

Math 3607: Week 14

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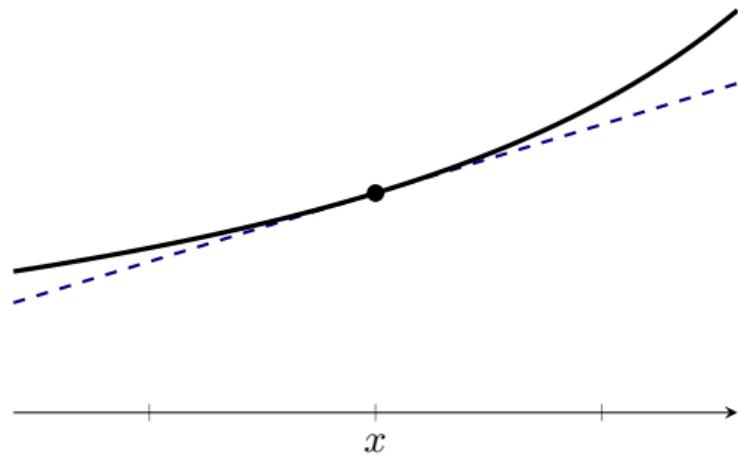
Overview

1 14.1 Numerical Differentiation

2 14.2 Numerical Integration

14.1 Numerical Differentiation

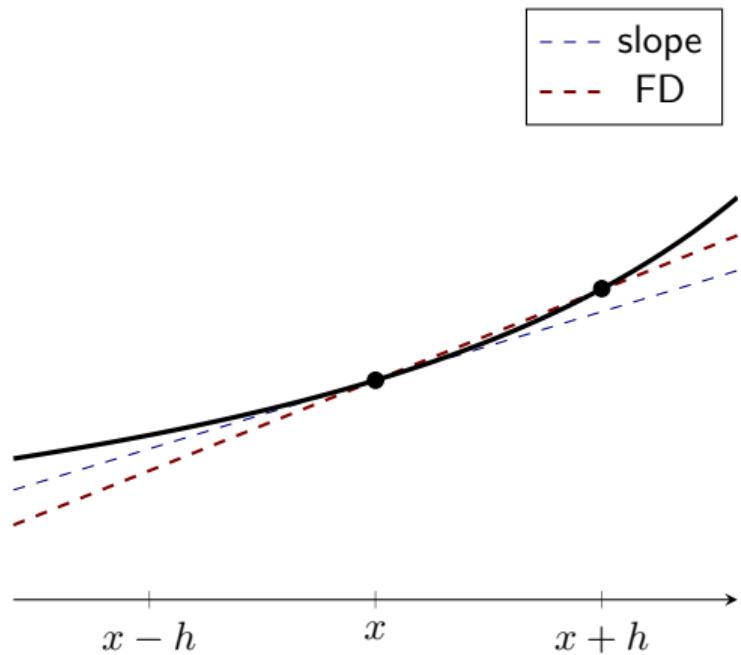
Introduction



Let f be a smooth function. Analytically, the derivative is calculated by

$$D\{f\}(x) = f'(x) = \lim_{h \rightarrow 0} \frac{f(x + h) - f(x)}{h}.$$

Introduction

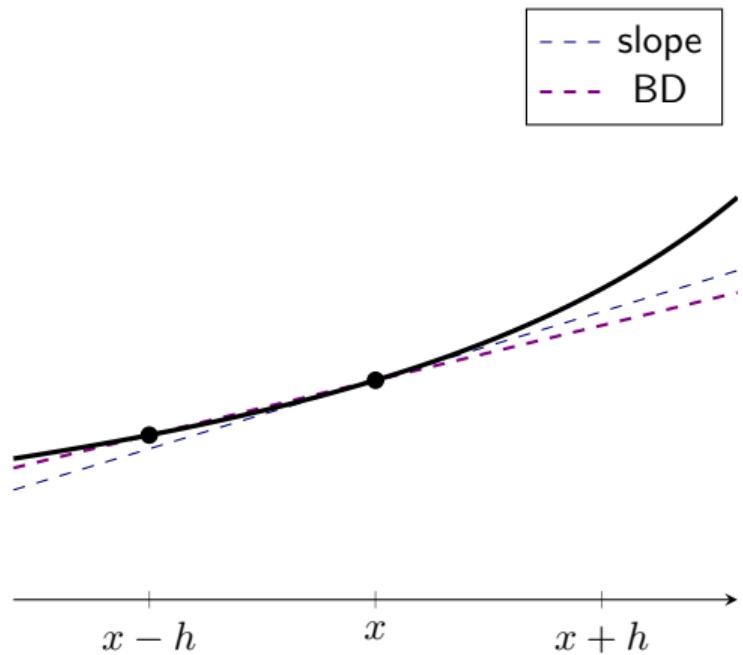


Numerically, $f'(x)$ can be approximately calculated by:

- Forward difference

$$D_h^{[1f]}\{f\}(x) = \frac{f(x+h) - f(x)}{h}$$

Introduction



Numerically, $f'(x)$ can be approximately calculated by:

