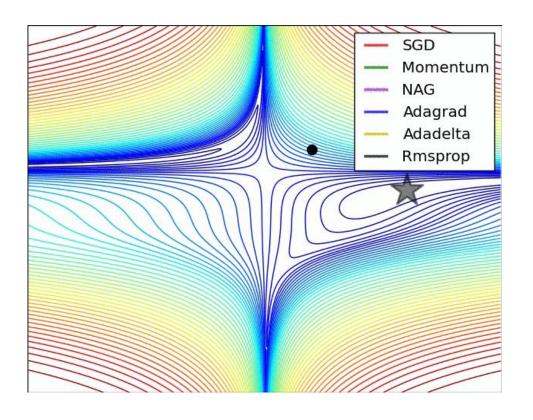
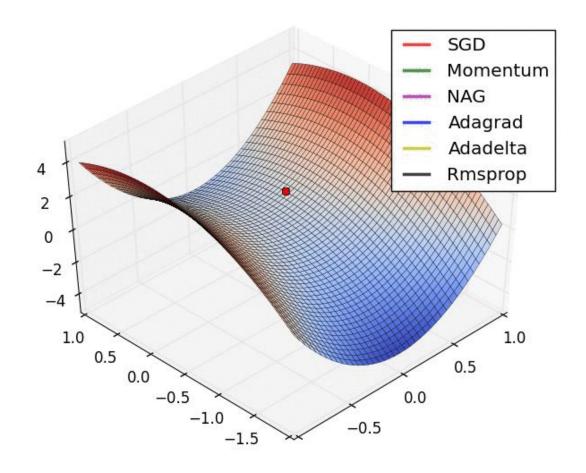
## **OPTIMIZERS**





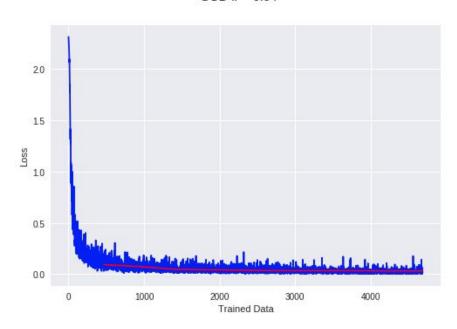
Francesc Cabrera Hamza Errahmouni David Molins Guillem Viladrich

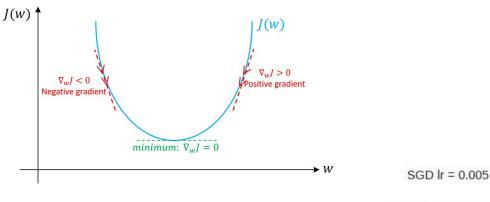
### **Stochastic Gradient Descent**

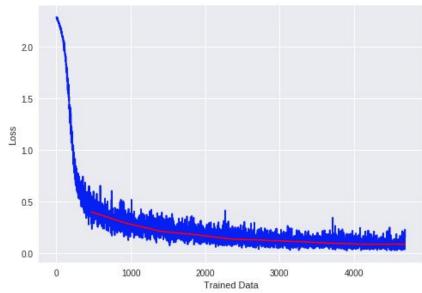
### **Learning Rate**

$$\theta_t = \theta_{t-1} - \alpha \nabla_{\theta} \mathcal{L}(\theta_{t-1})$$
 Evaluated on a mini-batch

