

# Allocation & Efficiency

## Generic Containers

### Notes on Assignment 5

---

CS 311 Data Structures and Algorithms  
Lecture Slides  
Wednesday, March 27, 2013

Chris Hartman  
Department of Computer Science  
University of Alaska Fairbanks  
cmhartman@alaska.edu  
Based on material by Glenn G. Chappell  
© 2005–2009 Glenn G. Chappell

## Unit Overview

### Handling Data & Sequences

---

#### Major Topics

- ✓ ■ Data abstraction
- ✓ ■ Introduction to Sequences
  - Smart arrays
    - ✓ ■ Array interface
    - ✓ ■ Basic array implementation
    - ✓ ■ Exception safety
      - Allocation & efficiency
      - Generic containers
  - Linked Lists
    - Node-based structures
    - More on Linked Lists
  - Sequences in the C++ STL
  - Stacks
  - Queues

Issues: Does a function ever signal client code that an error has occurred, and if it does:

- Are the data left in a usable state?
- Do we know something about that state?
- Are resource leaks avoided?

These issues are collectively referred to as **safety**.

We consider these in the context of exceptions: **exception safety**.

However, **most of the ideas we will discuss apply to any kind of error signaling technique.**

There are a number of commonly used safety levels.

- These are stated in the form of **guarantees** that a function makes.

In this class, we will adopt the convention that a function throws when it cannot satisfy its postconditions.

- When a function exits without satisfying its postconditions, we will say it has **failed**.

Thus, a function we write must do one of two things:

- Succeed (satisfy its postconditions), or
- Fail, throw an exception, and satisfy its safety guarantee.

## **Basic Guarantee**

- Data remain in a usable state, and resources are never leaked, even in the presence of exceptions.
- Don't say "Weak guarantee"

## **Strong Guarantee**

- If the operation throws an exception, then it makes no changes that are visible to the client code.

## **No-Throw Guarantee**

- The operation never throws an exception.

## Notes

- Each guarantee includes the previous one.
- The Basic Guarantee is the minimum standard for all code.
- The Strong Guarantee is the one we generally prefer.
- The No-Throw Guarantee is required in some special situations.

To make sure code is exception-safe:

- Look at **every** place an exception might be thrown.
- For each, make sure that, if an exception is thrown, either
  - we terminate normally and meet our postconditions, or
  - we throw and meet our guarantees.

A bad design can force us to be unsafe.

- Thus, good design is part of exception safety.
- An often helpful idea is that every module has exactly one well defined responsibility (the **Single Responsibility Principle**).
- In particular: A non-const member function should not return an object by value.

## TO DO

- Figure out and comment the exception-safety guarantees made by all functions implemented so far in class **SmArray**.

*Done. See the latest versions of `smarray.h`, `smarray.cpp`, on the web page.*

- Can/should any of these be improved?
  - *No. All the constructors offer the Strong Guarantee, which cannot be improved, since they do dynamic allocation, and so might fail. All other functions written so far offer the No-Throw Guarantee.*

Often it is tricky to offer the Strong Guarantee when modifying multiple parts of a large object.

#### Solution

- Create an entirely new object with the new value.
- If there is an error, destroy the new object. The old object has not changed, so there is nothing to roll back.
- If there is no error, **commit** to our changes using a non-throwing operation.

A good commit function is a non-throwing **swap** function.



Swap member functions usually look like this:

```
void MyClass::swap(MyClass & other);
```

- This should exchange the values of `*this` and `other`.

If the data members are all built-in types (including pointers!), then we can usually just call `std::swap` on them.

```
void MyClass::swap(MyClass & other)
{
    std::swap(x, other.x);
    std::swap(y, other.y);
}
```

