STAMATICS Mini Project 2

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1 Problem Statement

We observe multinomial data with parameters n, \mathbf{x} and \mathbf{p} (K dimensional) such that

$$\mathbf{x} = (x_1, \dots, x_K) \sim Multi(p_1, \dots, p_K), \qquad x_i \in \{0, \dots, n\} \text{ and } \sum_{i=1}^n x_i = n$$

$$Pr(\mathbf{x} = (x_1, \dots, x_K) \mid \mathbf{p}) = \frac{n!}{x_1! \dots x_K!} \prod_{i=1}^K p_i^{x_i}, \qquad \sum_{i=1}^K p_i = 1$$

We are also given the MLE of p_i as

$$\hat{p_i} = \frac{x_i}{n}$$

Now, we have to estimate **p** using Bayesian method taking Dirichlet as the prior distribution of **p** with $\alpha_i > 0$ as parameters.

Prior Distribution:
$$\mathbf{p} = (p_1, \dots, p_K) \sim Dir(\alpha_1, \dots, \alpha_K), \quad p_i \in (0, 1) \text{ and } \sum_{i=1}^n p_i = 1$$

$$f(\mathbf{p} = (p_1, \dots, p_K) \mid \alpha) = \frac{\Gamma(\sum_{i=1}^K \alpha_i)}{\prod_{i=1}^K \Gamma(\alpha_i)} \prod_{i=1}^K p_i^{\alpha_i - 1}, \quad (\alpha_i > 0)$$

(Here, f is the probability density function.)

2 Posterior Distribution of p

We need to calculate $f(\mathbf{p}|\mathbf{x})$ (the posterior distribution of \mathbf{p}). By applying Bayes theorem to probability distribution function, we know

$$f(\mathbf{p}|\mathbf{x}) = \frac{f(\mathbf{x}|\mathbf{p}) \cdot f(\mathbf{p})}{f(\mathbf{x})}$$

Here, $f(\mathbf{x})$ is the normalising constant and $f(\mathbf{x}|\mathbf{p})$ is proportional to the Likelihood function $Pr(\mathbf{x}|\mathbf{p})$ which gives us the following proportionality relation:

$$f(\mathbf{p}|\mathbf{x}) \propto Pr(\mathbf{x}|\mathbf{p}) \cdot f(\mathbf{p})$$

$$\propto \left(\prod_{i=1}^{K} p_i^{x_i}\right) \left(\prod_{i=1}^{K} p_i^{\alpha_i - 1}\right)$$

$$\propto \left(\prod_{i=1}^{K} p_i^{x_i + \alpha_i - 1}\right)$$

The above expression is that of Dirichlet distribution, so we get the posterior distribution as

Posterior Distribution:
$$\mathbf{p}|\mathbf{x} = (p_1^{'}, \dots, p_K^{'}) \sim Dir(\alpha_1 + x_1, \dots, \alpha_K + x_K)$$

Thus, posterior distribution of \mathbf{p} is also Dirichlet with updated parameters, which are updated according to data available.

3 Posterior Mean of p

Let us first calculate the prior mean of \mathbf{p} which is given by

$$E[\mathbf{p}] = \int \mathbf{p} \cdot f(\mathbf{p}) d\mathbf{p}$$

Since f is a probability density function, we know that $\int f(\mathbf{p})d\mathbf{p} = 1$ for entire space of \mathbf{p} . Also, because of the constraint that $\sum_{i=1}^{K} p_i = 1$, \mathbf{p} will be integrated for only K-1 dimensions (as K^{th} dimension is dependent). Let $\sum_{i=1}^{K} \alpha_i = m$, so $E[p_i]$ will be given by

$$E[p_i] = \int \cdots \int p_i \cdot \frac{\Gamma(m)}{\prod_{i=1}^K \Gamma(\alpha_i)} \prod_{i=1}^K p_i^{\alpha_i - 1} dp_1 \dots dp_{K-1}$$

