

The Quasi-Static Approximation

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For resting air, the equation of vertical motion reduces to

$$\frac{\partial p}{\partial z} = -\rho g . \quad (32.1)$$

This is called the hydrostatic approximation. With appropriate boundary conditions, (32.1) allows us to compute p from $\rho(z)$. Even when the air is moving, (32.1) gives a good approximation to $p(z)$, simply because $\frac{Dw}{Dt}$ is small. *Under what conditions can this approximate $p(z)$ be used to compute the pressure gradient force in the equation of horizontal motion?* To do so is to use the *quasi-static approximation*.

To investigate the range of validity of the quasistatic approximation, let

$$\begin{aligned} p &= p_s(z) + \delta p , \\ \alpha &= \alpha_s(z) + \delta \alpha , \end{aligned} \quad (32.2)$$

where subscript s denotes a “reference sounding” that varies with height only. Assume that the reference state is hydrostatically balanced, i.e.

$$\alpha_s \frac{\partial p_s}{\partial z} = -g . \quad (32.3)$$

The vertical momentum equation can be written as

$$\frac{Dw}{Dt} = -\alpha_s \frac{\partial p_s}{\partial z} - \delta \alpha \frac{\partial p_s}{\partial z} - \alpha_s \frac{\partial \delta p}{\partial z} - \delta \alpha \frac{\partial \delta p}{\partial z} - g . \quad (32.4)$$

Here we neglect friction. The first and last terms on the right-hand-side of (32.4) cancel, because of (32.3). The second-to-last term on the right-hand side of (32.4) is dropped because it contains the product of two δ 's. This is justified if $\alpha_s \gg |\delta\alpha|$, and $p_s \gg |\delta p|$.

Again neglecting friction, the horizontal momentum equation is

$$\frac{D\mathbf{V}_H}{Dt} = -\alpha \nabla_H(\delta p) - f\mathbf{k} \times \mathbf{V}_H.$$

$$NV \ll \alpha_s \frac{\delta p}{L} \ll fV \quad (32.5)$$

Here N^{-1} is a time scale, L is a horizontal length scale, and V is a horizontal velocity scale. We scale the remaining terms of (32.4) as follows:

$$\frac{Dw}{Dt} \equiv \frac{\delta\alpha}{\alpha_s} g - \alpha_s \frac{\partial}{\partial z}(\delta p).$$

$$NW \ll \alpha_s \frac{\delta p}{D} \quad (32.6)$$

Here W is a vertical velocity scale, and D is a depth scale.

Consider two cases:

1) $N \geq f$ (short time scale)

This is the case in which the advective time scale, N^{-1} , is small compared to an inertial period, which is usually true for *small-scale motions*. If $N \sim \frac{V}{L}$, then $N \geq f$ is equivalent to $Ro \geq 1$, where $Ro \equiv \frac{V}{fL}$. For this case, we find from (32.5) that

$$\alpha_s \delta p \sim NLV. \quad (32.7)$$

To have $\left| \frac{Dw}{Dt} \right| \ll \left| \alpha \frac{\partial}{\partial z}(\delta p) \right|$ we need

$$NW \ll \frac{NLV}{D}, \quad (32.8)$$

or

$$\left(\frac{W}{D} \cdot \frac{L}{V}\right) \left(\frac{D}{L}\right)^2 \ll 1 . \quad (32.9)$$

Normally (from continuity), we have

$$\frac{W}{D} \cdot \frac{L}{V} \leq 1 , \quad (32.10)$$

provided that the stratification is stable. Then (32.9) shows that “fast” motions can be quasistatic if they are “shallow,” but not if they are “deep.”

2) $N \leq f$ (long time scale)

This is the case in which the advective time scale is relatively long, which is usually true for *large-scale motions*. If we assume that $N \sim \frac{V}{L}$, then $N \leq f$ is equivalent to $Ro \leq 1$. For this case, (32.5) leads to

$$\alpha_s \delta p \sim f L V , \quad (32.11)$$

which is essentially an expression of geostrophic balance. To have $\left| \frac{Dw}{Dt} \right| \ll \left| \alpha_s \frac{\partial}{\partial z} (\delta p) \right|$ we need

$$N W \ll f L \frac{V}{D} , \quad (32.12)$$

or

$$\left(\frac{W}{D} \cdot \frac{L}{V}\right) \left(\frac{D}{L}\right)^2 \frac{N}{f} \ll 1 . \quad (32.13)$$

Compare this with (32.9). The only difference is the factor of $\frac{N}{f}$. From (32.9), we see that

$$\left(\frac{D}{L}\right)^2 \ll 1 , \quad (32.14)$$

i.e. “shallow motion,” is sufficient for quasistatic balance. When $N \ll f$ (long time scale), we can have quasistatic balance even for $\left(\frac{D}{L}\right)^2 \sim 1$.

When the quasistatic approximation is made, the effective kinetic energy is due

entirely to the horizontal motion; the vertical component, w , makes no contribution. For large-scale motions, $w \ll (u, v)$, so that this quasistatic kinetic energy is very close to the true kinetic energy.