## Review

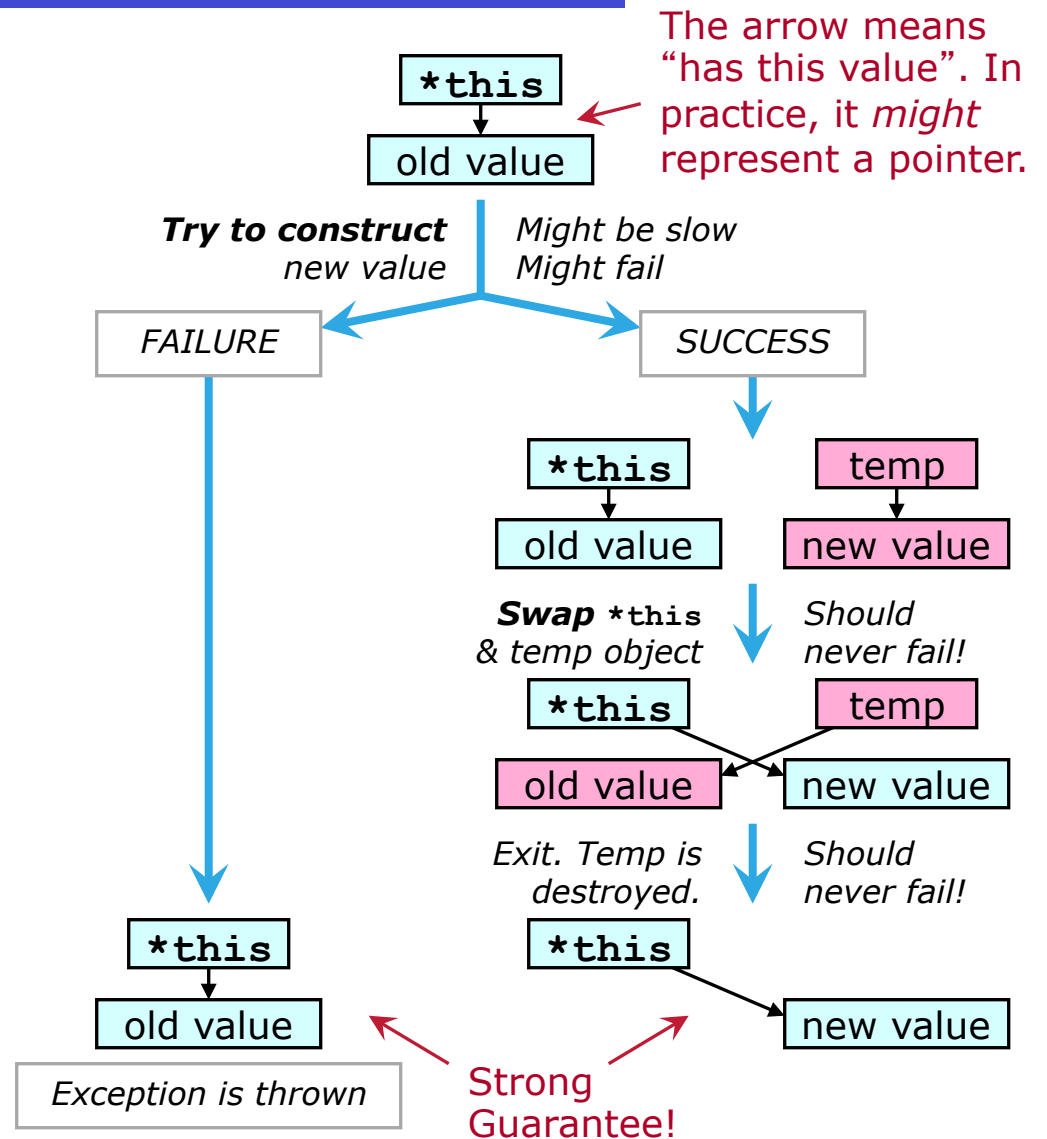
### Exception Safety — Commit Functions [3/5]

We can use a non-throwing swap function to get the Strong Guarantee.

To give our object a new value:

- First, **try to construct** a temporary object holding this new value.
- If this fails, exit. No change.
  - Exiting is automatic, if the failing operation throws.
- If the construction succeeds, then **swap** our object with the temporary object holding the new value.
- Exit. The destructor of the temporary object cleans up the old value of our object.
  - Destruction is automatic.
  - And it should never fail.

Note: boldface = code we write.



## Procedure

- **Try to construct** a temporary object holding the new value.
- **Swap** with this temporary object.

Example: “clear” by swapping with a default-constructed temporary object.

```
void MyClass::clear()    // Strong Guarantee
{
    MyClass temp;
    swap(temp);
}
```

## Review

### Exception Safety — Commit Functions [5/5]

---

This idea lets us write a copy assignment operator that makes the Strong Guarantee. We need:

- A copy ctor that offers the Strong Guarantee (this is usually not too difficult).
- A swap member function that makes the No-Throw Guarantee (usually easy).
- A dtor that makes the No-Throw Guarantee (of course).