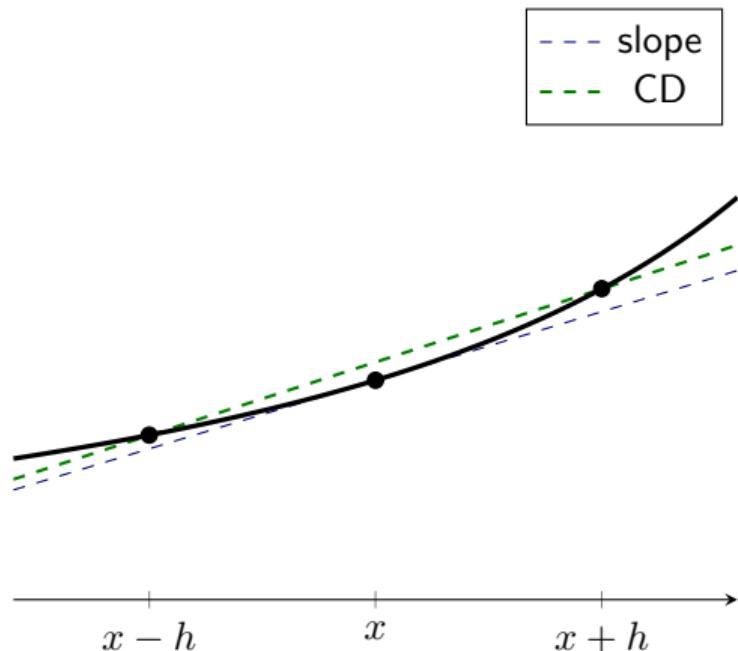
- Forward difference

$$D_h^{[1f]}\{f\}(x) = \frac{f(x + h) - f(x)}{h}$$

- Backward difference

$$D_h^{[1b]}\{f\}(x) = \frac{f(x) - f(x - h)}{h}$$

Introduction



Numerically, $f'(x)$ can be approximately calculated by:

- Forward difference

$$D_h^{[1f]}\{f\}(x) = \frac{f(x + h) - f(x)}{h}$$

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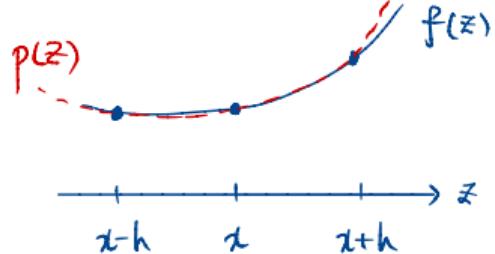
$$D_h^{[1b]}\{f\}(x) = \frac{f(x) - f(x - h)}{h}$$

- Centered difference

$$D_h^{[2c]}\{f\}(x) = \frac{f(x + h) - f(x - h)}{2h}$$

Interpolation and Centered Difference Formula

The centered difference formula can be understood from the viewpoint of 3-point interpolation.



Find the polynomial $p(z)$ satisfying

$$\begin{cases} p(z-h) = f(z-h) = y_1 \\ p(z) = f(z) = y_2 \\ p(z+h) = f(z+h) = y_3 \end{cases}$$

and then use $p'(z)$ to approximate $f'(z)$

Lagrange interp. form.

$$p(z) = y_1 \frac{(z-z)(z-z-h)}{2h^2} l_1 - y_2 \frac{(z-z+h)(z-z-h)}{h^2} l_2 + y_3 \frac{(z-z+h)(z-z)}{2h^2} l_3$$

$$p'(z) = \frac{y_1}{2h^2} [z-z + z-z-h] - \frac{y_2}{h^2} [z-z+h + z-z-h] + \frac{y_3}{2h^2} [z-z+h + z-z]$$

$$\therefore p'(z) = \frac{y_1}{2h^2} (-h) + \frac{y_3}{2h^2} (h) = \frac{y_3 - y_1}{2h} \quad \checkmark$$

Error Analysis – First-Order Difference Formulas

The formula $D_h^{[1f]} \{f\}$ is said to be a **first-order** method because ...

"error"

$$e_h^{[1f]} = D_h^{[1f]} \{f\}(x) - f'(x)$$

$$= \frac{f(x+h) - f(x)}{h} - f'(x)$$

Taylor expand!

$$= \frac{1}{h} \left[f(x) + f'(x)h + \frac{f''(x)}{2} h^2 + \dots - f(x) \right]$$

$$- f'(x)$$

$$= \left[f'(x) + \frac{f''(x)}{2} h + \frac{f'''(x)}{6} h^2 + \dots \right] - f'(x)$$

leading error term

Therefore,

$$e_h^{[1f]} = \frac{f''(x)}{2} h^1 + O(h^2)$$

↑
terms of order
higher than 2

Error Analysis – Second-Order Difference Formulas

The formula $D_h^{[2c]} \{f\}$ is said to be a **second-order** method because ...

