Package	Description
teleop_grasp `meta`	**Project package of the teleoperation system.**
teleop_grasp	Integration of the teleoperation pipeline.

Package	Description
franka_ros `meta`	**ROS integration of Franka robot.**
franka_gazebo	Simulation of the Franka robot in Gazebo.
...	

Package	Description
franka_controllers `pkg`	ROS Control controllers for the Franka robot.
hand_tracking `pkg`	Hand pose- and gesture estimation using MediaPipe.
ros_utils `pkg`	Utilities for interfacing ROS/Gazebo/MoveIt/Eigen etc.