Exception Safety

continued

CS 311 Data Structures and Algorithms Lecture Slides Monday, March 25, 2013

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Unit Overview Handling Data & Sequences

Major Topics

- ✓ Data abstraction
- ✓ Introduction to Sequences
 - Smart arrays
 - ✓ Array interface
 - ✓ Basic array implementation
 - (part) Exception safety
 - Allocation & efficiency
 - Generic containers
 - Linked Lists
 - Node-based structures
 - More on Linked Lists
 - Sequences in the C++ STL
 - Stacks
 - Queues

Review Array Interface

Ctors & Dctor

- Default ctor
- Ctor given size
- Copy ctor
- Dctor

Member Operators

- Copy assignment
- Bracket

Global Operators

None

Associated Global Functions

None

Named Public Member Functions

- size
- empty
- begin
- end
- resize
- insert
- remove
- swap

Review Basic Array Implementation

What data members should class **SmArray** have?

- Size of the array: size_type size_;
- Pointer to the array: value type * data ;

What class invariants should it have?

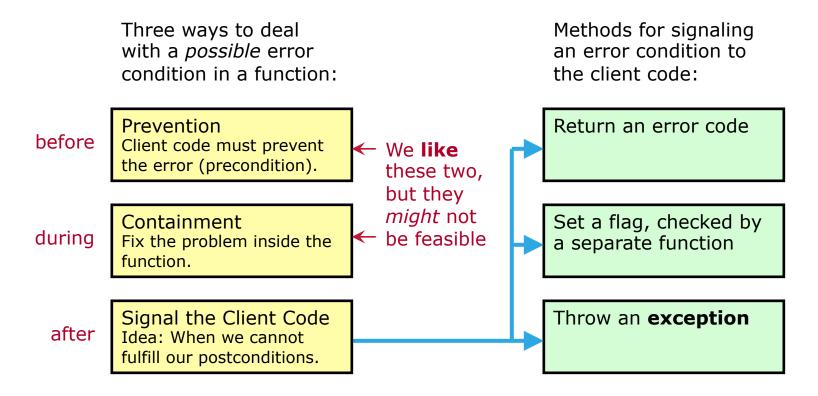
- Member "size" should be nonnegative.
- Member "data_" should point to an int array, allocated with new [], owned by *this, holding size ints.

Note: This design has a serious (but not obvious) problem, as we will see.

Review Exception Safety — Refresher [1/3]

An **error condition** (or "error") is a condition occurring during runtime that cannot be handled by the normal flow of execution.

- Not necessarily a bug or a user mistake.
- Example: Could not read file.



Review Exception Safety — Refresher [2/3]

Exceptions are objects that are "thrown", generally to signal error conditions.

We can catch **all** exceptions, using "...".

In this case, we do not get to look at the exception, since we do not know what type it is.

```
try {
    p = new Foo[mySize]; // May throw
}
catch (...) {
    fixThingsUp();
    throw;
}
```

• Inside any catch block, we can re-throw the same exception using throw with no parameters.

Review Exception Safety — Refresher [3/3]

The following can throw in C++:

- "throw" throws.
- "new" may throw std::bad_alloc if it cannot allocate.
- A function that (1) calls a function that throws, and (2) does not catch the exception, will throw.
- Functions written by others may throw. See their doc's.

The following do *not* throw:

- Built-in operations on built-in types.
 - Including the built-in operator[].
- Deallocation done by the built-in version of "delete".
 - Note: "delete" also calls destructors. These can throw.
- C++ Standard I/O Libraries (default behavior)

If a destructor is called between a throw and a catch, and that destructor throws, then the program terminates.

Therefore, destructors should not throw.

Exception Safety continued Introduction [1/2]

Issues: Does a function ever signal client code that an error has occurred, and if it does:

- Are the data left in a usable state?
- Do we know something about that state?
- Are resource leaks avoided?

These issues are collectively referred to as **safety**.

We consider these in the context of exceptions: **exception safety**.