SGD Ir = 0.04





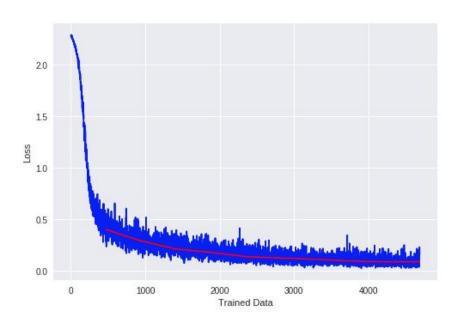


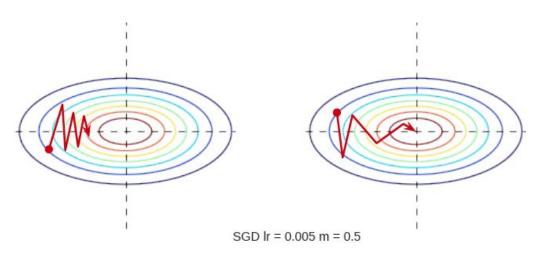
## **Stochastic Gradient Descent**

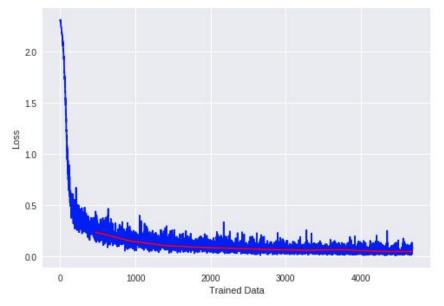
#### **Momentum**

$$v_t = \gamma v_{t-1} + \alpha \nabla_{\theta} \mathcal{L}(\theta_{t-1})$$
  
$$\theta_t = \theta_{t-1} - v_t$$

SGD lr = 0.005







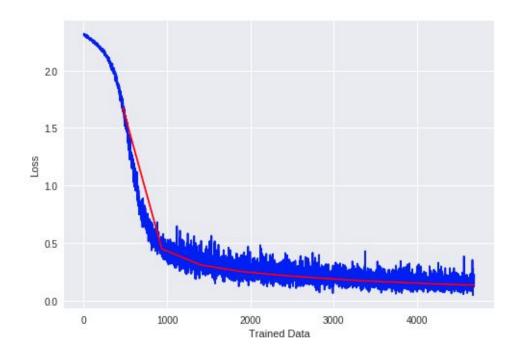
## **Stochastic Gradient Descent**

### **Nesterov momentum**

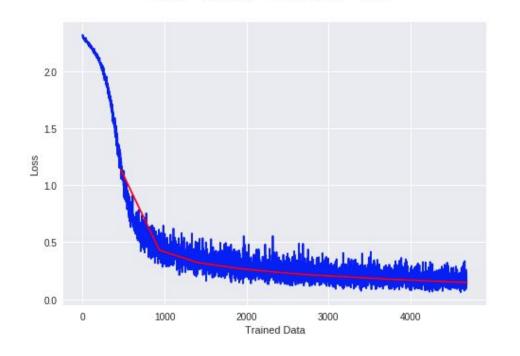
$$v_t = \gamma v_{t-1} + \alpha \nabla_{\theta} \mathcal{L}(\theta_{t-1} - \gamma v_{t-1})$$

$$\theta_t = \theta_{t-1} - v_t$$

SGD Ir = 0.001 m = 0.5 Nesterov = False



SGD lr = 0.001 m = 0.5 Nesteroy = True

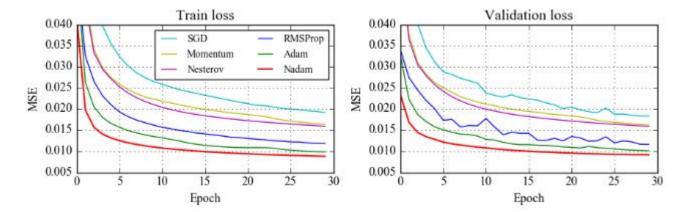


## Adam

Actual step size taken by the Adam in each iteration is approximately bounded the step size hyper-parameter. This property add intuitive understanding to previous unintuitive learning rate hyper-parameter.

Step size of Adam update rule is invariant to the magnitude of the gradient, which helps a lot when going through areas with tiny gradients (such as saddle points or ravines). In these areas SGD struggles to quickly navigate through them.

However, after a while people started noticing that despite superior training time, Adam in some areas does not converge to an optimal solution, so for some tasks



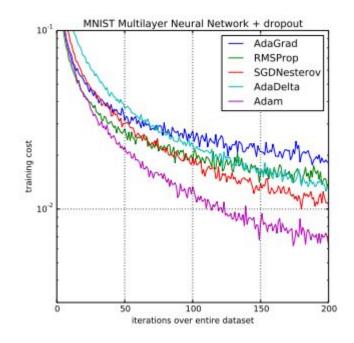
$$egin{aligned} \hat{m}_t &= egin{aligned} \hat{m}_t &= egin{aligned} \hat{m}_t &= egin{aligned} \hat{m}_t &= egin{aligned} \hat{v}_t &= eta_1 & & & & \\ v_t &= eta_2 v_{t-1} + (1-eta_2) g_t^2 & & & & & \\ v_t &= egin{aligned} \hat{v}_t &= egin{aligned} v_t & & & & \\ \hline 1-eta_1^t & & & & \\ \hline 1-eta_1^t & & & & \\ \hline 1-eta_1^t & & & \\ \hline \end{array} egin{aligned} \hat{v}_t &= egin{aligned} \phi_t &= eta_t - egin{aligned} \eta \\ \hline \sqrt{\hat{v}_t} + \epsilon & \\ \hline \end{array} egin{aligned} \hat{v}_t &= egin{aligned} \psi_t &= egin{ali$$

