# Map (Room/Terrain) Synthesis for Low-Poly 3D Scenes

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Research Group:

Interactive Graphic and Simulation Group

Procedural Content Generation (PCG)

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  - Manual creation can be tedious



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  - Algorithmic process



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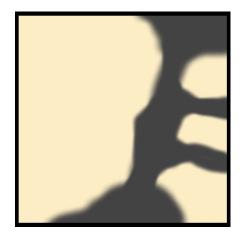
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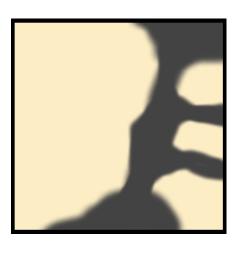
# Goal



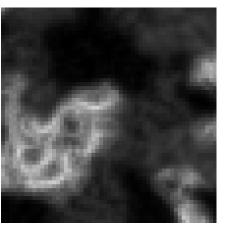
Input: 'Traversability'-Sketch



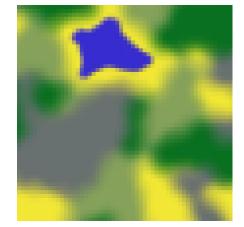
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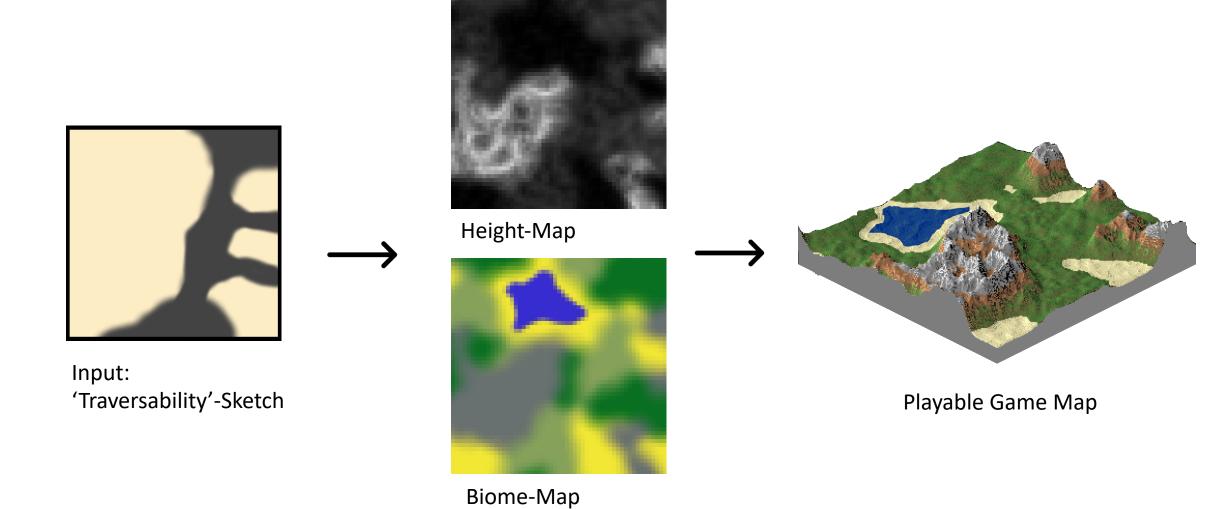
Height-Map



Biome-Map



# Goal

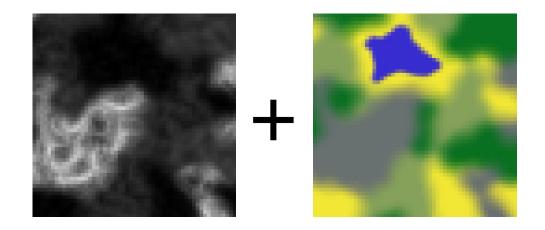




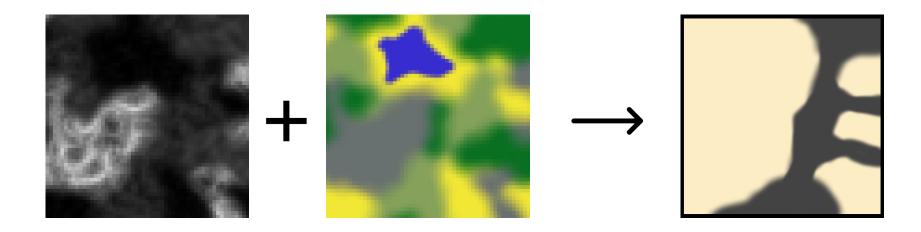
Dataset Creation



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  - Height map with a corresponding biome map