First, work out $f(x+h) - f(x-h)$:

$$f(x+h) = \cancel{f(x)} + f'(x)h + \frac{\cancel{f''(x)} h^2}{2} + \frac{f'''(x) h^3}{3!} + \frac{\cancel{f^{(4)}(x)} h^4}{4!} + \dots$$

$$-) \quad f(x-h) = \cancel{f(x)} - f'(x)h + \frac{\cancel{f''(x)} h^2}{2} - \frac{f'''(x) h^3}{3!} + \frac{\cancel{f^{(4)}(x)} h^4}{4!} - \dots$$

$$f(x+h) - f(x-h) = 2f'(x)h + 2 \frac{f'''(x)}{3!} h^3 + \dots$$

So,

$$e_h^{[2c]} = D_h^{[2c]} \{f\}(x) - f'(x) = \frac{2f'(x)h + 2 \frac{f''(x)}{3!} h^3 + 2 \frac{f^{(5)}(x)}{5!} h^5 + \dots}{2h} - f'(x)$$

$$= \frac{2f'(x)h + \frac{2f''(x)}{3!}h^3 + \frac{2f^{(5)}(x)}{5!}h^5 + \dots}{2h} - f'(x)$$

$$= \left(\cancel{f'(x)} + \frac{\cancel{f'''(x)} h^2}{3!} + \frac{f^{(5)}(x) h^4}{5!} + \dots \right) - \cancel{f'(x)}$$

$$= \underbrace{\frac{f''(x)}{3!} h^2}_{\text{leading error}} + \underbrace{O(h^4)}_{\text{term is 2nd-order!}}$$

$\rightarrow 4^{\text{th}}$ -order and higher.

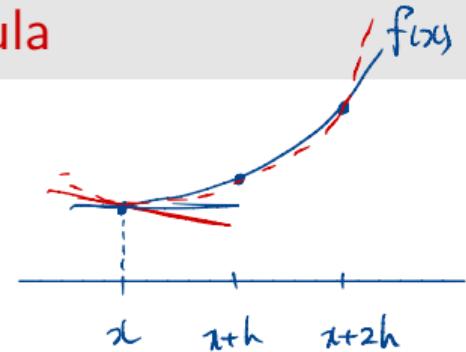
Derivation of Second-Order Forward Difference Formula

Seeking $D_h^{[2f]} \{f\}(x) = a_1 f(x) + a_2 f(x+h) + a_3 f(x+2h)$.

Strategy: Find the polynomial $p(z)$ satisfying

$$p(x) = f(x), \quad p(x+h) = f(x+h), \quad p(x+2h) = f(x+2h).$$

y_1 y_2 y_3



$$(\text{Lagrange}) \quad p(z) = y_1 \frac{(z-x-h)(z-x-2h)}{+2h^2} + y_2 \frac{(z-x)(z-x-2h)}{-h^2} + y_3 \frac{(z-x)(z-x-h)}{2h^2}$$

$$p'(z) = \frac{y_1}{2h^2} (2z - 2x - 3h) + \frac{y_2}{-h^2} (2z - 2x - 2h) + \frac{y_3}{2h^2} (2z - 2x - h)$$

$$\therefore p'(x) = \frac{-3y_1}{2h} + \frac{2y_2}{h} - \frac{y_3}{2h} = \boxed{\frac{-3f(x) + 4f(x+h) - f(x+2h)}{2h}} = D_h^{[2f]} \{f\}(x)$$

Determining Optimal h

* floating point evaluation of $f(x)$:

$$\left| \frac{\hat{f}(x) - f(x)}{f(x)} \right| \leq \frac{1}{2} \boxed{\text{eps}}$$

↑
relative error machine epsilon.

$$\begin{aligned} * |\hat{f}(x)| &= |f(x) + \hat{f}(x) - f(x)| \\ &\leq |f(x)| + |\hat{f}(x) - f(x)| \\ &\stackrel{\text{triangle ineq.}}{\leq} |f(x)| + \frac{1}{2} \boxed{\text{eps}} |f(x)| \end{aligned}$$

$$\Rightarrow \hat{f}(x) = f(x)(1 + \epsilon), \quad |\epsilon| \leq \frac{1}{2} \boxed{\text{eps}}$$

Determine h minimizing

$$\left| \underbrace{D_h^{[2c]} f f'(x)}_{\nearrow} - f'(x) \right|$$

numerical eval.

of $D_h^{[2c]} f f'(x)$

Assume: only round-off errors occur in eval. $f(x \pm h)$

Determining Optimal h

Write:

$$\left\{ \begin{array}{l} \hat{f}(x+h) = f(x+h)(1 + \epsilon_+) \\ \hat{f}(x-h) = f(x-h)(1 + \epsilon_-) \end{array} \right.$$

where $|e \pm 1| \leq \frac{1}{2} \boxed{\text{eps}}$

Their

$$\hat{D}_h^{[2c]} \{f\}(x) = f'(x)$$

$$= \frac{\hat{f}(x+h) - \hat{f}(x-h)}{2h} - f'(x)$$

Taylor @ 2

$$= \frac{f(x+h)(1+\epsilon_+) - f(x-h)(1+\epsilon_-)}{2h} - f'(x)$$

$$= \left(\frac{f(x+h) - f(x-h)}{2h} - f'(x) \right) + \frac{f(x+h)\epsilon_+ - f(x-h)\epsilon_-}{2h}$$

already worked out

$$= \frac{f''(x)}{3!} h^2 + O(h^4) + \frac{f(x)(\epsilon_+ - \epsilon_-)}{2h} + O(\boxed{\text{eps}})$$

$$\therefore \left| \hat{D}_h^{[2c]} \{f\}(x) - f'(x) \right| \leq \frac{|f''(x)|}{6} h^2 + \frac{|f(x)|}{2h} \boxed{\text{eps}}$$

ignoring higher-order terms

Determining Optimal h

Let $g(h) = \underbrace{\frac{|f''(x)|}{6} h^2}_{\alpha} + \underbrace{\frac{|f(x)|}{3h}}_{\beta \frac{|\text{eps}|}{h}}$

