixel q and P_1, \dots, P_m denote the corresponding (most similar) patches in S (i.e., $P_i = \arg \min_{P \in S} D(P, Q_i)$).
 - Let p_1, \dots, p_m be the pixels in P_1, \dots, P_m corresponding to the position of pixel q within Q_1, \dots, Q_m .



Method Overview-(2/3)



$$\frac{1}{N_S} \sum_{j=1}^n (S(\hat{p}_j) - T(q))^2 \quad \text{-the coherence term} \quad \frac{1}{N_T} \sum_{i=1}^m (S(p_i) - T(q))^2 \quad \text{-complete term}$$

Error or dissimilarity measure would be sum of these two. We differentiate this error term to find $T(q)$ which minimizes this expression to get

$$T(q) = \frac{\frac{1}{N_S} \sum_{j=1}^n S(\hat{p}_j) + \frac{1}{N_T} \sum_{i=1}^m S(p_i)}{\frac{n}{N_S} + \frac{m}{N_T}}$$

Method Overview-(3/3)

The above can be achieved as follows:-

Given the target image $T(l)$ obtained in the l -th iteration, we compute the colors of the target image $T(l+1)$ as follows:

1. For each target patch $Q \subset T(l)$ find the most similar source patch $P \subset S$ (minimize $D(P, Q)$). Colors of pixels in P are votes for pixels in Q with weight $1/NT$.
2. In the opposite direction: for each $P^{\wedge} \subset S$ find the most similar $Q^{\wedge} \subset T(l)$. Pixels in P^{\wedge} vote for pixels in Q^{\wedge} with weight $1/NS$.
3. For each target pixel q take weighted average of all its votes as its new color $T(l+1)(q)$. (Color votes $S(\pi_i)$ are found in step 1, $S^{\wedge}(\pi_i)$ in step 2.)

We iterate till we get a convergence point which would be output of image
summary