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- 3D Rendering of the Map





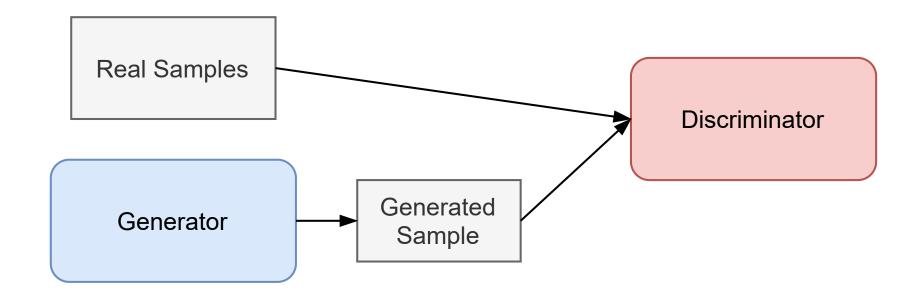
• Invented by Ian Goodfellow in 2014

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- Idea: create similar but novel data

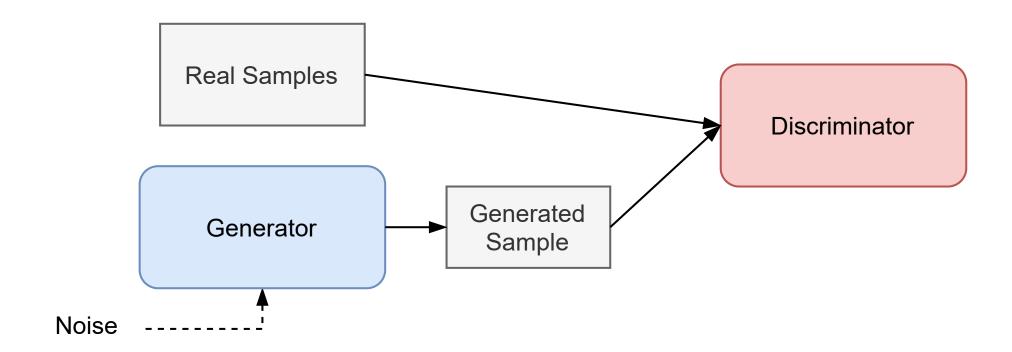


Discriminator

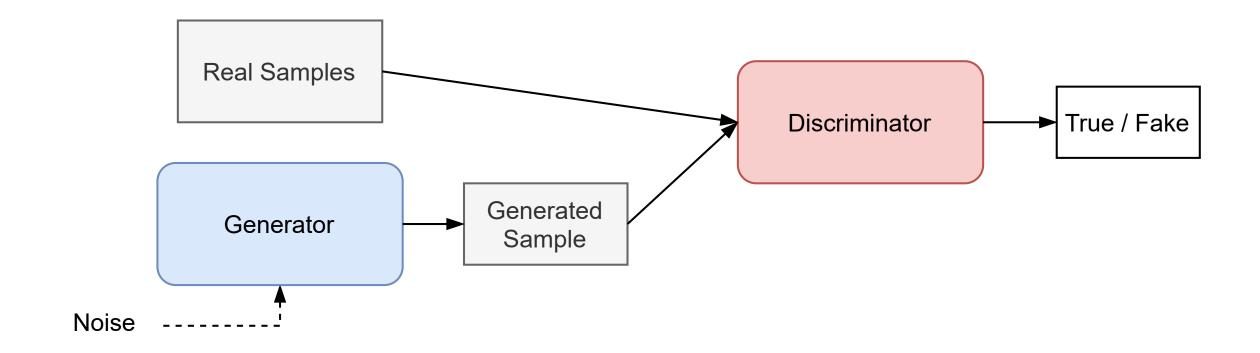