However, most of the ideas we will discuss apply to any kind of error signaling technique.

Exception Safety Introduction [2/2]

There are a number of commonly used safety levels.

These are stated in the form of guarantees that a function makes.

In this class, we will adopt the convention that a function throws when it cannot satisfy its postconditions.

 When a function exits without satisfying its postconditions, we will say it has failed.

Thus, a function we write must do one of two things:

- Succeed (satisfy its postconditions), or
- Fail, throw an exception, and satisfy its safety guarantee.

Exception Safety The Three Standard Guarantees

Basic Guarantee

- Data remain in a usable state, and resources are never leaked, even in the presence of exceptions.
- Some people say "Weak guarantee." This is wrong. Catch me when I say it.

Strong Guarantee

 If the operation throws an exception, then it makes no changes that are visible to the client code.

No-Throw Guarantee

The operation never throws an exception.

Notes

- First set out by Dave Abrahams in the mid-1990s.
 - Thus, they are sometimes called the "Abrahams Guarantees".
- Written as part of the effort to standardize the C++ Standard Library.
 - However, they are applicable to more general contexts, not just C++.
- Each guarantee includes the previous one.
- The Basic Guarantee is the minimum standard for all code.
- The Strong Guarantee is the one we generally prefer.
- The No-Throw Guarantee is required in some special situations.

Exception Safety The Three Standard Guarantees — Basic Guarantee

Data remain in a usable state, and resources are never leaked, even in the presence of exceptions.

When a member function throws, an object may end up in an unknown state, but it must be a valid state, with invariants maintained.

This is minimum standard that we expect well-written code to meet.

• What happens if this standard is not met, and an exception is thrown?

Exception Safety The Three Standard Guarantees — Strong Guarantee

If the operation throws an exception, then it makes no changes that are visible to the client code.

- Changes can be made, but the client must not see them.
- In practice, we exempt things like logging from these requirements.
- Generally, any work that has been done, must be undone.
- Thus, this is also called commit or roll-back semantics.

We like this level of safety, and we write code that meets it whenever it is reasonable to do so.

But sometimes it is not reasonable, often due to efficiency concerns.

Exception Safety The Three Standard Guarantees — No-Throw Guarantee

The operation never throws an exception.

This is also know as the "No-Fail Guarantee".

This is the **highest** level of exception safety, but it is not necessarily the **best** level.

- Exceptions are not "bad". They are a tool that can help us deal with problematic situations. If we make the No-Throw Guarantee, then we have prohibited ourselves from using this tool.
- The No-Throw Guarantee does not say "errors do not occur"; rather, it says that if an error condition occurs, then we are not allowed to signal the client; we must fix it ourselves.

Sometimes it is important to make the No-Throw Guarantee, often in situations in which we are "finishing something".

- One such situation: destructors.
- Another situation ("commit functions") will be covered shortly.

Exception Safety Writing Exception-Safe Code — Ideas

To make sure code is exception-safe:

- Look at every place an exception might be thrown.
- For each, make sure that, if an exception is thrown, either
 - we terminate normally and meet our postconditions, or
 - we throw and meet our guarantees.

That can be a lot of work. However, **modularity** helps.

 Once we can certify a function as exception-safe, we can use it as such without re-examining it.

A bad design can force us to be unsafe.

- Thus, good design is part of of exception safety.
- In particular, an often helpful idea is that every module has exactly one well defined responsibility (the Single Responsibility Principle). Code that follows this principle is cohesive.
 - Suppose that a function has two things to do, and the second thing produces an error.
 - Suppose that the second thing, above, is when the function returns a value.
 - Thus, the rule: A non-const member function should not return an object by value.

Exception Safety Writing Exception-Safe Code — Write It

TO DO

 Figure out and comment the exception-safety guarantees made by all functions implemented so far in class SmArray.

Can/should any of these be improved?

Exception Safety Writing Exception-Safe Code — Write It

TO DO

 Figure out and comment the exception-safety guarantees made by all functions implemented so far in class SmArray.