Goals-To perform Image Summarization

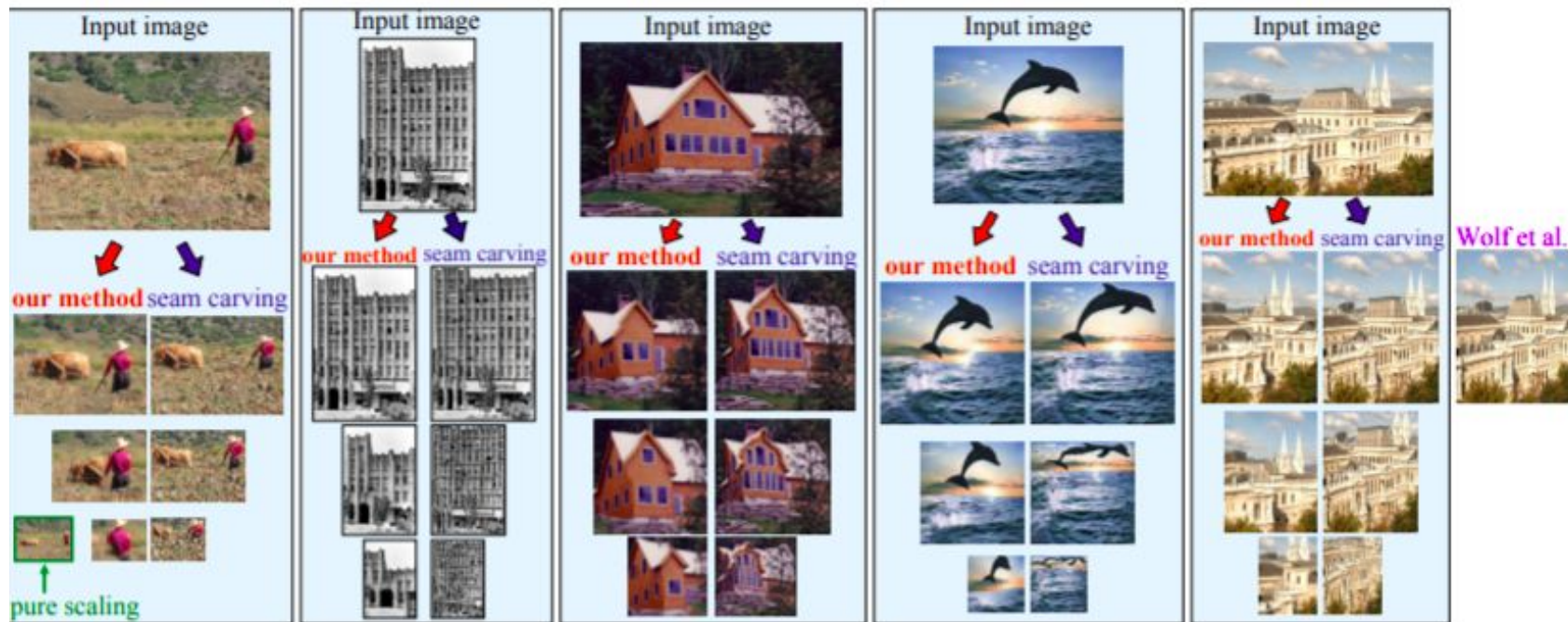


Figure 6. **Image summarization results.** Our method exploits redundancies in the images (bushes, waves, windows of the buildings, etc.), often creating coherently-looking images even for extremely small target sizes. “Seam Carving” prefers to remove low-gradient pixels, thus distorts the image considerably at small sizes, when there are no more low-gradient pixels left. Please view video on demo website. The Dolphin image is from Avidan and Shamir [1], the right-most building image from Wolf et al. [16].

Applications of this approach

- Image/video summarization
- Data completion and removal
- Image synthesis
- Image collage
- Photo reshuffling
- Auto-cropping



Image montage result

Input 2



Input 3



Input 1



Output montage

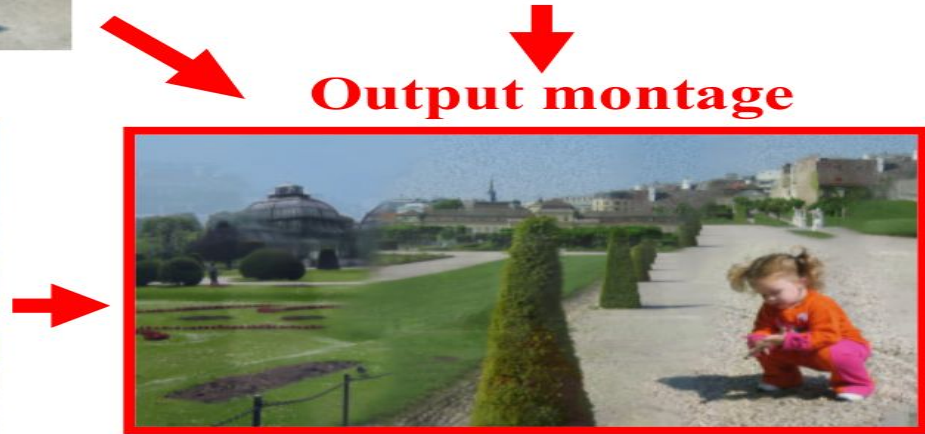
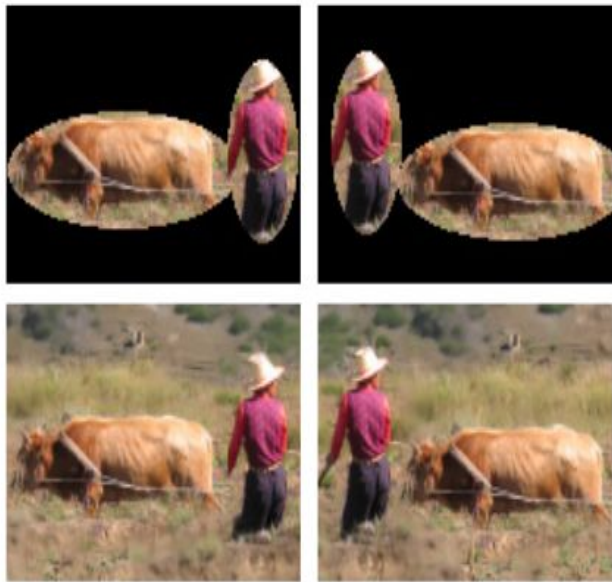