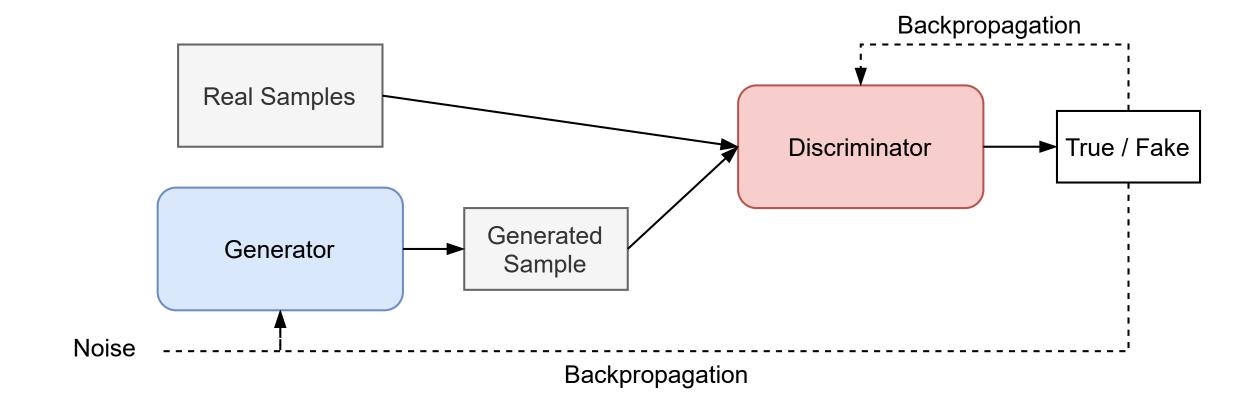






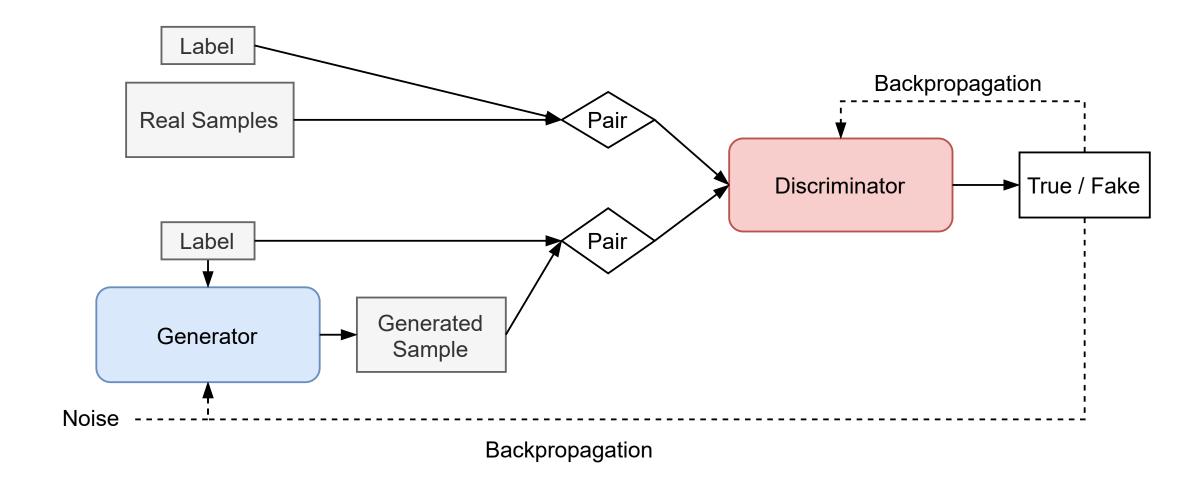






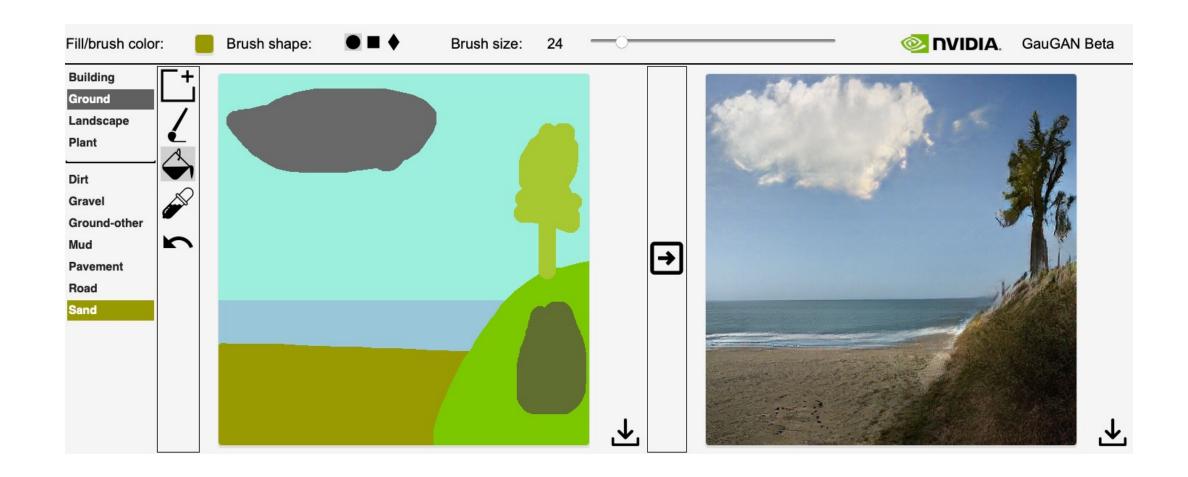


## **Conditional Generative Adversarial Networks**





# **Example – Nvidia GauGAN Beta**





# **Technologies**

- Programming Language
  - Python
- Frameworks
  - PyTorch
  - Tensorflow
- Rendering Software
  - Unity Engine