#### Algorithm 1. Adam Optimization Algorithm

1: **procedure** ADAM $(f, \theta_0; \alpha, \beta_1, \beta_2)$ 

**Require:** Objective function  $f(\theta)$ , initial parameters  $\theta_0$ , stepsize hyperparameter  $\alpha$ , exponential decay rates  $\beta_1, \beta_2$  for moment estimates, tolerance parameter  $\lambda > 0$  for numerical stability, and decision rule for declaring convergence of  $\theta_t$  in scheme.

```
m_0, v_0, t \leftarrow [0, 0, 0]
                                                                    # Initialize moment estimates
                                                                    # and timestep to zero
 3:
          # Begin optimization procedure
 4:
         while \theta_t has not converged do
 5:
              t \leftarrow t+1
                                                                    # Update timestep
              q_t \leftarrow \nabla_{\theta} f_t(\theta_{t-1})
                                                                    # Compute gradient of objective
              m_t \leftarrow \beta_1 \cdot m_{t-1} + (1 - \beta_1) \cdot q_t
                                                                    # Update first moment estimate
              v_t \leftarrow \beta_2 \cdot v_{t-1} + (1 - \beta_2) \cdot (g_t \odot g_t) \# \text{Update second moment estimate}
              \widehat{m}_t \leftarrow m_t/(1-\beta_1^t)
                                                                    # Create unbiased estimate \widehat{m}_t
10:
              \widehat{v}_t \leftarrow v_t/(1-\beta_2^t)
                                                                    # Create unbiased estimate \hat{v}_t
11:
              \theta_t \leftarrow \theta_{t-1} - \alpha \cdot \widehat{m}_t / (\sqrt{\widehat{v}_t} + \lambda)
                                                                    # Update objective parameters
12:
                                                                    # Return final parameters
         return \theta_t
13:
```



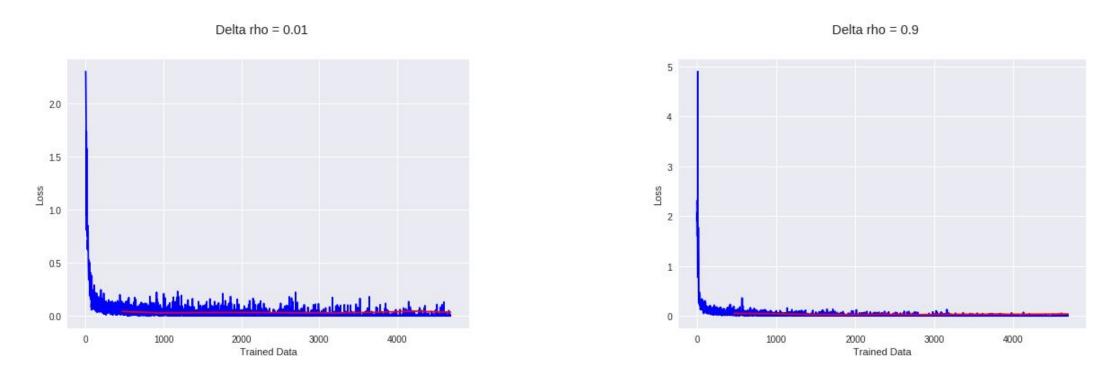
## Adadelta

Adadelta is a more robust extension of Adagrad that adapts learning rates based on a moving window of gradient updates, instead of accumulating all past gradients. This way, Adadelta continues learning even when many updates have been done, the recommended initialization values for pytorch are the following:

- rho (float, optional) coefficient used for computing a running average of squared gradients (default: 0.9)
- eps (*float*, *optional*) term added to the denominator to improve numerical stability (default: 1e-6)
- Ir (<u>float</u>, optional) coefficient that scale delta before it is applied to the parameters (default: 1.0)
- weight\_decay (*float*, *optional*) weight decay (L2 penalty) (default: 0)

## Adadelta

We tested Adadelta changing rho between 0.01 and 0.9 (recommendation):



As we can see there is not much difference between one case and the other, there's more loss when rho=0.01, but the accuracy is 99% in both cases. So we can assume Adadelta is so robust that can adapt its parameters properly.

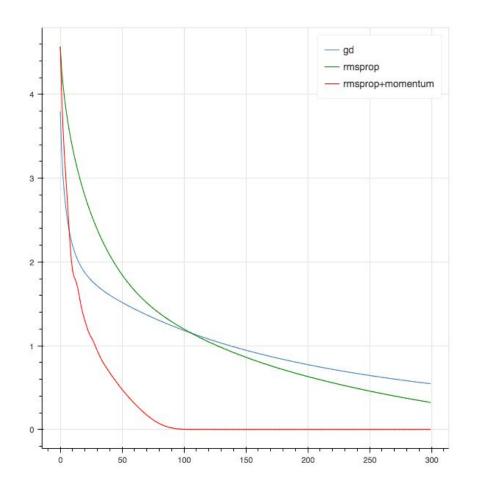
## **RMSprop**

Modification of Adagrad to address aggressively decaying learning rate.

Instead of storing sum of squares of gradient over all time steps so far, use a **decayed moving average** of sum of squares of gradients

$$G_t = \gamma G_{t-1} + (1 - \gamma) \operatorname{diag}(\nabla \mathcal{L}(\theta))^2$$

Update rule: 
$$heta_t = heta_{t-1} - lpha G_t^{-rac{1}{2}} 
abla \mathcal{L}( heta_{t-1})$$



The RMSprop optimizer is similar to the gradient descent algorithm with momentum.

## **RMSprop**

The RMSprop optimizer **restricts** the oscillations in the **vertical direction**. Therefore, we can increase our learning rate and our algorithm could take **larger steps** in the **horizontal direction** converging faster.