Code:

```
MyClass & MyClass::operator=(MyClass rhs)  // Strong Guarantee
{
    swap(rhs);
    return *this;
}
```

Do the actual assignment:  
2. **Swap** with the temporary copy.

The old value is cleaned up by the destructor of `temp` (which does not throw).

Always end an assignment operator this way.

Admittedly this is a bit mind-twisting. However, assuming the requirements are met, it is easy to write, and it always works.

## Allocation & Efficiency

### Write It?

---

#### TO DO

- Consider how to write `SmArray::resize`.

#### *Ideas*

## Allocation & Efficiency

### Write It?

---

#### TO DO

- Consider how to write `SmArray::resize`.

#### *Ideas*

- *If we are resizing smaller than (or equal to) the current size, just change the `size_` member to the new value.*
- *If we are resizing larger than the current size, then reallocate a large-enough chunk of memory for the array, copy the data there, and increase `size_` to the new value (“reallocate-and-copy”).*

## Allocation & Efficiency

### Write It?

---

#### TO DO

- Consider how to write `SmArray::resize`.

#### *Ideas*

- *If we are resizing smaller than (or equal to) the current size, just change the `size_` member to the new value.*
- *If we are resizing larger than the current size, then reallocate a large-enough chunk of memory for the array, copy the data there, and increase `size_` to the new value (“reallocate-and-copy”).*
- *But the above method has a problem. For example, suppose we are using a Sequence object to implement a Stack. Pushing a new item on the end always requires a reallocate-and-copy, which will be very inefficient.*

## Allocation & Efficiency

### Amortized Constant Time [1/2]

---

For a smart array, insert-at-end is linear time.

- It is constant time if space is available (already allocated).
- It is linear time in general, due to reallocate-and-copy.

We can speed this up much of the time if we reallocate very rarely.

- Idea: When we reallocate, get more memory than we need. Say twice as much. Then do not reallocate again until we fill this up.

Now, using this idea, suppose we do **many** insert-at-end operations. How much time is required by  $k$  insert-at-end operations?

- Answer:  $O(k)$ .
  - If, when we reallocate-and-copy, we increase the reserved memory by some constant factor.
- Even though a single operation is not  $O(1)$ .

If  $k$  consecutive operations require  $O(k)$  time, we say the operation is **amortized constant time**.

- Amortized constant time means constant time on average over a large number of consecutive operations.
- It does **not** mean constant time on average over all possible inputs.
- This is our last efficiency-related terminology.



## Allocation & Efficiency

### Amortized Constant Time [2/2]

---

Recall our time-efficiency categories.

Using Big-O	In Words
$O(1)$	Constant time
$O(\log n)$	Logarithmic time
$O(n)$	Linear time
$O(n \log n)$	Log-linear time
$O(n^2)$	Quadratic time
$O(b^n)$ , for some $b > 1$	Exponential time

Q: Where does “amortized constant time” fit in the above list?

## Allocation & Efficiency

### Amortized Constant Time [2/2]

---

Recall our time-efficiency categories.

Using Big-O	In Words
$O(1)$	Constant time
$O(\log n)$	Logarithmic time
$O(n)$	Linear time
$O(n \log n)$	Log-linear time
$O(n^2)$	Quadratic time
$O(b^n)$ , for some $b > 1$	Exponential time

Q: Where does “amortized constant time” fit in the above list?

A: It doesn't!

- The above are talking about the time taken by a single operation. “Amortized ...” is not.
- Insert-at-end for a well written smart array is amortized constant time. It is also still linear time.

## Allocation & Efficiency

### Write It Again

---

How can we redesign class `SmArray` internally, so that we can write an amortized constant-time insert-at-end?

#### TO DO

- Finish the details of this new design. How does it work?
- Rewrite (most of) the existing member functions and invariants in `SmArray` to use the new design.

## Allocation & Efficiency

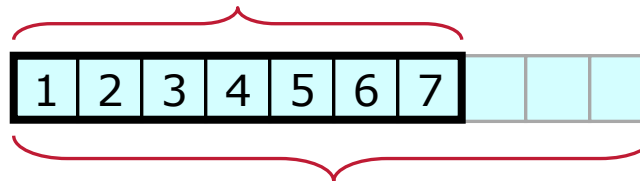
### Write It Again

---

How can we redesign class **SmArray** internally, so that we can write an amortized constant-time insert-at-end?

- A third data member can hold the amount of memory allocated. This is called the **capacity**.