$\approx 10^{-16}$

$$= \alpha h^2 + \beta \frac{|\text{eps}|}{h}$$

Want to minimize $g(h)$:

$$g'(h) = 2\alpha h - \frac{\beta |\text{eps}|}{h^2} = 0$$

$$\Rightarrow h^3 = \frac{\beta |\text{eps}|}{2\alpha} \quad \therefore h = \left(\frac{\beta |\text{eps}|}{2\alpha} \right)^{1/3} \approx 10^{-5}, 10^{-6} \quad \checkmark$$

Richardson Extrapolation

Set-up

$$V_h \approx V$$

↑ ↑
discretized analytical
numerical value
approx.

i.e. $V_h = V + \underbrace{c_1 h^{p_1} + c_2 h^{p_2} + \dots}_{\text{error}}$

$\left. \begin{array}{l} \\ \\ \end{array} \right\} 0 < p_1 < p_2 < p_3 \dots$

Richardson extrapolation is a procedure
to improve accuracy of V_h

Idea: Form a suitable linear comb. of V_h and V_{2h} (or $V_{h/2}$) that eliminates the leading error term.

Example: Take $V = f(x)$, $V_h = D_h^{[1f]} f f_i(x)$

Recall:

$$D_h^{[1f]} f f_i(x) - f'(x) = \frac{f''(x)}{2} h + \frac{f'''(x)}{6} h^2 + \dots$$

①: $V_h = V + c_1 h + c_2 h^2 + \dots$

②: $V_{2h} = V + 2c_1 h + 4c_2 h^2 + \dots$

Goal: Get rid of 1st-order terms!

Richardson Extrapolation

$$\textcircled{1}: V_h = V + c_1 h + c_2 h^2 + \dots$$

$$\textcircled{2}: V_{2h} = V + 2c_1 h + 4c_2 h^2 + \dots$$

$$2 \times \textcircled{1} - \textcircled{2}: \underbrace{2V_h - V_{2h}}_{\text{New algorithm}} = V + 0 - 2c_2 h^2 + \dots$$

↑
1st-order term gone!

New algorithm approximating \circlearrowleft whose leading error term is now of 2nd-order!

$$\therefore D_h^{[2f]} \{f\}(x) = 2D_h^{[1f]} - D_{2h}^{[1f]} = 2 \frac{f(x+h) - f(x)}{h} - \frac{f(x+2h) - f(x)}{2h}$$

Same as earlier!

$$= \frac{4f(x+h) - 4f(x) - f(x+2h) + f(x)}{2h} = \boxed{\frac{-3f(x) + 4f(x+h) - f(x+2h)}{2h}}$$

Recall:

$$V_h = D_h^{[1f]} \{f\}(x) = \frac{f(x+h) - f(x)}{h}$$

$$V_{2h} = D_{2h}^{[1f]} \{f\}(x) = \frac{f(x+2h) - f(x)}{2h}$$

$$c_2 = \frac{f'''(x)}{6}, c_3 = \frac{f^{(4)}(x)}{4!}, \dots$$

14.2 Numerical Integration

Introduction

Consider the definite integral

$$I\{f\} = \int_a^b f(x) dx = \underset{(FTC)}{\overset{\nearrow}{F(b)}} - \underset{\nearrow}{F(a)}$$

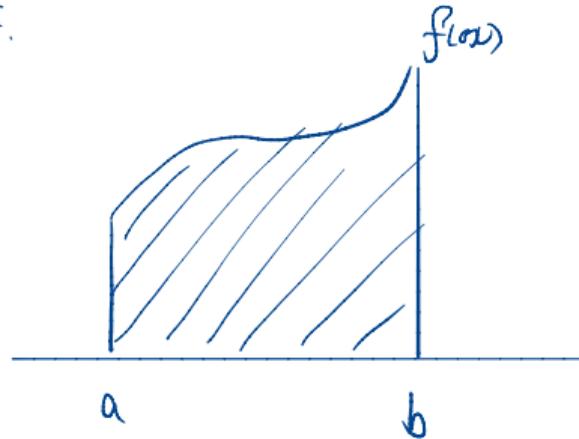
antiderivative of f .

which is approximated numerically by

$$I\{f\} \approx \sum_{i=1}^n \omega_i f(x_i).$$

weighted sum.

- ω_i 's are called the *weights*;
- x_i 's are called the *nodes* for the particular numerical method used.