The difference between RMSprop and gradient descent is on how the gradients are calculated. The value of momentum is denoted by beta and is usually set to 0.9. A good default value for the learning rate is 0.001.

$$egin{align} v_{dw} &= eta \cdot v_{dw} + (1-eta) \cdot dw^2 & v_{dw} &= eta \cdot v_{dw} + (1-eta) \cdot dw \ v_{db} &= eta \cdot v_{dw} + (1-eta) \cdot db^2 & v_{db} &= eta \cdot v_{dw} + (1-eta) \cdot db \ W &= W - lpha \cdot rac{dw}{\sqrt{v_{dw}} + \epsilon} & W &= W - lpha \cdot v_{dw} \ b &= b - lpha \cdot rac{db}{\sqrt{v_{db}} + \epsilon} & b &= b - lpha \cdot v_{db} \ \end{pmatrix}$$

# Analysis:

We'll observe how the optimizers work on the accuracy, convergence and its speed.

These factors vary a lot depending on the learning rate if we talk about SGD, Adam and RMSprop, so we'll analyse them depending on the value of this hyper parameter that we have.

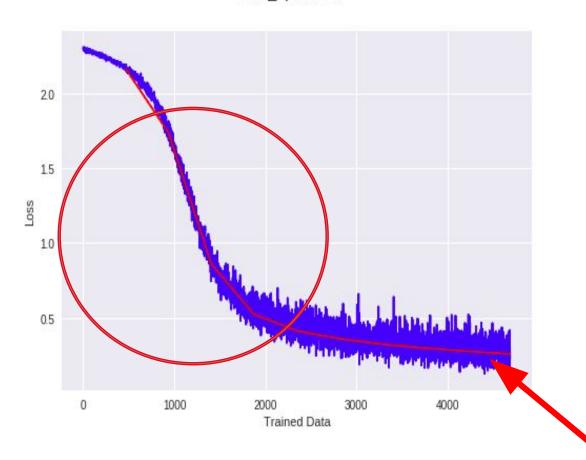
At the same time, the effect on the betas on Adam vary a lot so we'll analyze the general case scenarios

Adadelta depends specifically on the parameter rho.

```
Parameter Group 0
    dampening: 0
    lr: 0.0005
    momentum: 0.5
    nesterov: False
    weight_decay: 0
Validation set: Average loss: 2.1605, Accuracy: 5517/10000 (55%)
Validation set: Average loss: 1.7345, Accuracy: 7321/10000 (73%)
Validation set: Average loss: 0.8599, Accuracy: 8362/10000 (84%)
Validation set: Average loss: 0.5235, Accuracy: 8700/10000 (87%)
Validation set: Average loss: 0.4134, Accuracy: 8892/10000 (89%)
Validation set: Average loss: 0.3605, Accuracy: 8977/10000 (90%)
Validation set: Average loss: 0.3239, Accuracy: 9069/10000 (91%)
Validation set: Average loss: 0.2977, Accuracy: 9154/10000 (92%)
Validation set: Average loss: 0.2765, Accuracy: 9188/10000 (92%)
Validation set: Average loss: 0.2582, Accuracy: 9240/10000 (92%)
```

