# Understanding Camera Matrices Using OCaml + Python + E Theorem Prover + Z3-py Prover involving : Smart Devices + IoT + HPC Heterogeneous Systems -> A Simple Technical Notes w.r.t Medical Imaging & Satellites based Imaging.

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# [I] Main Idea + Inspiration + Introduction :

- [a] https://towardsdatascience.com/camera-intrinsic-matrix-with-example-in-python-d79bf2478c12
- [b] https://towardsdatascience.com/camera-extrinsic-matrix-with-example-in-python-cfe80acab8dd

## [II] Python based R&D Informatics Framework Using Above Mentioned Software Tools:

Please take a look @ our Short Technical Communications online on github and just fine tune our Algorithms ->

#### Our direct references:

- [i] https://github.com/tejdnk-2019-ShortNotes/tejdnk-Space-Medicine-Informatics-github.io/blob/master/Inceptionv3-OCaml-Python-21.pdf\*\*
- [ii] https://github.com/tejdnk-2019-ShortNotes/2021-Nir-Informatics/blob/main/OCaml-C-llvm-Inceptionv3-Nir-21.pdf\*\*

# [III] Important & Useful References:

- [a] https://en.wikipedia.org/wiki/Camera\_resectioning
- [b] https://wwwlehre.dhbw-stuttgart.de/~sschulz/E/E.html
- [c] https://ericpony.github.io/z3py-tutorial/guide-examples.htm
- [d] https://github.com/tejdnk-2019-ShortNotes -> Plenty of examples for your use -> Just Fine Tune our Algorithms Thanks Nirmal.
- [e] http://imageai.org/ && [f] https://deepstack.cc/ && https://www.cs.tau.ac.il/~msagiv/courses/asv/z3py/guide-examples.htm\*
- [g] https://www.vixra.org/pdf/1910.0009v1.pdf \*\*\*\*\*
- [h] https://www.cs.tau.ac.il/~msagiv/courses/asv/z3py/strategies-examples.htm\*

#### [IV] Acknowledgment/s:

 $Since \textit{Thanks to all WHO made this happen in my \textit{LIFE}. Non-Profit~R\&D. Inspire others~always. \\$ 

# $[V] \ Conclusion/s \ with \ Future \ Perspectives:$

As usual - We are putting forward one of the pioneering R&D Efforts in totally different way.Rigorous Testing in Progress @ the TIME of Submission.Theorem Proving and Image Processing is always one of the BEST Choices in Medicine & Space Image Processing Domains.

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