"quadrature"

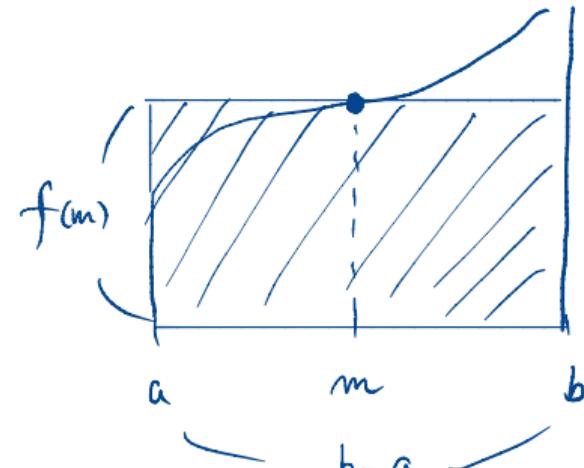
Newton-Cotes Formulas

In the *Newton-Cotes methods*, the nodes are equally spaced in $[a, b]$.

- **Midpoint Method:** one node

$$\int_a^b f(x) dx \approx f(m)(b - a), \quad m = \frac{1}{2}(a + b).$$

Idea
Replace $f(b)$ by a constant function and use its integral instead!



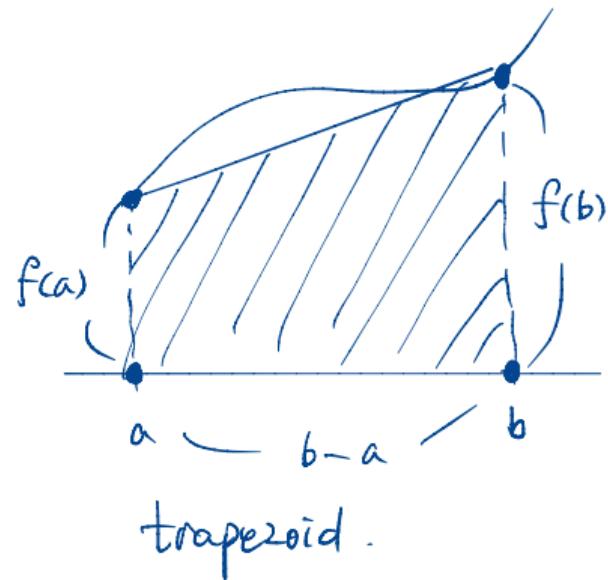
Newton-Cotes Formulas

In the *Newton-Cotes methods*, the nodes are equally spaced in $[a, b]$.

- **Trapezoidal Method:** two nodes

$$\int_a^b f(x) dx \approx \frac{1}{2} (f(a) + f(b)) (b - a).$$

Idea: Replace $f(x)$ by a linear function
and use its integral instead.



Newton-Cotes Formulas

In the *Newton-Cotes methods*, the nodes are equally spaced in $[a, b]$.

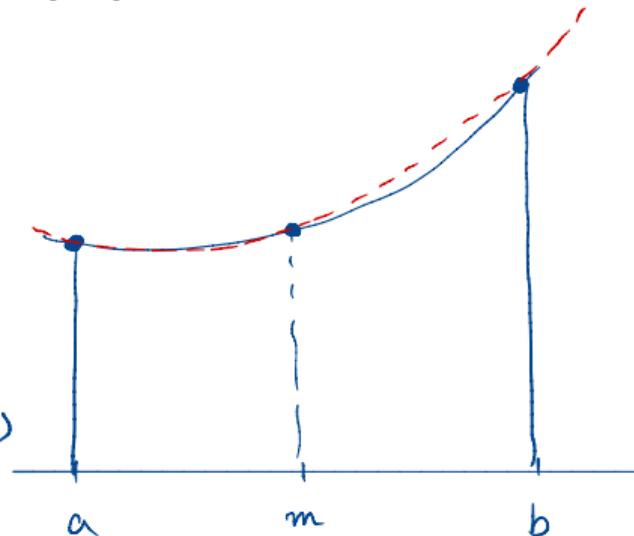
- **Simpson's Method:** three nodes

$$\int_a^b f(x) dx \approx \frac{1}{6} (f(a) + 4f(m) + f(b)) (b - a).$$

Idea: Replace $f(x)$ by a quadratic function
(polynomial)
and use its integral instead.



passing through $(a, f(a)), (m, f(m)), (b, f(b))$
" polynomial interpolation!"

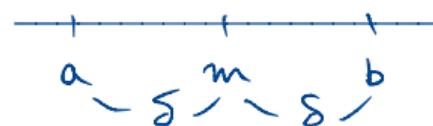


Derivation of Simpson's Rule

Find the quad. p(x) interpolating f(x)
at a, m, b. i.e.

$$p(a) = f(a), \quad p(m) = f(m), \quad p(b) = f(b).$$

then use $\int_a^b p(x) dx$ to approx. If ff.


$$\delta = \frac{b-a}{2}$$

Lagrange: $p(x) = f(a)l_1(x) + f(m)l_2(x) + f(b)l_3(x)$

where

$$l_1(x) = \frac{(x-m)(x-b)}{2\delta^2}$$

$$l_2(x) = \frac{(x-a)(x-b)}{-\delta^2}$$

$$l_3(x) = \frac{(x-a)(x-m)}{2\delta^2}$$

Need: $\int_a^b l_0(x) dx$

Why? $\int_a^b p(x) dx = f(a) \int_a^b l_1(x) dx + f(m) \int_a^b l_2(x) dx + f(b) \int_a^b l_3(x) dx$

$$l_1(x) = \frac{(x-a)(x-b)}{2\delta^2}, \quad l_2(x) = \frac{(x-a)(x-b)}{-\delta^2}, \quad l_3(x) = \frac{(x-a)(x-b)}{2\delta^2}$$