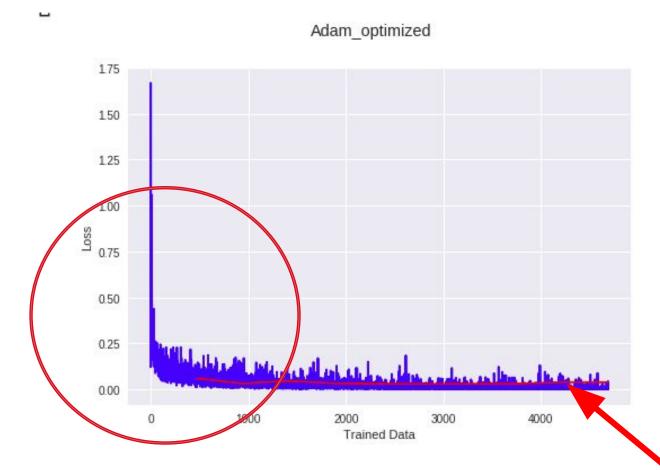
#### SGD Ir = 0.0005

SGD\_optimized



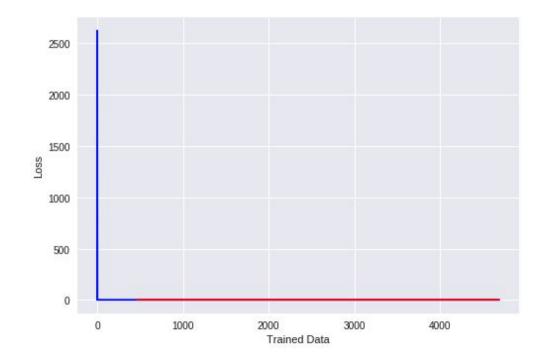
```
Adam (
Parameter Group 0
       amsgrad: False
       betas: (0.9, 0.999)
       eps: 1e-08
       lr: 0.0005
       weight decay: 0
   Validation set: Average loss: 0.0604, Accuracy: 9809/10000 (98%)
   Validation set: Average loss: 0.0331, Accuracy: 9891/10000 (99%)
   Validation set: Average loss: 0.0460, Accuracy: 9850/10000 (98%)
   Validation set: Average loss: 0.0340, Accuracy: 9880/10000 (99%)
   Validation set: Average loss: 0.0308, Accuracy: 9897/10000 (99%)
   Validation set: Average loss: 0.0292, Accuracy: 9907/10000 (99%)
   Validation set: Average loss: 0.0303, Accuracy: 9908/10000 (99%)
   Validation set: Average loss: 0.0310, Accuracy: 9914/10000 (99%)
   Validation set: Average loss: 0.0396, Accuracy: 9889/10000 (99%)
   Validation set: Average loss: 0.0393, Accuracy: 9900/10000 (99%)
```

#### ADAM Ir = 0.0005



# **RMSprop**

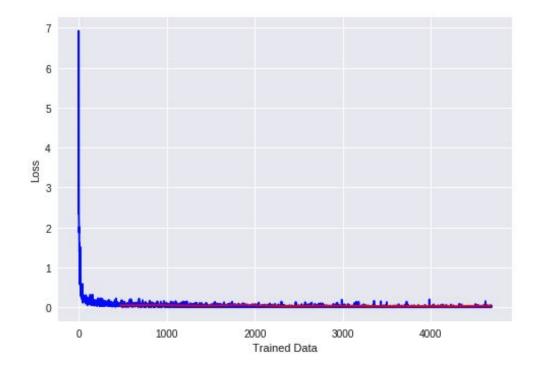
```
RMSprop (
Parameter Group 0
    alpha: 0.99
    centered: False
    eps: 1e-08
    lr: 0.01
    momentum: 0
    weight_decay: 0
)
```



```
Training with opt: RMS -- Train epoch: 1 -- Validation Average loss: 2.3016, Accuracy: 1135/10000 (11%)
Training with opt: RMS -- Train epoch: 2 -- Validation Average loss: 2.3026, Accuracy: 1135/10000 (11%)
Training with opt: RMS -- Train epoch: 3 -- Validation Average loss: 2.3016, Accuracy: 1135/10000 (11%)
Training with opt: RMS -- Train epoch: 4 -- Validation Average loss: 2.3011, Accuracy: 1135/10000 (11%)
Training with opt: RMS -- Train epoch: 5 -- Validation Average loss: 2.3015, Accuracy: 1135/10000 (11%)
Training with opt: RMS -- Train epoch: 6 -- Validation Average loss: 2.3017, Accuracy: 1135/10000 (11%)
Training with opt: RMS -- Train epoch: 7 -- Validation Average loss: 2.3015, Accuracy: 1135/10000 (11%)
Training with opt: RMS -- Train epoch: 8 -- Validation Average loss: 2.3016, Accuracy: 1135/10000 (11%)
Training with opt: RMS -- Train epoch: 9 -- Validation Average loss: 2.3015, Accuracy: 1135/10000 (11%)
Training with opt: RMS -- Train epoch: 10 -- Validation Average loss: 2.3015, Accuracy: 1135/10000 (11%)
```

# **RMSprop**

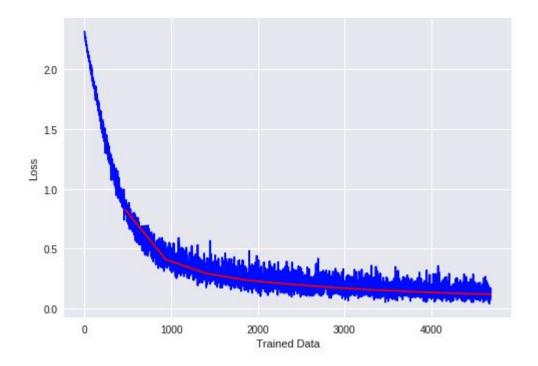
```
RMSprop (
Parameter Group 0
    alpha: 0.99
    centered: False
    eps: 1e-08
    lr: 0.001
    momentum: 0
    weight_decay: 0
)
```



```
Training with opt: RMS -- Train epoch: 1 -- Validation Average loss: 0.0520, Accuracy: 9831/10000 (98%)
Training with opt: RMS -- Train epoch: 2 -- Validation Average loss: 0.0571, Accuracy: 9809/10000 (98%)
Training with opt: RMS -- Train epoch: 3 -- Validation Average loss: 0.0424, Accuracy: 9864/10000 (99%)
Training with opt: RMS -- Train epoch: 4 -- Validation Average loss: 0.0583, Accuracy: 9821/10000 (98%)
Training with opt: RMS -- Train epoch: 5 -- Validation Average loss: 0.0291, Accuracy: 9907/10000 (99%)
Training with opt: RMS -- Train epoch: 6 -- Validation Average loss: 0.0414, Accuracy: 9864/10000 (99%)
Training with opt: RMS -- Train epoch: 7 -- Validation Average loss: 0.0324, Accuracy: 9903/10000 (99%)
Training with opt: RMS -- Train epoch: 8 -- Validation Average loss: 0.0315, Accuracy: 9909/10000 (99%)
Training with opt: RMS -- Train epoch: 9 -- Validation Average loss: 0.0304, Accuracy: 9920/10000 (99%)
Training with opt: RMS -- Train epoch: 10 -- Validation Average loss: 0.0411, Accuracy: 9901/10000 (99%)
```