- Can/should any of these be improved?
 - No. All the constructors offer the Strong Guarantee, which cannot be improved, since they do dynamic allocation, and so might fail. All other functions written so far offer the No-Throw Guarantee.

Exception Safety Commit Functions — The Need

Often it is tricky to offer the Strong Guarantee when modifying multiple parts of a large object.

- If we make several changes, and then we get an error, it can be difficult to undo the changes.
- In fact, it may be impossible, if the undo operation itself may result in an error.

Solution

- Create an entirely new object with the new value.
- If there is an error, destroy the new object. The old object has not changed, so there is nothing to roll back.
- If there is no error, commit to our changes using a non-throwing operation.

For many purposes, a good commit function is a non-throwing **swap** function.

Exception Safety Commit Functions — Swap [1/3]

Swap member functions usually look like this:

```
void MyClass::swap(MyClass & other);
```

This should exchange the values of *this and other.

Swap functions can *usually* be written very easily.

- Just swap the data members.
 - If they have swap methods, use them. Otherwise, use std::swap.
- Ownership issues are easy to handle properly (right?).

In fact, it is usually easy to write a swap function that is:

- Non-throwing.
- Very fast.

Exception Safety Commit Functions — Swap [2/3]

```
class MyClass {
private:
    int x;
    double y;
public:
    void swap(MyClass & other); // Does not throw
We can implement MyClass::swap like this:
void MyClass::swap(MyClass & other) // Does not throw
{
    int tempi = x;
    x = other.x;
    other.x = tempi;
    double tempd = y;
    y = other.y;
    other.y = tempd;
```

Exception Safety Commit Functions — Swap [3/3]

Alternatively, we can use std::swap, in <algorithm>:

```
void MyClass::swap(MyClass & other)
{
    std::swap(x, other.x);
    std::swap(y, other.y);
}
```

If we need to swap members that are **objects**, we might want to avoid std::swap.

- Algorithm std::swap uses the copy ctor and copy assignment. These might throw.
- If the objects have their own non-throwing swap member function, we can use that:

Note: if Foo is a class, then Foo is not a built-in type; it is an object. However, (Foo *) is a pointer, which **is** a built-in type.

Many C++ Standard Library classes have such a member function.

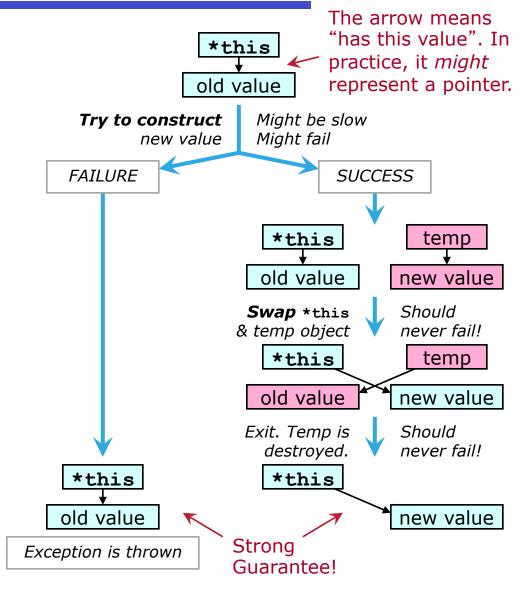
Exception Safety Commit Functions — Usage [1/3]

We can use a non-throwing swap function to get the Strong Guarantee.

To give our object a new value:

- First, try to construct a temporary object holding this new value.
- If this fails, exit. No change.
 - Exiting is automatic, if the failing operation throws.
- If the construction succeeds, then swap our object with the temporary object holding the new value.
- Exit. The destructor of the temporary object cleans up the old value of our object.
 - Destruction is automatic.
 - And it should never fail.

Note: boldface = code we write.



Exception Safety Commit Functions — Usage [2/3]

Thus, we can set an object to a new value, while offering the Strong Guarantee, as long as we have a way to construct the new value that offers the Strong Guarantee, along with a dctor and a swap function that offer the No-Throw Guarantee.

