

Introduction to Molecular Dynamics

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1

Molecular Dynamics

- Science of simulating the motions of a system of particles
- Can be applied to many systems
 - Atoms, small molecules,
 - Biological macromolecules – proteins, DNA, RNA, ...
 - Systems may go as large as a galaxy
- Essential elements
 - Interaction potential → forces on particles
 - Equations of motion

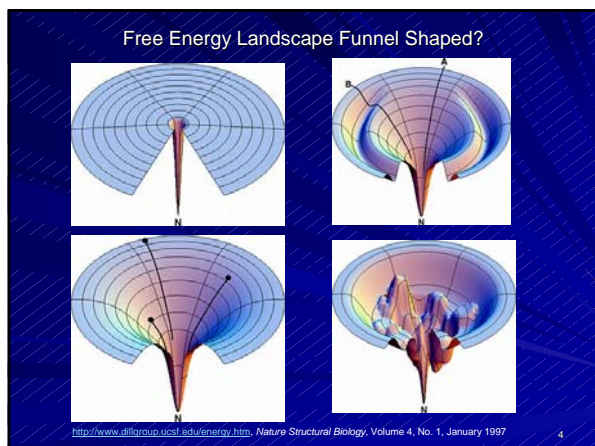
2

Why Molecular Dynamics

- Anfinsen's Hypothesis
 - All the information necessary to determine the structure of a protein is in the primary sequence.
 - The native conformation of a protein is the conformation with the lowest global free energy.
- Levinthal's Paradox
 - The number of possible conformations is far too large for a protein to visit them all in the time available for folding.

3 states for each of 50 a.a. x 2 dihedrals = 3^{100} conformations
 10^{15} conformations/sec x 3×10^7 sec/year = 3×10^{20} conformations per year
Approximately 1.7×10^{27} years to try all the conformations

3



Molecular Dynamics

- Simulates the behavior of molecules by integrating Newton's laws of motion
- A trajectory is obtained by solving the following equation for each time step

$$\frac{d^2 x_i}{dt^2} = \frac{F_{x_i}}{m_i}$$

Molecular Mechanics Energy Function

$$E = \sum_{\text{bonds}} \frac{1}{2} K_r (r - r_0)^2 + \sum_{\text{angles}} \frac{1}{2} K_\theta (q - q_0)^2 + \sum_{\text{torsions}} \frac{V}{2} [1 + \cos(n\phi - \phi_0)] + \sum_{i < j} \left[\frac{A_{ij}}{R_{ij}^{12}} - \frac{B_{ij}}{R_{ij}^6} + \frac{q_i q_j}{e R_{ij}} \right]$$

Molecular Dynamics

$$\frac{d^2 x_i}{dt^2} = \frac{F_{x_i}}{m_i}$$

$$x(t + \Delta t) = x(t) + x'(t) \Delta t + x''(t) \frac{\Delta t^2}{2} + \dots$$

Integration Methods

Finite Difference Methods

- Verlet Algorithm¹
- Leap-frog Algorithm²
- Velocity Verlet Method³

Predictor – Corrector Integration Methods

- Gear predictor – corrector method⁴

¹ Verlet, Physical Review 159:98-103, 1967

² Hockney, Methods in Computational Physics, 9:136-211, 1970

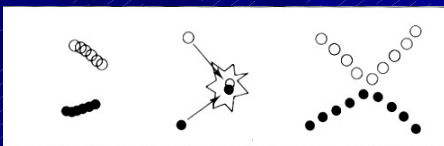
³ Swope et. al., Journal of Chemical Physics, 76:637-649, 1982

⁴ Gear, Numerical Initial Value Problems in Ordinary Differential Equations, Englewood Cliffs, NJ, Prentice Hall, 1971

7

Choosing a time step

- Too small → incomplete sampling
- Too large → instabilities
- Typical Time Steps: 1 – 2 fs (10^{-15} s)



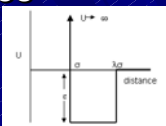
Leach, Molecular Modelling, 2nd Edition, 2001

8

Simulation Types

Simple Models

- Hard-sphere model
- Square-well potential



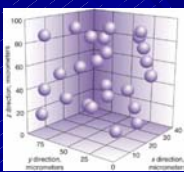
<http://physchem.ox.ac.uk/~rkt/lectures/figpotnsg/problems1.html>

Continuous Potentials

- Lattice / Off lattice simulations
- United-Atom / All-Atom simulations
- Implicit / Explicit solvent simulations

Enhanced Sampling Techniques

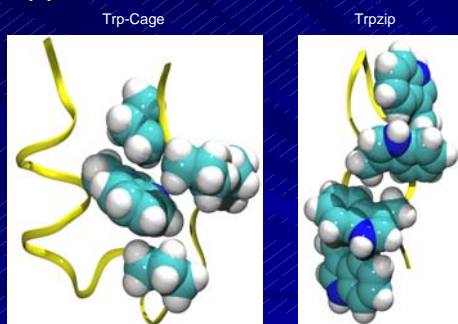
- Replica Exchange Method
- Locally Enhanced Sampling etc...



<http://www.lml.gov.it/December01/Claudio.html>

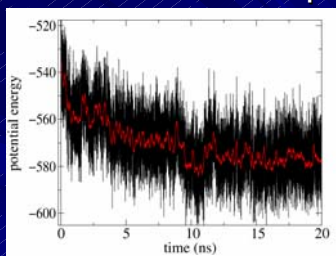
9

Applications and Selected Results



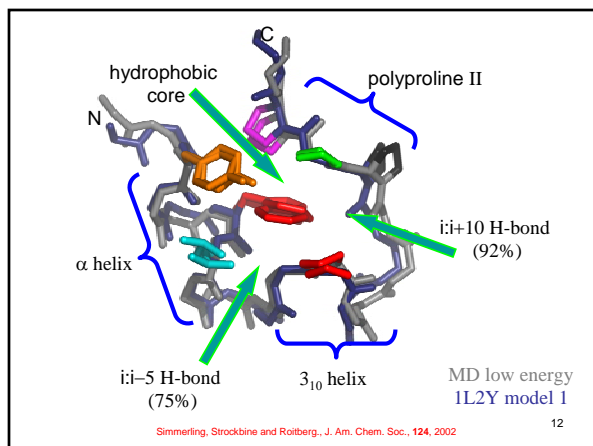
10

Structure Prediction – Trp-Cage



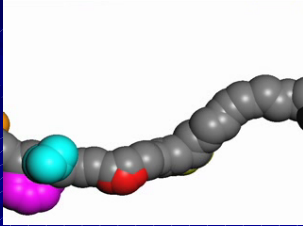
- Linear initial structure
- Potential energy reaches plateau
- Structure with lowest potential energy selected as "best"

11



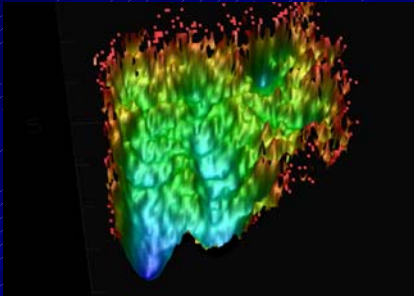
12

Folding of Trp-Cage



13

Free Energy Landscape of Trp-Cage



14

Conclusions

- Molecular Dynamics can be used in
 - Structure prediction
 - Loop modeling and structure refinement
 - Folding and unfolding kinetics and pathways
 - Thermodynamic properties
 - Drug design
 - Free energy calculations
- Common problems
 - Parameterization
 - Convergence

15



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17

6