Let us change the parameters as $\alpha'_{j} = \alpha_{j}$ for $j \neq i$ and $\alpha'_{j} = \alpha_{j} + 1$ for j = i. This will give m' = m + 1. Putting these values in above equation will give

$$E[p_i] = \frac{\Gamma(m)}{\Gamma(m')} \cdot \frac{\Gamma(a_i + 1)}{\Gamma(a_i)} \int \cdots \int \frac{\Gamma(m')}{\prod_{i=1}^K \Gamma(\alpha'_i)} \prod_{i=1}^K p_i^{\alpha'_i - 1} dp_1 \dots dp_{K-1}$$

The integral is integrating f with updated parameters so it will still give 1 and prior mean will be

$$E[p_i] = \frac{\alpha_i}{m}$$

As the posterior distribution differs from prior distribution only in terms of parameters α_i , so posterior mean will be given by

$$E[p_i] = \frac{\alpha_i + x_i}{\sum_{i=1}^k (\alpha_i + x_i)}$$

$$\implies E[p_i] = \frac{\alpha_i + x_i}{\sum_{i=1}^k x_i + \sum_{i=1}^k \alpha_i}$$

$$\implies E[p_i] = \frac{\alpha_i + x_i}{n + m}$$

We can represent the posterior mean as a convex combination of prior mean and MLE of p_i ($=\frac{x_i}{n}$) as follows:

$$E[p_i] = \frac{\alpha_i}{n+m} + \frac{x_i}{n+m}$$

$$\implies E[p_i] = \frac{m}{n+m} \cdot (\frac{\alpha_i}{m}) + \frac{n}{m+n} \cdot (\frac{x_i}{n})$$

$$\implies E[p_i] = \beta \cdot (\frac{\alpha_i}{m}) + (1-\beta) \cdot (\frac{x_i}{n}) \qquad (\beta > 0)$$

The posterior mean is a weighted average between the prior mean and the data mean, so as n increases, posterior mean comes closer to MLE of p_i given by data.

4 IMDB Rating System

We have to prove that the rating used by IMDB can be derived from the model used above.

$$Rating = \frac{n}{n+m}R + \frac{m}{n+m}C$$

Denote the prior probability parameters as \mathbf{p} and posterior probability parameters as \mathbf{p} . The Dirichlet parameters are α_i ($i \in \{1...10\}$) and there sum as m. The number of voters giving rating i to a particular movie are x_i and their sum(i.e total votes for a movie) is n. To get the Rating, we use the posterior mean \mathbf{p} as follows:

$$Rating = \sum_{i=1}^{10} p'_{i} \cdot i$$

$$= \sum_{i=1}^{10} \left(\frac{\alpha_{i} + x_{i}}{n + m}\right) \cdot i$$

$$= \frac{1}{n + m} \sum_{i=1}^{10} (x_{i} \cdot i) + \frac{1}{n + m} \sum_{i=1}^{10} (\alpha_{i} \cdot i)$$

$$= \frac{n}{n + m} \sum_{i=1}^{10} \frac{x_{i}}{n} \cdot i + \frac{m}{n + m} \sum_{i=1}^{10} \frac{\alpha_{i}}{m} \cdot i$$

As given, R is the average rating of the movie based on votes, so we know that

$$R = \sum_{i=1}^{10} \frac{x_i}{n} \cdot i$$

By looking at the rating formula, we can conclude that C is average prior rating given by

$$C = \sum_{i=1}^{10} \frac{\alpha_i}{m} \cdot i$$

Putting the given data ($C=5.5,\,m=2500$), we can say that α_i follow the above linear relation and final rating is given by

$$Rating = \frac{n}{n+m}R + \frac{m}{n+m}C$$

Using the above formula for sorting the movies gives us the following movies as "Top 10":

IMDB ID

- (1) tt5074352
- (2) tt8108198
- (3) tt8291224
- (4) tt1954470
- (5) tt4430212
- (6) tt3322420
- (7) tt2356180
- (8) tt0073707
- (9) tt2283748
- (10) tt2338151

5 References

- [1] http://www.mas.ncl.ac.uk/ nlf8/teaching/mas2317/notes/chapter2.pdf
- [2] http://www.mas.ncl.ac.uk/ nmf16/teaching/mas3301/week6.pdf
- [3] https://dvats.github.io/assets/course/mth511/notes/W12L26_notes.pdf
- [4] http://users.cecs.anu.edu.au/ssanner/MLSS2010/Johnson1.pdf