# **RMSprop**

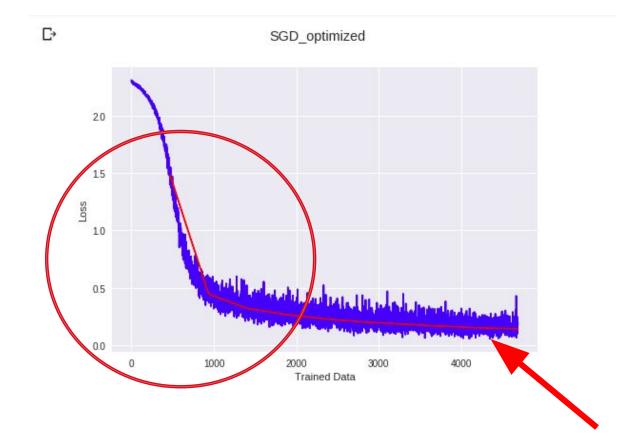
```
RMSprop (
Parameter Group 0
    alpha: 0.99
    centered: False
    eps: 1e-08
    lr: 1e-05
    momentum: 0
    weight_decay: 0
)
```



```
Training with opt: RMS -- Train epoch: 1 -- Validation Average loss: 0.8277, Accuracy: 8580/10000 (86%)
Training with opt: RMS -- Train epoch: 2 -- Validation Average loss: 0.4112, Accuracy: 9013/10000 (90%)
Training with opt: RMS -- Train epoch: 3 -- Validation Average loss: 0.2947, Accuracy: 9203/10000 (92%)
Training with opt: RMS -- Train epoch: 4 -- Validation Average loss: 0.2382, Accuracy: 9335/10000 (93%)
Training with opt: RMS -- Train epoch: 5 -- Validation Average loss: 0.2062, Accuracy: 9424/10000 (94%)
Training with opt: RMS -- Train epoch: 6 -- Validation Average loss: 0.1802, Accuracy: 9475/10000 (95%)
Training with opt: RMS -- Train epoch: 7 -- Validation Average loss: 0.1598, Accuracy: 9535/10000 (95%)
Training with opt: RMS -- Train epoch: 8 -- Validation Average loss: 0.1438, Accuracy: 9593/10000 (96%)
Training with opt: RMS -- Train epoch: 9 -- Validation Average loss: 0.1296, Accuracy: 9632/10000 (96%)
Training with opt: RMS -- Train epoch: 10 -- Validation Average loss: 0.1217, Accuracy: 9665/10000 (97%)
```

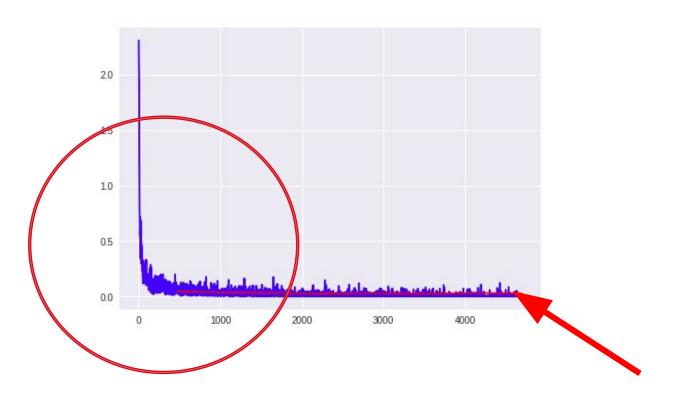
```
Parameter Group 0
        dampening: 0
        lr: 0.001
        momentum: 0.5
        nesterov: False
       weight_decay: 0
   Validation set: Average loss: 1.4816, Accuracy: 7719/10000 (77%)
   Validation set: Average loss: 0.4470, Accuracy: 8855/10000 (89%)
   Validation set: Average loss: 0.3211, Accuracy: 9098/10000 (91%)
   Validation set: Average loss: 0.2686, Accuracy: 9231/10000 (92%)
   Validation set: Average loss: 0.2310, Accuracy: 9320/10000 (93%)
   Validation set: Average loss: 0.2034, Accuracy: 9430/10000 (94%)
   Validation set: Average loss: 0.1857, Accuracy: 9481/10000 (95%)
   Validation set: Average loss: 0.1670, Accuracy: 9524/10000 (95%)
   Validation set: Average loss: 0.1527, Accuracy: 9562/10000 (96%)
   Validation set: Average loss: 0.1426, Accuracy: 9613/10000 (96%)
```

