

Cost of LU Factorization

① Cost of PLU Factorization Algorithm

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Key result: In solving $A\vec{x} = \vec{b}$ where $A \in \mathbb{R}^{n \times n}$:

- PLU factorization requires about $\frac{2}{3}n^3$ flops
- Forward & Backward substitutions
require only about n^2 flops

Notation: Big-O and Asymptotic

$f(1), f(2), f(3), \dots$

Let f, g be positive functions defined on \mathbb{N} .

- $\underbrace{f(n)}_{\text{complex}} = O(\underbrace{g(n)}_{\text{simple}})$ (" f is big-O of g ") as $n \rightarrow \infty$ if $\frac{f(n)}{g(n)} \leq C$, for all sufficiently large n .

} "rough" idea of what $f(n)$ is like for large n .

- $f(n) \sim g(n)$ (" f is asymptotic to g ") as $n \rightarrow \infty$ if

$$\lim_{n \rightarrow \infty} \frac{f(n)}{g(n)} = 1.$$

} more accurate description

Examples Let $f(n) = 3n^3 + 2n - 1$

- $f(n) = O(n^3)$ because $\frac{3n^3 + 2n - 1}{n^3} = 3 + \frac{2}{n^2} - \frac{1}{n^3} \leq 3 + 1 + 1 = 5$ for all large n .

($f(n) = O(n^3)$, $f(n) = O(n^4)$, $f(n) = O(n^5)$, ...)

- $f(n) \sim 3n^3$ because $\lim_{n \rightarrow \infty} \frac{3n^3 + 2n - 1}{3n^3} = 1$.

Timing Vector/Matrix Operations – FLOPS

- One way to measure the “efficiency” of a numerical algorithm is to count the number of floating-point arithmetic operations (FLOPS) necessary for its execution. (+, −, *, ÷, sqrt)
- The number is usually represented by $\sim cn^p$ where c and p are given explicitly.
- We are interested in this formula when n is large.

that is, as $n \rightarrow \infty$.

FLOPS for Major Operations

Vector/Matrix Operations

Let $x, y \in \mathbb{R}^n$ and $A, B \in \mathbb{R}^{n \times n}$. Then

- (vector-vector) $x^T y$ requires $\sim 2n$ flops.
- (matrix-vector) Ax requires $\sim 2n^2$ flops.
- (matrix-matrix) AB requires $\sim 2n^3$ flops.

$$\cdot \quad \vec{x}^T \vec{y} = [x_1 \ x_2 \ \dots \ x_n] \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{bmatrix} \quad (\text{inner product})$$

$$= x_1 y_1 + x_2 y_2 + \dots + x_n y_n$$

(n-1) \oplus 's

n \otimes 's

$$\begin{aligned} \text{Total flops} &: n + (n-1) \\ &= 2n-1 \sim \underline{\underline{2n}} \end{aligned}$$

$$A \vec{x} = \begin{bmatrix} \frac{\vec{\alpha}_1^T}{\vdots} \\ \frac{\vec{\alpha}_n^T}{\vdots} \end{bmatrix} \cdot \vec{x} = \begin{bmatrix} \frac{\vec{\alpha}_1^T \vec{x}}{\vdots} \\ \frac{\vec{\alpha}_n^T \vec{x}}{\vdots} \end{bmatrix} \begin{matrix} \rightarrow \sim 2n \\ \rightarrow \sim 2n \\ \rightarrow \sim 2n \end{matrix} \quad n \text{ times.}$$

$$A = \begin{bmatrix} \frac{\vec{\alpha}_1^T}{\vdots} \\ \frac{\vec{\alpha}_n^T}{\vdots} \end{bmatrix}$$

$$\underline{\text{Total flops}}: (2n-1) \times n$$

$$= 2n^2 - n \sim 2n^2$$

$\vec{\alpha}_i^T$: i^{th} row of A .

Cost of PLU Factorization

- pivot : $R_i \leftrightarrow R_j$ (No flops needed)
- row replacement : $R_i \rightarrow R_i + (-a_{ij}/a_{jj}) R_j$

Note that we only need to count the number of *flops* required to zero out elements below the diagonal of each column.

(flop counting needed)

Suppose you are working out the j^{th} column.

- For each $i > j$, we replace R_i by $R_i + cR_j$ where $c = -a_{i,j}/a_{j,j}$. This requires approximately $2(n - j + 1)$ flops:

- 1 division to form c
 - $n - j + 1$ multiplications to form cR_j
 - $n - j + 1$ additions to form $R_i + cR_j$
- $$\left. \begin{array}{l} 1 + 2(n-j+1) \\ \sim 2(n-j+1) \end{array} \right\}$$

- Since $i \in \mathbb{N}[j+1, n]$, the total number of flops needed to zero out all elements below the diagonal in the j^{th} column is approximately $2(n - j + 1)(n - j)$.