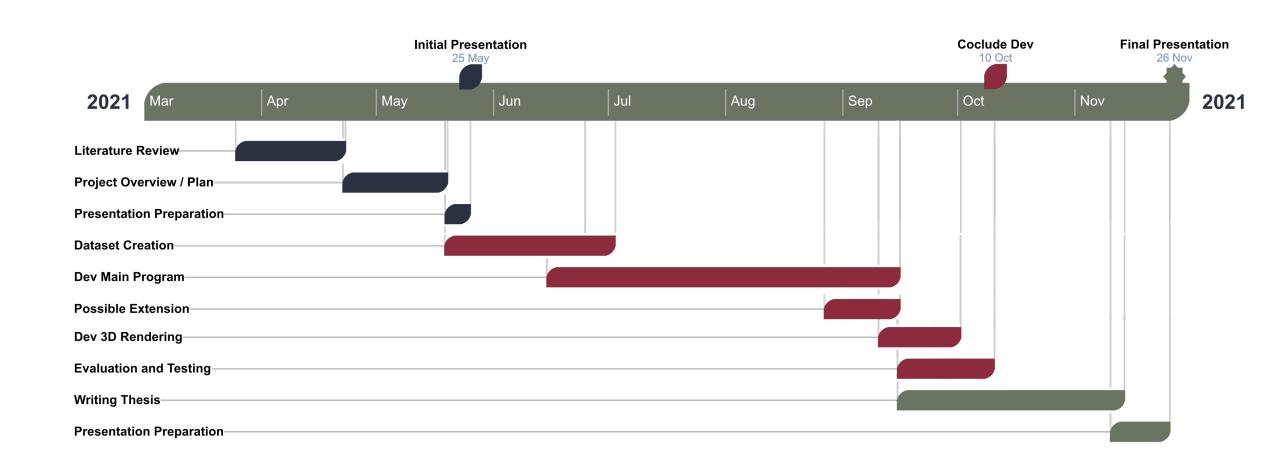








## **Timeline**





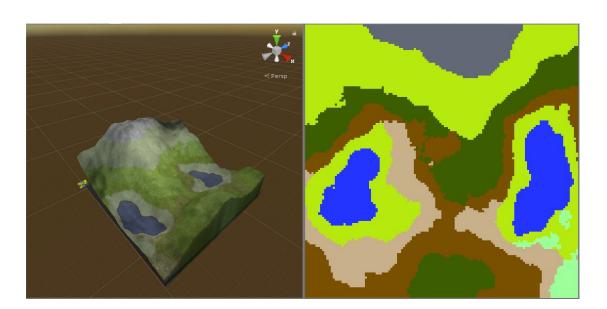
#### References

- [Liapis A., Yannakakis G.N., Togelius J. 2013] Sentient World: Human-Based Procedural Cartography. In: Machado P., McDermott J., Carballal A. (eds) Evolutionary and Biologically Inspired Music, Sound, Art and Design. EvoMUSART 2013.
- [Ping K., Dingli L. 2020] Conditional Convolutional Generative Adversarial Networks Based Interactive Procedural Game Map Generation. In: Arai K., Kapoor S., Bhatia R. (eds) Advances in Information and Communication. FICC 2020. Advances in Intelligent Systems and Computing, vol 1129
- [NoisePosti.ng] A Procedural Generation and Game Development blog, link: <a href="https://noiseposti.ng/posts/2021-03-13-Fast-Biome-Blending-Without-Squareness.html">https://noiseposti.ng/posts/2021-03-13-Fast-Biome-Blending-Without-Squareness.html</a>
- [Nvidia GauGAN] *link*: <a href="http://nvidia-research-mingyuliu.com/gaugan/">http://nvidia-research-mingyuliu.com/gaugan/</a>
- [Tensorflow] link: <a href="https://www.tensorflow.org">https://www.tensorflow.org</a>