#### **SGD** Ir = 0.001



```
Adam (
Parameter Group 0
    amsgrad: False
   betas: (0.9, 0.999)
    eps: 1e-08
    lr: 0.001
   weight decay: 0
Validation set: Average loss: 0.0478, Accuracy: 9854/10000 (99%)
Validation set: Average loss: 0.0376, Accuracy: 9863/10000 (99%)
Validation set: Average loss: 0.0357, Accuracy: 9886/10000 (99%)
Validation set: Average loss: 0.0309, Accuracy: 9898/10000 (99%)
Validation set: Average loss: 0.0275, Accuracy: 9917/10000 (99%)
Validation set: Average loss: 0.0328, Accuracy: 9897/10000 (99%)
Validation set: Average loss: 0.0289, Accuracy: 9914/10000 (99%)
Validation set: Average loss: 0.0290, Accuracy: 9901/10000 (99%)
Validation set: Average loss: 0.0325, Accuracy: 9900/10000 (99%)
Validation set: Average loss: 0.0286, Accuracy: 9927/10000 (99%)
```

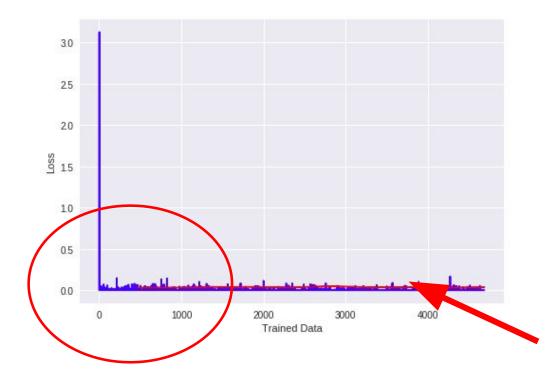
#### **ADAM** Ir = 0.001



```
RMSprop (
Parameter Group 0
    alpha: 0.99
    centered: False
    eps: 1e-08
    lr: 0.001
    momentum: 0
    weight decay: 0
Validation set: Average loss: 0.0538, Accuracy: 9868/10000 (99%)
Validation set: Average loss: 0.0702, Accuracy: 9832/10000 (98%)
Validation set: Average loss: 0.0437, Accuracy: 9915/10000 (99%)
Validation set: Average loss: 0.0293, Accuracy: 9934/10000 (99%)
Validation set: Average loss: 0.0354, Accuracy: 9924/10000 (99%)
Validation set: Average loss: 0.0454, Accuracy: 9906/10000 (99%)
Validation set: Average loss: 0.0294, Accuracy: 9937/10000 (99%)
Validation set: Average loss: 0.0357, Accuracy: 9938/10000 (99%)
Validation set: Average loss: 0.0589, Accuracy: 9893/10000 (99%)
Validation set: Average loss: 0.0461, Accuracy: 9923/10000 (99%)
```