- Summing up over $j \in \mathbb{N}[1, n-1]$, we need about $(2/3)n^3$ flops:

$$\sum_{j=1}^{n-1} \underbrace{2(n-j+1)}_{\sim n-j} (n-j) \sim 2 \sum_{j=1}^{n-1} (n-j)^2 = 2 \sum_{j=1}^{n-1} j^2 \sim \frac{2}{3}n^3$$

↑
reversing the term
(change of indices)

x	x	x	x	x
0	x	x	x	x
0	0	x	x	x
0	0	x	x	x
0	0	x	x	x

$i=4 \rightarrow$
 $i=5 \rightarrow$

↑
 $j=3$

$$\begin{aligned} 3 &= 5 - 3 + 1 \\ &= n - j + 1 \end{aligned}$$

Why $2 \sum_{j=1}^{n-1} j^2 \sim \frac{2}{3} n^3$?

One way Recall $\sum_{j=1}^n j^2 = 1^2 + 2^2 + \dots + n^2 = \frac{n(n+1)(2n+1)}{6}$.

So
$$\begin{aligned} \sum_{j=1}^{n-1} j^2 &= \frac{(n-1)[(n-1)+1][2(n-1)+1]}{6} \\ &= \frac{(n-1)n(2n-1)}{6} = \frac{2n^3 + (\text{lower order terms})}{6} \\ &\sim \frac{2n^3}{6} = \frac{n^3}{3} \end{aligned}$$

Another Using the following result.

$$\sum_{j=1}^{n-1} j^p \sim \frac{j^{p+1}}{p+1}$$

Think $\int x^p dx = \frac{x^{p+1}}{p+1} + C$

$$\sum_{j=1}^{n-1} j^2 \sim \frac{j^{2+1}}{2+1} = \frac{j^3}{3}$$

Cost of Forward Elimination and Backward Substitution

Forward Elimination

- The calculation of $y_i = \beta_i - \sum_{j=1}^{i-1} \ell_{ij}y_j$ for $i > 1$ requires approximately $2i$ flops:
 - 1 subtraction
 - $i - 1$ multiplications
 - $i - 2$ additions
- Summing over all $i \in \mathbb{N}[2, n]$, we need about n^2 flops:

$$\sum_{i=2}^n 2i \sim 2 \frac{n^2}{2} = n^2.$$

Backward Substitution

- The cost of backward substitution is also approximately n^2 flops, which can be shown in the same manner.

Cost of G.E. with Partial Pivoting

Gaussian elimination with partial pivoting involves three steps:

- PLU factorization: $\sim (2/3)n^3$ flops \leftarrow heavy
- Forward elimination: $\sim n^2$ flops
- Backward substitution: $\sim n^2$ flops \leftarrow light

Summary

The total cost of Gaussian elimination with partial pivoting is approximately

$$\frac{2}{3}n^3 + n^2 + n^2 \sim \frac{2}{3}n^3$$

flops for large n .

Application: Solving Multiple Square Systems Simultaneously

To solve two systems $Ax_1 = b_1$ and $Ax_2 = b_2$. (Note both involve the same matrix.)

Method 1. (inefficient)

- Use G.E. for both.
- It takes $\sim (4/3)n^3$ flops.

```
% method 1
x1 = A \ b1;  ~ 2/3 n^3
x2 = A \ b2;  ~ 2/3 n^3
```

Method 2. (efficient)

- Do it in two steps:
 - 1 Do PLU factorization $PA = LU$.
 - 2 Then solve $LUx_1 = Pb_1$ and $LUx_2 = Pb_2$.
- It takes $\sim (2/3)n^3$ flops.

```
% method 2
[L, U, P] = lu(A);  ~ 2/3 n^3
x1 = U \ (L \ (P*b1));  ~ 2n^2
x2 = U \ (L \ (P*b2));  ~ 2n^2
```

} $\frac{2}{3}n^3 + 4n^2 \sim \frac{2}{3}n^3$

```
% compact implementation
X = A \ [b1, b2];
x1 = X(:, 1);
x2 = X(:, 2);
```

$$A \underbrace{[\vec{x}_1, \vec{x}_2]}_X = \underbrace{[\vec{b}_1, \vec{b}_2]}_B$$