What the client code sees (*size* = 7)



Allocated space (*capacity* = 10)

### TO DO

- Finish the details of this new design. How does it work?
- Rewrite (most of) the existing member functions and invariants in **SmArray** to use the new design.

## Generic Containers

### Introduction

---

A **generic container** is a container that can hold a client-specified data type.

Examples

- Arrays
- STL containers, including `std::vector`.

In C++, we usually implement a generic container using a **class template**.

## Generic Containers

### Class Templates — Recall ...

---

The C++ Standard does **not** require compilers to be able to do separate compilation of templates.

- Thus, you should define all member functions of a class template and all associated global function templates in your header file.
- With templates, you probably will not have a source (`.cpp`) file.

When people write code that uses your template, they need to know what types it is usable with.

- In this class, when writing a template, include comments indicating **requirements on the types** it takes as template parameters.
  - Typically: must have certain member functions and/or operators.
- It is assumed that member functions must all offer at least the Basic Guarantee. You do not need to mention this.
  - If you need some member function to offer a stronger guarantee (e.g., swap must not throw), then you *do* need to mention this.

## Generic Containers

### Exception Safety [1/3]

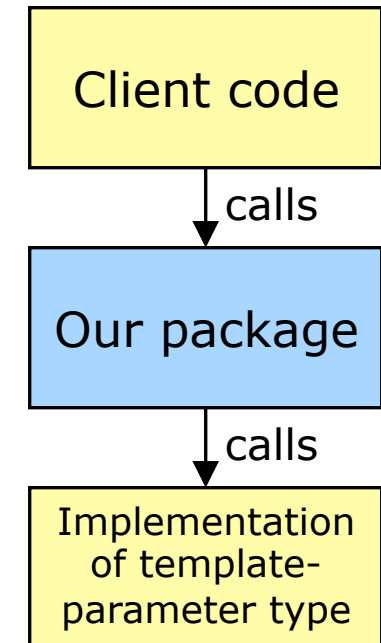
---

When we write a template, we deal with the type given to us using its own member functions. These client-provided functions **may throw**.

- Unless we require that they do not (in our “requirements on types”).

Exception safety gets trickier.

- The same procedures apply, but now we have many more places that might generate exceptions.



↑  
This code  
might throw ...

## Generic Containers

### Exception Safety [2/3]

---


Since **every** member function of a template parameter type, that is not specifically prohibited from throwing, may throw, we need to check **every** use of such a member function, to make sure that we deal with them correctly.

Do not forget:

- Silently called functions (default ctor & copy ctor).
- Operators (in particular: assignment).
- STL algorithms. Those that modify a data set (`std::copy`, `std::swap`, `std::rotate`, etc.) generally do so using the assignment operator. If the assignment operator can throw, then these STL algorithms can throw.

Do *not* worry about these when they are called on built-in types.

```
void size(std::size_t theSize) const;
```



Passed by value. Copy ctor call? But `std::size_t` is a built-in type; this will not throw.



## Generic Containers

### Exception Safety [3/3]

---

One tricky situation is copying the data in a dynamic array. Copy assignment of a class type can throw, often requiring deallocation.

```
arr = new MyType[size];  
std::copy(a, a+size, arr); // Memory leak, if MyType  
                           // copy assignment throws
```

We will come back to this example shortly.

## Generic Containers

### Exception Neutrality

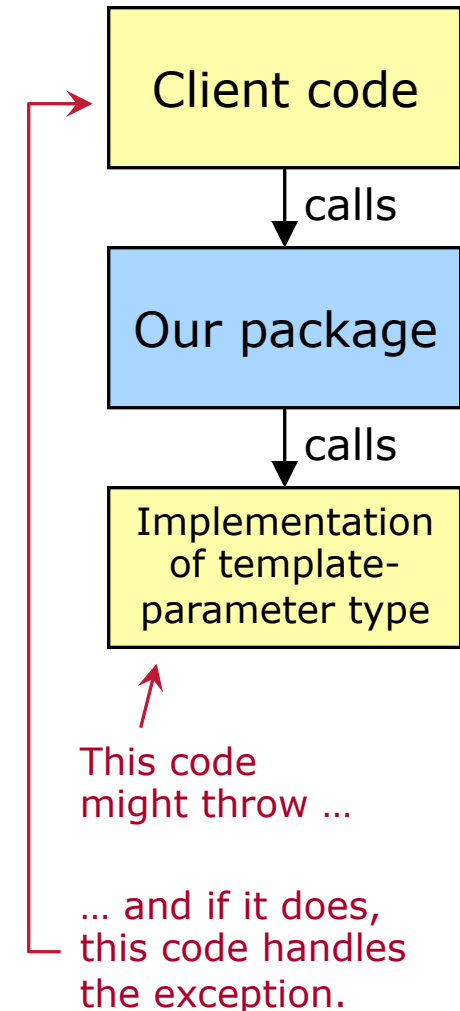
When we call client-provided functions, the client code generally handles any exceptions thrown.