#### RMSprop lr = 0.001



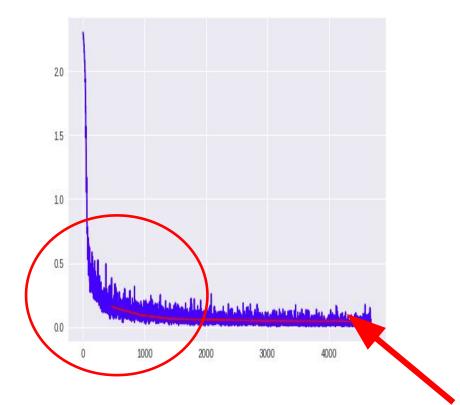


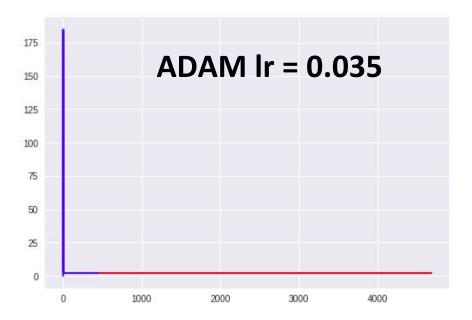
#### ADAM Ir = 0.00025

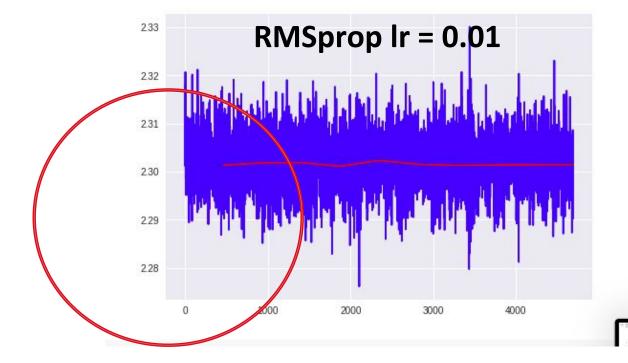
```
[18] Adam (
    Parameter Group 0
        amsgrad: False
        betas: (0.9, 0.999)
        eps: 1e-08
        lr: 0.00025
        weight decay: 0
    Validation set: Average loss: 0.0639, Accuracy: 9807/10000 (98%)
    Validation set: Average loss: 0.0472, Accuracy: 9851/1000( (99%)
    Validation set: Average loss: 0.0383, Accuracy: 9875/1000( (99%)
    Validation set: Average loss: 0.0323, Accuracy: 9898/1000( (99%)
    Validation set: Average loss: 0.0333, Accuracy: 9895/10000 (99%)
    Validation set: Average loss: 0.0420, Accuracy: 9863/1000( (99%)
    Validation set: Average loss: 0.0313, Accuracy: 9898/1000( (99%)
    Validation set: Average loss: 0.0285, Accuracy: 9916/1000( (99%)
    Validation set: Average loss: 0.0325, Accuracy: 9908/1000 (99%)
    Validation set: Average loss: 0.0293, Accuracy: 9905/1000( (99%)
```

#### **RMSprop Ir = 0.00025**

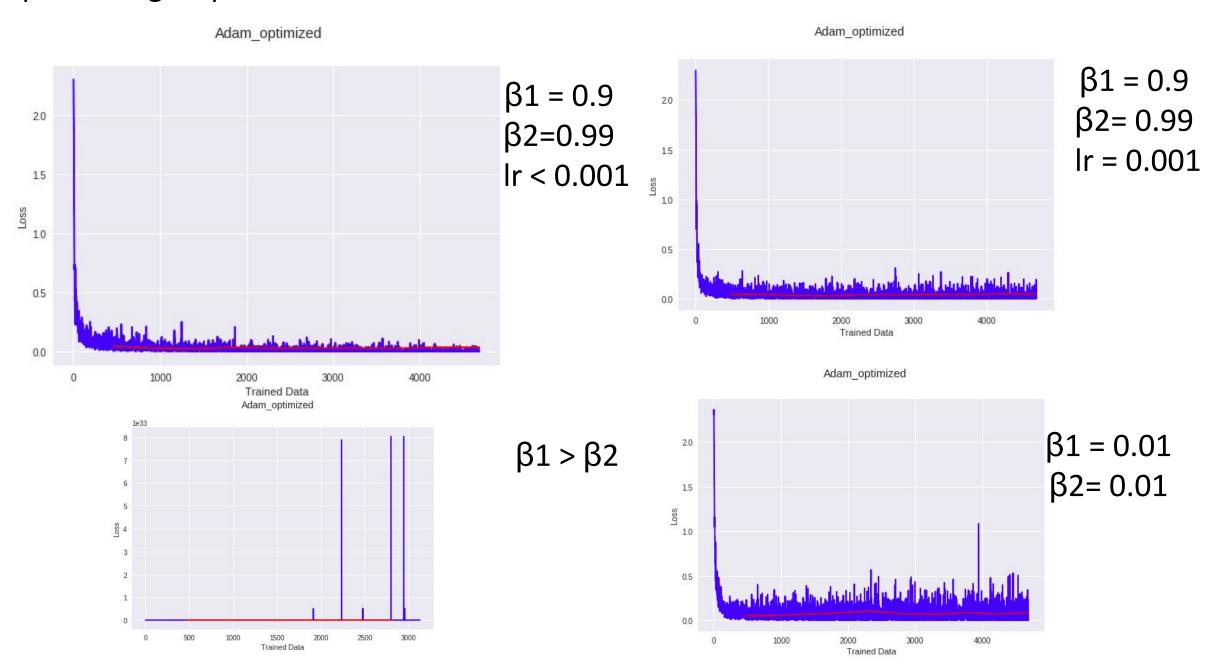
```
RMSprop (
Parameter Group 0
    alpha: 0.99
    centered: False
    eps: 1e-08
    lr: 0.00025
    momentum: 0
    weight decay: 0
Validation set: Average loss: 0.0295, Accuracy: 9911/1000 (99%)
Validation set: Average loss: 0.0285, Accuracy: 9917/1000
                                                           (99%)
Validation set: Average loss: 0.0312, Accuracy: 9911/1000
                                                           (99%)
Validation set: Average loss: 0.0316, Accuracy: 9914/1000 (99%)
Validation set: Average loss: 0.0311, Accuracy: 9917/1000
                                                           (99%)
Validation set: Average loss: 0.0415, Accuracy: 9898/1000
                                                           (99%)
Validation set: Average loss: 0.0414, Accuracy: 9890/1000
                                                           (99%)
Validation set: Average loss: 0.0409, Accuracy: 9900/1000
                                                           (99%)
Validation set: Average loss: 0.0379, Accuracy: 9917/1000
                                                           (99%)
Validation set: Average loss: 0.0344, Accuracy: 9928/1000 (99%)
```







#### Effect on the betas



## Conclusions

