Exercises: Numerical Calculus (Solutions)

1. (Derivation of the third-order forward difference formulan; solution by extrapolation)

Let V = f'(x) and $V_h = D_h^{[1f]}\{f\}(x)$, the first-order forward difference formula, for simplicity. Recall that

$$V_h = V + \underbrace{\frac{f''(x)}{2}}_{b_1} h + \underbrace{\frac{f'''(x)}{6}}_{b_2} h^2 + \underbrace{\frac{f^{(4)}(x)}{24}}_{b_3} h^3 + O(h^4).$$

$$= V + b_1 h + b_2 h^2 + b_3 h^3 + O(h^4).$$

To obtain a third-order method, the first two error terms b_1h and b_2h^2 must be eliminated. To this end, we look for a linear combination of V_h , V_{2h} , and V_{3h} such that

$$\alpha_1 V_h + \alpha_2 V_{2h} + \alpha_3 V_{3h} = V + O(h^3),$$

where α_j are to be determined. Writing the left-hand side out and collecting like-terms, we have

$$\alpha_1 V_h + \alpha_2 V_{2h} + \alpha_3 V_{3h}$$

$$= (\alpha_1 + \alpha_2 + \alpha_3)V + (\alpha_1 + 2\alpha_2 + 3\alpha_3)b_1 h + (\alpha_1 + 4\alpha_2 + 9\alpha_3)b_2 h^2 + O(h^3).$$

Matching coefficients, we obtain a linear system of three equations for the unknown weights α_j , for j = 1, 2, 3:

$$\alpha_1 + \alpha_2 + \alpha_3 = 1$$

 $\alpha_1 + 2\alpha_2 + 3\alpha_3 = 0$
 $\alpha_1 + 4\alpha_2 + 9\alpha_3 = 0$

Solving the system (say by Gaussian elimination), we obtain

$$\begin{bmatrix} \alpha_1 \\ \alpha_2 \\ \alpha_3 \end{bmatrix} = \begin{bmatrix} 3 \\ -3 \\ 1 \end{bmatrix}.$$

Therefore, $3V_h - 3V_{2h} + V_{3h}$ is a new formula approximating V with third-order accuracy:

$$D_h^{[3f]}{f}(x) = 3V_h - 3V_{2h} + V_{3h}$$

$$= 3\frac{f(x+h) - f(x)}{h} - 3\frac{f(x+2h) - f(x)}{2h} + \frac{f(x+3h) - f(x)}{3h}$$

$$= \frac{-11f(x) + 18f(x+h) - 9f(x+2h) + 2f(x+3h)}{6h}.$$

2. **(LM** 14.1–12)

(a) Recall that

$$D_h^{[2c]}{f}(x) = f'(x) + c_2h^2 + c_4h^4 + O(h^6).$$

It follows that

$$D_{2h}^{[2c]}{f}(x) = f'(x) + 4c_2h^2 + 16c_4h^4 + O(h^6),$$

and so

$$\frac{4D_h^{[2c]}\{f\}(x) - D_{2h}^{[2c]}\{f\}(x)}{3} = f'(x) - 4c_4h^4 + O(h^6).$$

Therefore, the fourth-order centered difference formula is given by

$$\begin{split} D_h^{[4c]}\{f\}(x) &= \frac{4D_h^{[2c]}\{f\}(x) - D_{2h}^{[2c]}\{f\}(x)}{3} \\ &= \frac{4}{3}\frac{f(x+h) - f(x-h)}{2h} - \frac{1}{3}\frac{f(x+2h) - f(x-2h)}{4h} \\ &= \frac{f(x-2h) - 8f(x-h) + 8(x+h) - f(x+2h)}{12h}. \end{split}$$

(c) The second-order centered difference formula for f''(x) is given by

$$D_h^2\{f\}(x) = \frac{f(x+h) - 2f(x) + f(x-h)}{h^2} = f''(x) + \frac{1}{12}f''''(x)h^2 + O(h^4).$$

(See Lecture 33 or LM p.1766-7.) By a similar argument as above, we see that

$$\frac{4D_h^2\{f\}(x) - D_{2h}^2\{f\}(x)}{3} = f''(x) + O(h^4),$$

yields a fourth-order centered difference formula for f''(x):

$$(4\text{th-order CD for } f''(x))$$

$$= \frac{4D_h^2\{f\}(x) - D_{2h}^2\{f\}(x)}{3}$$

$$= \frac{4}{3} \frac{f(x+h) - 2f(x) + f(x-h)}{h^2} - \frac{1}{3} \frac{f(x+2h) - 2f(x) + f(x-2h)}{4h^2}$$

$$= \frac{-f(x-2h) + 16f(x-h) - 30f(x) + 16f(x+h) - f(x+2h)}{12h^2}.$$

3. (Approximating π again; **LM** 14.1–17) Applying the suggested change of variables h=1/n and Taylor-expanding about h=0, we obtain

$$p_n = \frac{\sin(\pi h)}{h} = \pi - \frac{\pi^3}{6}h^2 + \frac{\pi^5}{120}h^4 + \dots = \pi + a_1h^2 + a_2h^4 + \dots$$
$$P_n = \frac{\tan(\pi h)}{h} = \pi + \frac{\pi^3}{3}h^2 + \frac{2\pi^5}{15}h^4 + \dots = \pi + b_1h^2 + b_2h^4 + \dots$$

Note that both are second-order accurate. The average of the two algorithms gives another second-order algorithm as h^2 term survives:

$$\mathfrak{B}_n = \pi + c_1 h^2 + c_2 h^4 + \cdots,$$

where

$$c_1 = \frac{a_1 + b_1}{2} = \frac{\pi^3}{12}, \quad c_2 = \frac{a_2 + b_2}{2} = \frac{17\pi^5}{240}.$$

One way to obtain a fourth-order algorithm is to extrapolate p_n and P_n . Calculation shows that

$$\Re_n \equiv \frac{2}{3}p_n + \frac{1}{3}P_n = \pi + \frac{\pi^5}{20}h^4 + \cdots$$

The above is not the only way. One may, for instance, construct another fourth-order algorithm by extrapolating $\mathfrak{B}_{\mathfrak{n}}$ and $\mathfrak{B}_{\mathfrak{n}/2}$:

$$\mathfrak{S}_n \equiv \frac{4}{3}\mathfrak{B}_n - \frac{1}{3}\mathfrak{B}_{n/2} = \pi - \frac{17\pi^5}{60}h^4 + \cdots$$