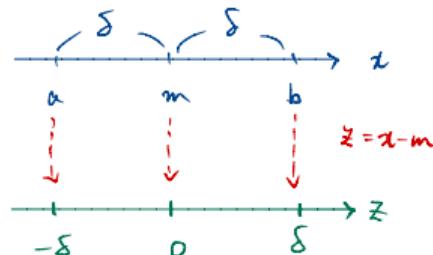
① $\int_a^b l_1(x) dx = \frac{1}{2\delta^2} \int_a^b (x-a)(x-b) dx$

$$z = x - m$$

$$\begin{aligned} x-b &= x-m-\delta \\ &= z-\delta \\ &= z-\delta &= \frac{1}{2\delta^2} \int_{-\delta}^{\delta} \underbrace{z(z-\delta)}_{\substack{\text{even} \\ \text{odd}}} dz \\ &= z^2 - \delta z \end{aligned}$$

$$= \frac{1}{2\delta^2} \cdot 2 \int_0^{\delta} z^2 dz$$

$$= \frac{1}{2\delta^2} \cdot 2 \cdot \frac{\delta^3}{3} = \frac{\delta}{3} = \frac{b-a}{6}$$



$$\begin{aligned}
 ② \int_a^b l_2(x) dx &= -\frac{1}{\delta^2} \int_a^b (x-a)(x-b) dx \\
 &= -\frac{1}{\delta^2} \int_{-\delta}^{\delta} \underbrace{(z-\delta)(z+\delta)}_{z^2 - \delta^2} dz \\
 &= -\frac{2}{\delta^2} \int_0^\delta (z^2 - \delta^2) dz = \dots = \frac{4\delta}{3} = \frac{2}{3}(b-a)
 \end{aligned}$$

$$③ \int_a^b l_3(x) dx = \dots = \frac{b-a}{6}$$

Therefore,

$$\begin{aligned} \int_a^b f(x) dx &\approx \int_a^b p(x) dx \\ &= f(a) \underbrace{\int_a^b l_1(x) dx}_{\frac{b-a}{6}} + f(m) \underbrace{\int_a^b l_2(x) dx}_{\frac{2}{3}(b-a)} + f(b) \underbrace{\int_a^b l_3(x) dx}_{\frac{b-a}{6}} \\ &= \boxed{\frac{b-a}{6} (f(a) + 4f(m) + f(b))} \end{aligned}$$

Simpson's method !

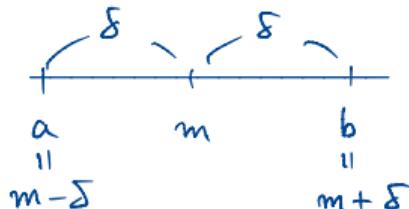
Error Analysis

"Trapezoidal method..

$$I^{[t]} \{f\} = \frac{b-a}{2} (f(a) + f(b))$$

$$I \{f\} = \int_a^b f(x) dx$$

Strategy: Taylor expansion at $m = \frac{a+b}{2}$



$$\begin{aligned} f(a) &= f(m-\delta) = f(m) - f'(m)\delta + \frac{f''(m)}{2}\delta^2 - \dots \\ f(b) &= f(m+\delta) = f(m) + f'(m)\delta + \frac{f''(m)}{2}\delta^2 + \dots \\ \hline f(a) + f(b) &= 2 \left[f(m) + \frac{f''(m)}{2}\delta^2 + \frac{f^{(4)}(m)}{4!}\delta^4 + \dots \right] \end{aligned}$$

$$\begin{aligned} \therefore I^{[t]} &= \underbrace{\frac{b-a}{2}}_{\delta} (f(a) + f(b)) \\ &= 2\delta \left[f(m) + \frac{f''(m)}{2}\delta^2 + \frac{f^{(4)}(m)}{4!}\delta^4 + \dots \right] \end{aligned}$$

Error Analysis

$$\begin{aligned} \bullet \quad I &= \int_a^b f(x) dx \\ &= \int_a^b f(m + x - m) dx \\ &= \int_a^b \sum_{k=0}^{\infty} \frac{f^{(k)}(m)}{k!} (x-m)^k dx \\ &= \sum_{k=0}^{\infty} \frac{f^{(k)}(m)}{k!} \underbrace{\int_a^b (x-m)^k dx}_{\substack{x = u - m \\ = \int_{-\delta}^{\delta} u^k dz}} \\ &\quad \begin{cases} 0 & , k \text{ odd} \\ \frac{2\delta^{k+1}}{k+1} & , k \text{ even} \end{cases} \\ k=2j &= \sum_{j=0}^{\infty} \frac{f^{(2j)}(m)}{(2j)!} \cdot \frac{2\delta^{2j+1}}{2j+1} = 2\delta \left[f(m) + \frac{f''(m)}{3!} \delta^2 + \frac{f^{(4)}(m)}{5!} \delta^4 + \dots \right] \end{aligned}$$