Photo reshuffling

Reshuffle 1 Reshuffle 2



Input



Output

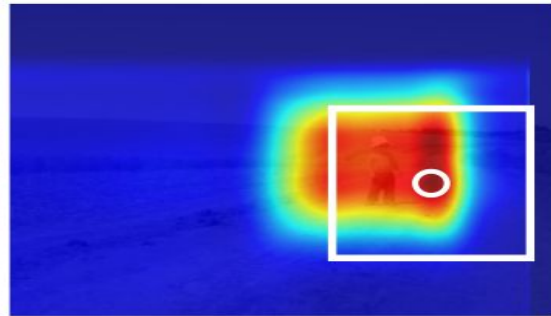


Automatic optimal cropping

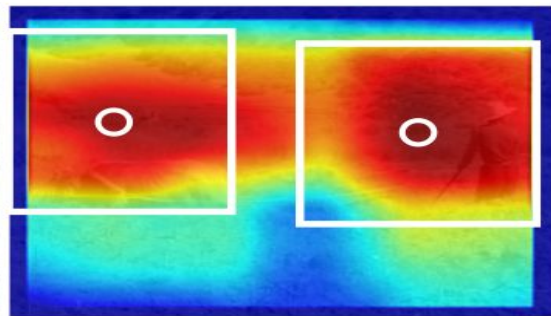
(a) Input image



(b) Bidirectional similarity map



(c) Detected optimal cropping



Incorporating non-uniform importance

Input image



Importance weights



**Our summary
without weights**



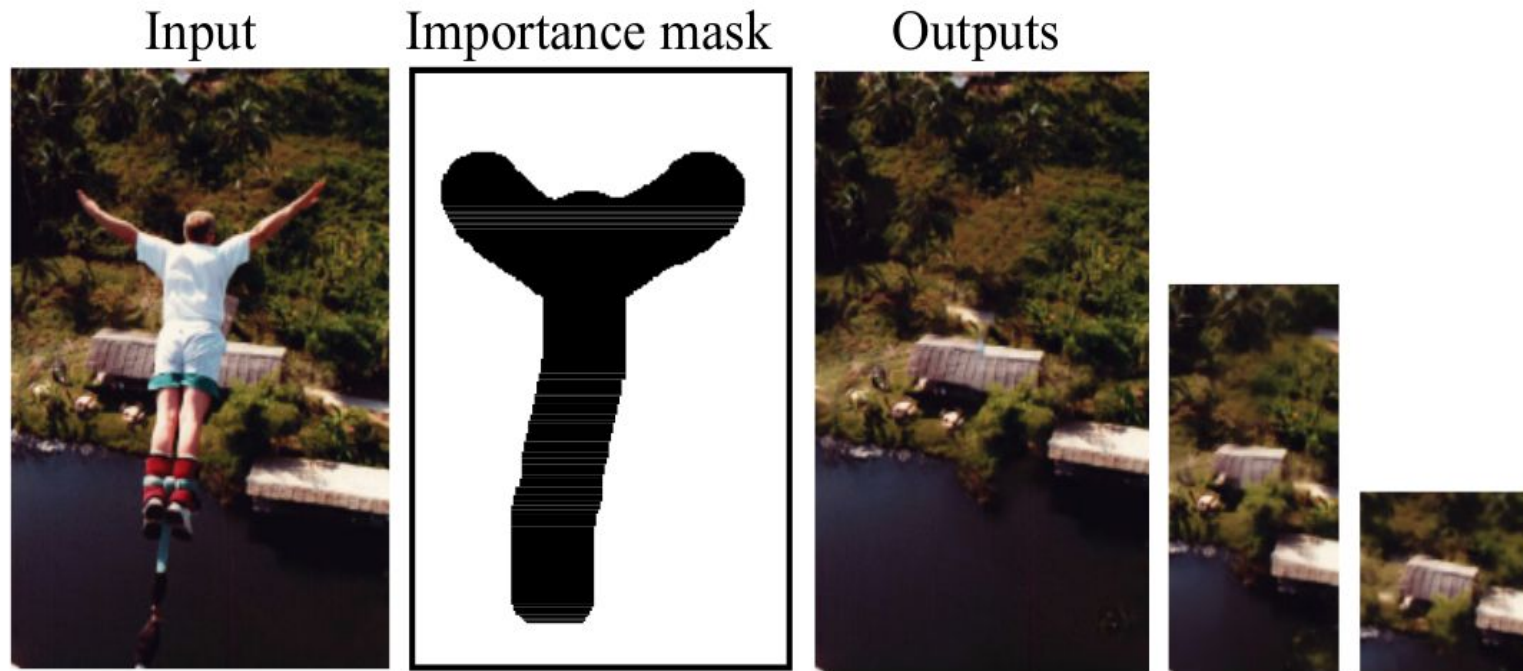
**Our summary
with weights**



**Wolf et al.
(with weights)**



Summarization with object removal constraints



Conclusion

- Includes a bidirectional similarity measure between two images/videos of different sizes.
- Described a principled approach to retargeting and summarization of visual data (images and videos) by optimizing this bidirectional similarity measure.
- And the applications of this approach to image/video summarization, data completion and removal, image synthesis, image collage, photo reshuffling and auto-cropping.



Timeline

Understanding paper in depth and begin to implement paper	25 February
Basic implementation of distance function and debugging	10 March
Rough implementation of the whole algorithm	10 March - 25 March
Final implementation	13 April
Final testing	14 April
Documentation	15 April
Final commit	17 April (approximately)

Deliverables for the mid evaluation, We will going to complete the work up-to the implementation of bidirectional similarity algorithm and present some outputs of how our approach will work on the different applications listed above.