- [Python] *link*: <a href="https://www.python.org">https://www.python.org</a>
- [PyTorch] link: <a href="https://pytorch.org">https://pytorch.org</a>
- [Unity] link: <a href="https://unity.com">https://unity.com</a>

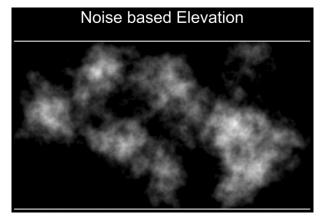


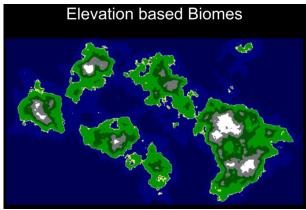
# Misc – 1 Height + Biome Map

https://github.com/pecarprimoz/procedural-gen-dipl



https://tenjix.de/projects/climate-based-biomes/

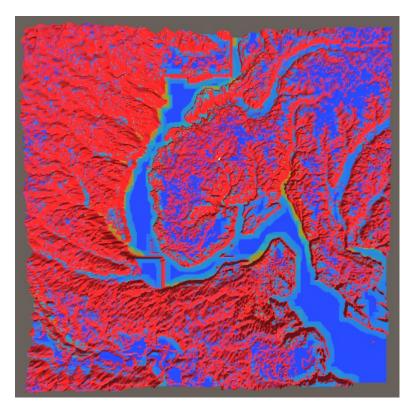




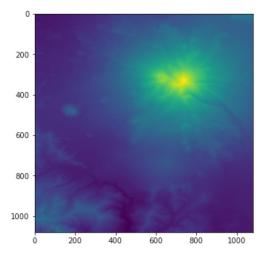


# Misc – 2 Traversability Map

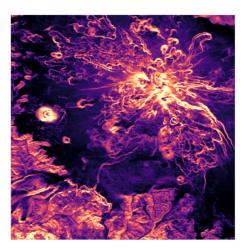
Rough Terrain Exploration With a Legged Humanoid Robot
https://github.com/misha-savchenko/Footstep\_planner



 Calculating slope and aspect from a digital elevation model in Python – Matt Oakley, Max Joseph -<a href="https://www.earthdatascience.org/tutorials/get-slope-aspect-from-digital-elevation-model/">https://www.earthdatascience.org/tutorials/get-slope-aspect-from-digital-elevation-model/</a>



Elevation (brighter = higher)



Slopes (brighter = steeper)

