Piecewise Cubic Interpolation

Framework (Set -up)

Given nodes
$$t_i, t_i, t_i, t_i$$

Dur interpolant is

the piecewise defined function

 t_i, t_i, t_i, t_i
 t_i, t_i, t_i, t_i
 t_i, t_i, t_i, t_i

Fig. (a) for $t_i \in [t_i, t_i, t_i]$

Fig. (b) for $t_i \in [t_i, t_i, t_i]$
 t_i, t_i, t_i, t_i
 t_i, t_i, t_i, t_i

Fig. (c) t_i, t_i, t_i, t_i
 t_i, t_i, t_i, t_i

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Hermite Cubic Interpolation

Problem Set-Up: General Piecewise Cubic Interpolation

We now seek a piecewise cubic polynomial which interpolates the data (x_i, y_i) for $i = 1, \ldots, n$, with $x_1 < x_2 < \cdots < x_n$, defined as

$$\mathcal{P}(x) = \begin{cases} p_1(x), & x \in [x_1, x_2) \\ p_2(x), & x \in [x_2, x_3) \\ \vdots & \vdots \\ p_{n-1}(x), & x \in [x_{n-1}, x_n] \end{cases} ,$$
 where the i th $local$ cubic polynomial p_i is written in shifted power form as
$$p_i(x) = c_{i,1} + c_{i,2}(x-x_i) + c_{i,2}(x-x_i)^2 + c_{i,4}(x-x_i)^3$$
 where i th i th

$$p_i(x) = c_{i,1} + c_{i,2}(x - x_i) + c_{i,3}(x - x_i)^2 + c_{i,4}(x - x_i)^3.$$

Unknown weffs: 4 (N-1)

four coeff (N-1) intervals

for each i

Hermite Cubic Interpolation

If the slopes at the breakpoints are prescribed, i.e., for each $i = 1, \dots, n-1$,

$$p_i(x_i) = y_i$$
, $p'_i(x_i) = \sigma_i$, $p_i(x_{i+1}) = y_{i+1}$, $p'_i(x_{i+1}) = \sigma_{i+1}$,

then we can solve for the four unknown coefficients $c_{i,j}$, $j=1,\ldots,4$:

$$c_{i,1} = y_i$$
, $c_{i,3} = \frac{3y[x_i, x_{i+1}] - 2\sigma_i - \sigma_{i+1}}{\Delta x_i}$, $c_{i,2} = \sigma_i$, $c_{i,4} = \frac{\sigma_i + \sigma_{i+1} - 2y[x_i, x_{i+1}]}{(\Delta x_i)^2}$.

where $\Delta x_i = x_{i+1} - x_i$ and

$$y[x_i, x_{i+1}] = \frac{y_{i+1} - y_i}{x_{i+1} - x_i}.$$

This is called **Hermite cubic interpolation**.

(Newton's divided difference)

$$P_{i}(x) = C_{i,1} + C_{i,2}(x-A_{i}) + C_{i,3}(x-A_{i})^{2} + C_{i,4}(x-A_{i})^{3}$$

•
$$p_i(x_i) = C_{i,i} = y_i$$

$$P_{i}'(x) = C_{i,2} + 2C_{i,3}(x-x_{i}) + 3C_{i,4}(x-x_{i})^{2}$$

$$P_{i}'(x_{i}) = C_{i,2} + 2C_{i,3}(x-x_{i}) + 3C_{i,4}(x-x_{i})^{2}$$

$$Pi'(\lambda_i) = G_{i,2} = \sigma_i$$

Implementation

```
function c = hermiteCoeff(x, y, s)
% Input:
 x,y,s data points and slopes
% Ouput:
  c coefficients in matrix form
   n = length(x);
   c = zeros(n-1, 4);
   dx = diff(x);
   dv = diff(v);
   dvdx = dv./dx;
   c(:,1) = v;
   c(:,2) = s;
    c(:,3) = (3*dydx - 2*s(1:n-1) - s(2:n))./dx;
    c(:,4) = (s(1:n-1) + s(2:n-1) - 2*dydx))./(dx.^2);
end
```

Convergence: Error Analysis

ror Analysis continuously of the collection of all four times ____ differentiable functions.

Theorem 1 (Error Theorem for Hermite Cubic Interpolation)

Let $f \in C^4[a,b]$ and let x be the Hermite cubic interpolant of

$$(x_i, f(x_i), f'(x_i)), \quad \text{for } i = 1, \dots, n,$$

 $x_j = a + (j-1)h$ and $h = \frac{b-a}{n-1}$.

$$x_j = a + (j-1)h$$
 and $h = \frac{1}{n-1}$

 $\|f - \mathcal{P}\|_{\infty} \leq \frac{1}{384} \|f^{(4)}\|_{\infty} h^4. \qquad (A^{+h} - \text{order accurate})$ Then

E.g. Suppose
$$\|f - p\|_{\infty} \le 10^{-4}$$
 when $h = 0.2$
What is an upper bound on $\|f - pp\|_{\infty}$ when $h = 0.1$?

where

Drawbacks of Hermite Cubic Interpolation

- si.e., IP is continuously differentiable
- The interpolant f(x) is in C^1 and so its display may be to crude in graphical applications.
- In other applications, there may be difficulties if p(x) is discontinuous.
- In experimental settings where y_i are measurements of some sort, we may not have the first derivative information required for the cubic Hermite process.

Cubic Splines

Cubic Splines

In fancy terms, we seek $P \in C^2[a,b]$, i.e., twice continuously differentiable interpolant.

Idea: Put together cubic polynomials to make the result as smooth as possible.

- At interior breakpoints: for $j=2,3,\cdots,n-1$
 - matching values: $p_{i-1}(x_i) = p_i(x_i)$
 - matching first derivatives: $p'_{i-1}(x_i) = p'_i(x_i)$
 - matching second derivative: $p_{j-1}''(x_j) = p_j''(x_j)$
- So, together with the n interpolating conditions, we have total of (4n-6) equations.

• To match up with the number of unknowns (4n-4), we need to impose two

- more conditions on the boundary:
 - 1 slopes at each end (clamped cubic spline)
 - second derivatives at the endpoints (natural cubic spline)
 - 3 periodic boundary condition
- 4 not-a-knot) boundary condition: $p_1(x) \equiv p_2(x)$ and $p_{n-2}(x) \equiv p_{n-1}(x)$.

25-1 25 25+1 P5-(2x) P5 (4x)

fegus: 4n-6 # of nnk:: 4n-4

[(n-2) eqns]

[(n-2) eqns]

[(n-2) egns]

Convergence: Error Analysis

Theorem 2 (Error Theorem for Clamped Cubic Splines)

Let $f \in C^4[a,b]$ and let $\mathbb{R}^2 x$ be the cubic spline interpolant of

$$(x_i, f(x_i)), \quad \text{for } i = 1, \dots, n,$$

with the exact boundary conditions

$$\sigma_1 = f'(x_1)$$
 and $\sigma_n = f'(x_n)$,

in which

$$x_j=a+(j-1)h$$
 and $h=rac{b-a}{n-1}.$

Then

$$\|f - \mathcal{P}\|_{\infty} \leq \frac{5}{384} \|f^{(4)}\|_{\infty} h^4. \qquad (A^{th} \text{ order accurate})$$

Remarks

- Hermite cubic interpolation is about five times as accurate as cubic spline interpolation, yet both have *fourth-order accuracy*.
- Unlike the former, the latter does not require first derivatives.