Error Analysis

Finally, $e^{[t]} = I^{[t]} - I$

$$= 2\delta \left[\cancel{f(m)} + \frac{\cancel{f''(m)}}{2} \delta^2 + \frac{\cancel{f^{(4)}(m)}}{4!} \delta^4 + \dots \right]$$

$$- 2\delta \left[\cancel{f(m)} + \frac{\cancel{f''(m)}}{3!} \delta^2 + \frac{\cancel{f^{(4)}(m)}}{5!} \delta^4 + \dots \right]$$

$$= 2\delta \left[\underbrace{\left(\frac{1}{2} - \frac{1}{3!} \right)}_{\frac{1}{3}} f''(m) \delta^2 + \underbrace{\left(\frac{1}{4!} - \frac{1}{5!} \right)}_{\frac{4}{5!} = \frac{1}{3 \cdot 5} = \frac{1}{30}} f^{(4)}(m) \delta^4 + \dots \right]$$

$$\delta = \frac{b-a}{2}$$

$$= \frac{2}{3} f''(m) \left(\frac{b-a}{2} \right)^3 + \underbrace{\frac{1}{15} f^{(4)}(m) \left(\frac{b-a}{2} \right)^5}_{+ O((b-a)^7)}$$

$$= \frac{1}{12} f''(m) (b-a)^3 + O((b-a)^5) \quad \frac{1}{15 \cdot 32} f^{(4)}(m) (b-a)^5$$

leading error.

$\therefore 3^{\text{rd}}$ -order accurate.

Error Analysis

Note:

$$\left\{ \begin{array}{l} \cdot e^{[+]} = I^{[+]} - I = \frac{1}{12} f''(m) (b-a)^3 + \frac{1}{480} f^{(4)}(m) (b-a)^5 + O((b-a)^7) \\ \cdot e^{[m]} = I^{[m]} - I = -\frac{1}{24} f''(m) (b-a)^3 - \frac{1}{1920} f^{(4)}(m) (b-a)^5 + O((b-a)^7) \end{array} \right.$$

both are 3rd-order accurate!

$$\left(\begin{array}{l} \cdot e^{[5]} = I^{[5]} - I = \frac{1}{2880} f^{(4)}(m) (b-a)^5 + O((b-a)^7) \end{array} \right)$$

5th-order accurate!

Simpson Revised – Derivation Via Extrapolation

Know : $I^{[m]} = I - \frac{1}{24} f''(m) (b-a)^3 + \frac{1}{1920} f^{(4)}(m) (b-a)^5 + \dots$

$$I^{[t]} = I + \frac{1}{12} f''(m) (b-a)^3 + \frac{1}{480} f^{(4)}(m) (b-a)^5 + \dots$$

Want: Construct a higher-order method based on the two.

strategy: Extrapolate! Form a suitable linear comb. of
 $I^{[m]}$ and $I^{[t]}$ to remove their leading errors.

In our case:

$$\frac{2I^{[m]}}{3} + \frac{I^{[t]}}{3} = 2I + \left(\frac{1}{3} \left(\frac{1}{960} + \frac{1}{480} \right) f^{(4)}(m) (b-a)^5 \right) \overset{\frac{1}{2880}}{\ll} O((b-a)^7)$$

Simpson Revisted – Derivation Via Extrapolation

Upshot:

$$\frac{2}{3} I^{[m]} + \frac{1}{3} I^{[t]} = I + \frac{1}{2880} f^{(4)}(m) (b-a)^5 + O((b-a)^7)$$

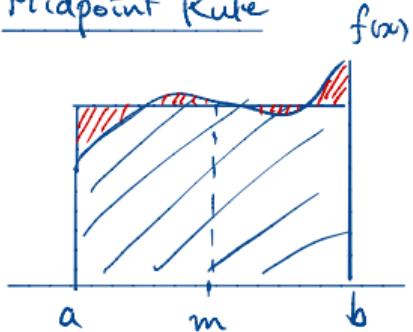
new algorithm approx. "I" with 5^{th} -order error.

$$\frac{2}{3} f(m)(b-a) + \frac{1}{3} (f(a) + f(b)) \cdot \frac{b-a}{2}$$

$$= \frac{b-a}{6} (4f(m) + f(a) + f(b)) \quad \checkmark \text{ Simpson's method!}$$

Composite Methods

Midpoint Rule

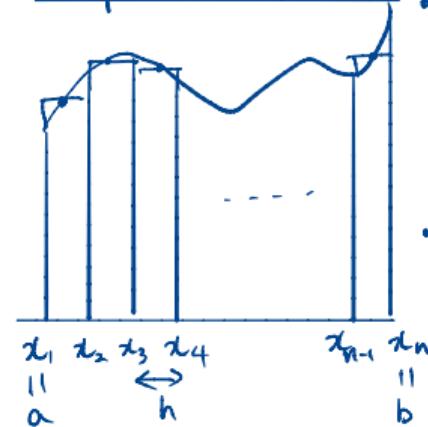


$$I^{[m]} = I + \underbrace{O((b-a)^3)}_{\text{3rd-order accurate}}$$

$$I^{[m]} - I \rightarrow 0 \quad \text{as} \quad b-a \rightarrow 0$$

divide into
multiple
subintervals

Composite Midpoint Rule



- n grid points:

$$x_j = a + j \frac{b-a}{n-1}$$

where $1 \leq j \leq n$.