Procedure

- Try to construct a temporary object holding the new value.
- Swap with this temporary object.

Example: "clear" by swapping with a default-constructed temporary object.

Exception Safety Commit Functions — Usage [3/3]

This idea lets us write a copy assignment operator that makes the Strong Guarantee. We need:

- A copy ctor that offers the Strong Guarantee (this is usually not too difficult).
- A swap member function that makes the No-Throw Guarantee (usually easy).
- A dctor that makes the No-Throw Guarantee (of course).

Code:

```
MyClass & MyClass::operator=(const MyClass & rhs) // Strong Guarantee

Do the actual assignment:

1. Try to construct a temporary copy of rhs.

2. Swap with the temporary copy.

The old value is cleaned up by the destructor of temp (which does not throw).

Always end an assignment operator this way.
```

Admittedly this is a bit mind-twisting. However, assuming the requirements are met, it is easy to write, and it always works.

operator= Alternate version

Even better, we can pass by value (!):

```
MyClass & MyClass::operator=(MyClass rhs) // Strong Guarantee
{
    swap(rhs);
    return *this;
}
```

This will occasionally be more efficient because of copy elision. (Essentially, the compiler may optimize away some copies if they are unnecessary.)

This is the canonical version of operator=. Short, efficient, exception safe (Strong Guarantee), and correct!

Allocation & Efficiency Write It?

TO DO

Consider how to write SmArray::resize.

Ideas

Allocation & Efficiency Write It?

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Consider how to write SmArray::resize.

Ideas

- If we are resizing smaller than (or equal to) the current size, just change the size member to the new value.
- If we are resizing larger than the current size, then reallocate a large-enough chunk of memory for the array, copy the data there, and increase size to the new value ("reallocate-and-copy").

Allocation & Efficiency Write It?

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Consider how to write SmArray::resize.

Ideas

- If we are resizing smaller than (or equal to) the current size, just change the size member to the new value.
- If we are resizing larger than the current size, then reallocate a large-enough chunk of memory for the array, copy the data there, and increase size to the new value ("reallocate-and-copy").
- But the above method has a problem. For example, suppose we are using a Sequence object to implement a Stack. Pushing a new item on the end always requires a reallocate-and-copy, which will be very inefficient.

Allocation & Efficiency Amortized Constant Time [1/2]

For a smart array, insert-at-end is linear time.

- It is constant time if space is available (already allocated).
- It is linear time in general, due to reallocate-and-copy.

We can speed this up much of the time if we reallocate very rarely.

Idea: When we reallocate, get more memory than we need. Say twice as much. Then
do not reallocate again until we fill this up.

Now, using this idea, suppose we do **many** insert-at-end operations. How much time is required by *k* insert-at-end operations?

- Answer: O(k).
 - If, when we reallocate-and-copy, we increase the reserved memory by some constant factor.
- Even though a single operation is not O(1).

If k consecutive operations require O(k) time, we say the operation is **amortized** constant time.

- Amortized constant time means constant time on average over a large number of consecutive operations.
- It does **not** mean constant time on average over all possible inputs.
- This is our last efficiency-related terminology.

Allocation & Efficiency Amortized Constant Time [2/2]

Recall our time-efficiency categories.

Using Big-O	In Words
O(1)	Constant time
<i>O</i> (log <i>n</i>)	Logarithmic time
<i>O</i> (<i>n</i>)	Linear time
$O(n \log n)$	Log-linear time
$O(n^2)$	Quadratic time
$O(b^n)$, for some $b > 1$	Exponential time

Q: Where does "amortized constant time" fit in the above list?

Allocation & Efficiency Amortized Constant Time [2/2]

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Q: Where does "amortized constant time" fit in the above list?

A: It doesn't!

- The above are talking about the time taken by a single operation. "Amortized ..." is not.
- Insert-at-end for a well written smart array is amortized constant time. It is also still linear time.