**Exception-neutral** code allows exceptions thrown by client-provided code to propagate unchanged.

When such code calls a client-provided function that may throw, it must do one of two things:

- Call the function outside a try block, so that any exceptions terminate our code immediately.
- Or, call the function inside a try block, catch all exceptions, do necessary clean-up, and re-throw:

```
try {  
    x.func();    // May throw  
}  
catch (...) {    // Exception not handled here  
    [Do our own clean-up here]  
    throw;      // Re-throw same exception  
}
```



## Generic Containers

### Exception Safety & Neutrality Together

---

Putting it all together, we can use catch-all, clean-up, re-throw to get both exception safety and exception neutrality.

```
arr = new MyType[size];  
try  
{  
    std::copy(a, a+size, arr);  
}  
catch (...)  
{  
    delete [] arr;  
    throw;  
}
```

← Called outside any `try` block. If this fails, we exit immediately, throwing an exception.

← Called inside a `try` block. If this fails, we need to deallocate the array before exiting.

← This helps us meet the Basic Guarantee (also the Strong Guarantee if this function does nothing else).

← This makes our code exception-neutral.

## Notes on Assignment 5

### Overview of Ideas

---

This ends the material that Assignment 5 covers.

Next, we will look at node-based structures. You do *not* need to worry about these on Assignment 5.

You *do* need to be concerned with:

- Invariants, Templates
  - Document everything properly.
- Exception Safety
  - Are your member functions offering the proper guarantee?
    - All functions must offer *at least* the Basic Guarantee.
    - Constructors generally need to offer a high level of exception safety.
    - Destructors and commit functions (`swap`) offer an even higher level.
    - Functions that do large-scale modifications (`resize`, `insert`, `remove`) will probably not offer a high level, for the sake of efficiency.
  - Are your member functions *satisfying* their guarantees?
    - Have you checked every place that might throw.
    - For a template, this includes things like `std::copy`, `std::rotate`.
- Allocation & Efficiency
  - Are functions that might need to do a reallocate-and-copy (`resize`, `insert`) written to handle this efficiently?

## Notes on Assignment 5

### Individual Functions [1/2]

---

Thoughts on making some Assignment 5 member functions exception-safe and exception-neutral.

- Function **swap**
  - Use `std::swap` on all data members. *Example is on earlier slide.*
- Copy ctor
  - Allocate *outside* `try` block. Copy *inside* a `try` block. Catch-all, clean-up, re-throw. *Same idea as the code two slides back.*
- Copy assignment
  - Write as discussed earlier, using the copy ctor and **swap** (the member, *not* `std::swap`!). *Example is on an earlier slide.*
- Function **resize**
  - If resizing to  $\leq$  capacity: just set **size**.
  - If resizing to  $>$  capacity: create temp with the right size & capacity, `std::copy`, delete old & set members to new values.
    - The temp *could* be a separate object, and then you could use the swap trick. But if you do this, then make sure the temp's capacity and size are set correctly!
    - Alternatively, do not create a separate object. Have 3 variables that hold new values for the data members: **newSize**, **newCapacity**, **newData**. If this works, then delete the old data, and set all 3 data members to the new values.

## Notes on Assignment 5

### Individual Functions [2/2]

---

#### Thoughts (cont' d)

- Function **remove**
  - You need to resize the array. Function **resize** does this. Use it!
  - Suggestion: Do a **std::rotate**, and then call **resize**.
- Function **insert**
  - Again, call **resize** to do the resizing of the array. Do not duplicate code!
  - Suggestion: Call **resize**, put the new item in, and then **std::rotate**.
  - At the end, you need to return an iterator to the inserted item. This *would* be the same as the parameter, except that **resize** might have done a reallocate-and-copy. So: *Before* calling **resize**, save the *index* of the spot to insert, and then afterwards recreate the iterator from this index, and return it.