- $n-1$ s/int. of

length $h = \frac{b-a}{n-1}$

$$I \approx \sum_{j=1}^{n-1} f(x_{j+\frac{1}{2}}) \cdot h = I_h^{[m]}$$

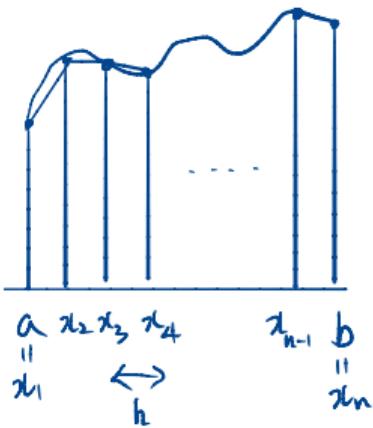
height width

$$x_{j+\frac{1}{2}} = \frac{x_j + x_{j+1}}{2}$$

j^{th} midpoint

Composite Methods

Composite Trapezoidal Rule



$$h = \frac{b-a}{n-1}$$

$$I = \sum_{j=1}^{n-1} \int_{x_j}^{x_{j+1}} f(x) dx \approx \sum_{j=1}^{n-1} \frac{h}{2} (f(x_j) + f(x_{j+1}))$$

jth subint.
L.E.P. R.E.P.

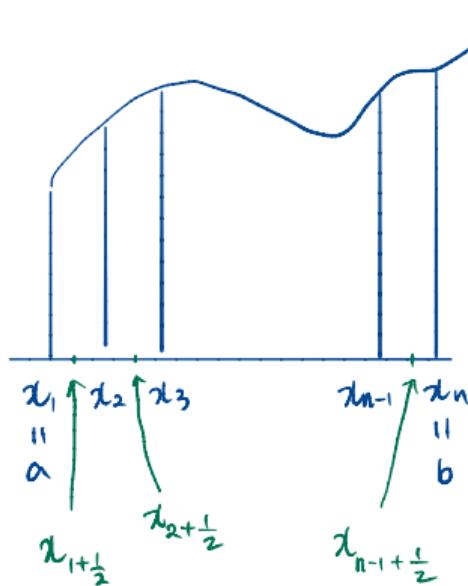
$$\begin{aligned} &= \frac{h}{2} \left(\sum_{j=1}^{n-1} f(x_j) + \sum_{j=1}^{n-1} f(x_{j+1}) \right) \\ &= \frac{h}{2} \left(f(x_1) + 2 \sum_{j=2}^{n-1} f(x_j) + f(x_n) \right) \\ &= h \left(\frac{f(x_1) + f(x_n)}{2} + \sum_{j=2}^{n-1} f(x_j) \right) \end{aligned}$$

* Note: If f is periodic w/
period $b-a$, then $f(x_1) = f(x_n)$

$$I_h^{[t]} = h \sum_{j=1}^{n-1} f(x_j)$$

Composite Methods

Composite Simpson's Rule



$$\text{I}_{[s]}^{[h]} = \sum_{j=1}^{n-1} \frac{h}{6} \left(f(x_j) + 4f(x_{j+\frac{1}{2}}) + f(x_{j+1}) \right)$$

Composite method
with $h = \frac{b-a}{n-1}$

Errors for Composite Methods

Trapezoidal Method

Comp.

$$\begin{aligned} I &= \sum_{j=1}^{n-1} \int_{x_j}^{x_{j+1}} f(x) dx \\ &= \sum_{j=1}^{n-1} \left(I_j^{[t]} + O(h^3) \right) \\ &= \underbrace{\sum_{j=1}^{n-1} I_j^{[t]}}_{\text{(comp. T.M)}} + \underbrace{\sum_{j=1}^{n-1} O(h^3)}_{\text{error}} \\ &= I_h^{[t]} + (n-1) O(h^3) \end{aligned}$$

$I_j^{[t]}$

(comp. T.M) error

$$I^{[t]} = I + O((b-a)^3)$$

Notice that $n-1 = \frac{b-a}{h}$. Thus

$$\begin{aligned} (\text{error}) &= \frac{b-a}{h} O(h^3) \\ &= (b-a) O(h^2) = O(h^2) \end{aligned}$$

↑
const.

local error

∴ { trap. method : 3rd-order accurate
Comp. trap. method : 2nd-order accurate
 ↳ global error

Errors for Composite Methods

Precisely:

$$e_h^{[m]} = -\frac{f''(\xi_m)}{24} (b-a) h^2 \quad \left. \right\} \text{2nd-order accurate}$$

$$e_h^{[t]} = \frac{f''(\xi_t)}{12} (b-a) h^2$$

$$e_h^{[s]} = \frac{f^{(4)}(\xi_s)}{2880} (b-a) h^4 \quad \left. \right\} \text{4th-order accurate}$$